nRF9161

Product Specification

v1.0



nRF9161 features

Features:

Microcontroller:

- Arm Cortex -M33
 - 247 EEMBC CoreMark score running from flash memory
 - Data watchpoint and trace (DWT), embedded trace macrocell (ETM), and instrumentation trace macrocell (ITM)
 - Serial wire debug (SWD)
 - Trace port
- 1 MB flash
- 256 kB low leakage RAM
- Arm TrustZone®
- Arm CryptoCell 310
- Up to 4x SPI master/slave with EasyDMA
- Up to 4x I2C compatible two-wire master/slave with EasyDMA
- Up to 4x UART (CTS/RTS) with EasyDMA
- I2S with EasyDMA
- Digital microphone interface (PDM) with EasyDMA
- 4x pulse width modulator (PWM) unit with EasyDMA
- 12-bit, 200 ksps ADC with EasyDMA eight configurable channels with programmable gain
- 3x 32-bit timer with counter mode
- 2x real-time counter (RTC)
- Programmable peripheral interconnect (PPI)
- 32 general purpose I/O pins
- Single supply voltage: 3.0 5.5 V
- All necessary clock sources integrated
- Package: 10 × 16 × 1.04 mm LGA

LTE modem:

- Transceiver and baseband
- 3GPP LTE release 14 Cat-M1 compliant
- 3GPP LTE release 14 Cat-NB1 and Cat-NB2 compliant
- GPS receiver
 - GPS L1 C/A supported
 - QZSS L1 C/A supported
- RF transceiver for global coverage
 - Up to 23 dBm output power
 - -108 dBm sensitivity (Cat-M1) for low band, -107 dBm for mid band
 - Single 50 Ω antenna interface
- LTE band support in hardware:
 - Cat-M1: B1, B2, B3, B4, B5, B8, B12, B13, B18, B19, B20, B25, B26, B28, B66, B85
 - Cat-NB1/NB2: B1, B2, B3, B4, B5, B8, B12, B13, B17, B19, B20, B25, B26, B28, B65, B66, B85
- Supports SIM and eSIM with an ETSI TS 102 221 compatible UICC
- Power saving features: DRX, eDRX, PSM
- IP v4/v6 stack
- Secure socket (TLS/DTLS) API

DECT NR+:

• NR+ band: 1, 2, 9

Current consumption @ 3.7 V:

- LTE power saving mode (PSM) floor current: 2.7 μA
- eDRX @ 81.92s: 19 μA in Cat-M1, 33 μA in Cat-NB1 (UICC included)

Applications:

- Sensor networks
- Logistics and asset tracking
- Smart energy
- Smart building automation
- Smart agriculture

- Industrial
- Retail and monitor devices
- Medical devices
- Wearables



4510_057 v1.0 ii

Contents

	nRF9161 features	ii
1	Revision history.	10
2	About this document.	11
	2.1 Document status.	11 11
	2.2.2 Peripheral instantiation	12
	2.3.1 Fields and values. 2.3.2 Permissions. 2.4 Registers.	. 13
	2.4.1 DUMMY	13
3	Product overview.	14
	3.1 Block diagram.	
	3.2.2 Peripherals with shared ID	. 17 . 17
	3.2.4 Bit set and clear	. 18
	3.2.6 Events.	. 18
	3.2.10 Secure/non-secure peripherals.	. 18
4	Application core	20
	4.1 CPU	. 20
	4.1.3 Electrical specification	. 21
	4.2.1 Memory map	
	4.3 VMC — Volatile memory controller. 4.3.1 Registers.	. 28
	4.4 NVMC — Non-volatile memory controller	
	4.4.2 Erasing a secure page in flash. 4.4.3 Erasing a non-secure page in flash. 4.4.4 Writing to user information configuration registers (UICR).	30
	4.4.5 Erase all	
	4.4.7 Cache. 4.4.8 Registers. 4.4.9 Electrical specification.	31 32 35



4510_057 v1.0 iii



4510_057 v1.0 iv

6.1.4 Cryptographic key selection	. 81
6.1.5 Direct memory access (DMA).	. 81
6.1.6 Standards	. 81
6.1.7 Registers	. 82
6.1.8 Host interface	. 83
6.2 DPPI - Distributed programmable peripheral interconnect.	
6.2.1 Subscribing to and publishing on channels.	
6.2.2 DPPI configuration (DPPIC)	
6.2.3 Connection examples.	
6.2.4 Special considerations for a system implementing TrustZone for Cortex-M processors.	
6.2.5 Registers	
6.3 EGU — Event generator unit.	
6.3.1 Registers.	
6.3.2 Electrical specification.	. 97 . 97
6.4 GPIO — General purpose input/output.	
6.4.1 Pin configuration.	
6.4.2 Pin sense mechanism.	
6.4.3 GPIO security	
6.4.4 Registers	
6.4.5 Electrical specification.	
6.5 GPIOTE — GPIO tasks and events	
6.5.1 Pin events and tasks	
6.5.2 Port event	
6.5.3 Tasks and events pin configuration	
6.5.4 Registers	. 109
6.6 IPC — Interprocessor communication	
6.6.1 IPC and PPI connections.	115
6.6.2 Registers	. 116
6.6.3 Electrical specification.	. 119
6.7 I2S — Inter-IC sound interface	119
6.7.1 Mode	. 120
6.7.2 Transmitting and receiving	
6.7.3 Left right clock (LRCK).	
6.7.4 Serial clock (SCK)	
6.7.5 Master clock (MCK).	. 122
6.7.6 Width, alignment, and format.	
6.7.7 EasyDMA	124
6.7.8 Module operation.	
6.7.9 Pin configuration.	
6.7.10 Registers.	
6.7.11 Electrical specification.	139
6.8 KMU — Key management unit.	
6.8.1 Functional view.	
6.8.2 Access control.	
6.8.3 Protecting the UICR content.	140
6.8.4 Usage	
6.8.5 Registers.	
6.9 PDM — Pulse density modulation interface	
6.9.1 Master clock generator.	149
6.9.2 Module operation.	
6.9.3 Decimation filter	150
6.9.4 EasyDMA	150
6.9.5 Hardware example	151
6.9.6 Pin configuration	152



4510_057 v1.0 V

6.9.7 Registers	152
6.9.8 Electrical specification.	161
6.10 PWM — Pulse width modulation	161
6.10.1 Wave counter	162
6.10.2 Decoder with EasyDMA.	165
6.10.3 Limitations	173
	173
	173
	184
	185
	185
	186
	186
	187
	187
	187
·	189
, ,	
9	191
11 8 8	199
	199
	200
9 1	201
· ·	201
,	203
	204
	205
6.12.8 Acquisition time	205
6.12.9 Limits event monitoring.	206
6.12.10 Registers	207
· ·	224
6.12.12 Performance factors	225
	225
6.13.1 SPI master transaction sequence	226
6.13.2 Master mode pin configuration.	227
	228
	228
·	228
·	229
	240
·	241
·	242
	242
•	242
	244
	245
	245
·	255
,	257
'	257
	258
	261
'	264
	266
6.15.6 DPPI access control	266



6.15.7 External domain access control	. 268
6.15.8 TrustZone for Cortex-M ID allocation	269
6.15.9 Registers	270
6.16 TIMER — Timer/counter	279
6.16.1 Capture	280
6.16.2 Compare	280
6.16.3 Task delays	280
6.16.4 Task priority	280
6.16.5 Registers	281
6.17 TWIM $- I^2C$ compatible two-wire interface master with EasyDMA	288
6.17.1 Shared resources	289
6.17.2 EasyDMA	289
6.17.3 Master write sequence.	290
6.17.4 Master read sequence	290
6.17.5 Master repeated start sequence	291
6.17.6 Low power	292
6.17.7 Master mode pin configuration.	
6.17.8 Registers.	
6.17.9 Electrical specification.	307
6.17.10 Pullup resistor.	308
$6.18 \text{ TWIS} - I^2 \text{C}$ compatible two-wire interface slave with EasyDMA	308
6.18.1 Shared resources.	310
6.18.2 EasyDMA.	
6.18.3 TWI slave responding to a read command.	
6.18.4 TWI slave responding to a write command	
6.18.5 Master repeated start sequence.	313
6.18.6 Terminating an ongoing TWI transaction.	
6.18.7 Low power.	314
6.18.8 Slave mode pin configuration.	314
6.18.9 Registers.	314
6.18.10 Electrical specification.	328
6.19 UARTE — Universal asynchronous receiver/transmitter with EasyDMA	328
6.19.1 EasyDMA.	329
6.19.2 Transmission.	329
	. 330
6.19.3 Reception.	. 330 332
6.19.4 Error conditions.	
6.19.5 Using the UARTE without flow control.	
6.19.6 Parity and stop bit configuration.	332 332
6.19.7 Low power.	
6.19.8 Pin configuration.	
6.19.9 Registers.	333
6.19.10 Electrical specification.	351
6.20 WDT — Watchdog timer.	351
6.20.1 Reload criteria.	
6.20.2 Temporarily pausing the watchdog.	352
6.20.3 Watchdog reset.	352
6.20.4 Registers	352
6.20.5 Electrical specification	356
	o = =
LTE modem	357
7.1 SIM card interface	358
7.2 LTE coexistence interface	359
7.3 LTE RF control external interface	360
7.4 RF front-end interface	361

4510_057 v1.0 vii

7



	7.5 Registers	361
	7.6 Electrical specification	361
	7.6.1 Key RF parameters for Cat-M1	361
	7.6.2 Key RF parameters for Cat-NB1 and Cat-NB2.	. 361
	7.6.3 Receiver parameters for Cat-M1.	362
	7.6.4 Receiver parameters for Cat-NB1 and Cat-NB2.	362
	7.6.5 Transmitter parameters for Cat-M1.	362
	7.6.6 Transmitter parameters for Cat-NB1 and Cat-NB2.	
8	DECT NR+	363
	8.1 massive Machine Type Communication (mMTC)	364
	8.2 Ultra-Reliable Low-Latency Communication (URLLC).	364
	8.3 DECT NR+ on the nRF9161	. 364
	8.4 Key RF Parameters	
	8.5 DECT NR+ coexistence interface	
9	GPS receiver.	366
	9.1 Electrical specification.	366
	3.1 Electrical Specimeation.	. 500
10	Debug and trace.	368
	10.1 DAP - Debug access port	368
	10.2 Access port protection	369
	10.2.2 Registers	371
	10.3 Debug interface mode	373
	10.4 Real-time debug.	. 373
	10.5 Registers	373
	10.5.1 TARGETID	. 373
	10.6 Electrical specification.	374
	10.6.1 Trace port	374
	10.7 Trace	374
	10.7.1 ATB Funnel	375
	10.7.2 ATB Replicator.	. 382
	10.7.3 ETB — Embedded trace buffer.	
	10.7.4 ETM — Embedded trace macrocell	402
	10.7.5 TPIU — Trace port interface unit	423
	10.8 CTRL-AP - Control access port.	437
	10.8.1 Reset request	438
	10.8.2 Erase all	438
	10.8.3 Mailbox interface.	438
	10.8.4 Disabling erase protection.	439
	10.8.5 Debugger registers.	
	10.8.6 Registers	443
	10.9 TAD - Trace and debug control.	. 445
	10.9.1 Registers.	445
11	Hardware and layout	1 E0
тт	•	
	11.1 Pin assignments.	
	11.1.1 LGA pin assignments.	450
	11.2 Mechanical specifications	
	11.2.1 16.0 x 10.5 mm package	453
	11.3 Reference circuitry.	
	11.3.1 nRF9161 reference design	454



4510_057 v1.0 viii

	11.4 Reflow conditions	
12	Operating conditions.	455
	12.1 VDD_GPIO considerations	455
13	Absolute maximum ratings	456
14	Ordering information.	457
	14.1 SiP marking	457
	14.2 Box labels	457
	14.3 Order code	
	14.4 Code ranges and values	459 460
15	Regulatory information.	461
13	- ,	_
	15.1 Certified bands	461 462
	15.3 FCC/ISED regulatory notices	
	15.4 RF exposure considerations.	465
	15.5 Host device manufacturer responsibility.	465
	15.6 Antenna interface	465
	15.7 Antenna port test connector	466
16	Legal notices.	467



4510_057 v1.0 ix

1 Revision history

Date	Version	Description
January 2024	1.0	First release



2 About this document

This document is organized into chapters that are based on the modules and peripherals available in the IC.

2.1 Document status

The document status reflects the level of maturity of the document.

Document name	Description
Objective Product Specification (OPS)	Applies to document versions up to 1.0. This document contains target specifications for product development.
Product Specification (PS)	Applies to document versions 1.0 and higher. This document contains final product specifications. Nordic Semiconductor ASA reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

Table 1: Defined document names

2.2 Peripheral chapters

Every peripheral has a unique capitalized name or an abbreviation of its name, e.g. TIMER, used for identification and reference. This name is used in chapter headings and references, and it will appear in the Arm Cortex Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer to identify the peripheral.

The peripheral instance name, which is different from the peripheral name, is constructed using the peripheral name followed by a numbered postfix, starting with 0, for example, TIMERO. A postfix is normally only used if a peripheral can be instantiated more than once. The peripheral instance name is also used in the CMSIS to identify the peripheral instance.

The chapters describing peripherals may include the following information:

- A detailed functional description of the peripheral.
- The register configuration for the peripheral.
- The electrical specification tables, containing performance data which apply for the operating conditions described in Operating conditions on page 455.

2.2.2 Peripheral instantiation

The peripherals have a set of security capabilities listed in the instantiation tables.

The following table describes the abbreviations used.



Abbreviation	Description
NS	Trustzone/security attribute is Non-secure - The peripheral is always accessible as a Non-secure peripheral.
S	Trustzone/security attribute is Secure - The peripheral is always accessible as a Secure peripheral.
US	Trustzone Map is user selectable - The Trustzone/security attribute of the peripheral is configurable.
HF	Trustzone Map is Hardware Fixed - The Trustzone/security attribute of the peripheral cannot be changed.
NA	Not Applicable - Peripheral has no DMA capability.
NSA	NoSeparateAttribute - Peripheral with DMA and DMA transfer has the same security attribute as assigned to the peripheral.
SA	SeparateAttribute - Peripheral with DMA and DMA transfers can have a different security attribute than the one assigned to the peripheral.

Table 2: Instantiation table abbreviations

The Secure mapping column in the peripheral instantiation table defines configuration capabilities for the Arm TrustZone for Armv8-M secure attribute. The DMA security column describes the DMA capabilities of the peripheral.

The instantiation table has the following columns:

- Instance Column Indicates the peripheral instance name followed by optional Trustzone attribute. A corresponding address is listed in Base address column indicating the base address for Secure and Non-secure Trustzone attribute. This optional Trustzone attribute is separated by a colon (:).
- Trustzone Column This has 3 sub-columns indicating the Trustzone map, Trustzone attribute and DMA capability. The options are as listed in Instantiation table abbreviations on page 12.

2.3 Register tables

Individual registers are described using register tables. These tables are built up of two sections. The first three colored rows describe the position and size of the different fields in the register. The following rows describe the fields in more detail.

2.3.1 Fields and values

The **Id (Field Id)** row specifies the bits that belong to the different fields in the register. If a field has enumerated values, then every value will be identified with a unique value id in the **Value Id** column.

A blank space means that the field is reserved and read as undefined, and it also must be written as 0 to secure forward compatibility. If a register is divided into more than one field, a unique field name is specified for each field in the **Field** column. The **Value Id** may be omitted in the single-bit bit fields when values can be substituted with a Boolean type enumerator range, e.g. true/false, disable(d)/enable(d), on/ off, and so on.

Values are usually provided as decimal or hexadecimal. Hexadecimal values have a $0 \times$ prefix, decimal values have no prefix.

The Value column can be populated in the following ways:

- Individual enumerated values, for example 1, 3, 9.
- Range of values, e.g. [0..4], indicating all values from and including 0 and 4.

NORDIC

• Implicit values. If no values are indicated in the **Value** column, all bit combinations are supported, or alternatively the field's translation and limitations are described in the text instead.

If two or more fields are closely related, the **Value Id**, **Value**, and **Description** may be omitted for all but the first field. Subsequent fields will indicate inheritance with '..'.

A feature marked **Deprecated** should not be used for new designs.

2.3.2 Permissions

Different fields in a register might have different access permissions enforced by hardware.

The access permission for each register field is documented in the Access column in the following ways:

Access	Description	Hardware behavior
RO	Read-only	Field can only be read. A write will be ignored.
WO	Write-only	Field can only be written. A read will return an undefined value.
RW	Read-write	Field can be read and written multiple times.
W1	Write-once	Field can only be written once per reset. Any subsequent write will be ignored. A read will return an undefined value.
RW1	Read-write-once	Field can be read multiple times, but only written once per reset. Any subsequent write will be ignored.
W1C	Write 1 to clear	Field can be read multiple times. A one clears (set to zero) the corresponding bit in the register. Bits set to zero are ignored.
W1S	Write 1 to set	Field can be read multiple times. A one sets the corresponding bit in the register. Bits set to zero are ignored.

Table 3: Register field permission schemes

2.4 Registers

Register overview

Register	Offset	Description
DUMMY	0x514	Example of a register controlling a dummy feature

2.4.1 DUMMY

Address offset: 0x514

Example of a register controlling a dummy feature

Bit n	umber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	1 0		
ID			D D D D C C C B	Α		
Rese	t 0x00050002		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1 0		
ID						
-A	RW FIELD0		Example of a read-write field with several enumerated values			
		Disabled	The example feature is disabled			
		NormalMode	1 The example feature is enabled in normal mode			
		ExtendedMode	2 The example feature is enabled along with extra functionality			
В	RW FIELD1		Example of a deprecated read-write field			
			This field is deprecated.			
		Disabled	0 The override feature is disabled			
		Enabled	1 The override feature is enabled			
С	RW FIELD2		Example of a read-write field with a valid range of values			
		ValidRange	[27] Example of allowed values for this field			
D	RW FIELD3		Example of a read-write field with no restriction on the values			



3 Product overview

The nRF9161 System-in-Package (SiP) is a low-power IoT (Internet of Things) solution integrating an Arm Cortex-M33 processor with advanced security features, a range of peripherals and a Low-Power Wide-Area (LPWA) network processor. The LPWA network processor can operate as a 5G DECT NR+ (NR+) device, independent of cellular network provider or as an LTE modem compliant with 3GPP LTE release 14 Cat-M1 and Cat-NB1/NB2 standards.

The LPWA network processor integrates a flexible transceiver with frequency range 700 MHz to 2200 MHz, through a single $50~\Omega$ antenna pin and a baseband processor. NR+ or LTE operation is supported depending on which network protocol firmware the customer installs on the LPWA network processor of the nRF9161. Nordic Semiconductor provides firmware to support NR+ or LTE, layers L1-L3 and upper IP layers, providing a secure socket API to the application.

The nRF9161 LPWA network processor also integrate a GPS receiver, enabling local positioning support when supported by the installed firmware.

The Arm Cortex-M33 processor is exclusively for the user application, with 1 MB of flash and 256 kB of RAM dedicated for this. The M33 application processor shares the power, clock, and peripheral architecture with Nordic Semiconductor nRF5 Series of PAN/LAN SoCs, ensuring minimal porting efforts.

The peripheral set offers a variety of analog and digital functionality enabling single-chip implementation of a wide range of IoT applications. Arm TrustZone technology, CryptoCell 310 and supporting blocks for system protection and key management, are embedded to enable advanced security needed for IoT applications.

3.1 Block diagram

The block diagram illustrates the overall system. Arrows with white heads indicate signals that share physical pins with other signals.



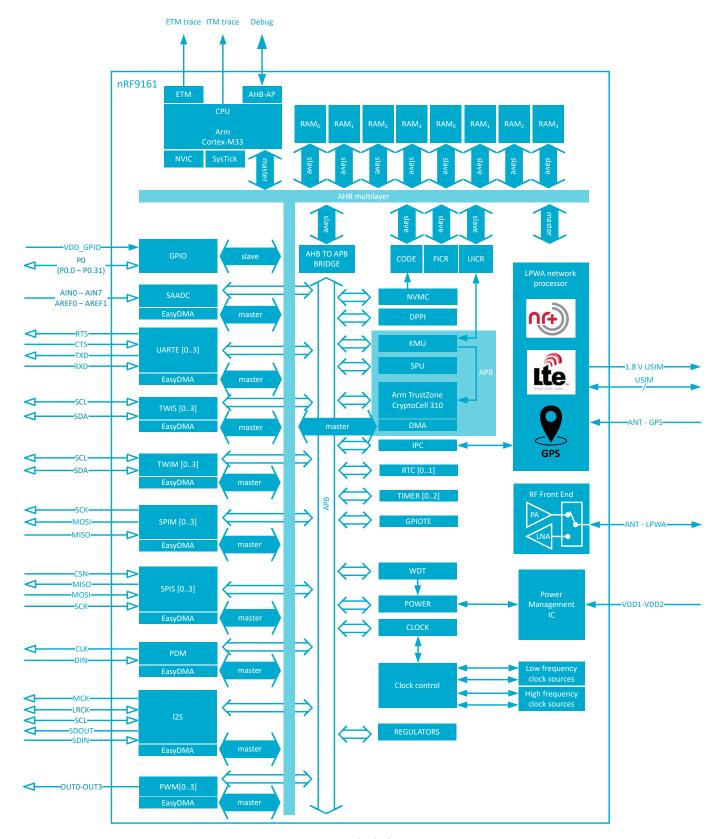


Figure 1: Block diagram

3.2 Peripheral interface

Peripherals are controlled by the CPU through configuration registers, as well as task and event registers. Task registers are inputs, enabling the CPU and other peripherals to initiate a functionality. Event registers



Channel inputs from DPPI

EN SUBSCRIBE in CHIDX

TASK in Write

OR SHORTS

Peripheral core event

EVENT in EVENT in EVENT in IRQ signal to NVIC

are outputs, enabling a peripheral to trigger tasks in other peripherals and/or the CPU by tying events to CPU interrupts.

Figure 2: Peripheral interface

Channel outputs to DPPI

The distributed programmable peripheral interconnect (DPPI) feature enables peripherals to connect events to tasks without CPU intervention. For more information on DPPI and the DPPI channels, see DPPI - Distributed programmable peripheral interconnect on page 86.

3.2.1 Peripheral ID

Every peripheral is assigned a fixed block of 0x1000 bytes of address space, which is equal to 1024 x 32-bit registers.

See Instantiation on page 25 for more information about which peripherals are available and where they are located in the address map.

There is a direct relationship between peripheral ID and base address. For example, a peripheral with base address 0x40000000 is assigned ID=0, a peripheral with base address 0x40001000 is assigned ID=1, and a peripheral with base address 0x4001F000 is assigned ID=31.

Peripherals may share the same ID, which may impose one or more of the following limitations:

- Shared registers or common resources
- Limited availability due to mutually exclusive operation; only one peripheral in use at a time

• Enforced peripheral behavior when switching between peripherals (disable the first peripheral before enabling the second)

3.2.2 Peripherals with shared ID

In general (with the exception of ID 0), peripherals sharing an ID and base address may not be used simultaneously. Only one peripheral can be enabled at a given ID.

When switching between two peripherals sharing an ID, the following should be performed to prevent unwanted behavior:

- 1. Disable the previously used peripheral.
- 2. Disable any publish/subscribe connection to the DPPI system for the peripheral that is being disabled.
- 3. Clear all bits in the INTEN register, i.e. INTENCLR = 0xFFFFFFFF.
- **4.** Explicitly configure the peripheral being enabled. Do not rely on inherited configuration from the disabled peripheral.
- **5.** Enable the now configured peripheral.

For a list of which peripherals that share an ID see Instantiation on page 25.

3.2.3 Peripheral registers

Most peripherals feature an ENABLE register. Unless otherwise specified, the peripheral registers must be configured before enabling the peripheral.

PSEL registers need to be set before a peripheral is enabled or started. Updating PSEL registers while the peripheral is running has no effect. To connect a peripheral to a different GPIO, the following must be performed:

- 1. Disable the peripheral.
- 2. Update the PSEL register.
- 3. Re-enable the peripheral.

It takes four CPU cycles between the PSEL register update and the connection between a peripheral and a GPIO becoming effective.

Note: The peripheral must be enabled before tasks and events can be used.

Most of the register values are lost during System OFF or when a reset is triggered. Some registers will retain their values in System OFF or for some specific reset sources. These registers are marked as retained in the register description for a given peripheral. For more information on their behavior, see chapter Reset on page 56.

3.2.4 Bit set and clear

Registers with multiple single-bit bit fields may implement the set-and-clear pattern. This pattern enables firmware to set and clear individual bits in a register without having to perform a read-modify-write operation on the main register.

This pattern is implemented using three consecutive addresses in the register map, where the main register is followed by dedicated SET and CLR registers (in that exact order).

In the main register, the SET register sets individual bits and the CLR register clears them. Writing 1 to a bit in the SET or CLR register will set or clear the same bit in the main register respectively. Writing 0 to a bit in the SET or CLR register has no effect. Reading the SET or CLR register returns the value of the main register.

Note: The main register may not be visible and therefore not directly accessible in all cases.



3.2.5 Tasks

Tasks are used to trigger actions in a peripheral, such as to start a particular behavior. A peripheral can implement multiple tasks with each task having a separate register in that peripheral's task register group.

A task is triggered when firmware writes 1 to the task register, or when the peripheral itself or another peripheral toggles the corresponding task signal. See the figure Peripheral interface on page 16.

3.2.6 Events

Events are used to notify peripherals and the CPU about events that have happened, for example a state change in a peripheral. A peripheral may generate multiple events, where each event has a separate register in that peripheral's event register group.

An event is generated when the peripheral itself toggles the corresponding event signal, and the event register is updated to reflect that the event has been generated, see figure Peripheral interface on page 16. An event register is cleared when a 0 is written to it by firmware. Events can be generated by the peripheral even when the event register is set to 1.

3.2.7 Publish and subscribe

Events and tasks from different peripherals can be connected together through the DPPI system using the PUBLISH and SUBSCRIBE registers in each peripheral. See Peripheral interface on page 16. An event can be published onto a DPPI channel by configuring the event's PUBLISH register. Similarly, a task can subscribe to a DPPI channel by configuring the task's SUBSCRIBE register.

See DPPI - Distributed programmable peripheral interconnect on page 86 for details.

3.2.8 Shortcuts

A shortcut is a direct connection between an event and a task within the same peripheral. If a shortcut is enabled, the associated task is automatically triggered when its associated event is generated.

Using shortcuts is equivalent to making the connection outside the peripheral and through the DPPI. However, the propagation delay when using shortcuts is usually shorter than the propagation delay through the DPPI.

Shortcuts are predefined, which means that their connections cannot be configured by firmware. Each shortcut can be individually enabled or disabled through the shortcut register, one bit per shortcut, giving a maximum of 32 shortcuts for each peripheral.

3.2.9 Interrupts

All peripherals support interrupts which are generated by events.

A peripheral only occupies one interrupt, and the interrupt number follows the peripheral ID. For example, the peripheral with ID=4 is connected to interrupt number 4 in the nested vectored interrupt controller (NVIC).

Using registers INTEN, INTENSET, and INTENCLR, every event generated by a peripheral can be configured to generate that peripheral's interrupt. Multiple events can be enabled to generate interrupts simultaneously. To resolve the correct interrupt source, the event registers in the event group of peripheral registers will indicate the source.

Some peripherals implement only INTENSET and INTENCLR registers, and the INTEN register is not available on those peripherals. See the individual peripheral chapters for details. In all cases, reading back the INTENSET or INTENCLR register returns the same information as in INTEN.

Each event implemented in the peripheral is associated with a specific bit position in the INTEN, INTENSET, and INTENCLR registers.



The relationship between tasks, events, shortcuts, and interrupts is illustrated in figure Peripheral interface on page 16.

3.2.9.1 Interrupt clearing and disabling

Interrupts should always be cleared by writing 0 to the corresponding EVENT register.

Until cleared, interrupts will immediately be re-triggered and cause software interrupt service routines to be executed repeatedly.

Because the clearing of the EVENT register may take a number of CPU clock cycles, the program should perform a read from the EVENT register that has been cleared before exiting the interrupt service routine. This will ensure that the EVENT clearing has taken place before the interrupt service routine is exited. Care should be taken to ensure that the compiler does not remove the read operation as an optimization.

Similarly, when disabling an interrupt inside an interrupt service routine, the program should perform a read from the INTEN or INTENCLR registers to ensure that the interrupt is disabled before exiting the interrupt service routine.

3.2.10 Secure/non-secure peripherals

For some peripherals, the security configuration can change from secure to non-secure, or vice versa. Care must be taken when changing the security configuration of a peripheral, to prevent security information leakage and ensure correct operation.

The following sequence should be followed, where applicable, when configuring and changing the security settings of a peripheral in the SPU — System protection unit on page 257.

- 1. Stop peripheral operation.
- 2. Disable the peripheral.
- 3. Remove pin connections.
- 4. Disable DPPI connections.
- 5. Clear sensitive registers (e.g. writing back default values).
- **6.** Change peripheral security setting in the SPU System protection unit on page 257.
- **7.** Re-enable the peripheral.

Note: Changing security settings on a peripheral during runtime is not advisable.



4 Application core

The nRF9161 application core has a modern and powerful Arm Cortex-M33 with on-chip flash and RAM exclusively for application use.

4.1 CPU

The Arm Cortex-M33 processor has a 32-bit instruction set (Thumb[®]-2 technology) that implements a superset of 16 and 32-bit instructions to maximize code density and performance.

This processor implements several features that enable energy-efficient arithmetic and high-performance signal processing, including:

- Digital signal processing (DSP) instructions
- Single-cycle multiply and accumulate (MAC) instructions
- Hardware divide
- 8- and 16-bit single instruction, multiple data (SIMD) instructions
- Single-precision floating-point unit (FPU)
- Memory Protection Unit (MPU)
- Arm TrustZone for ARMv8-M

The Arm Cortex Common Microcontroller Software Interface Standard (CMSIS) hardware abstraction layer for the Arm Cortex processor series is implemented and available for the M33 CPU.

Real-time execution is highly deterministic in thread mode, to and from sleep modes, and when handling events at configurable priority levels via the nested vectored interrupt controller (NVIC).

Executing code from internal or external flash will have a wait state penalty. The instruction cache can be enabled to minimize flash wait states when fetching instructions. For more information on cache, see Cache on page 31. The section Electrical specification on page 21 shows CPU performance parameters including the wait states in different modes, CPU current and efficiency, and processing power and efficiency based on the CoreMark® benchmark.

4.1.1 Floating-point interrupt

The floating-point unit (FPU) might generate exceptions when used (for example, due to overflow or underflow), which trigger the FPU interrupt.

See Instantiation on page 25 for more information about which exception number (peripheral ID) is triggered by an FPU exception.

The FPU is not affected by any security configuration. It is presented as non-secure in register PERIPHID[n].PERM. See SPU — System protection unit on page 257 for more information.

To clear the IRQ (interrupt request) line when an exception occurs, the relevant exception bit within the floating-point status and control register (FPSCR) must be cleared. For more information about the FPSCR or other FPU registers, see the *Arm Cortex-M33 Devices Generic User Guide*.

4.1.2 CPU and support module configuration

The Arm Cortex-M33 processor has a number of CPU options and support modules implemented on the device.



Option / Module	Description	Implemented
Core options		
NVIC	Nested vectored interrupt controller	YES
PRIORITIES	Priority bits	3
WIC	Wake-up interrupt controller	NO
Endianness	Memory system endianness	Little endian
DWT	Data watchpoint and trace	YES
Modules		
MPU_NS	Number of non-secure memory protection unit (MPU) regions	16
MPU_S	Number of secure MPU regions	16
SAU	Number of security attribution unit (SAU) regions	0, see SPU for more information about
		secure regions.
FPU	Floating-point unit	YES
DSP	Digital signal processing extension	YES
ARMv8-M TrustZone	ARMv8-M security extensions	YES
CPIF	Co-processor interface	NO
ETM	Embedded trace macrocell	YES
ITM	Instrumentation trace macrocell	YES
МТВ	Micro trace buffer	NO
СТІ	Cross trigger interface	YES
BPU	Breakpoint unit	YES
HTM	AMBA® AHB trace macrocell	NO

4.1.3 Electrical specification

4.1.3.1 CPU performance

The CPU clock speed is 64 MHz. Current and efficiency data is taken when in System ON and the CPU is executing the CoreMark benchmark. It includes power regulator and clock base currents. All other blocks are IDLE.

Symbol	Description	Min.	Тур.	Max.	Units
W _{FLASH}	CPU wait states, running from flash, cache disabled	0		4	
W _{FLASHCACHE}	CPU wait states, running from flash, cache enabled	0		2	
W _{RAM}	CPU wait states, running from RAM			0	
CM_{FLASH}	CoreMark ¹ , running from flash, cache enabled		247		CoreMark
CM _{FLASH/MHz}	CoreMark per MHz, running from flash, cache enabled		3.86		CoreMark/
					MHz
CM _{FLASH/mA}	CoreMark per mA, running from flash, cache enabled		91		CoreMark/mA

4.2 Memory

The application microcontroller has embedded 1024 kB flash and 256 kB RAM for application code and data storage.

As illustrated in Memory layout on page 22, both CPU and EasyDMA are able to access RAM via the AHB multilayer interconnect. See AHB multilayer interconnect on page 46 and EasyDMA on page 43 for more information about AHB multilayer interconnect and EasyDMA respectively. The LTE modem can access all application MCU memory, but typically a small portion of RAM is dedicated to data exchange between application MCU and the modem baseband controller.

NORDIC*

¹ Using armclang compiler

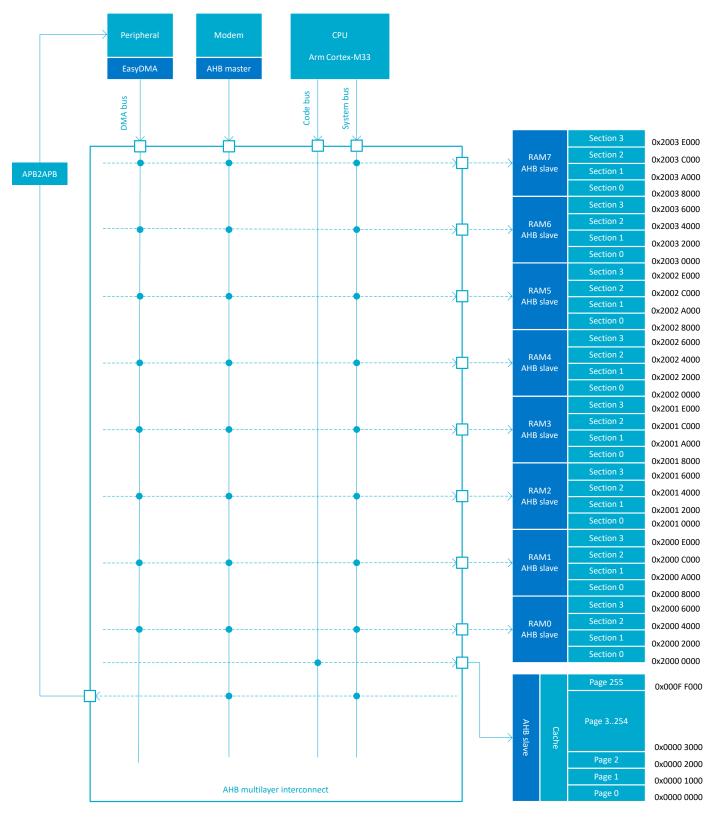


Figure 3: Memory layout

RAM - Random access memory

RAM can be read and written an unlimited number of times by the CPU and the EasyDMA.

Each RAM AHB slave is connected to one or more RAM sections. See Memory layout on page 22 for more information.



The RAM blocks power states and retention states in System ON and System OFF modes are controlled by the VMC.

Flash - Non-volatile memory

Flash can be read an unlimited number of times by the CPU and is accessible via the AHB interface connected to the CPU, see Memory layout on page 22 for more information. There are restrictions on the number of times flash can be written and erased, and also on how it can be written. For more information, see Absolute maximum ratings on page 456. Writing to flash is managed by the non-volatile memory controller (NVMC).

4.2.1 Memory map

All memory and registers are found in the same address space, as illustrated in the device memory map below.



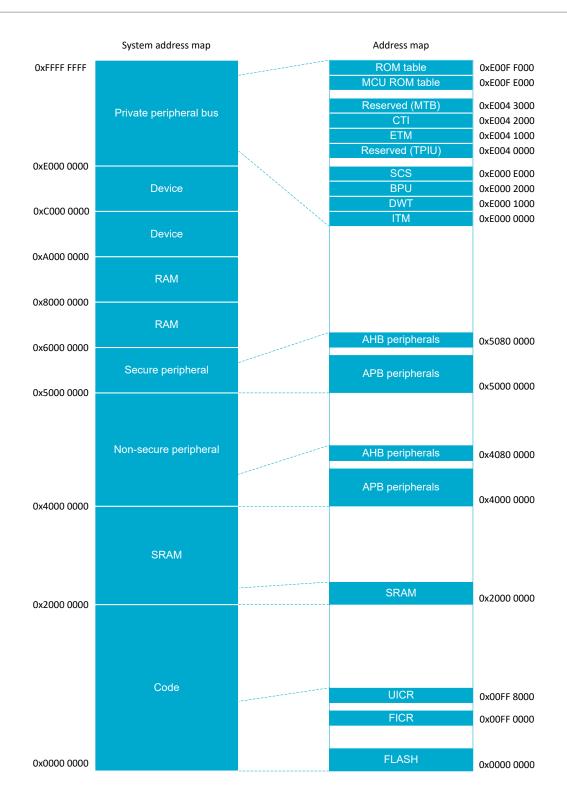


Figure 4: Memory map

Some of the registers are retained (their values kept). Read more about retained registers in Retained registers on page 57 and Reset behavior on page 57.



4.2.2 Instantiation

ID	Base address	Instance	TrustZone			Split access	Description						
			Мар	Att	DMA								
3	0x50003000	SPU	HF	S	NA	No	System Protection Unit						
4	0x50004000	REGULATORS : S	US	NS	NA	No	Degulator configuration						
4	0x40004000	REGULATORS : NS	US	IND	NA	No	Regulator configuration						
5	0x50005000	CLOCK: S	US	NS	NA	No	Clock control						
,	0x40005000	CLOCK : NS	03	145	IVA	140							
5	0x50005000	POWER: S	US	NS	NA	No	Power control						
	0x40005000	POWER : NS											
6	0x50006000	CTRL_AP_PERI	HF	S	NA	No	CTRL-AP-PERI						
8	0x50008000	SPIM0 : S	US	NS	SA	No	SPI master 0						
	0x40008000	SPIM0 : NS											
8	0x50008000	SPISO : S	US	NS	SA	No	SPI slave 0						
	0x40008000	SPISO : NS											
8	0x50008000	TWIMO: S	US	NS	SA	No	Two-wire interface master 0						
	0x40008000	TWINO : NS											
8	0x50008000 0x40008000	TWIS0 : S TWIS0 : NS	US	NS	SA	No	Two-wire interface slave 0						
	0x40008000	UARTEO: S					Universal asynchronous receiver/transmitter with						
8	0x40008000	UARTEO: NS	US	NS	SA	No	EasyDMA 0						
	0x50009000	SPIM1:S					Lusyellinto						
9	0x40009000	SPIM1 : NS	US	NS	SA	No	SPI master 1						
	0x50009000	SPIS1 : S											
9	0x40009000	SPIS1 : NS	US	NS	SA	No	SPI slave 1						
	0x50009000	TWIM1 : S											
9	0x40009000	TWIM1 : NS	US	NS	SA	No	Two-wire interface master 1						
	0x50009000	TWIS1 : S											
9	0x40009000	TWIS1: NS	US	NS	SA	No	Two-wire interface slave 1						
0	0x50009000	UARTE1: S	uc	NC	C A	NI-	Universal asynchronous receiver/transmitter with						
9	0x40009000	UARTE1: NS	US	NS	SA	No	EasyDMA 1						
10	0x5000A000	SPIM2 : S	US	NS	SA	No	SPI master 2						
10	0x4000A000	SPIM2 : NS	03	NS	JA.	NO	SFI Master 2						
10	0x5000A000	SPIS2 : S	US	NS	SA	No	SPI slave 2						
	0x4000A000	SPIS2 : NS	00		57.		5.1.5.0.1.2.2						
10	0x5000A000	TWIM2 : S	US	NS	SA	No	Two-wire interface master 2						
	0x4000A000	TWIM2 : NS											
10	0x5000A000	TWIS2 : S	US	NS	SA	No	Two-wire interface slave 2						
	0x4000A000	TWIS2 : NS											
10	0x5000A000	UARTE2 : S	US	NS	SA	No	Universal asynchronous receiver/transmitter with						
	0x4000A000	UARTE2 : NS					EasyDMA 2						
11	0x5000B000	SPIM3 : S	US	NS	SA	No	SPI master 3						
	0x4000B000 0x5000B000	SPIM3 : NS SPIS3 : S											
11	0x4000B000	SPIS3 : NS	US	NS	SA	No	SPI slave 3						
	0x4000B000	TWIM3 : S											
11	0x4000B000	TWINS : S	US	NS	SA	No	Two-wire interface master 3						
	0x5000B000	TWIS3: NS											
11	0x4000B000	TWIS3 : NS	US	NS	SA	No	Two-wire interface slave 3						
	0x5000B000	UARTE3 : S					Universal asynchronous receiver/transmitter with						
11	0x4000B000	UARTE3 : NS	US	NS	SA	No	EasyDMA 3						
13	0x5000D000	GPIOTE0	HF	S	NA	No	Secure GPIO tasks and events						



ID	Base address	Instance	TrustZone			Split access	Description
			Мар	Att	DMA		
14	0x5000E000	SAADC : S	US	NS	SA	No	Analog to digital converter
	0x4000E000	SAADC : NS					
15	0x5000F000	TIMERO : S	US	NS	NA	No	Timer 0
	0x4000F000 0x50010000	TIMER0 : NS TIMER1 : S					
16	0x40010000	TIMER1 : NS	US	NS	NA	No	Timer 1
	0x50011000	TIMER2 : S					
17	0x40011000	TIMER2 : NS	US	NS	NA	No	Timer 2
20	0x50014000	RTC0:S	US	NS	NA	No	Real time counter 0
20	0x40014000	RTC0 : NS	03	NS	IVA	NO	real time counter o
21	0x50015000	RTC1:S	US	NS	NA	No	Real time counter 1
	0x40015000	RTC1: NS					
23	0x50017000	DPPIC: S	HF	NS	NA	Yes	DPPI configuration
	0x40017000 0x50018000	DPPIC: NS WDT: S					
24	0x40018000	WDT:NS	US	NS	NA	No	Watchdog timer
	0x5001B000	EGU0 : S					
27	0x4001B000	EGU0 : NS	US	NS	NA	No	Event generator unit 0
28	0x5001C000	EGU1:S	US	NS	NA	No	Event generator unit 1
28	0x4001C000	EGU1: NS	US	INS	INA	No	Event generator unit 1
29	0x5001D000	EGU2:S	US	NS	NA	No	Event generator unit 2
	0x4001D000	EGU2 : NS					<u> </u>
30	0x5001E000	EGU3:S	US	NS	NA	No	Event generator unit 3
	0x4001E000 0x5001F000	EGU3 : NS EGU4 : S					
31	0x4001F000	EGU4 : NS	US	NS	NA	No	Event generator unit 4
	0x50020000	EGU5 : S					
32	0x40020000	EGU5 : NS	US	NS	NA	No	Event generator unit 5
33	0x50021000	PWM0 : S	US	NS	SA	No	Pulse width modulation unit 0
33	0x40021000	PWM0 : NS	03	INS	ЭА	INO	ruise width modulation diff. 0
34	0x50022000	PWM1:S	US	NS	SA	No	Pulse width modulation unit 1
	0x40022000	PWM1 : NS					
35	0x50023000 0x40023000	PWM2 : S PWM2 : NS	US	NS	SA	No	Pulse width modulation unit 2
	0x50024000	PWM3:S					
36	0x40024000	PWM3 : NS	US	NS	SA	No	Pulse width modulation unit 3
	0x50026000	PDM:S					Pulse density modulation (digital microphone)
38	0x40026000	PDM: NS	US	NS	SA	No	interface
40	0x50028000	12S : S	US	NS	SA	No	Inter-IC Sound
40	0x40028000	12S : NS	03	113	371	110	mer re sound
42	0x5002A000	IPC:S	US	NS	NA	No	Interprocessor communication
4.4	0x4002A000	IPC : NS	ШЕ	NC	NA	No	Floating point unit
44	0x4002C000 0x40031000	FPU GPIOTE1	HF HF	NS NS	NA NA	No No	Floating-point unit Non Secure GPIO tasks and events
+3	0x50039000	APPROTECT : S		145	IVA	140	non secure of to tasks and events
57	0x40039000	APPROTECT : NS	HF	NS	NA	Yes	APPROTECT control
	0x50039000	KMU : S	115	NC	NA	V	Karananan II
57	0x40039000	KMU : NS	HF	NS	NA	Yes	Key management unit
57	0x50039000	NVMC : S	HF	NS	NA	Yes	Non-volatile memory controller
3.	0x40039000	NVMC : NS					
58	0x5003A000	VMC:S	US	NS	NA	No	Volatile memory controller
	0x4003A000	VMC : NS					



ID	Base address	Instance	TrustZone Split a		Split access	Description				
			Мар	Att	DMA					
64	0x50840000	CC_HOST_RGF	HF	S	NSA	No	Host platform interface			
64	0x50840000	CRYPTOCELL	HF	S	NSA	No	CryptoCell sub-system control interface			
66	0x50842500	P0 : S	HF	NS	NA	Yes	General purpose input and output			
00	0x40842500	P0 : NS	пг	INS	INA	res	General purpose input and output			
N/A	0x00FF0000	FICR	HF	S	NA	No	Factory information configuration			
N/A	0x00FF8000	UICR	HF	S	NA	No	User information configuration			
N/A	0xE0041000	ETM	HF	NS	NA	No	ETM			
N/A	0xE0051000	ETB	HF	NS	NA	No	ETB			
N/A	0xE0054000	TPIU	HF	NS	NA	No	TPIU			
N/A	0xE0058000	ATBREPLICATOR	HF	NS	NA	No	ATBREPLICATOR			
N/A	0xE005A000	ATBFUNNEL1	HF	NS	NA	No	ATBFUNNEL unit 1			
N/A	0xE005B000	ATBFUNNEL2	HF	NS	NA	No	ATBFUNNEL unit 2			
N/A	0xE0080000	TAD	HF	S	NA	No	Trace and debug control			

Table 4: Instantiation table

4.2.3 Peripheral access control capabilities

Information about the peripheral access control capabilities can be found in the instantiation table.

The instantiation table has two columns containing the information about access control capabilities for a peripheral:

- Secure mapping: This column defines configuration capabilities for TrustZone-M secure attribute.
- DMA security: This column indicates whether the peripheral has DMA capabilities, and if DMA transfer can be assigned to a different security attribute than the peripheral itself.

For details on options in secure mapping column and DMA security column, see the following tables respectively.

Abbreviation	Description
NS	Non-secure: This peripheral is always accessible as a non-secure peripheral.
S	Secure: This peripheral is always accessible as a secure peripheral.
US	User-selectable: Non-secure or secure attribute for this peripheral is defined by the PERIPHID[0].PERM register.
SPLIT	Both non-secure and secure: The same resource is shared by both secure and non-secure code.

Table 5: Secure mapping column options

Abbreviation	Description
NA	Not applicable: Peripheral has no DMA capability.
NSA	No separate attribute: Peripheral has DMA, and DMA transfers always have the same security attribute as assigned to the peripheral.
SA	Separate attribute: Peripheral has DMA, and DMA transfers can have a different security attribute than the one assigned to the peripheral.

Table 6: DMA security column options



4.3 VMC — Volatile memory controller

The volatile memory controller (VMC) provides power control of RAM blocks.

Each of the available RAM blocks, which can contain multiple RAM sections, can be turned on or off independently in System ON mode, using the RAM[n]registers. These registers also control if a RAM block, or some of its sections, is retained in System OFF mode. See Memory chapter for more information about RAM blocks and sections.

Note: Powering up a RAM block takes typically 10 cycles. Thus, it is recommended reading the POWER register before accessing a RAM block that has been recently powered on.

4.3.1 Registers

Instances

Instance	Base address	TrustZone	e e		Split access	Description		
		Мар	Att	DMA				
VMC : S	0x5003A000	US	NS	NIA	No	Valatila mamanu aantrollar		
VMC : NS	0x4003A000	US	INS	NA	No	Volatile memory controller		

Register overview

Register	Offset	TZ	Description
RAM[n].POWER	0x600		RAMn power control register
RAM[n].POWERSET	0x604		RAMn power control set register
RAM[n].POWERCLR	0x608		RAMn power control clear register

4.3.1.1 RAM[n].POWER (n=0..7)

Address offset: $0x600 + (n \times 0x10)$ RAMn power control register

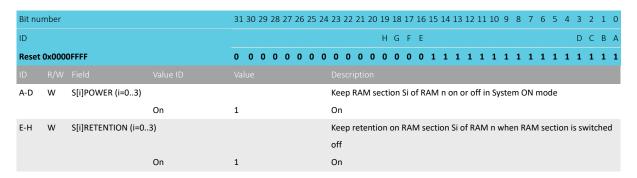
Bit nu	ımber			31	30 29	28	27 2	26 2	5 24	4 23	22	2 21	20	19	18	17 1	6 1	5 14	13	12	11	10	9 8	3 7	6	5	4	3	2	1 0
ID														Н	G	F E												D	С	В А
Reset	0x000	OFFFF		0	0 0	0	0 (0 (0	0	0	0	0	0	0	0 () 1	. 1	1	1	1	1	1 :	l 1	1	1	1	1	1	1 1
ID																														
A-D	RW	S[i]POWER (i=03)								Ke	ер	RAN	√l se	ectio	on S	i of	RAN	/1 n	on o	or of	ff in	Sys	tem	ON	mo	ode				
										All	R/	AM s	ect	ions	s wi	ll be	sw	itch	ed c	off ir	n Sy	sten	n O	FF m	od	e				
			Off	0						Of	f																			
			On	1						On	1																			
E-H	RW	S[i]RETENTION (i=0.	.3)							Ke	ер	rete	entic	on c	n R	AM	sec	tion	Si	of R	AM	n w	hen	RAI	√l s	ecti	on i	s sw	/itcl	hed
										off	f																			
			Off	0						Of	f																			
			On	1						On	1																			

4.3.1.2 RAM[n].POWERSET (n=0..7)

Address offset: $0x604 + (n \times 0x10)$ RAMn power control set register



When read, this register will return the value of the POWER register.

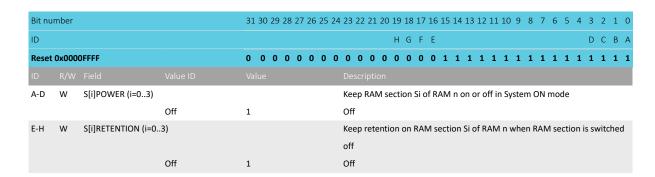


4.3.1.3 RAM[n].POWERCLR (n=0..7)

Address offset: $0x608 + (n \times 0x10)$

RAMn power control clear register

When read, this register will return the value of the POWER register.



4.4 NVMC — Non-volatile memory controller

The non-volatile memory controller (NVMC) is used for writing and erasing of the internal flash memory and the user information configuration register (UICR).

The NVMC is a split security peripheral. This means that when the NVMC is configured as non-secure, only a subset of the registers is available from the non-secure code. See SPU — System protection unit on page 257 and Registers on page 32 for more details.

When the NVMC is configured to be a secure peripheral, only secure code has access.

Before a write can be performed, the NVMC must be enabled for writing in CONFIG.WEN. Similarly, before an erase can be performed, the NVMC must be enabled for erasing in CONFIG.EEN, see CONFIG on page 33. The user must make sure that writing and erasing are not enabled at the same time. Failing to do so may result in unpredictable behavior.

4.4.1 Writing to flash

When writing is enabled, in CONFIG register for secure region, or in CONFIGNS register for non-secure region, flash is written by writing a full 32-bit word to a word-aligned address in flash.

Secure code has access to both secure and non-secure regions, by using the appropriate configuration of CONFIG and CONFIGNS registers. Non-secure code, in contrast, has access to non-secure regions only. Thus, non-secure code only needs CONFIGNS.



The NVMC is only able to write '0' to erased bits in flash, that is bits set to '1'. It cannot write a bit back to '1'.

As illustrated in Memory on page 21, flash is divided into multiple pages. The same address in flash can only be written n_{WRITE} number of times before a page erase must be performed.

Only full 32-bit words can be written to flash using the NVMC interface. To write less than 32 bits to flash, write the data as a word, and set all the bits that should remain unchanged in the word to '1'. Note that the restriction about the number of writes (see above) still applies in this case.

The time it takes to write a word to flash is specified by t_{WRITE} . If CPU executes code from flash while the NVMC is writing to flash, the CPU will be stalled.

Only word-aligned writes are allowed. Byte or half-word-aligned writes will result in a bus fault.

4.4.2 Erasing a secure page in flash

When secure region erase is enabled (in CONFIG register), a flash page can be erased by writing 0xFFFFFFF into the first 32-bit word in a flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by $t_{\text{ERASEPAGE}}$. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

See Partial erase of a page in flash for information on splitting the erase time in smaller chunks.

4.4.3 Erasing a non-secure page in flash

When non-secure region erase is enabled, a non-secure flash page can be erased by writing 0xFFFFFFF into the first 32-bit word of the flash page.

Page erase is only applicable to the code area in the flash and does not work with UICR.

After erasing a flash page, all bits in the page are set to '1'. The time it takes to erase a page is specified by t_{ERASEPAGE}. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.4 Writing to user information configuration registers (UICR)

User information configuration registers (UICR) are written in the same way as flash. After UICR has been written, the new UICR configuration only takes effect after a reset.

UICR is only accessible by secure code. Any write from non-secure code will be faulted.

In order to lock the chip after uploading non-secure code, a simple sequence must be followed:

- 1. Block access to secure code by setting UICR register SECUREAPPROTECT on page 41 to protected
- 2. Use the WRITEUICRNS on page 35 register, via non-secure debugger, in order to set APPROTECT (APPROTECT is automatically written to 0x00000000 by the NVMC)

UICR can only be written n_{WRITE} number of times before an erase must be performed using ERASEALL.

The time it takes to write a word to the UICR is specified by t_{WRITE} . The CPU is stalled if the CPU executes code from the flash while the NVMC is writing to the UICR.

4.4.5 Erase all

When erase is enabled, the whole flash and UICR can be erased in one operation by using the ERASEALL register. ERASEALL does not erase the factory information configuration registers (FICR).

This functionality can be blocked by some configuration of the UICR protection bits, see the table NVMC protection (1 - Enabled, 0 - Disabled, X - Don't care) on page 31.



The time it takes to perform an ERASEALL on page 33 command is specified by t_{ERASEALL}. The CPU is stalled if the CPU executes code from the flash while the NVMC performs the erase operation.

4.4.6 NVMC protection mechanisms

This chapter describes the different protection mechanisms for the non-volatile memory.

4.4.6.1 NVMC blocking

UICR integrity is assured through use of multiple levels of protection. UICR protection bits can be configured to allow or block certain operations.

The table below shows the different statuses of UICR protection bits, and which operations are allowed or blocked.

	UICR protection bit	NVMC protection				
SECUREAPPRO	TECT APPROTECT	ERASEPROTECT	CTRL-AP	NVMC		
			ERASEALL	ERASEALL		
0	0	0	Available	Available		
1	X	0	Available	Blocked		
Х	1	0	Available	Blocked		
Χ	Х	1	Blocked	Blocked		

Table 7: NVMC protection (1 - Enabled, 0 - Disabled, X - Don't care)

Note: Erase can still be performed through CTRL-AP, regardless of the above settings. See CTRL-AP - Control access port on page 437 for more information.

Uploading code with secure debugging blocked

Non-secure code can program non-secure flash regions. In order to perform these operations, the NVMC has the following non-secure registers: CONFIGNS, READY and READYNEXT.

Register CONFIGNS on page 34 works as the CONFIG register but it is used only for non-secure transactions. Both page erase and writing to flash require a write transaction (see Erasing a secure page in flash on page 30 or Erasing a non-secure page in flash on page 30). The SPU — System protection unit on page 257 prevents non-secure code from writing to a secure page since the transaction will never reach the NVMC controller.

4.4.6.2 NVMC power failure protection

NVMC power failure protection is possible using a power-fail comparator which monitors the power supply. If the power-fail comparator is enabled, and the power supply voltage is below V_{POF} threshold, the comparator prevents the NVMC from performing erase or write operations in non-volatile memory (NVM).

If a power failure warning is present at the start of an NVM write or erase operation, the NVMC blocks the operation and a bus error is signaled.

If the power failure warning occurs during an ongoing NVM write operation, the NVMC will try to finish the operation. However, if the power failure warning persists, consecutive NVM write operations are blocked by the NVMC, and a bus error is signaled.

If a power failure warning occurs during an NVM erase operation, the operation is aborted and a bus error is signaled.

4.4.7 Cache

An instruction cache (I-Cache) can be enabled for the ICODE bus in the NVMC.



See Memory map on page 23 for the location of flash.

A cache hit is an instruction fetch from the cache, and it has a 0 wait-state delay. The number of wait-states for a cache miss, where the instruction is not available in the cache and needs to be fetched from flash, depends on the processor frequency, see CPU parameter W_FLASHCACHE.

Enabling the cache can increase the CPU performance and reduce power consumption, by reducing the number of wait cycles and the number of flash accesses. This depends on the cache hit rate. Cache draws current when enabled. If the reduction in average current due to reduced flash accesses is larger than the cache power requirement, the average current to execute the program code is reduced.

When disabled, the cache does not draw current and its content is not retained.

It is possible to enable cache profiling to analyze the performance of the cache for your program using the register ICACHECNF. When profiling is enabled, registers IHIT and IMISS are incremented for every instruction cache hit or miss respectively.

4.4.8 Registers

Instances

Instance	Base address	TrustZone	:		Split access	Description
		Мар	Att	DMA		
NVMC : S	0x50039000	HF	NS	NIA	Yes	New veletile memory controller
NVMC : NS	0x40039000	HF	INS	NA	Yes	Non-volatile memory controller

Register overview

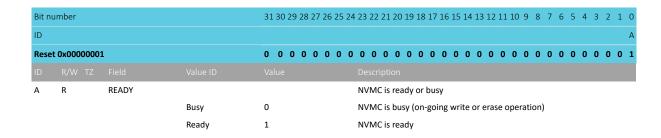
Register	Offset	TZ	Description
READY	0x400	NS	Ready flag
READYNEXT	0x408	NS	Ready flag
CONFIG	0x504	S	Configuration register
ERASEALL	0x50C	S	Register for erasing all non-volatile user memory
ERASEPAGEPARTIALCFG	0x51C	S	Register for partial erase configuration
ICACHECNF	0x540	S	I-code cache configuration register
IHIT	0x548	S	I-code cache hit counter
IMISS	0x54C	S	I-code cache miss counter
CONFIGNS	0x584	NS	
WRITEUICRNS	0x588	NS	Non-secure APPROTECT enable register

4.4.8.1 READY

Address offset: 0x400

Ready flag

4510 057 v1.0

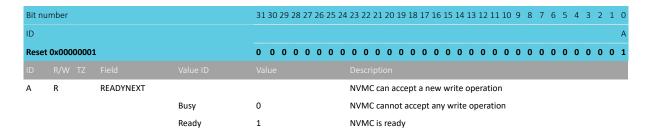




4.4.8.2 READYNEXT

Address offset: 0x408

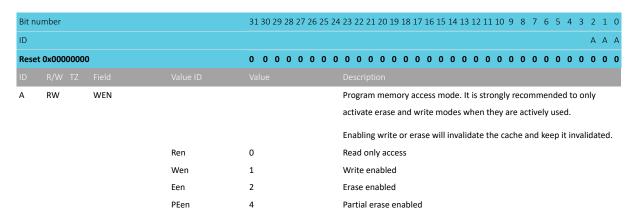
Ready flag



4.4.8.3 CONFIG

Address offset: 0x504 Configuration register

Note: This register is one hot



4.4.8.4 ERASEALL

Address offset: 0x50C

Register for erasing all non-volatile user memory

Bit n	umber			31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x0000000	0		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	ERASEALL			Erase all non-volatile memory including UICR registers.
					Note that erasing must be enabled by setting CONFIG.WEN = Een before
					the non-volatile memory can be erased.
			NoOperation	0	No operation
			Erase	1	Start chip erase

4.4.8.5 ERASEPAGEPARTIALCFG

Address offset: 0x51C

Register for partial erase configuration



Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0 10 Reset 0x00000000A Description	Α	RW	DURATION							Dı	ırat	ion	of th	he p	artia	ıl er	ase	in m	illise	cond	ls								
ID A A A A A A A	ID																												
	Reset (0x0000000A	•	0	0 0	0	0	0	0 (0 0	0	0	0 (0 0	0	0	0 (0	0	0 0	0	0	0	0	0) 1	0	1	0
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 (ID																							Α	A .	Δ Δ	Α	Α	Α
	Bit nur	mber		313	30 29	9 28	27	26 2	25 2	4 23	22	21	20 1	9 1	3 17	16	15 1	4 13	12	11 10	9	8	7	6	5 -	4 3	2	1	0

The user must ensure that the total erase time is long enough for a complete erase of the flash page

4.4.8.6 ICACHECNF

Address offset: 0x540

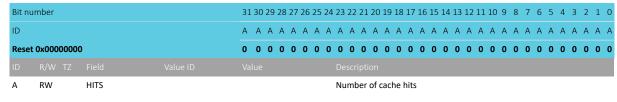
I-code cache configuration register

Bit nu	mber			3	1 30	29	28 2	27 2	6 2	5 24	23	22	21 2	20 1	19 1	8 1	7 16	5 15	14	13	12 1	1 10	9	8	7	6	5	4 3	2	1 0
ID																								В						Δ
Reset	0x0000000)		0	0	0	0	0 (0 0	0	0	0	0	0	0 () (0	0	0	0	0 (0	0	0	0	0	0	0 0	0	0 0
ID																														
Α	RW	CACHEEN									Ca	che	ena	ble	9															
			Disabled	0							Dis	sabl	e ca	che	e. In	val	dat	es a	II ca	che	ent	ries								
			Enabled	1							En	able	e ca	che	•															
В	RW	CACHEPROFEN									Ca	che	pro	filir	ng e	nal	ole													
			Disabled	0							Dis	sabl	e ca	che	e pr	ofili	ng													
			Enabled	1							En	able	e ca	che	pro	fili	ng													

4.4.8.7 IHIT

Address offset: 0x548

I-code cache hit counter

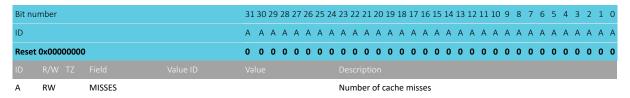


Write zero to clear

4.4.8.8 IMISS

Address offset: 0x54C

I-code cache miss counter



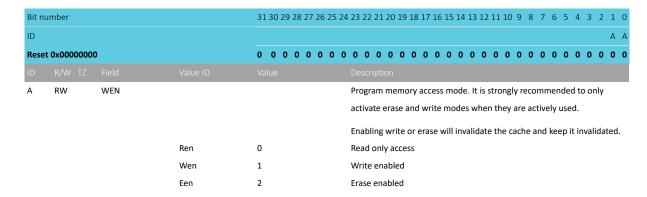
Write zero to clear

4.4.8.9 CONFIGNS

Address offset: 0x584



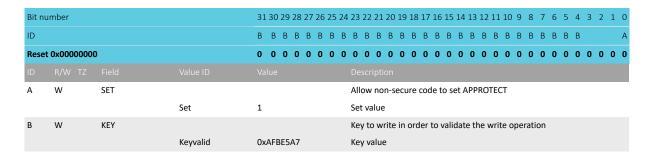
Note: This register is one hot



4.4.8.10 WRITEUICRNS

Address offset: 0x588

Non-secure APPROTECT enable register



4.4.9 Electrical specification

4.4.9.1 Flash programming

Symbol	Description	Min.	Тур.	Max.	Units
n _{WRITE}	Number of times a 32-bit word can be written before erase			2	
n _{ENDURANCE}	Erase cycles per page	10,000			
t _{WRITE}	Time to write one 32-bit word			43	μs
t _{ERASEPAGE}	Time to erase one page			87	ms
t _{ERASEALL}	Time to erase all flash			173	ms
t _{ERASEPAGEPARTIAL} ,setup	Setup time for one partial erase			1.08	ms

4.4.9.2 Cache size

Symbol	Description	Min.	Тур.	Max.	Units
Size _{ICODE}	I-Code cache size		2048		Bytes

4.5 FICR — Factory information configuration registers

Factory information configuration registers (FICR) are pre-programmed in factory and cannot be erased by the user. These registers contain chip-specific information and configuration.



4.5.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
FICR	0x00FF0000	HF	S	NA	No	Factory information configuration

Register overview

Register	Offset	TZ	Description
SIPINFO.PARTNO	0x140		SIP part number
SIPINFO.HWREVISION[n]	0x144		SIP hardware revision, encoded in ASCII, for example B0A or B1A
SIPINFO.VARIANT[n]	0x148		SIP VARIANT, encoded in ASCII, for example LACA. See Ordering information for details.
INFO.DEVICEID[n]	0x204		Device identifier
INFO.RAM	0x218		RAM variant
INFO.FLASH	0x21C		Flash variant
INFO.CODEPAGESIZE	0x220		Code memory page size
INFO.CODESIZE	0x224		Code memory size
INFO.DEVICETYPE	0x228		Device type
TRIMCNF[n].ADDR	0x300		Address
TRIMCNF[n].DATA	0x304		Data

4.5.1.1 SIPINFO

SIP-specific device information is provided in the following chapters.

4.5.1.1.1 SIPINFO.PARTNO

Address offset: 0x140

SIP part number

Bit number	31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	A A A A A A A	. A A A A A A A A A A A A A A A A A A A
Reset 0xFFFFFFF	1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID R/W Field Value ID		Description
A R PARTNO		
9161	0x00009161	Device is an nRF9161 sip
9160	0x00009160	Device is an nRF9160 sip
9131	0x00009131	Device is an nRF9131 sip

4.5.1.1.2 SIPINFO.HWREVISION[n] (n=0..3)

Address offset: $0x144 + (n \times 0x1)$

SIP hardware revision, encoded in ASCII, for example B0A or B1A

Note: When treated as a c-string, content is not NULL-terminated





4.5.1.1.3 SIPINFO.VARIANT[n] (n=0..3)

Address offset: $0x148 + (n \times 0x1)$

SIP VARIANT, encoded in ASCII, for example LACA. See Ordering information for details.

Note: When treated as a c-string, content is not NULL-terminated

Bit n	umber				7 6 5 4 3 2 1 (
ID					A A A A A A A
Rese	t OxFF				1 1 1 1 1 1 1
Α	R	VARIANT			VARIANT[0] contains the most significant character of the SIP VARIANT.
					VARIANT[3] contains the least significant character of the SIP VARIANT.
			Α	0x41	
			В	0x42	
			С	0x43	
			1	0x49	
			L	0x4C	
			S	0x53	

4.5.1.2 INFO

Device info

4.5.1.2.1 INFO.DEVICEID[n] (n=0..1)

Address offset: $0x204 + (n \times 0x4)$

Device identifier

Reset 0xFFFFFFFF 1	111111111
Reset 0xFFFFFFFF 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	111111111
$\begin{array}{cccccccccccccccccccccccccccccccccccc$. A A A A A A A
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10	8 7 6 5 4 3 2 1 0

DEVICEID[0] contains the least significant bits of the device identifier. DEVICEID[1] contains the most significant bits of the device identifier.

4.5.1.2.2 INFO.RAM

Address offset: 0x218

RAM variant



Bit nu	mber			31 3	0 29	28	27	26	25 2	24	23 :	22 2	21 2	20 1	19 1	.8 1	7 16	5 15	5 14	13	12	11	10	9	8	7	6	5	4 3	3 2	1	0
ID				Α /	4 A	Α	Α	Α	Α.	Α	Α	Α ,	Α.	A	A A	4 Α	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	A	Α	A	4 A	Α	Α
Reset	0x000	00100		0 (0 0	0	0	0	0	0	0	0 (0	0	0 (0 (0	0	0	0	0	0	0	0	1	0	0	0	0 (0	0	0
ID											Des																					
Α	R	RAM									RAN	/I va	aria	nt																		
			K256	0x10	00						256	kBy	yte	RAI	М																	
			Unspecified	0xFF	FFFF	FF					Uns	pec	ifie	d																		

4.5.1.2.3 INFO.FLASH

Address offset: 0x21C

Flash variant

Bit nu	mber			31	30 2	9 28	3 27	7 26	25	24	23	22	21 2	20 1	19 1	L8 1	7 1	6 1	5 14	13	12	11 :	10 9	9 8	3	7 6	5	4	3	2	1	0
ID				Α	A A	A A	A	Α	Α	Α	Α	Α	Α	Α	A .	A ,	A A	λ Α	ι A	Α	Α	Α	A A	Δ ,	Δ ,	A A	. 4	A	Α	Α	Α	Α
Reset	0x000	00400		0	0 0	0	0	0	0	0	0	0	0	0	0	0	0 0) (0	0	0	0	1 (0 (0 (0	0	0	0	0	0	0
ID																																
Α	R	FLASH									Fla	sh v	aria	nt																		
			K1024	0x4	00						1 N	1By	te F	LAS	Н																	

4.5.1.2.4 INFO.CODEPAGESIZE

Address offset: 0x220 Code memory page size

Bit nu	mber			31	30	29 :	28 2	27 2	26 2	5 2	4 2	3 22	21	20	19	18	17	16	15	14 :	L3 1	2 1	1 10	9	8	7	6	5	4	3	2	1 0
ID				Α	Α	Α	Α /	Α.	A A	۸ ۸	4 Δ	A	Α	Α	Α	Α	Α	Α	Α	Α	A .	4 Δ	Α	Α	Α	Α	Α	Α	Α	Α	Α	А А
Reset	0x000	01000		0	0	0	0 (0	0 () (0 0	0	0	0	0	0	0	0	0	0	0	1 0	0	0	0	0	0	0	0	0	0	0 0
ID																																
Α	R	CODEPAGESIZE									C	ode	me	moi	ry p	age	siz	e														
			K4096	0x2	1000	0					4	kBy	te																			

4.5.1.2.5 INFO.CODESIZE

Address offset: 0x224 Code memory size

Bit nu	ımber			31	30	29 2	28 2	27 2	6 2	5 24	1 23	22	21	20 1	19 1	8 1	7 16	5 15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID				А	Α	Α.	Α	A	4 Δ	A	Α	Α	Α	Α	A A	Д Д	. A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A	А А
Reset	t 0x000	00100		0	0	0	0	0 (0 (0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0 0
ID																																
Α	R	CODESIZE									Со	de	mer	nor	y siz	e in	nur	nbe	r of	pa	ges											
											То	tal o	code	e spa	ace	is: C	OD	EPA	GES	IZE	* C	OD	ESIZ	ΖE								
			P256	250	6						25	6 p	ages	5																		

4.5.1.2.6 INFO.DEVICETYPE

Address offset: 0x228

Device type

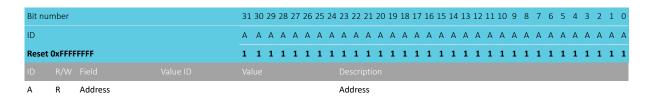


Bit numb	er			31	30	29 2	8 2	7 26	5 25	24	23	22 2	21 2	0 19	9 18	17	16	15 1	.4 1	3 12	11	10	9	8	7	6	5 .	4 3	2	1 0
ID				А	Α	A A	Δ Δ	A A	Α	Α	Α	Α,	Α Α	A A	Α	Α	Α	A	Δ ,	A A	Α	Α	Α	Α	Α	A	Α,	А А	Α	A A
Reset 0xF	FFFF	FFFF		1	1	1 1	1 1	l 1	1	1	1	1	1 1	l 1	1	1	1	1	1 :	l 1	1	1	1	1	1	1	1	1 1	1	1 1
ID R																														
A R		DEVICETYPE									Dev	ice	type	9																
			Die	0x0	0000	0000)				Dev	ice	is ar	n ph	ysic	al D	ΙE													
			FPGA	0xl	FFFF	FFFF	=				Dev	ice	is ar	n FP	GΑ															

4.5.1.3 TRIMCNF[n].ADDR (n=0..255)

Address offset: $0x300 + (n \times 0x8)$

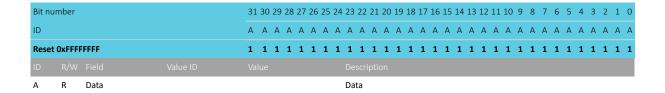
Address



4.5.1.4 TRIMCNF[n].DATA (n=0..255)

Address offset: $0x304 + (n \times 0x8)$

Data



4.6 UICR — User information configuration registers

The user information configuration registers (UICRs) are non-volatile memory (NVM) registers for configuring user specific settings.

For information on writing UICR registers, see the NVMC — Non-volatile memory controller on page 29 and Memory on page 21 chapters.

4.6.1 Registers

Instances

Instance	Base address	TrustZone	•		Split access	Description
		Мар	Att	DMA		
UICR	0x00FF8000	HF	S	NA	No	User information configuration

Register overview

Register	Offset T	ΓZ	Description
APPROTECT	0x000		Access port protection





Register	Offset	TZ	Description
XOSC32M	0x014		Oscillator control
HFXOSRC	0x01C		HFXO clock source selection
HFXOCNT	0x020		HFXO startup counter
APPNVMCPOFGUARD	0x024		Enable blocking NVM WRITE and aborting NVM ERASE for Application NVM in POFWARN
			condition.
SECUREAPPROTECT	0x02C		Secure access port protection
ERASEPROTECT	0x030		Erase protection
OTP[n]	0x108		One time programmable memory
KEYSLOT.CONFIG[n].DEST	0x400		Destination address where content of the key value registers (KEYSLOT.KEYn.VALUE[0-3]) will
			be pushed by KMU. Note that this address must match that of a peripheral's APB mapped
			write-only key registers, otherwise the KMU can push this key value into an address range
			which the CPU can potentially read.
KEYSLOT.CONFIG[n].PERM	0x404		Define permissions for the key slot. Bits 0-15 and 16-31 can only be written when equal to
			0xFFFF.
KEYSLOT.KEY[n].VALUE[o]	0x800		Define bits [31+o*32:0+o*32] of value assigned to KMU key slot.

4.6.1.1 APPROTECT

Address offset: 0x000 Access port protection

Bit nu	ımber			31	30	29 2	28	27 2	26 2	25 2	4 23	22	21	20	19	18 1	17 1	.6 1	15 1	14 :	13 1	.2 1	1 10) 9	8	7	6	5	4	3	2	1 0
ID				Α	Α	Α	Α	Α.	Α /	Α Δ	A	Α	Α	Α	Α	Α	A	Δ.	Α	Α	Α .	Α,	Δ Δ	ι A	Α	Α	Α	Α	Α	Α	Α	А А
Reset	0xFFFF	FFFF		1	1	1	1	1	1	1 1	. 1	1	1	1	1	1	1	1	1	1	1	1	l 1	. 1	1	1	1	1	1	1	1	1 1
ID																																
Α	RW	PALL									Bl	ocks	del	bug	ger	rea	ad/v	vrit	e a	cce	ss t	o al	I СР	U re	gis	ters	and	m b	em	ory	ma	pped
											ad	dre	sses	;																		
											Ar	ıy va	alue	dif	fere	ent 1	to H	lwl	Jnp	rot	ecte	ed v	vill r	nak	e ac	ces	s pc	ort p	prot	tect	ed.	
			HwUnprotected	0x5	0FA	450I	FA				Нν	vUn	pro	tect	ted																	
			Protected	0x0	000	0000	00				Pr	ote	ted																			

4.6.1.2 XOSC32M

Address offset: 0x014 Oscillator control

Bit no	umber	31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A
Rese	t 0xFFFFFFCF	1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID			
Α	RW CTRL		Pierce current DAC control signals

4.6.1.3 HFXOSRC

Address offset: 0x01C

HFXO clock source selection



Bit nu	ımber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0		
ID	ID				A		
Reset 0xFFFFFFF				1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		
ID					Description		
Α	RW	HFXOSRC			HFXO clock source selection		
			XTAL	1	32 MHz crystal oscillator		
			TCXO	0 32 MHz temperature compensated crystal oscillator (TCXO)			

4.6.1.4 HFXOCNT

Address offset: 0x020 HFXO startup counter

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0			
ID					A A A A A A A			
Reset	Reset 0xFFFFFFF			1 1 1 1 1 1 1 1	$1 \; 1 \; 1 \; 1 \; 1 \; 1 \; 1 \; 1 \; 1 \; 1 \;$			
ID					Description			
Α	RW	HFXOCNT			HFXO startup counter. Total debounce time = HFXOCNT*64 us + 0.5 us			
			MinDebounceTime	0	Min debounce time = $(0*64 \text{ us} + 0.5 \text{ us})$			
			MaxDebounceTime	255	Max debounce time = (255*64 us + 0.5 us)			

4.6.1.5 APPNVMCPOFGUARD

Address offset: 0x024

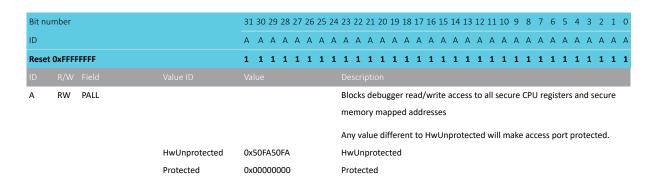
Enable blocking NVM WRITE and aborting NVM ERASE for Application NVM in POFWARN condition.

Bit nu	umber			31 30	29 :	28 2	7 26	5 25	24	23	22 :	21 2	20 1	9 1	8 1	7 16	5 15	14	13	12	11 1	0 9	8	7	6	5	4	3 2	1	0
ID																														Α
Reset 0xFFFFFFF			1 1	1	1 1	l 1	1	1	1	1	1	1	1 :	1 1	. 1	1	1	1	1	1	l 1	1	1	1	1	1	1 1	1	1	
ID																														
Α	RW	NVMCPOFGUARDEN	I							Enable blocking NVM WRITE and aborting NVM ERASE in POFWARN																				
										con	diti	on																		
			Disabled	0									TE a	nd	IVN	vi El	RAS	E ar	e n	ot b	ock	ed ir	ı PO	FW.	ARN	V со	ndi	ion		

4.6.1.6 SECUREAPPROTECT

Address offset: 0x02C

Secure access port protection



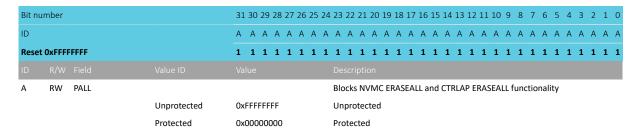




4.6.1.7 ERASEPROTECT

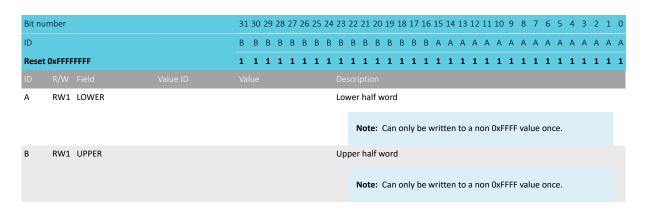
Address offset: 0x030

Erase protection



4.6.1.8 OTP[n] (n=0..189)

Address offset: $0x108 + (n \times 0x4)$ One time programmable memory

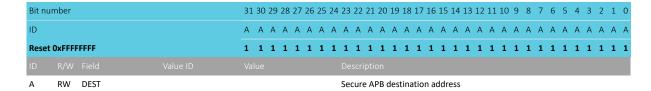


4.6.1.9 KEYSLOT.CONFIG[n].DEST (n=0..127)

Address offset: $0x400 + (n \times 0x8)$

Destination address where content of the key value registers (KEYSLOT.KEYn.VALUE[0-3]) will be pushed by KMU. Note that this address must match that of a peripheral's APB mapped write-only key registers, otherwise the KMU can push this key value into an address range which the CPU can potentially read.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.



4.6.1.10 KEYSLOT.CONFIG[n].PERM (n=0..127)

Address offset: $0x404 + (n \times 0x8)$

Define permissions for the key slot. Bits 0-15 and 16-31 can only be written when equal to 0xFFFF.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.



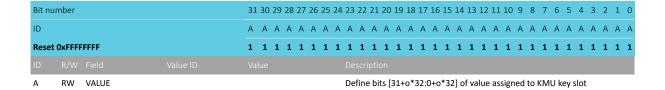
Bit number Bit							
Reset 0xFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF	Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
Note that it is not possible to undo a key revocation by writing the value Description	ID					D C B A	
A RW WRITE Disabled 0 Disable write to the key value registers Enabled 1 Enable write to the key value registers Read permission for key slot Disable write to the key value registers Read permission for key slot Disabled 0 Disable read from key value registers Enabled 1 Enable read from key value registers C RW PUSH Disabled 0 Disable permission for key slot Disable read from key value registers Push permission for key slot Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed	Rese	t OxFFF	FFFFF		1 1 1 1 1 1 1 1	1111111111111111111111111111	
Disabled 0 Disable write to the key value registers Enabled 1 Enable write to the key value registers Read permission for key slot Disabled 0 Disable read from key value registers Enable read from key value registers Enable read from key value registers Push permission for key slot Disable read from key value registers Push permission for key slot Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enable Disabled 1 Enabled Enabled Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed	ID					Description	
B RW READ Disabled 0 Disable read from key value registers C RW PUSH Disabled 0 Disable read from key value registers Disabled 1 Enable read from key value registers Disabled 0 Disable read from key value registers Push permission for key slot Disabled 0 Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enable Disabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed	Α	RW	WRITE			Write permission for key slot	
B RW READ Disabled 0 Disable read from key value registers Enabled 1 Enable read from key value registers C RW PUSH Disabled 0 Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGn.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed				Disabled	0	Disable write to the key value registers	
Disabled 0 Disable read from key value registers Enabled 1 Enable read from key value registers Push permission for key slot Disabled 0 Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed				Enabled	1	Enable write to the key value registers	
Enabled 1 Enable read from key value registers C RW PUSH Disabled Disabled Disabled Disabled Enabled Enabled Enabled Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enabled Enabled Enabled Enabled Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked O Key value registers can no longer be read or pushed	В	RW	READ			Read permission for key slot	
Push permission for key slot Disabled Disabled Disabled Disabled Disabled Enabled Enabled Disabled Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked O Key value registers can no longer be read or pushed				Disabled	0	Disable read from key value registers	
Disabled 0 Disable pushing of key value registers over secure APB, but can be read if field READ is Enabled Enabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGn.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed				Enabled	1	Enable read from key value registers	
field READ is Enabled Enabled Enabled Enabled Enabled Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGN.DEST must contain a valid destination address! Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked O Key value registers can no longer be read or pushed	С	RW	PUSH			Push permission for key slot	
Enabled 1 Enable pushing of key value registers over secure APB. Register KEYSLOT.CONFIGn.DEST must contain a valid destination address! D RW STATE Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed				Disabled	0	Disable pushing of key value registers over secure APB, but can be read if	
KEYSLOT.CONFIGn.DEST must contain a valid destination address! Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed						field READ is Enabled	
Revocation state for the key slot Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed				Enabled	1	Enable pushing of key value registers over secure APB. Register	
Note that it is not possible to undo a key revocation by writing the value '1' to this field Revoked 0 Key value registers can no longer be read or pushed						KEYSLOT.CONFIGn.DEST must contain a valid destination address!	
to this field Revoked 0 Key value registers can no longer be read or pushed	D	RW	STATE			Revocation state for the key slot	
Revoked 0 Key value registers can no longer be read or pushed						Note that it is not possible to undo a key revocation by writing the value '1'	
						to this field	
Active 1 Key value registers are readable (if enabled) and can be pushed (if enabled)				Revoked	0	Key value registers can no longer be read or pushed	
				Active	1	Key value registers are readable (if enabled) and can be pushed (if enabled)	

4.6.1.11 KEYSLOT.KEY[n].VALUE[o] (n=0..127) (o=0..3)

Address offset: $0x800 + (n \times 0x10) + (o \times 0x4)$

Define bits [31+o*32:0+o*32] of value assigned to KMU key slot.

Note: Writing/reading this register requires the KMU SELECTKEYSLOT register to be set to n+1.



4.7 EasyDMA

EasyDMA is a module implemented by some peripherals to gain direct access to Data RAM.

EasyDMA is an AHB bus master similar to CPU and is connected to the AHB multilayer interconnect for direct access to Data RAM. EasyDMA is not able to access flash.

A peripheral can implement multiple EasyDMA instances to provide dedicated channels. For example, for reading and writing of data between the peripheral and RAM. This concept is illustrated in EasyDMA example on page 44.



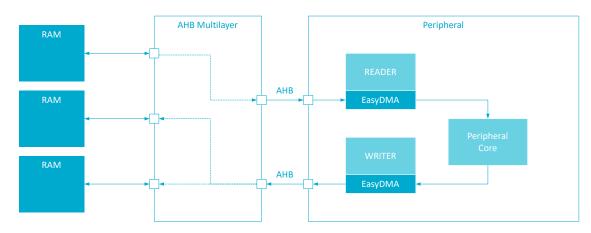


Figure 5: EasyDMA example

An EasyDMA channel is implemented in the following way, but some variations may occur:

```
READERBUFFER_SIZE 5
WRITERBUFFER_SIZE 6

uint8_t readerBuffer[READERBUFFER_SIZE] __at__ 0x20000000;
uint8_t writerBuffer[WRITERBUFFER_SIZE] __at__ 0x200000005;

// Configuring the READER channel
MYPERIPHERAL->READER.MAXCNT = READERBUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &readerBuffer;

// Configure the WRITER channel
MYPERIPHERAL->WRITER.MAXCNT = WRITEERBUFFER_SIZE;
MYPERIPHERAL->WRITER.PTR = &writerBuffer;
```

This example shows a peripheral called MYPERIPHERAL that implements two EasyDMA channels - one for reading called READER, and one for writing called WRITER. When the peripheral is started, it is assumed that the peripheral will perform the following tasks:

- Read 5 bytes from the readerBuffer located in RAM at address 0x20000000
- Process the data
- Write no more than 6 bytes back to the writerBuffer located in RAM at address 0x20000005

The memory layout of these buffers is illustrated in EasyDMA memory layout on page 44.

0x20000000	readerBuffer[0]	readerBuffer[1]	readerBuffer[2]	readerBuffer[3]
0x20000004	readerBuffer[4]	writerBuffer[0]	writerBuffer[1]	writerBuffer[2]
0x20000008	writerBuffer[3]	writerBuffer[4]	writerBuffer[5]	

Figure 6: EasyDMA memory layout

The WRITER.MAXCNT register should not be specified larger than the actual size of the buffer (writerBuffer). Otherwise, the channel would overflow the writerBuffer.

Once an EasyDMA transfer is completed, the AMOUNT register can be read by the CPU to see how many bytes were transferred. For example, CPU can read MYPERIPHERAL->WRITER.AMOUNT register to see how many bytes WRITER wrote to RAM.



Note: The PTR register of a READER or WRITER must point to a valid memory region before use. The reset value of a PTR register is not guaranteed to point to valid memory. See Memory on page 21 for more information about the different memory regions and EasyDMA connectivity.

4.7.1 EasyDMA error handling

Some errors may occur during DMA handling.

If READER.PTR or WRITER.PTR is not pointing to a valid memory region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 21 for more information about the different memory regions.

If several AHB bus masters try to access the same AHB slave at the same time, AHB bus congestion might occur. An EasyDMA channel is an AHB master. Depending on the peripheral, the peripheral might either stall and wait for access to be granted, or lose data.

4.7.2 EasyDMA array list

EasyDMA can operate in Array List mode.

The Array List mode is implemented in channels where the LIST register is available.

The array list does not provide a mechanism to explicitly specify where the next item in the list is located. Instead, it assumes that the list is organized as a linear array where items are located one after the other in RAM.

The EasyDMA Array List can be implemented by using the data structure ArrayList_type as illustrated in the code example below using a READER EasyDMA channel as an example:

```
#define BUFFER_SIZE 4

typedef struct ArrayList
{
   uint8_t buffer[BUFFER_SIZE];
} ArrayList_type;

ArrayList_type ReaderList[3] __at__ 0x20000000;

MYPERIPHERAL->READER.MAXCNT = BUFFER_SIZE;
MYPERIPHERAL->READER.PTR = &ReaderList;
MYPERIPHERAL->READER.LIST = MYPERIPHERAL_READER_LIST_ArrayList;
```

The data structure only includes a buffer of size equal to the size of READER.MAXCNT register. EasyDMA uses the READER.MAXCNT register to determine when the buffer is full.

READER.PTR = &ReaderList

 0x20000000 : ReaderList[0]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

 0x200000004 : ReaderList[1]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

 0x200000008 : ReaderList[2]
 buffer[0]
 buffer[1]
 buffer[2]
 buffer[3]

Figure 7: EasyDMA array list



4.8 AHB multilayer interconnect

On the AHB multilayer interconnect, the application CPU and all EasyDMA instances are AHB bus masters while RAM, cache, and peripherals are AHB slaves. External MCU subsystems can be seen both as master and slave on the AHB multilayer interconnect.

Multiple AHB masters can access slave resources within the AHB multilayer interconnect as illustrated in Memory on page 21. Access rights to each of the AHB slaves are resolved using the default natural priority of the different bus masters in the system.

4.8.1 AHB multilayer priorities

Each master connected to the AHB multilayer is assigned a default natural priority.

Bus master name	Natural relative priority	In/Out
System (CPU)	Highest priority	I/O
LTE Modem		I/O
125		I/O
PDM		1
SPIMO/SPISO/TWIMO/TWISO/UARTEO		I/O
SPIM1/SPIS1/TWIM1/TWIS1/UARTE1		I/O
SPIM2/SPIS2/TWIM2/TWIS2/UARTE2		I/O
SPIM3/SPIS3/TWIM3/TWIS3/UARTE3		I/O
SAADC		1
PWM0		0
PWM1		0
PWM2		0
PWM3		0
CC310	Lowest priority	I/O

Table 8: AHB bus masters (listed from highest to lowest priority)



5 Power and clock management

The power and clock management system automatically ensures maximum power efficiency.

The nRF9161 has three power modes - System Disabled, System ON and System OFF. The System ON and System OFF are internal (automatically handled by the device) and the System Disabled is external (driven by the ENABLE pin and overriding internal ones).

The core of the automatic power and clock management is the power management unit (PMU) illustrated in the following image.

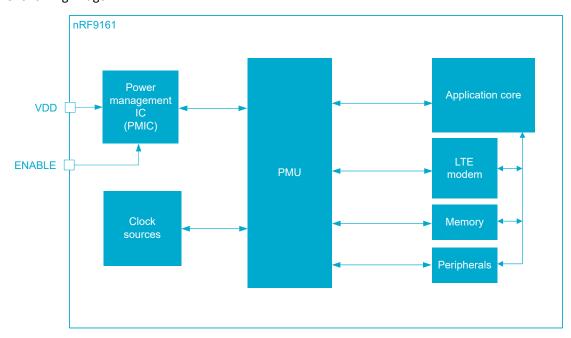


Figure 8: Power management unit

When the device is powered and enabled, the PMU automatically tracks the power and clock resources required by the different components in the system. It then starts/stops and chooses operation modes in supply regulators and clock sources, without user interaction, to achieve the lowest power consumption possible.

5.1 Power management

The two internal modes are handled by the power management unit (PMU), whereas the external is handled by the user via the ENABLE pin.

The System Disabled mode provides a way to override the PMU by manipulating voltages presented to the ENABLE pin.

The PMU steers system-wide clock and power in order to provide the power modes - System ON and System OFF. Under the various modes, internal blocks are automatically powered by the PMU as required by the application.

5.1.1 System Disabled mode

The entire device can be powered down by presenting the appropriate voltage to the externally available ENABLE pin.

The nRF9161 provides a feature to be able disable power throughout the entire device externally. This can be useful when the device is operating as slave processor where it does not need to be powered on at all times, then it is possible to avoid unnecessary current leaking by driving the ENABLE pin to low. The nRF9161 will not start if is not enabled. Moreover, a change from disable to enable, will result in a power-on-reset behavior inside the device.

Note: VDD_GPIO input must be driven low when device is disabled, failing to do so could result in increased leakage. For more information, see VDD_GPIO considerations in Operating conditions on page 455.

Note: In case the System Disabled mode is not used, ENABLE must be connected to VDD.

Pin Value	Power status	description
Low	Disabled	Device's internal power regulator disabled
High	Enabled	Device's internal power regulator enabled

Table 9: ENABLE pin configuration

5.1.2 System OFF mode

System OFF is the deepest internal power saving mode the system can enter.

In this mode, the core system functionality is powered down and ongoing tasks terminated, and only the reset and the wakeup functions are available and responsive.

The device is put into System OFF mode using the REGULATORS register interface. When in System OFF mode, one of the following signals/actions will wake up the device:

- 1. DETECT signal, generated by the GPIO peripheral
- 2. RESET
- 3. Debug session start

When the device wakes up from System OFF mode, a system reset is performed.

One or more RAM blocks can be retained in System OFF mode depending on the settings in the RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 57. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

Before entering System OFF mode, the user must make sure that all on-going EasyDMA transactions have completed. This can be done by making sure that EasyDMA enabled peripherals have stopped and END events from them received. The LTE modem must also be stopped, by issuing a command through the modem API, before entering System OFF mode. Once the command is issued, wait for the modem to respond that it actually has stopped, as there may be a delay until the modem is disconnected from the network.

5.1.2.1 Emulated System OFF mode

If the device is in debug interface mode, System OFF will be emulated to ensure that all resources required for debugging are available during System OFF.

See Debug and trace on page 368 chapter for more information. Resources required for debugging include the following key components: Debug and trace on page 368, CLOCK — Clock control on page 70, POWER — Power control on page 63, NVMC — Non-volatile memory controller on page 29, CPU on page 20, flash, and RAM. To prevent the CPU from executing unwanted code, an infinite loop must be added directly after entering System OFF mode.



5.1.3 System ON mode

System ON is the power mode entered after a power-on reset.

While in System ON, the system can reside in one of two sub modes:

- · Low power
- Constant latency

The low power mode is default after power-on reset.

In low power mode, whenever no application or wireless activity takes place, function blocks like the application CPU, LTE modem and all peripherals are in IDLE state. That particular state is referred to as System ON IDLE. In this state, all function blocks retain their state and configuration, so they are ready to become active once configured by the CPU.

If any application or modem activity occurs, the system leaves the System ON IDLE state. Once a given activity in a function block is completed, the system automatically returns to IDLE, retaining its configuration.

As long as the system resides in low power mode, the PMU ensures that the appropriate regulators and clock sources are started or stopped based on the needs of the function blocks active at any given time.

This automatic power management can be overridden by switching to constant latency mode. In this mode, the CPU wakeup latency and the PPI task response are constant and kept at a minimum. This is secured by keeping a set of base resources that are always enabled. The advantage of having a constant and predictable latency will be at the cost of having significantly increased power consumption compared to the low power mode. The constant latency mode is enabled by triggering the CONSTLAT task (TASKS_CONSTLAT on page 64).

While the system is in constant latency mode, the low power mode can be enabled by triggering LOWPWR task (TASKS LOWPWR on page 64).

To reduce power consumption while in System ON IDLE, RAM blocks can be turned off in System ON mode while enabling the retention of these RAM blocks in RAM[n].POWER registers in VMC. RAM[n].POWER are retained registers, see Reset behavior on page 57. Note that these registers are usually overwritten by the startup code provided with the nRF application examples.

5.1.4 Registers

5.1.5 Electrical specification

5.1.5.1 **ENABLE** pin

Symbol	Description	Min.	Тур. Ма	ax. Units
V _{SYSTEM_DISABLED_ON}	Operational voltage to enforce System-Disabled power mode.	0.8*VDD		V
$V_{SYSTEM_DISABLED_OFF}$	Operational voltage to cancel System-Disabled power mode.		0.4	V V
t _{HOLDENABLE}	ENABLE pin hold time	TBA		ms

5.2 Power supply

The nRF9161 has a single main power supply VDD, and the internal components are powered by integrated voltage regulators. The PMU manages these regulators automatically, no voltage regulator control needs to be included in application firmware.



5.2.1 General purpose I/O supply

The input/output (I/O) drivers of P0.00 - P0.31 pins are supplied independently of VDD through VDD_GPIO. This enables easy match to signal voltage levels in the printed circuit board design.

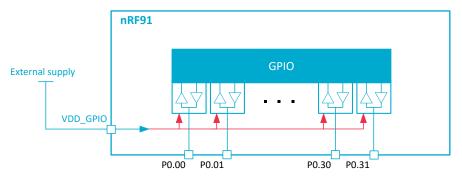


Figure 9: GPIO supply input (VDD_GPIO)

The I/Os are supplied via VDD_GPIO pin as shown in figure above. VDD_GPIO pin supports voltage levels within range given in table Operating conditions on page 455. See VDD_GPIO considerations on page 455 for more information on how to control VDD_GPIO power supply.

5.3 Power supply monitoring

Power monitor solutions are available in the device, in order to survey the VDD (battery voltage).

5.3.1 Power supply supervisor

The power supply supervisor enables monitoring of the connected power supply.

Two functionalities are implemented:

- Power-on reset (POR): Generates a reset when the supply is applied to the device, and ensures that the device starts up in a known state
- Brownout reset (BOR): Generates a reset when the supply drops below the minimum voltage required for safe operations

Two BOR levels are used:

- V_{BOROFF}, used in System OFF
- V_{BORON}, used in System ON

The power supply supervisor is illustrated in the image below.



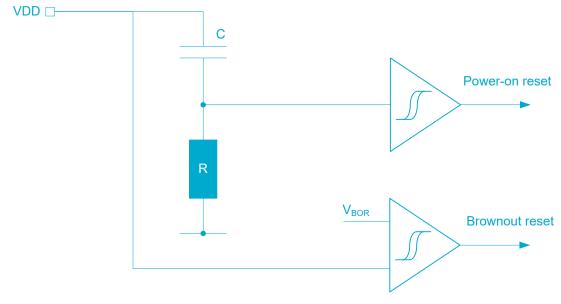


Figure 10: Power supply supervisor

5.3.2 External power failure warning

The external power failure (EXTPOF) warning can provide the CPU an early warning of an imminent power failure. It does not reset the system, but gives the CPU time to prepare for an orderly power-down. EXTPOF detects power failures external to PMU from the device internal PMIC.

Note: All nRF9161 modem firmware versions support this feature.

The user can start and stop the PMIC EXTPOF feature and set the battery voltage low threshold level through the modem API.

For application core to receive the power failure warning events, EXTPOFCON on page 78 register in REGULATORS — Voltage regulators control on page 77 must be enabled. If this is disabled, the state of the PMIC warning input is ignored and the power failure warning events are not delivered to application core.

The available time for the CPU to prepare for a power-down depends on the set warning threshold level, the load of the running tasks, and the type of power source used.

Note: For details on services provided by the modem AT command interface, see nRF Connect SDK AT interface and nRF91 AT Commands.

The EXTPOF functional overview is shown in the following figure.



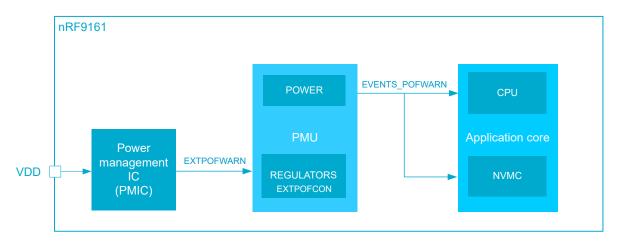


Figure 11: External power failure warning arrangement

If EXTPOF is enabled and the device's internal PMIC detects that battery voltage has dropped below the low threshold level, an POFWARN event is generated (see EVENTS_POFWARN on page 65). The POFWARN event to the CPU can be cleared in the event register, however the PMIC input continues to indicate a warning as long as the battery voltage remains below the low threshold level.

POFWARN event also sets the LTE modem in offline mode.

Note: If a power failure warning occurs during an ongoing NVM write operation, the NVMC tries to finish the operation. Consecutive NVM write operations will be blocked by the NVMC as long as the PMIC input indicates a warning. The CPU interprets a blocked NVM write as a fault, which needs to be handled by the application. If a power failure warning occurs during an ongoing NVM erase operation, the operation will be aborted. Blocking NVM writes and aborting NVM erase operations can be disabled in APPNVMCPOFGUARD on page 41.

The external power failure warning doesn't trigger wakeup from System OFF.

The external power failure warning is disabled in System OFF mode.

5.3.3 Battery monitoring on VDD

A battery voltage (VDD) monitoring capability is provided via a modem API.

Note: For details on services provided by the modem AT command interface, see nRF Connect SDK AT interface and nRF91 AT Commands.

5.3.4 Registers

5.3.5 Electrical specification

5.3.5.1 Device startup times

Symbol	Description	Min.	Тур.	Max.	Units
t _{POR}	Time in power-on reset after VDD has reached 3V, ENABLE is tied to VDD.		1.2		ms
t _{PINR}	The maximum time taken to pull up the nRESET pin and release reset after				
	power-on reset. Dependent on the pin capacitive load (C) 2 : t=TRC; Typical:				
	T=2 R=13 kΩ; Max: T=5 R=16 kΩ.				

² To decrease the maximum time a device can be held in reset, a strong external pull-up resistor can be used.



Symbol	Description	Min.	Тур.	Max.	Units
t _{PINR,500nF}	C=500 nF		13	40	ms
t _{PINR,10uF}	C=10 μF		260	800	ms
t _{R2ON}	Time from reset to ON (CPU execute)		127	135	μs
t _{OFF2ON}	Time from OFF to CPU execute		73	92	μs
t _{WFE2CPU}	Time from WFE to CPU execute		70	90	μs
t _{WFI2CPU}	Time from WFI to CPU execute		69	90	μs
t _{EVTSET,CL1}	Time from HW event to PPI event in constant latency System ON mode		0.1	0.1	μs
t _{EVTSET,CLO}	Time from HW event to PPI event in low power System ON mode		0.1	0.7	μs
t _{LTEMODEM,TYP}	LTE modem typical startup time. Time from application core powering up the			200	ms
	modem until the modem is ready to receive the first AT command. $% \label{eq:command} % \lab$				
t _{LTEMODEM,WORSTCASE}	LTE modem worst case startup time. Time from application core powering up			250	ms
	the modem until the modem is ready to receive the first AT command, with				
	modem firmware variable elements included.				
t _{LTEMODEM} ,FOTA	LTE modem startup time after modem FOTA update. Time from application			7.5	S
	core powering up the modem after a modem FOTA update until the modem is	S			
	ready to receive the first AT command.				
t _{LTEMODEM} ,FOTAREJECT	LTE modem startup time after a rejected modem FOTA update. Time from			90	S
	application core powering up the modem after a rejected modem FOTA				
	update until the modem is ready to receive the first AT command. Modem				
	will revert back to original firmware image.				
t _{LTEMODEM,STOP,TYP}	LTE modem typical shutdown time. Time from application core calling			1.6	S
	bsd_shutdown command until bsd_shutdown returns.				
$t_{\text{LTEMODEM}, \text{STOP}, \text{WORSTCASE}}$	LTE modem worst case shutdown time. Time from application core calling			79	S
	bsd_shutdown command until bsd_shutdown returns, including modem				
	firmware variable elements.				

5.3.5.2 Power supply supervisor

Symbol	Description Min	in.	Тур.	Max.	Units
V_{BOR}	Brownout reset voltage threshold.		2.80		V
V_{POR}	Voltage threshold at which the device enters power-on reset (POR) when VDD			3.0	V
	is ramping up.				

5.4 Clock management

The clock control system can source the system clocks from a range of high and low frequency oscillators, and distribute them to modules based upon a module's individual requirements.

Clock generation and distribution is handled automatically by PMU to optimize current consumption. This optimization will affect the predictability of the oscillators' startup times under different device operating conditions. However, it is possible to bypass some of the power saving mechanisms by explicitly keeping the system on constant latency sub mode (more about constant latency in System ON mode on page 49) and/or manipulating START/STOP clock task registers.

The following are the available clock signal sources:

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)
- 32.768 kHz RC oscillator (LFRC)
- 32.768 kHz high accuracy oscillator (LFXO)

The clock and oscillator resources are configured and controlled via the CLOCK peripheral as illustrated below.



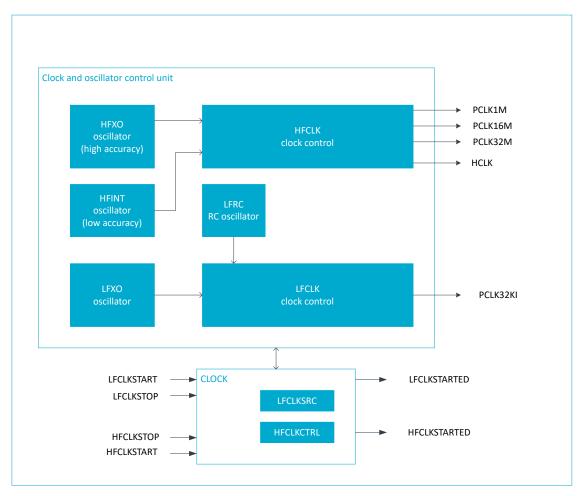


Figure 12: Clock and oscillator setup

5.4.1 HFCLK clock controller

The HFCLK clock controller provides several clocks in the system.

These are as follows:

- HCLK: 64 MHz CPU clock
- PCLK1M: 1 MHz peripheral clock
- PCLK16M: 16 MHz peripheral clock
- PCLK32M: 32 MHz peripheral clock

The HFCLK controller uses the following high frequency clock (HFCLK) sources:

- 64 MHz oscillator (HFINT)
- 64 MHz high accuracy oscillator (HFXO)

For illustration, see Clock and oscillator setup on page 54.

The HFCLK controller automatically provides the clock(s) requested by the system. If the system does not request any clocks from the HFCLK controller, the controller switches off all its clock sources and enters a power saving mode.

The HFINT source is used when HFCLK is requested and HFXO has not been started.

The HFXO is started by triggering the HFCLKSTART task and stopped using the HFCLKSTOP task. A HFCLKSTARTED event is generated when the HFXO has started and its frequency is stable.



5.4.2 LFCLK clock controller

The system supports several low frequency clock sources.

As illustrated in Clock and oscillator setup on page 54, the system supports the following low frequency clock sources:

- LFXO: 32.768 kHz high accuracy oscillator
- LFRC: 32.768 kHz RC oscillator

The LFCLK clock controller and all LFCLK clock sources are always switched off when in System OFF mode.

The LFCLK clock is started by first selecting the preferred clock source in the LFCLKSRC on page 77 register and then triggering the LFCLKSTART task. LFXO is highly recommended as the LFCLK clock source, since the LFRC has a large frequency variation.

Note: The LTE modem requires use of LFXO as the LFCLK source.

Switching between LFCLK clock sources can be done without stopping the LFCLK clock. A LFCLK clock source which is running prior to triggering the LFCLKSTART task continues to run until the selected clock source is available. After that the clock sources will be switched. Switching between clock sources will stretch a clock pulse by 0.5 to 1.0 clock cycle (i.e. will delay rising edge by 0.5 to 1.0 clock cycle).

Note: If the watchdog timer (WDT) is running, the default LFCLK clock source (LFRC - see LFCLKSRC on page 77) is started automatically (LFCLKSTART task doesn't have to be triggered).

A LFCLKSTARTED event will be generated when the selected LFCLK clock source has started.

Note: The first time LFXO is selected, LFRC quality is provided until LFXO is stable.

A LFCLKSTOP task will prevent global requesting of the LFCLK clock, unless a system component such as WDT or modem requires the LFCLK, in which case the clock is not stopped. The LFCLKSTOP task should only be triggered after the STATE field in the LFCLKSTAT register indicates a LFCLK running state.

5.4.2.1 32.768 kHz RC oscillator (LFRC)

The default source of the low frequency clock (LFCLK) is the 32.768 kHz RC oscillator (LFRC).

The LFRC frequency is affected by variation in temperature.

5.4.3 Registers

5.4.4 Electrical specification

5.4.4.1 64 MHz internal oscillator (HFINT)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFINT}	Nominal output frequency		64		MHz
f _{TOL_HFINT}	Frequency tolerance		±1	±5	%
t _{START_HFINT}	Startup time		3.2		μs

5.4.4.2 64 MHz high accuracy oscillator (HFXO)



Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_HFXO}	Nominal output frequency		64		MHz
f_{TOL_HFXO}	Frequency tolerance		±1		ppm
t _{START_HFXO}	Startup time		2		ms

5.4.4.3 32.768 kHz high accuracy oscillator (LFXO)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFXO}	Frequency		32.768		kHz
f _{TOL_LFXO}	Frequency tolerance		±20		ppm
t _{START_LFXO}	Startup time		450		ms

5.4.4.4 32.768 kHz RC oscillator (LFRC)

Symbol	Description	Min.	Тур.	Max.	Units
f _{NOM_LFRC}	Nominal frequency		32.768		kHz
f _{TOL_LFRC}	Frequency tolerance		30		%
t _{START_LFRC}	Startup time		600		μs

5.5 Reset

A system reset can be triggered by multiple sources. After a reset the CPU can query the RESETREAS (reset reason register) to find out which source generated the reset.

5.5.1 Power-on reset

The power-on reset generator initializes the system at power-on. The system is held in reset state until the supply has reached the minimum operating voltage and the internal voltage regulators have started.

5.5.2 Pin reset

A pin reset is generated when the physical reset pin (nRESET) on the device is pulled low.

To ensure that reset is issued correctly, the reset pin should be held low for the time specified in Pin reset on page 58.

nRESET pin has an always-on internal pull-up resistor connected to nRF9161 internal voltage typically of 2.2 V level, as illustrated in the following figure. The value of the pull-up resistor is given in Pin reset on page 58.

Note: Driving nRESET high with a voltage lower than 2.2V will result in additional leakage.

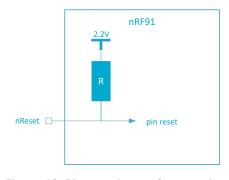


Figure 13: Pin reset internal generation



5.5.3 Wakeup from System OFF mode reset

The device is reset when it wakes up from System OFF mode.

The Debug access port is not reset following a wake up from System OFF mode if the device is in debug interface mode, see Debug and trace on page 368 chapter for more information.

5.5.4 Soft reset

A soft reset is generated when the SYSRESETREQ bit of the application interrupt and reset control register (AIRCR register) in the Arm core is set.

5.5.5 Watchdog reset

A watchdog reset is generated when the watchdog timer (WDT) times out.

See WDT — Watchdog timer on page 351 chapter for more information.

5.5.6 Brownout reset

The brownout reset generator puts the system in reset state if the supply voltage drops below the brownout reset threshold.

5.5.7 Retained registers

A retained register is a register that will retain its value in System OFF mode, and through a reset depending on reset source. For information on which peripheral registers are retained, see the corresponding peripheral's chapter.

5.5.8 Reset behavior

Reset behavior depends on the reset source.

The reset behavior is summarized in the table below.

Reset source	Reset target							
	CPU	Modem	Debug ³	SWJ-DP	Not retained	d Retained	WDT	RESETREAS
					RAM ⁴	RAM ⁴		
CPU lockup ⁵	х	х						
Soft reset	х	х						
Wakeup from System OFF	x	x	x ⁶		х		x	
mode reset								
Watchdog reset ⁷	x	x	х		х	х	х	
Pin reset	x	x	х	x	х	х	x	
Brownout reset	x	x	х	х	х	x	x	х
Power-on reset	х	x	х	х	х	х	х	

Table 10: Reset behavior for the main components



³ All debug components excluding SWJ-DP. See Debug and trace on page 368 chapter for more information about the different debug components in the system.

⁴ RAM can be configured to be retained using registers in VMC — Volatile memory controller on page 28

Reset from CPU lockup is disabled if the device is in debug interface mode. CPU lockup is not possible in System OFF.

⁶ The debug components will not be reset if the device is in debug interface mode.

Watchdog reset is not available in System OFF.

Note: The RAM is never reset but its content might be corrupted after reset in the cases given in the table above.

Reset source	Reset target						
	Regular peripheral	Regular peripheral GPIO, SPU N\		NVMC	REGULATORS,	POWER.GPREGRET	
	registers		WAITSTATENUM	I IFCREADDELAY	OSCILLATORS		
CPU lockup ⁵	х	x	X				
Soft reset	х	х	х				
Wakeup from System OFF mode reset	х		х				
Watchdog reset ⁷	х	х	х		х		
Pin reset	х	х	х		х		
Brownout reset	х	х	х	х	х	х	
Power-on reset	х	х	х	х	х	х	

Table 11: Reset behavior for the retained registers

5.5.9 Registers

5.5.10 Electrical specification

5.5.10.1 Pin reset

Symbol	Description	Min.	Тур.	Max.	Units
t _{HOLDRESET}	Hold time for reset pin when doing a pin reset	5			μs
R _{PULL-UP}	Value of the internal pull-up resistor		13		kΩ

5.6 Current consumption

As the system is constantly tuned by the PMU described in Power and clock management on page 47, estimating the current consumption of an application can be challenging if the designer cannot perform measurements directly on the hardware. To facilitate the estimation process, a set of current consumption scenarios are provided to show the typical current drawn from the VDD supply.

Each scenario specifies a set of operations and conditions that apply to the given scenario. The following table shows a set of common conditions used in all scenarios, unless otherwise is stated in the scenario's description. Similarly, Current consumption scenarios, common conditions for LTE modem on page 59 describes the conditions used for the modem current consumption specifications. For a list of all scenarios, see Electrical specification on page 59.

Peripherals typically share one or more power sources. This results in a current consumption that does not scale linearly with the number of peripherals enabled. For example, the current consumption for an application with two peripherals enabled, is not the sum of the currents reported by their individual peripherals.



Condition	Value
Supply	3.7 V
Temperature	25 °C
CPU	WFI (wait for interrupt)/WFE (wait for event) sleep
Peripherals	All idle ⁸
Clock	HFCLK=HFINT Not running
	LFCLK=Not running
RAM	No retention
Cache enabled	Yes

Table 12: Current consumption scenarios, common conditions

Condition
Cat-M1 and Cat-NB1 HD FDD mode
Good channel, RF cable, no errors in DL/UL communication
Minimum network response times
Output power at antenna port, single-ended 50 Ω
Modem eDRX current consumption quoted with UICC that allows UICC supply shut down at eDRX intervals. $^{9\ 10\ 11}$
Modem PSM TAU event energy is measured from the modem PSM wake-up until end of RX inactivity time
All LTE modem current consumption numbers include application core idle mode consumption ¹²

Table 13: Current consumption scenarios, common conditions for LTE modem

5.6.1 Electrical specification

5.6.1.1 Current consumption during System Disabled

Symbol	Description	Min.	Тур.	Max.	Units
I _{SYSTEM} DISABLED	ENABLE and VDD_GPIO pins grounded		150		nA

⁸ Except for currents reported for a given peripheral. Peripherals' currents are estimated during momentary transmission.



⁹ Required UICC restart current consumption is included.

If the UICC used does not support supply shut down, then UICC will remain in clock stop mode. Depending on the UICC used, a clock stop current in the range of 20 μ A to 60 μ A@3.7 V must be added to get the total average consumption.

Minimum UICC supply shut down interval and clock stop mode current consumption must be obtained from the UICC supplier.

Application RAM leakage not included. Application RAM leakage quoted separately under Sleep on page 60

5.6.1.2 Sleep

Symbol	Description	Min.	Тур.	Max.	Units
I _{MCUOFF0}	MCU off, modem off, wake on GPIO and reset		1.4		μΑ
I _{MCUONO}	MCU on IDLE, modem off, RTC off		1.8		μΑ
I _{MCUON1}	MCU on IDLE, modem off, RTC on		2.2		μΑ
I _{MCUON2}	MCU on IDLE, modem off, wake on GPIOTE input (event mode), Constant		600		μΑ
	latency System ON mode				
I _{MCUON3}	MCU on IDLE, modem off, wake on GPIOTE input (event mode), Low power		18		μΑ
	System ON mode				
I _{MCUON4}	MCU on IDLE, modem off, wake on GPIOTE input (port event)		1.8		μΑ
I _{RAM}	RAM retention leakage current of a 32kB block		0.1		μΑ

5.6.1.3 Application CPU active current consumption

The application CPU running parameters are obtained using the following compiler version:

Compiler: Arm version 6.16 (armclang)

Compiler flags:

-Wno-unused-command-line-argument --target=arm-arm-none-eabi -c -g -masm=auto -Wno-unused-value -mcpu=cortex-m33 -mfpu=fpv5-sp-d16 -mfloat-abi=hard -fno-rtti -flto -funsigned-char -mcmse -Omax -ffunction-sections

Symbol	Description	Min.	Тур.	Max.	Units
I _{CPU0_FLASH}	CPU running CoreMark @64 MHz from flash, clock = HFINT, cache enabled		2.7		mA
I _{COREMARK_PER_MA_FLASH}	CoreMark per mA, executing from flash, CoreMark=247		91		CoreMark/mA
I _{CPU0_RAM}	CPU running CoreMark @64 MHz from RAM, clock = HFINT		2.1		mA
I _{COREMARK_PER_MA_RAM}	CoreMark per mA, executing from RAM, CoreMark=239		114		CoreMark/mA

5.6.1.4 I2S

Symbol	Description	Min.	Тур.	Max.	Units
I _{12S0}	I2S transferring data left-channel (mono) @ 16 bit x 16 kHz		600		μΑ
	(CONFIG.MCKFREQ = 32MDIV8, CONFIG.RATIO = 256X), Clock = HFINT				
I _{12S1}	I2S transferring data left-channel (mono) @ 16 bit x 16 kHz		1620		μΑ
	(CONFIG.MCKFREQ = 32MDIV8, CONFIG.RATIO = 256X), Clock = HFXO				

5.6.1.5 PDM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PDM}	PDM receiving and processing data 16KHz, with FREQ = 1.28MHz,		620		μΑ
	MODE.OPERATION = mono				
I _{PDM}	PDM receiving and processing data 16KHz, with FREQ = 1.28MHz,		1630		μΑ
	MODE.OPERATION = mono, clock HFXO				

5.6.1.6 PWM

Symbol	Description	Min.	Тур.	Max.	Units
I _{PWM0}	PWM running @ 125 kHz, fixed duty cycle		510		μΑ
I _{PWM1}	PWM running @ 16 MHz, fixed duty cycle		680		μΑ



5.6.1.7 SAADC

Symbol	Description	Min.	Тур.	Max.	Units
I _{SAADC_HFXO}	SAADC sampling @ 16 ksps, with high accuracy clock HFXO, acquisition time		1550		μΑ
	= 20 μs				
I _{SAADC_HFINT}	SAADC sampling @ 16 ksps, with low accuracy clock HFINT, acquisition time =	•	540		μΑ
	20 μs				

5.6.1.8 TIMER

Symbol	Description	Min.	Тур.	Max.	Units
I _{TIMERO}	TIMER running @ 1 MHz		390		μΑ
I _{TIMER1}	TIMER running @ 16 MHz		440		μΑ

5.6.1.9 SPIM

Symbol	Description	Min.	Тур.	Max.	Units
I _{SPIM0}	SPIM transferring data @ 2 Mbps, Clock = HFINT		610		μΑ
I _{SPIM1}	SPIM transferring data @ 2 Mbps, Clock = HFXO		1620		μΑ
I _{SPIM2}	SPIM transferring data @ 8 Mbps, Clock = HFINT		640		μΑ
I _{SPIM3}	SPIM transferring data @ 8 Mbps, Clock = HFXO		1660		μΑ

5.6.1.10 SPIS

Symbol	Description	Min.	Тур.	Max.	Units
I _{SPIS_2M}	SPIS receiving data @ 2 Mbps, Clock=HFINT		500		μΑ
I _{SPIS_2MXO}	SPIS receiving data @ 2 Mbps, Clock=HFXO		1510		μΑ
I _{SPIS_8M}	SPIS receiving data @ 8 Mbps, Clock=HFINT		510		μΑ
I _{SPIS_8MXO}	SPIS receiving data @ 8 Mbps, Clock=HFXO		1520		μΑ

5.6.1.11 TWIM

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIM_100}	TWIM running @ 100 kbps, Clock=HFINT		590		μΑ
I _{TWIM_400}	TWIM running @ 400 kbps, Clock = HFINT		590		μΑ
I _{TWIM_100XO}	TWIM running @ 100 kbps, Clock = HFXO		1600		μΑ
I _{TWIM_400XO}	TWIM running @ 400 kbps, Clock = HFXO		1610		μΑ

5.6.1.12 TWIS

Symbol	Description	Min.	Тур.	Max.	Units
I _{TWIS,RUN_100}	TWIS transferring data @ 100 kbps, Clock=HFINT		590		μΑ
I _{TWIS1,RUN_400}	TWIS transferring data @ 400 kbps, Clock=HFINT		510		μΑ
I _{TWIS,RUN_100XO}	TWIS transferring data @ 100 kbps, Clock = HFXO		1480		μΑ
I _{TWIS,RUN_400XO}	TWIS transferring data @ 400 kbps, Clock = HFXO		1370		μΑ



5.6.1.13 UARTE

Symbol	Description	Min.	Тур.	Max.	Units
I _{UARTE,1M}	UARTE transferring data @ 1Mbps		700		μΑ
I _{UARTE,115K}	UARTE transferring data @ 115200 bps		510		μΑ

5.6.1.14 WDT

Symbol	Description	Min.	Тур.	Max.	Units
I _{WDT}	WDT started		2.5		μΑ

5.6.1.15 Modem current consumption

To estimate specific use cases, see Online Power Profiler for LTE

Symbol	Description	B13	B20	В3	B4	Units
		(typ.)	(typ.)	(typ.)	(typ.)	
Sleep curren	t consumption, Cat-M1 and Cat-NB1					
I _{PSM}	PSM floor current	2.7	2.7	2.7	2.7	μΑ
PSM TAU eve	ent energy and duration, Cat-M1					
E _{PSM_TAU}	Pout 23 dBm, QPSK, resource blocks 6, TBS index 9, UICC included	93	94	99	99	mJ
T _{PSM_TAU}	Pout 23 dBm, QPSK, resource blocks 6, TBS index 9, UICC included	1.3	1.3	1.3	1.3	S
PSM TAU eve	ent energy and duration, Cat-NB1					
E _{PSM_TAU}	Pout 23 dBm, QPSK, UICC included; UL: 12SC, MCS Index 5 Resource Units 1, Repetitions 1; DL, 12SC,	306	319	315	335	mJ
	MCS Index 6, Subframes 3, Repetitions 1					
T _{PSM_TAU}	Pout 23 dBm, QPSK, UICC included; UL: 12SC, MCS Index 5 Resource Units 1, Repetitions 1; DL, 12SC,	2.7	2.7	2.7	2.7	S
	MCS Index 6, Subframes 3, Repetitions 1					
Average curi	ent consumption, radio resource control (RRC) mode, Cat-M1					
I _{EDRX}	eDRX average current, 81.92 s, one PO/PTW, PTW = 2.56 s	19	-	19	-	μΑ
I _{IEDRX}	Idle eDRX average current, 655 s, one PO/PTW, PTW = 2.56 s	6	-	6	-	μΑ
I _{RMC_ODBM}	Uplink 180 kbit/s, Pout 0 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	45	45	47	46	mA
I _{RMC_10DBM}	Uplink 180 kbit/s, Pout 10 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	49	50	51	54	mA
I _{RMC_23DBM}	Uplink 180 kbit/s, Pout 23 dBm, RMC settings as per 3GPP TS 36.521-1 Annex A.2	102	114	118	117	mA
Average curi	ent consumption, radio resource control (RRC) mode, Cat-NB1					
I _{EDRX}	eDRX average current, 81.92 s, one PO/PTW, PTW = 2.56 s	33	-	33	-	μΑ
I _{IEDRX}	Idle eDRX average current, 655 s, one PO/PTW, PTW = 2.56 s	8	-	8	-	μΑ
I _{RMC_ODBM}	Pout 0 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP TS	30	30	30	30	mA
	36.101 Annex A.2.4					
I _{RMC_10DBM}	Pout 10 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP	30	30	35	35	mA
	TS 36.101 Annex A.2.4					
I _{RMC_23DBM}	Pout 23 dBm, QPSK, 1SC, 15 kHz, TX 33% RX 33% ("balanced TX and RX"), RMC settings as per 3GPP	90	100	105	100	mA
	TS 36.101 Annex A.2.4					
I _{RMC_ODBM}	Pout 0 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	50	50	50	50	mA
	36.101 Annex A.2.4					
I _{RMC_10DBM}	Pout 10 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	55	55	60	60	mA
	36.101 Annex A.2.4					
I _{RMC_23DBM}	Pout 23 dBm, BPSK, 1SC, 3.75 kHz, TX 80% RX 10% ("TX intensive"), RMC settings as per 3GPP TS	180	200	225	205	mA
	36.101 Annex A.2.4					



5.6.1.16 DECT NR+ current consumption

Symbol	Description	Тур.	Units				
Average currer	Average current consumption, nominal operating conditions						
I _{TX40DBM}	TX measured over one slot, Pout -40 dBm	TBA	mA				
I _{TX20DBM}	TX measured over one slot, Pout -20 dBm	TBA	mA				
I _{TX_ODBM}	TX measured over one slot, Pout 0 dBm	TBA	mA				
I _{TX_10DBM}	TX measured over one slot, Pout 10 dBm	TBA	mA				
I _{TX_19DBM}	TX measured over one slot, Pout 19 dBm	TBA	mA				
I _{RX90DBM}	RX measured over one slot, Pin -90 dBm	TBA	mA				

5.6.1.17 GPS current consumption

Symbol	Description	Min.	Тур.	Max.	Units
I _{GPS_CONTINUOUS}	Continuous tracking, without power saving mode		43.1		mA
I _{GPS_CONTINUOUS_PSM}	Continuous tracking, power saving mode		7.8		mA
I _{GPS_PERIODIC}	Periodic fix average current with A-GPS ¹³ , one fix every 2 minutes		0.5		mA

5.7 Register description

5.7.1 POWER — Power control

The POWER module provides an interface to tasks, events, interrupt, and reset related configuration settings of the power management unit.

Note: Registers INTEN on page 67, INTENSET on page 67, and INTENCLR on page 67 are the same registers (at the same address) as corresponding registers in CLOCK — Clock control on page 70.

5.7.1.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
POWER : S	0x50005000	US	NS	NA	No	Power control
POWER : NS	0x40005000	US	CNI	INA	INU	rower control

Register overview

Register	Offset	TZ	Description
TASKS_CONSTLAT	0x78		Enable constant latency mode.
TASKS_LOWPWR	0x7C		Enable low power mode (variable latency)
SUBSCRIBE_CONSTLAT	0xF8		Subscribe configuration for task CONSTLAT
SUBSCRIBE_LOWPWR	0xFC		Subscribe configuration for task LOWPWR
EVENTS_POFWARN	0x108		Power failure warning
EVENTS_SLEEPENTER	0x114		CPU entered WFI/WFE sleep

¹³ Including LTE current consumption.



Register	Offset	TZ	Description
EVENTS_SLEEPEXIT	0x118		CPU exited WFI/WFE sleep
PUBLISH_POFWARN	0x188		Publish configuration for event POFWARN
PUBLISH_SLEEPENTER	0x194		Publish configuration for event SLEEPENTER
PUBLISH_SLEEPEXIT	0x198		Publish configuration for event SLEEPEXIT
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RESETREAS	0x400		Reset reason
POWERSTATUS	0x440		Modem domain power status
GPREGRET[n]	0x51C		General purpose retention register
LTEMODEM.STARTN	0x610		Start LTE modem
LTEMODEM.FORCEOFF	0x614		Force off LTE modem

5.7.1.1.1 TASKS_CONSTLAT

Address offset: 0x78

Enable constant latency mode.

Bit nu	ımber			31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2 :	1 0
ID																																		Α
Reset	t 0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0
ID																																		
Α	W	TASKS_CONSTLAT										En	abl	e cc	nst	ant	lat	enc	y n	od	e.													
			Trigger	1								Tri	gge	er ta	sk																			

5.7.1.1.2 TASKS_LOWPWR

Address offset: 0x7C

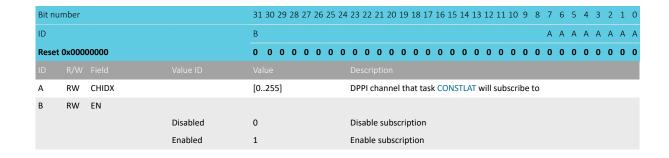
Enable low power mode (variable latency)

Bit nu	ımber			31	30	29	28	27	26	25	24	23	22	21	20	19	18	17 1	16	15	14	13 :	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																																			Α
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																			
Α	W	TASKS_LOWPWR										Ena	able	e lo	w p	ow	er n	nod	e (\	/ari	abl	e la	ten	icy)											
			Trigger	1								Trig	gge	r ta	sk																				

5.7.1.1.3 SUBSCRIBE_CONSTLAT

Address offset: 0xF8

Subscribe configuration for task CONSTLAT



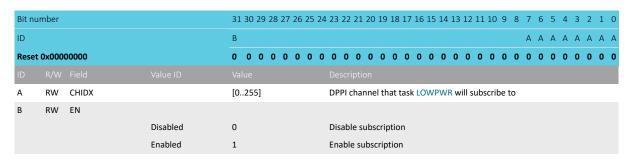




5.7.1.1.4 SUBSCRIBE_LOWPWR

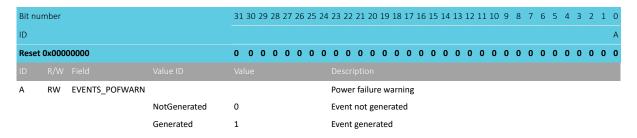
Address offset: 0xFC

Subscribe configuration for task LOWPWR



5.7.1.1.5 EVENTS POFWARN

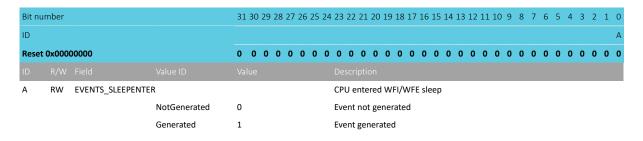
Address offset: 0x108 Power failure warning



5.7.1.1.6 EVENTS_SLEEPENTER

Address offset: 0x114

CPU entered WFI/WFE sleep



5.7.1.1.7 EVENTS_SLEEPEXIT

Address offset: 0x118

CPU exited WFI/WFE sleep



Bit number			31 30 29 28 27	26 25 2	4 23 2	22 21 :	20 19	18 17	16 15	5 14 1	13 12	11 1	10 9	8	7	6 5	5 4	3	2	1 0
ID																				Α
Reset 0x0000	00000		0 0 0 0 0	0 0 0	0 0	0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0	0 (0	0	0	0 0
ID R/W																				
A RW	EVENTS_SLEEPEXIT				CPL	Jexite	d WFI/	WFE s	sleep											
		NotGenerated	0		Eve	nt not	genera	ated												
		Generated	1		Eve	nt gen	erated													

5.7.1.1.8 PUBLISH_POFWARN

Address offset: 0x188

Publish configuration for event POFWARN

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event POFWARN will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

5.7.1.1.9 PUBLISH_SLEEPENTER

Address offset: 0x194

Publish configuration for event SLEEPENTER

Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event SLEEPENTER will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

5.7.1.1.10 PUBLISH_SLEEPEXIT

Address offset: 0x198

Publish configuration for event SLEEPEXIT

Bit nu	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event SLEEPEXIT will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing



5.7.1.1.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	mber			31 30 2	9 28 27	26 25	24	23 22	2 21 2	20 19	18	17 1	6 15	14 1	L3 1	.2 11	10	9	8 7	6	5	4	3 2	1	0
ID																				Ε	D		А		
Reset	0x000000	00		0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0	0 (0 0	0	0	0 0	0	0	0 (0 0	0	0
ID																									
Α	RW PO	FWARN						Enab	le or (disab	le in	terru	upt fo	or ev	ent	POF	WAF	RN							
			Disabled	0				Disab	le																
			Enabled	1				Enab	le																
D	RW SLE	EEPENTER						Enab	le or (disab	le in	terru	upt fo	or ev	ent	SLE	EPEN	ITER							
			Disabled	0				Disab	le																
			Enabled	1				Enab	le																
E	RW SLE	EEPEXIT						Enab	le or	disab	le in	terru	upt fo	or ev	ent	SLE	EPEX	IT							
			Disabled	0				Disab	le																
			Enabled	1				Enab	le																

5.7.1.1.12 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	POFWARN			Write '1' to enable interrupt for event POFWARN
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	SLEEPENTER			Write '1' to enable interrupt for event SLEEPENTER
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E	RW	SLEEPEXIT			Write '1' to enable interrupt for event SLEEPEXIT
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.1.1.13 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber			31 30 29 28 27 26	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D A
Reset	0x000	00000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	POFWARN			Write '1' to disable interrupt for event POFWARN
			Clear	1	Disable





Bit nu	mher			31 30	י מכר	ר פר	26	25 2/	1 22	วว	21 2	n 10	10	17 1	6 11	5 1 1	12	12 1	1 1	0 9	8	7	6	5	1 2	2	1 0
	ilibei			31 3	J Z J Z	20 27	20	23 2-	+ 23	22	21 2	0 13	, 10	1/ 1	0 1.	J 14	13	12 1	. 1 1	.0 3	- 0		-	J .	+ 3		1 0
ID																							Ε	D		Α	
Reset	0x0000	0000		0 0	0	0 0	0	0 0	0	0	0 0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0 0	0	0 0
ID																											
			Disabled	0					Rea	ad:	Disal	oled															
			Enabled	1					Rea	ad:	Enab	led															
D	RW	SLEEPENTER							Wr	ite '	'1' to	disa	able	inte	rrup	t fo	eve	ent S	LEE	PEN	TER						
			Clear	1					Dis	abl	е																
			Disabled	0					Rea	ad:	Disal	oled															
			Enabled	1					Rea	ad:	Enab	led															
E	RW	SLEEPEXIT							Wr	ite '	'1' to	disa	ble	inte	rrup	t fo	eve	ent S	LEE	PEX	IT						
			Clear	1					Dis	abl	е																
			Disabled	0					Rea	ad:	Disal	oled															
			Enabled	1					Rea	ad:	Enab	led															

5.7.1.1.14 RESETREAS

Address offset: 0x400

Reset reason

Note: Unless cleared, the RESETREAS register will be cumulative. A field is cleared by writing '1' to it. If none of the reset sources are flagged, this indicates that the chip was reset from the on-chip reset generator, which will indicate a power-on reset or a brownout reset.

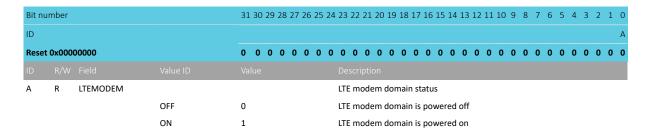
Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					G F E D C B A
Reset	0x0000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	RESETPIN			Reset from pin reset detected
			NotDetected	0	Not detected
			Detected	1	Detected
В	RW	DOG			Reset from global watchdog detected
			NotDetected	0	Not detected
			Detected	1	Detected
С	RW	OFF			Reset due to wakeup from System OFF mode, when wakeup is triggered by
					DETECT signal from GPIO
			NotDetected	0	Not detected
			Detected	1	Detected
D	RW	DIF			Reset due to wakeup from System OFF mode, when wakeup is triggered by
					entering debug interface mode
			NotDetected	0	Not detected
			Detected	1	Detected
E	RW	SREQ			Reset from AIRCR.SYSRESETREQ detected
			NotDetected	0	Not detected
			Detected	1	Detected
F	RW	LOCKUP			Reset from CPU lock-up detected
			NotDetected	0	Not detected
			Detected	1	Detected
G	RW	CTRLAP			Reset triggered through CTRL-AP
			NotDetected	0	Not detected
			Detected	1	Detected



5.7.1.1.15 POWERSTATUS

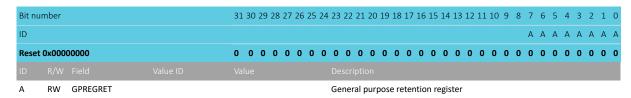
Address offset: 0x440

Modem domain power status



5.7.1.1.16 GPREGRET[n] (n=0..1)

Address offset: $0x51C + (n \times 0x4)$ General purpose retention register



This register is a retained register

5.7.1.1.17 LTEMODEM

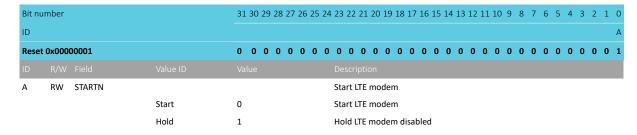
LTE Modem

5.7.1.1.17.1 LTEMODEM.STARTN

Address offset: 0x610

Start LTE modem

Note: Starting and stopping LTE modem must only be done through the LTE modem API to guarantee correct sequence in FW and HW and to avoid possible malfunctions.

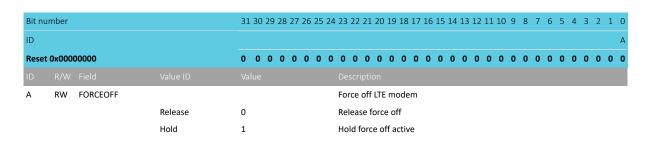


5.7.1.1.17.2 LTEMODEM.FORCEOFF

Address offset: 0x614
Force off LTE modem

Note: Starting and stopping LTE modem must only be done through the LTE modem API to guarantee correct sequence in FW and HW and to avoid possible malfunctions.





5.7.2 CLOCK — Clock control

The CLOCK module provides one of the interfaces to power and clock management configuration settings.

Through CLOCK module it is able to configure the following:

- LFCLK clock source setup
- LFCLK and HFCLK status
- Tasks and events
- Interrupts
- Reset

Note: Registers INTEN on page 74, INTENSET on page 74, and INTENCLR on page 74 are the same registers (at the same address) as corresponding registers in POWER — Power control on page 63.

5.7.2.1 Registers

Instances

Instance	Base address	TrustZone	:		Split access	Description
		Мар	Att	DMA		
CLOCK : S	0x50005000	uc	NC	NI A	NI-	Clark and the
CLOCK : NS	0x40005000	US	NS	NA	No	Clock control

Register overview

Register	Offset	TZ	Description
TASKS_HFCLKSTART	0x000		Start HFCLK source
TASKS_HFCLKSTOP	0x004		Stop HFCLK source
TASKS_LFCLKSTART	0x008		Start LFCLK source
TASKS_LFCLKSTOP	0x00C		Stop LFCLK source
SUBSCRIBE_HFCLKSTART	0x080		Subscribe configuration for task HFCLKSTART
SUBSCRIBE_HFCLKSTOP	0x084		Subscribe configuration for task HFCLKSTOP
SUBSCRIBE_LFCLKSTART	0x088		Subscribe configuration for task LFCLKSTART
SUBSCRIBE_LFCLKSTOP	0x08C		Subscribe configuration for task LFCLKSTOP
EVENTS_HFCLKSTARTED	0x100		HFCLK oscillator started
EVENTS_LFCLKSTARTED	0x104		LFCLK started
PUBLISH_HFCLKSTARTED	0x180		Publish configuration for event HFCLKSTARTED
PUBLISH_LFCLKSTARTED	0x184		Publish configuration for event LFCLKSTARTED
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
HFCLKRUN	0x408		Status indicating that HFCLKSTART task has been triggered



Register	Offset	TZ	Description
HFCLKSTAT	0x40C		The register shows if HFXO has been requested by triggering HFCLKSTART task and if it has
			been started (STATE)
LFCLKRUN	0x414		Status indicating that LFCLKSTART task has been triggered
LFCLKSTAT	0x418		The register shows which LFCLK source has been requested (SRC) when triggering LFCLKSTART
			task and if the source has been started (STATE)
LFCLKSRCCOPY	0x41C		Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered
LFCLKSRC	0x518		Clock source for the LFCLK. LFCLKSTART task starts a clock source selected with this register.

5.7.2.1.1 TASKS_HFCLKSTART

Address offset: 0x000 Start HFCLK source

Bit nu	ımber			31	30	29 2	28 2	7 20	6 25	24	23	22	21	20	19 1	18 1	7 16	15	14	13 1	2 1	1 10	9	8	7	6	5	4	3 2	1	0
ID																															Α
Reset	0x000	00000		0	0	0 (0 0	0	0	0	0	0	0	0	0	0 (0	0	0	0 (0 (0	0	0	0	0	0	0 (0	0	0
ID																															
Α	W	TASKS_HFCLKSTART									Sta	rt F	HFCI	LK s	our	ce															
			Trigger	1							Trig	gge	r tas	sk																	

5.7.2.1.2 TASKS_HFCLKSTOP

Address offset: 0x004 Stop HFCLK source

Bit nu	ımber			31 30 29 28	8 27 26 2	5 24	23 22	21 2	0 19	18 17	16	15 14	4 13	12 1	1 10	9	8	7 (5 5	4	3	2	1 0
ID																							Α
Reset	0x000	00000		0 0 0 0	0 0 0	0	0 0	0 (0 0	0 0	0	0 0	0	0 (0 0	0	0	0 (0	0	0	0	0 0
ID							Descr																
Α	W	TASKS_HFCLKSTOP					Stop I	HFCL	(sou	rce													
			Trigger	1			Trigge	er tasl	k														

5.7.2.1.3 TASKS_LFCLKSTART

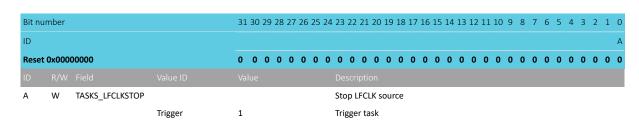
Address offset: 0x008 Start LFCLK source

Bit no	umber			31	30 2	9 28	3 27	26	25 2	24 2	23 2	22 2	1 2	0 1	9 1	8 1	7 1	6 1	5 14	13	3 12	11	10	9	8	7	6	5 -	4	3 2	! 1	L 0
ID																																Α
Rese	t 0x000	00000		0	0	0 0	0	0	0	0	0	0 () (0 () (0 () (0	0	0	0	0	0	0	0	0	0	0	0 (0 0) (0
ID																																
Α	W	TASKS_LFCLKSTART								S	tar	t LF	CLK	so	urc	e																
			Trigger	1						Т	rig	ger 1	tasl	k																		

5.7.2.1.4 TASKS_LFCLKSTOP

Address offset: 0x00C Stop LFCLK source





5.7.2.1.5 SUBSCRIBE_HFCLKSTART

Address offset: 0x080

Subscribe configuration for task HFCLKSTART

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task HFCLKSTART will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription

5.7.2.1.6 SUBSCRIBE_HFCLKSTOP

Address offset: 0x084

Subscribe configuration for task HFCLKSTOP

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task HFCLKSTOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

5.7.2.1.7 SUBSCRIBE_LFCLKSTART

Address offset: 0x088

Subscribe configuration for task LFCLKSTART

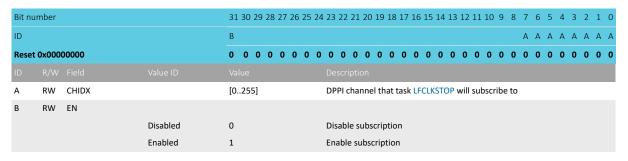
Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task LFCLKSTART will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

5.7.2.1.8 SUBSCRIBE_LFCLKSTOP

Address offset: 0x08C

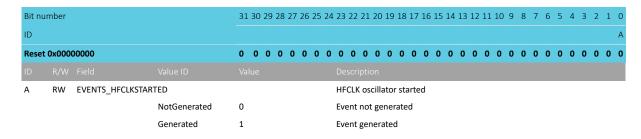


Subscribe configuration for task LFCLKSTOP



5.7.2.1.9 EVENTS HFCLKSTARTED

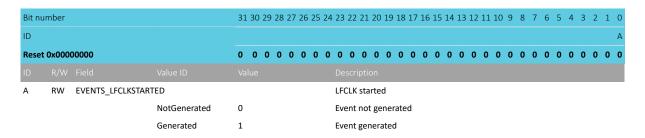
Address offset: 0x100 HFCLK oscillator started



5.7.2.1.10 EVENTS_LFCLKSTARTED

Address offset: 0x104

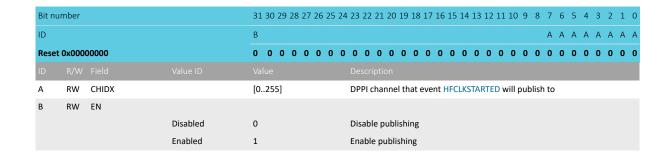
LFCLK started



5.7.2.1.11 PUBLISH HFCLKSTARTED

Address offset: 0x180

Publish configuration for event HFCLKSTARTED



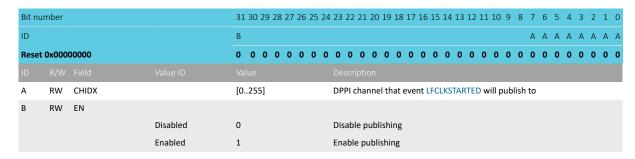




5.7.2.1.12 PUBLISH_LFCLKSTARTED

Address offset: 0x184

Publish configuration for event LFCLKSTARTED



5.7.2.1.13 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	ımber			31	30	29 2	8 2	27 2	26 2	25 2	4 2	23 2	2 2:	1 20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																																	ВА
Reset	0x000	00000		0	0	0 (כ	0	0	0 () (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																	
Α	RW	HFCLKSTARTED									Е	Enab	le c	or di	sab	le in	ter	rup	t fo	r e	/en	t HI	CL	KST	٩R٦	ΓED							
			Disabled	0								Disab	le																				
			Enabled	1							Е	Enab	le																				
В	RW	LFCLKSTARTED									E	Enab	le c	or di	sab	le in	ter	rup	t fo	r e	/en	t LF	CLI	KSTA	ART	ED							
			Disabled	0							0	Disab	le																				
			Enabled	1							E	Enab	le																				

5.7.2.1.14 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					B A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	HFCLKSTARTED			Write '1' to enable interrupt for event HFCLKSTARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	LFCLKSTARTED			Write '1' to enable interrupt for event LFCLKSTARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.2.1.15 INTENCLR

Address offset: 0x308

Disable interrupt



Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					В А
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	HFCLKSTARTED			Write '1' to disable interrupt for event HFCLKSTARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	LFCLKSTARTED			Write '1' to disable interrupt for event LFCLKSTARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

5.7.2.1.16 INTPEND

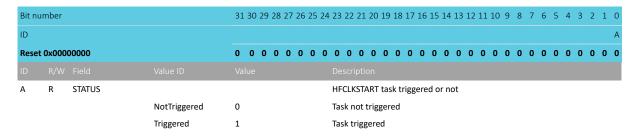
Address offset: 0x30C Pending interrupts

Bit nu	ımber			31	30 2	9 28	3 27	26	25	24 2	23 2	2 2	1 2	0 1	9 1	8 1	7 1	5 15	14	13	12	11	. 10	9	8	7	6	5	4	3	2	1 0
ID																																ВА
Reset	0x000	00000		0	0	0 0	0	0	0	0	0 (0) (0 0) (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																
Α	R	HFCLKSTARTED								F	Reac	d pe	end	ing	stat	tus	of i	ntei	rup	t fo	or e	ver	t H	FCLI	KST	AR1	ED					
			NotPending	0						ı	Read	d: N	ot	pen	din	g																
			Pending	1						F	Reac	d: P	enc	ding																		
В	R	LFCLKSTARTED								ı	Read	d pe	end	ing	stat	tus	of i	ntei	rup	t fo	r e	ver	t LF	CLk	(ST/	١RT	ED					
			NotPending	0						F	Read	d: N	ot	pen	din	g																
			Pending	1						ı	Read	d: P	enc	ding																		

5.7.2.1.17 HFCLKRUN

Address offset: 0x408

Status indicating that HFCLKSTART task has been triggered

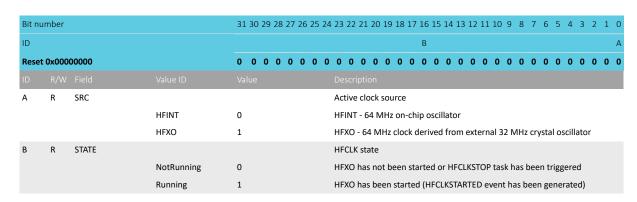


5.7.2.1.18 HFCLKSTAT

Address offset: 0x40C

The register shows if HFXO has been requested by triggering HFCLKSTART task and if it has been started (STATE)

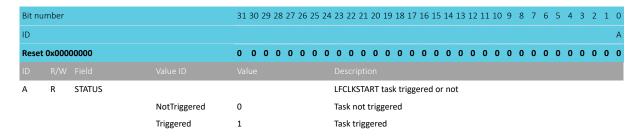




5.7.2.1.19 LFCLKRUN

Address offset: 0x414

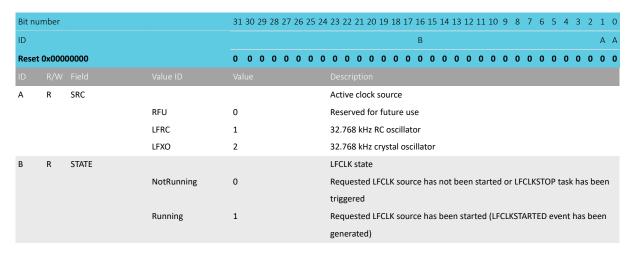
Status indicating that LFCLKSTART task has been triggered



5.7.2.1.20 LFCLKSTAT

Address offset: 0x418

The register shows which LFCLK source has been requested (SRC) when triggering LFCLKSTART task and if the source has been started (STATE)

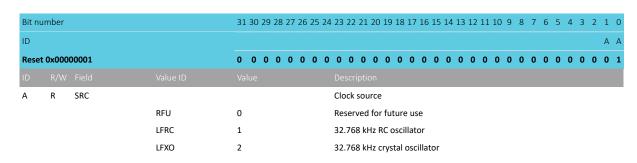


5.7.2.1.21 LFCLKSRCCOPY

Address offset: 0x41C

Copy of LFCLKSRC register, set after LFCLKSTART task has been triggered

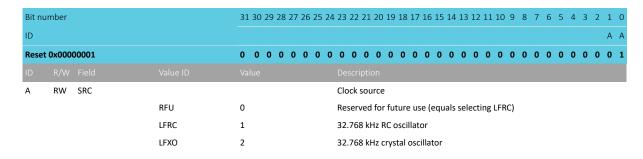




5.7.2.1.22 LFCLKSRC

Address offset: 0x518

Clock source for the LFCLK. LFCLKSTART task starts a clock source selected with this register.



5.7.3 REGULATORS — Voltage regulators control

The REGULATORS module provides an interface to certain configuration settings of on-chip voltage regulators.

5.7.3.1 Registers

Instances

Instance	Base address	TrustZone	TrustZone Sp			Description
		Мар	Att	DMA		
REGULATORS : S	0x50004000	LIC	NC	NI A	N-	Decidates and investiga
REGULATORS : NS	0x40004000	US	NS	NA	No	Regulator configuration

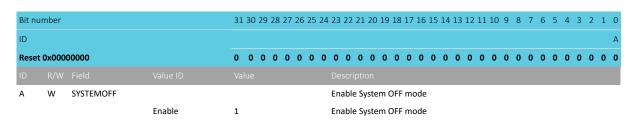
Register overview

Register	Offset	TZ	Description
SYSTEMOFF	0x500		System OFF register
EXTPOFCON	0x514		External power failure warning configuration
DCDCEN	0x578		Enable a step-down DC/DC voltage regulator

5.7.3.1.1 SYSTEMOFF

Address offset: 0x500 System OFF register

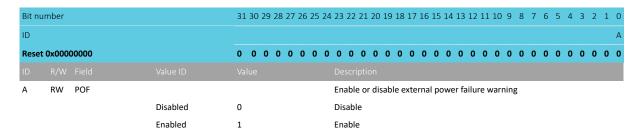




5.7.3.1.2 EXTPOFCON

Address offset: 0x514

External power failure warning configuration

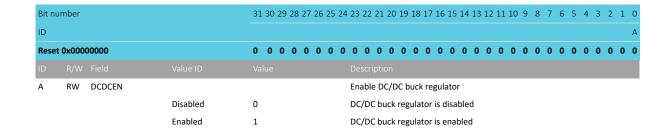


5.7.3.1.3 DCDCEN

Address offset: 0x578

Enable a step-down DC/DC voltage regulator

Note: DCDCEN must be set to 1 (enabled) before the LTE modem is started.





6 Peripherals

The nRF9161 application core peripherals are found in Instantiation on page 25.

6.1 CRYPTOCELL — ARM TrustZone CryptoCell 310

ARM TrustZone CryptoCell 310 (CRYPTOCELL) is a security subsystem which provides root of trust (RoT) and cryptographic services for a device.

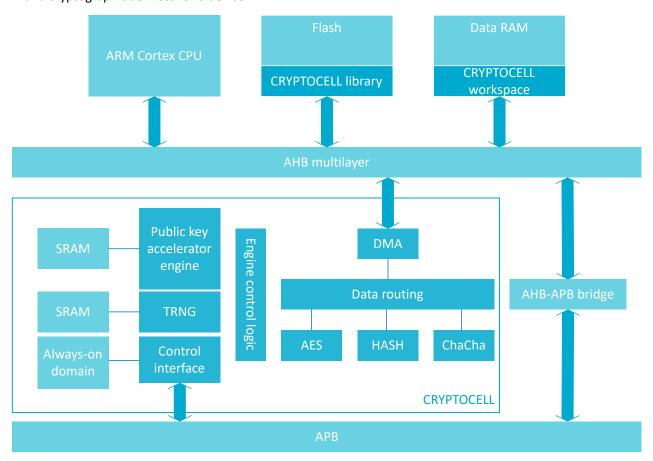


Figure 14: Block diagram for CRYPTOCELL

The following cryptographic features are provided:

- True random number generator (TRNG) compliant with NIST 800-90B, AIS-31, and FIPS 140-2
- Pseudorandom number generator (PRNG) using underlying AES engine compliant with NIST 800-90A
- RSA public key cryptography
 - Up to 2048-bit key size
 - PKCS#1 v2.1/v1.5
 - Optional CRT support
- Elliptic curve cryptography (ECC)
 - NIST FIPS 186-4 recommended curves using pseudorandom parameters, up to 521 bits:
 - Prime field: P-192, P-224, P-256, P-384, P-521
 - SEC 2 recommended curves using pseudorandom parameters, up to 521 bits:

NORDIC*

- Prime field: secp160r1, secp192r1, secp224r1, secp256r1, secp384r1, secp521r1
- Koblitz curves using fixed parameters, up to 256 bits:
 - Prime field: secp160k1, secp192k1, secp224k1, secp256k1
- Edwards/Montgomery curves:
 - Ed25519, Curve25519
- ECDH/ECDSA support
- Secure remote password protocol (SRP)
 - Up to 3072-bit operations
- · Hashing functions
 - SHA-1, SHA-2 up to 256 bits
 - Keyed-hash message authentication code (HMAC)
- · AES symmetric encryption
 - General purpose AES engine (encrypt/decrypt, sign/verify)
 - 128-bit key size
 - Supported encryption modes: ECB, CBC, CMAC/CBC-MAC, CTR, CCM/CCM* (CCM* is a minor variation of CCM)
- ChaCha20/Poly1305 symmetric encryption
 - Supported key size: 128 and 256 bits
 - Authenticated encryption with associated data (AEAD) mode

6.1.1 Usage

The CRYPTOCELL state is controlled via a register interface. The cryptographic functions of CRYPTOCELL are accessible by using a software library provided in the device SDK, not directly via a register interface.

To enable CRYPTOCELL, use register **ENABLE** on page 83.

Note: Keeping the CRYPTOCELL subsystem enabled will prevent the device from reaching the System ON, All Idle state.

6.1.2 Always-on (AO) power domain

The CRYPTOCELL subsystem has an internal always-on (AO) power domain for retaining device secrets when CRYPTOCELL is disabled.

The following information is retained by the AO power domain:

- 4 bits indicating the configured CRYPTOCELL lifecycle state (LCS)
- 1 bit indicating if the hard-coded RTL key, K_{PRTL} (see RTL key on page 81), is available for use
- 128-bit device root key, K_{DR} (see Device root key on page 81)

A reset from any reset source will erase the content in the AO power domain.

6.1.3 Lifecycle state (LCS)

Lifecycle refers to multiple states a device goes through during its lifetime. Two valid lifecycle states are offered for the device - debug and secure.

The CRYPTOCELL subsystem lifecycle state (LCS) is controlled through register HOST_IOT_LCS on page 85. A valid LCS is configured by writing either value <code>Debug</code> or <code>Secure</code> into the LCS field of this register. A correctly configured LCS can be validated by reading back the read-only field LCS_IS_VALID from the abovementioned register. The LCS_IS_VALID field value will change from <code>Invalid</code> to <code>Valid</code> once a valid LCS value has been written.



LCS field value	LCS_IS_VALID field value	Description
Secure	Invalid	Default reset value indicating that LCS has not been configured.
Secure	Valid	$LCS \ set \ to \ secure \ mode, \ and \ LCS \ is \ valid. \ Registers \ HOST_IOT_KDR[03] \ can \ only \ be \ written \ once \ per \ reset \ cycle.$
		Any additional writes will be ignored.
Debug	Valid	LCS set to debug mode, and LCS is valid. Registers HOST_IOT_KDR[03] can be written multiple times.

Table 14: Lifecycle states

6.1.4 Cryptographic key selection

The CRYPTOCELL subsystem can be instructed to operate on different cryptographic keys.

Through register HOST_CRYPTOKEY_SEL on page 83, the following key types can be selected for cryptographic operations:

- RTL key K_{PRTL}
- Device root key K_{DR}
- Session key

K_{PRTL} and K_{DR} are configured as part of the CRYPTOCELL initialization process, while session keys are provided by the application through the software library API.

6.1.4.1 RTL key

The ARM TrustZone CryptoCell 310 contains one hard-coded RTL key referred to as K_{PRTL} . This key is set to the same value for all devices with the same part code in the hardware design and cannot be changed.

The K_{PRTL} key can be requested for use in cryptographic operations by the CRYPTOCELL, without revealing the key value itself. Access to use of K_{PRTL} in cryptographic operations can be disabled until next reset by writing to register HOST_IOT_KPRTL_LOCK on page 84. If a locked K_{PRTL} key is requested for use, a zero vector key will be routed to the AES engine instead.

6.1.4.2 Device root key

The device root key K_{DR} is a 128-bit AES key programmed into the CRYPTOCELL subsystem using firmware. It is retained in the AO power domain until the next reset.

Once configured, it is possible to perform cryptographic operations using the CRYPTOCELL subsystem where K_{DR} is selected as key input without having access to the key value itself. The K_{DR} key value must be written to registers HOST_IOT_KDR[0..3]. These 4 registers are write-only if LCS is set to debug mode, and write-once if LCS is set to secure mode. The K_{DR} key value is successfully retained when the read-back value of register HOST_IOT_KDR0 on page 84 changes to 1.

6.1.5 Direct memory access (DMA)

The CRYPTOCELL subsystem implements direct memory access (DMA) for accessing memory without CPU intervention.

Any data stored in memory type(s) not accessible by the DMA engine must be copied to SRAM before it can be processed by the CRYPTOCELL subsystem. Maximum DMA transaction size is limited to 2¹⁶-1 bytes.

6.1.6 Standards

ARM TrustZone CryptoCell 310 (CRYPTOCELL) supports a number of cryptography standards.



Algorithm family	Identification code	Document title
TRNG	NIST SP 800-90B	Recommendation for the Entropy Sources Used for Random Bit Generation
	AIS-31	A proposal for: Functionality classes and evaluation methodology for physical random number generators
	FIPS 140-2	Security Requirements for Cryptographic Modules
PRNG	NIST SP 800-90A	Recommendation for Random Number Generation Using Deterministic Random Bit Generators
Stream cipher	Chacha	ChaCha, a variant of Salsa20, Daniel J. Bernstein, January 28th 2008
MAC	Poly1305	The Poly1305-AES message-authentication code, Daniel J. Bernstein
		Cryptography in NaCl, Daniel J. Bernstein
Key agreement	SRP	The Secure Remote Password Protocol, Thomas Wu, November 11th 1997
AES	FIPS-197	Advanced Encryption Standard (AES)
	NIST SP 800-38A	Recommendation for Block Cipher Modes of Operation - Methods and Techniques
	NIST SP 800-38B	Recommendation for Block Cipher Modes of Operation: The CMAC Mode for Authentication
	NIST SP 800-38C	Recommendation for Block Cipher Modes of Operation: The CCM Mode for Authentication and
		Confidentiality
	ISO/IEC 9797-1	AES CBC-MAC per ISO/IEC 9797-1 MAC algorithm 1
	IEEE 802.15.4-2011	IEEE Standard for Local and metropolitan area networks - Part 15.4: Low-Rate Wireless Personal Area
		Networks (LR-WPANs), Annex B.4: Specification of generic CCM* mode of operation
Hash	FIPS 180-3	Secure Hash Standard (SHA1, SHA-224, SHA-256)
	RFC2104	HMAC: Keyed-Hashing for Message Authentication
RSA	PKCS#1	Public-Key Cryptography Standards (PKCS) #1: RSA Cryptography Specifications v1.5/2.1
Diffie-Hellman	ANSI X9.42	Public Key Cryptography for the Financial Services Industry: Agreement of Symmetric Keys Using Discrete
		Logarithm Cryptography
	PKCS#3	Diffie-Hellman Key-Agreement Standard
ECC	ANSI X9.63	Public Key Cryptography for the Financial Services Industry - Key Agreement and Key Transport Using
		Elliptic Curve Cryptography
	IEEE 1363	Standard Specifications for Public-Key Cryptography
	ANSI X9.62	Public Key Cryptography For The Financial Services Industry: The Elliptic Curve Digital Signature Algorithm
		(ECDSA)
	Ed25519	Edwards-curve, Ed25519: high-speed high-security signatures, Daniel J. Bernstein, Niels Duif, Tanja Lange,
		Peter Schwabe, and Bo-Yin Yang
	Curve25519	Montgomery curve, Curve25519: new Diffie-Hellman speed records, Daniel J. Bernstein
	FIPS 186-4	Digital Signature Standard (DSS)
	SEC 2	Recommended Elliptic Curve Domain Parameters, Certicom Research
	NIST SP 800-56A rev. 2	Recommendation for Pair-Wise Key Establishment Schemes Using Discrete Logarithm Cryptography

Table 15: CRYPTOCELL cryptography standards

6.1.7 Registers

Instances

Instance	Base address	TrustZone	:		Split access	Description
		Мар	Att	DMA		
CRYPTOCELL	0x50840000	HF	S	NSA	No	CryptoCell sub-system control interface

Register overview

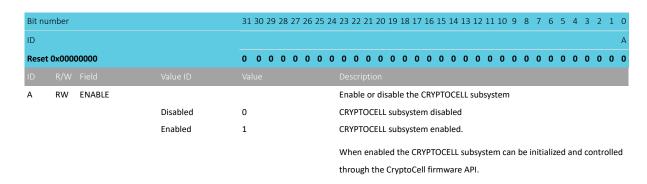
Register	Offset	TZ	Description
ENABLE	0x500		Enable CRYPTOCELL subsystem



6.1.7.1 ENABLE

Address offset: 0x500

Enable CRYPTOCELL subsystem



6.1.8 Host interface

This chapter describes host registers used to control the CRYPTOCELL subsystem behavior.

6.1.8.1 HOST_RGF block

The HOST_RGF block contains registers for configuring LCS and device root key K_{DR}, in addition to selecting which cryptographic key is connected to the AES engine.

6.1.8.1.1 Registers

Instances

Instance	Base address	TrustZone	:		Split access	Description
		Мар	Att	DMA		
CC_HOST_RGF	0x50840000	HF	S	NSA	No	Host platform interface

Register overview

Register	Offset	TZ	Description
HOST_CRYPTOKEY_SEL	0x1A38		AES hardware key select
HOST_IOT_KPRTL_LOCK	0x1A4C		This write-once register is the K_PRTL lock register. When this register is set, K_PRTL cannot
			be used and a zeroed key will be used instead. The value of this register is saved in the
			CRYPTOCELL AO power domain.
HOST_IOT_KDR0	0x1A50		This register holds bits 31:0 of K_DR. The value of this register is saved in the CRYPTOCELL AO
			power domain. Reading from this address returns the K_DR valid status indicating if K_DR is
			successfully retained.
HOST_IOT_KDR1	0x1A54		This register holds bits 63:32 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_KDR2	0x1A58		This register holds bits 95:64 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_KDR3	0x1A5C		This register holds bits 127:96 of K_DR. The value of this register is saved in the CRYPTOCELL
			AO power domain.
HOST_IOT_LCS	0x1A60		Controls lifecycle state (LCS) for CRYPTOCELL subsystem

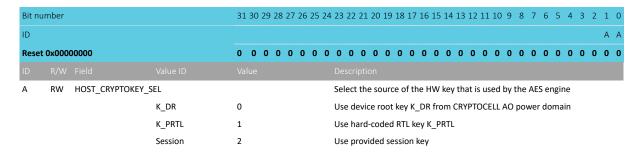
6.1.8.1.1.1 HOST_CRYPTOKEY_SEL

Address offset: 0x1A38



AES hardware key select

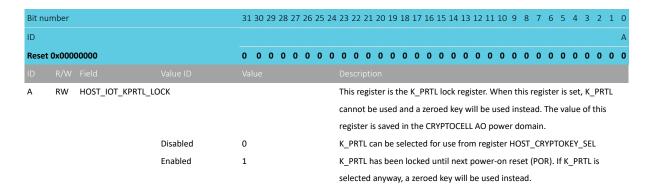
Note: If the HOST_IOT_KPRTL_LOCK register is set, and the HOST_CRYPTOKEY_SEL register set to 1, then the HW key that is connected to the AES engine is zero



6.1.8.1.1.2 HOST_IOT_KPRTL_LOCK

Address offset: 0x1A4C

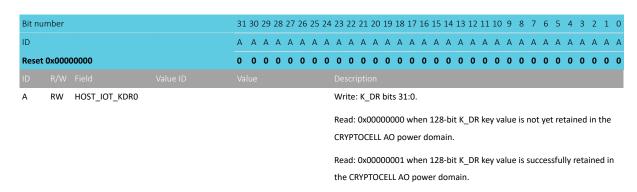
This write-once register is the K_PRTL lock register. When this register is set, K_PRTL cannot be used and a zeroed key will be used instead. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.3 HOST_IOT_KDR0

Address offset: 0x1A50

This register holds bits 31:0 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain. Reading from this address returns the K_DR valid status indicating if K_DR is successfully retained.

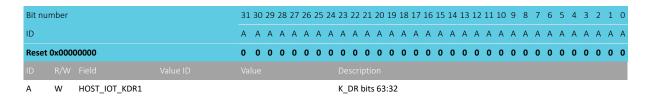


6.1.8.1.1.4 HOST_IOT_KDR1

Address offset: 0x1A54



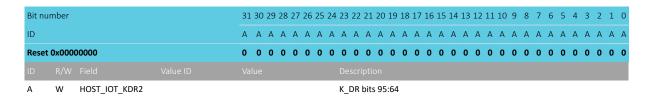
This register holds bits 63:32 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.5 HOST_IOT_KDR2

Address offset: 0x1A58

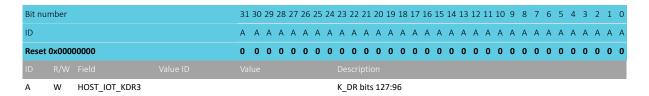
This register holds bits 95:64 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.6 HOST_IOT_KDR3

Address offset: 0x1A5C

This register holds bits 127:96 of K_DR. The value of this register is saved in the CRYPTOCELL AO power domain.



6.1.8.1.1.7 HOST_IOT_LCS

Address offset: 0x1A60

Controls lifecycle state (LCS) for CRYPTOCELL subsystem

Bit nu	umber			31 3	0 29 :	28 2	27 26	5 25	5 24	23	22	21	20	19 1	L8 1	7 1	5 15	14	13	12 1	1 1	10 9	8	7	6	5	4	3	2	1 0
ID																							В						Α	А А
Reset	t 0x000	00002		0 0	0	0	0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	1 0
ID																														
Α	RW	LCS								Life	ecyc	cle s	state	e va	lue.	Thi	s fie	ld is	wr	ite-d	once	e pe	r res	et.						
			Debug	0						CC	310	ор (erat	tes i	n d	ebu	g m	ode												
			Secure	2						CC	310	ор (erat	tes i	n se	cur	e m	ode												
В	RW	LCS_IS_VALID								Rea	ad-c	only	y fie	ld. I	ndi	cate	s if	CRY	РТО	CEL	L LC	S ha	ıs be	en	suc	ces	sfull	y		
										100	nfig	ure	d sii	nce	last	res	et.													
			Invalid	0						Val	lid L	.CS	not	yet	reta	aine	d in	the	CR'	YPT	OCE	LL A	Ор	owe	er do	oma	ain			
			Valid	1						Val	lid L	.CS	suc	cess	full	y re	ain	ed ii	n th	e CF	YP	гос	ELL	10	oow	er	don	nain		



6.2 DPPI - Distributed programmable peripheral interconnect

The distributed programmable peripheral interconnect (DPPI) enables peripherals to interact autonomously with each other by using tasks and events, without any intervention from the CPU. DPPI allows precise synchronization between peripherals when real-time application constraints exist and eliminates the need for CPU involvement to implement behavior which can be predefined using the DPPI.

Note: For more information on tasks, events, publish/subscribe, interrupts, and other concepts, see Peripheral interface on page 15.

The DPPI has the following features:

- · Peripheral tasks can subscribe to channels
- Peripheral events can be published on channels
- Publish/subscribe pattern enabling multiple connection options that include the following:
 - · One-to-one
 - · One-to-many
 - Many-to-one
 - Many-to-many

The DPPI consists of several PPIBus modules, which are connected to a fixed number of DPPI channels and a DPPI configuration (DPPIC).



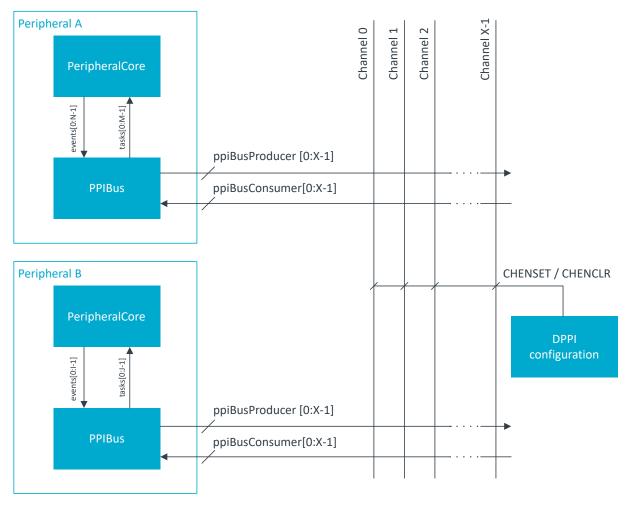


Figure 15: DPPI overview

6.2.1 Subscribing to and publishing on channels

The PPIBus can route peripheral events onto the channels (publishing), or route events from the channels into peripheral tasks (subscribing).

All peripherals include the following:

- One subscribe register per task
- One publish register per event

Publish and subscribe registers use a channel index field to determine the channel to which the event is published or tasks subscribed. In addition, there is an enable bit for the subscribe and publish registers that needs to be enabled before the subscription or publishing takes effect.

Writing non-existing channel index (CHIDX) numbers into a peripheral's publish or subscribe registers will yield unexpected results.

One event can trigger multiple tasks by subscribing different tasks to the same channel. Similarly, one task can be triggered by multiple events by publishing different events to the same channel. For advanced use cases, multiple events and multiple tasks can connect to the same channel forming a many-to-many connection. If multiple events are published on the same channel at the same time, the events are merged and only one event is routed through the DPPI.

How peripheral events are routed onto different channels based on publish registers is illustrated in the following figure.



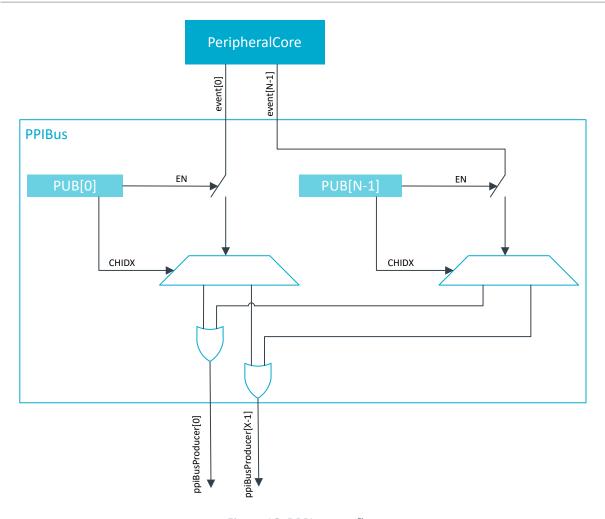


Figure 16: DPPI events flow

The following figure illustrates how peripheral tasks are triggered from different channels based on subscribe registers.



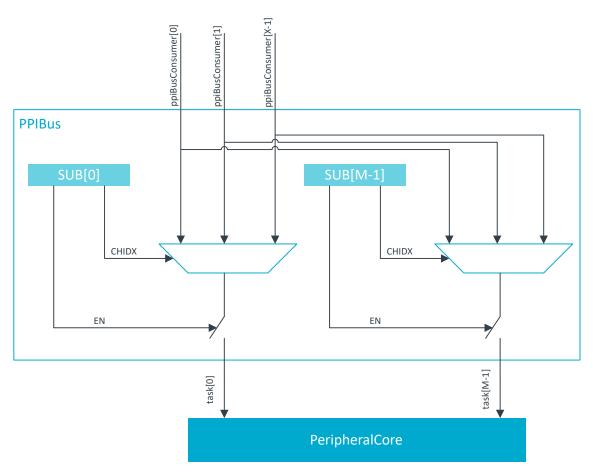


Figure 17: DPPI tasks flow

6.2.2 DPPI configuration (DPPIC)

Enabling and disabling of channels globally is handled through the DPPI configuration (DPPIC). Connection (connect/disconnect) between a channel and a peripheral is handled locally by the PPIBus.

There are two ways of enabling and disabling global channels using the DPPI configuration:

- Enable or disable channels individually using registers CHEN, CHENSET, and CHENCLR.
- Enable or disable channels in channel groups using the groups' tasks ENABLE and DISABLE. It needs to be defined which channels belong to which channel groups before these tasks are triggered.

Note: ENABLE tasks are prioritized over DISABLE tasks. When a channel belongs to two or more groups, for example group m and n, and the tasks CHG[m].EN and CHG[n].DIS occur simultaneously (m and n can be equal or different), the CHG[m].EN task on that channel is prioritized.

The DPPI configuration tasks (for example CHG[0].EN) can be triggered through DPPI like any other task, which means they can be linked to a DPPI channel through the subscribe registers.

In order to write to CHG[x], the corresponding CHG[x].EN and CHG[x].DIS subscribe registers must be disabled. Writes to CHG[x] are ignored if any of the two subscribe registers are enabled.

6.2.3 Connection examples

DPPI offers several connection options. Examples are given for how to create one-to-one and many-to-many connections.



One-to-one connection

This example shows how to create a one-to-one connection between TIMER compare register and SAADC start task.

The channel configuration is set up first. TIMERO will publish its COMPAREO event on channel 0, and SAADC will subscribe its START task to events on the same channel. After that, the channel is enabled through the DPPIC.

Many-to-many connection

The example shows how to create a many-to-many connection, showcasing the DPPIC's channel group functionality.

A channel group that includes only channel 0 is set up first. Then the GPIOTE and TIMERO configure their INO and COMPAREO events respectively to be published on channel 0, while the SAADC configures its START task to subscribe to events on channel 0. Through DPPIC, the CHGO DISABLE task is configured to subscribe to events on channel 0. After an event is received on channel 0 it will be disabled. Finally, channel 0 is enabled using the DPPIC task to enable a channel group.

6.2.4 Special considerations for a system implementing TrustZone for Cortex-M processors

DPPI is implemented with split security, meaning it handles both secure and non-secure accesses. In a system implementing the TrustZone for Cortex-M technology, DPPI channels can be defined as secure or non-secure using the SPU.

A peripheral configured as non-secure will only be able to subscribe to or publish on non-secure DPPI channels. A peripheral configured as secure will be able to access all DPPI channels. DPPI handles both secure and non-secure accesses, but behaves differently depending on the access type:

• A non-secure peripheral access can only configure and control the DPPI channels defined as non-secure in the SPU.DPPI.PERM[] register(s)



A secure peripheral access can control all the DPPI channels, independently of the SPU.DPPI.PERM[]
register(s)

A group of channels can be created, making it possible to simultaneously enable or disable all channels within the group. The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all channels (enabled or not) within a group are non-secure, then the group is considered non-secure
- If at least one of the channels (enabled or not) within the group is secure, then the group is considered secure

A non-secure access to a DPPI register, or a bit field, controlling a channel marked as secure in SPU.DPPI[].PERM register(s) will be ignored. Write accesses will have no effect, and read accesses will always return a zero value.

No exceptions are triggered when non-secure accesses target a register or a bit field controlling a secure channel. For example, if the bit \pm is set in the SPU.DPPI[0].PERM register (declaring DPPI channel i as secure), then:

- Non-secure write accesses to registers CHEN, CHENSET, and CHENCLR cannot write bit \mathtt{i} of these registers
- Non-secure write accesses to TASK_CHG[j].EN and TASK_CHG[j].DIS registers are ignored if the channel group j contains at least one channel defined as secure (it can be the channel i itself or any channel declared as secure)
- Non-secure read accesses to registers CHEN, CHENSET, and CHENCLR always read 0 for the bit at position \mathtt{i}

For the channel configuration registers (CHG[]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a CHG[g] register included one or more secure channel(s), then the group g is considered as secure, and only secure transfers can read to or write from CHG[g]. A non-secure write access is ignored, and a non-secure read access returns 0.

The DPPI can subscribe to secure and non-secure channels through the SUBSCRIBE_CHG[] registers, in order to trigger the task for enabling or disabling groups of channels. An event from a secure channel will be ignored if the group subscribing to this channel is non-secure. A secure group can subscribe to a non-secure channel or a secure channel.

6.2.5 Registers

Instances

Instance	Base address	TrustZone	•		Split access	Description
		Мар	Att	DMA		
DPPIC : S	0x50017000	ПЕ	NC	NA	Yes	DDDL configuration
DPPIC : NS	0x40017000	HF	HF NS		res	DPPI configuration



Register overview

Register	Offset	TZ	Description
TASKS_CHG[n].EN	0x000		Enable channel group n
TASKS_CHG[n].DIS	0x004		Disable channel group n
SUBSCRIBE_CHG[n].EN	0x080		Subscribe configuration for task CHG[n].EN
SUBSCRIBE_CHG[n].DIS	0x084		Subscribe configuration for task CHG[n].DIS
CHEN	0x500		Channel enable register
CHENSET	0x504		Channel enable set register
CHENCLR	0x508		Channel enable clear register
CHG[n]	0x800		Channel group n
			Note: Writes to this register are ignored if either SUBSCRIBE_CHG[n].EN or
			SUBSCRIBE_CHG[n].DIS is enabled

6.2.5.1 TASKS_CHG[n] (n=0..5)

Channel group tasks

6.2.5.1.1 TASKS_CHG[n].EN (n=0..5)

Address offset: $0x000 + (n \times 0x8)$

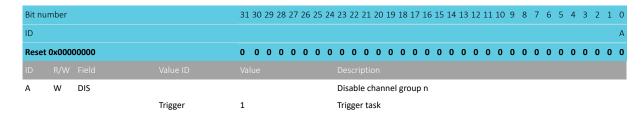
Enable channel group n

Bit no	umber			31 30 29	28 27	26 25	24 2	3 22	2 21	20 1	19 1	8 17	16	15 3	14 1	.3 12	11	10	9 8	3 7	6	5	4	3	2 :	1 0
ID																										Α
Rese	t 0x000	00000		0 0 0	0 0	0 0	0 (0	0	0	0 (0 0	0	0	0	0 0	0	0	0 (0 0	0	0	0	0	0 (0 0
ID																										
Α	W	EN					Е	nab	le ch	ann	el g	roup	n													
			Trigger	1			Т	rigg	er ta	sk																

6.2.5.1.2 TASKS_CHG[n].DIS (n=0..5)

Address offset: $0x004 + (n \times 0x8)$

Disable channel group n



6.2.5.2 SUBSCRIBE_CHG[n] (n=0..5)

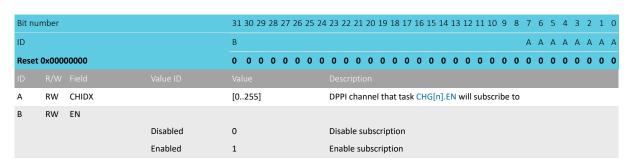
Subscribe configuration for tasks

6.2.5.2.1 SUBSCRIBE_CHG[n].EN (n=0..5)

Address offset: $0x080 + (n \times 0x8)$

Subscribe configuration for task CHG[n].EN





6.2.5.2.2 SUBSCRIBE_CHG[n].DIS (n=0..5)

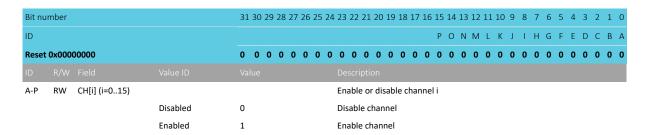
Address offset: $0x084 + (n \times 0x8)$

Subscribe configuration for task CHG[n].DIS

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task CHG[n].DIS will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.2.5.3 CHEN

Address offset: 0x500 Channel enable register



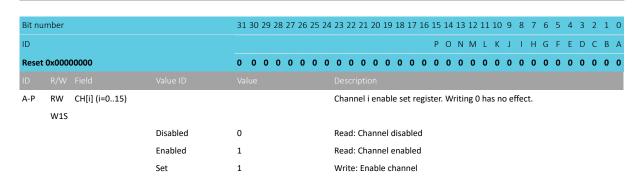
6.2.5.4 CHENSET

Address offset: 0x504

Channel enable set register

Note: Read: Reads value of CHi field in CHEN register



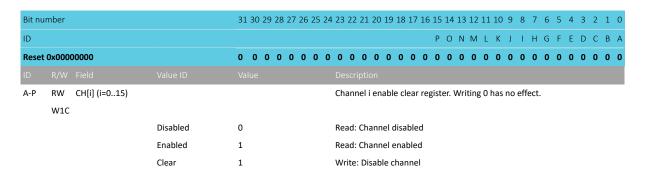


6.2.5.5 CHENCLR

Address offset: 0x508

Channel enable clear register

Note: Read: Reads value of CHi field in CHEN register



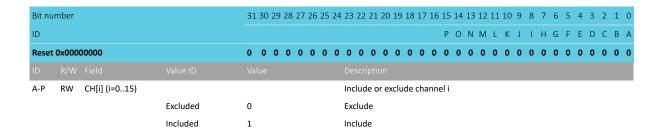
6.2.5.6 CHG[n] (n=0..5)

Address offset: $0x800 + (n \times 0x4)$

Channel group n

Note: Writes to this register are ignored if either SUBSCRIBE_CHG[n].EN or SUBSCRIBE_CHG[n].DIS is

enabled



6.3 EGU — Event generator unit

Event generator unit (EGU) provides support for interlayer signaling. This means providing support for atomic triggering of both CPU execution and hardware tasks, from both firmware (by CPU) and hardware (by PPI). This feature can, for instance, be used for triggering CPU execution at a lower priority execution from a higher priority execution, or to handle a peripheral's interrupt service routine (ISR) execution at a lower priority for some of its events. However, triggering any priority from any priority is possible.

Listed here are the main EGU features:



- Software-enabled interrupt triggering
- Separate interrupt vectors for every EGU instance
- Up to 16 separate event flags per interrupt for multiplexing

Each instance of EGU implements a set of tasks which can individually be triggered to generate the corresponding event, for example, the corresponding event for TASKS_TRIGGER[n] is EVENTS_TRIGGERED[n]. See Instances on page 95 for a list of EGU instances.

6.3.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
EGU0: S	0x5001B000	US	NS	NA	No	Event generator unit 0
EGU0: NS	0x4001B000	03	145	NA .	140	Event generator unit o
EGU1:S	0x5001C000	US	NS	NA	No	Event generator unit 1
EGU1: NS	0x4001C000	03	INS	INA	INO	Event generator unit 1
EGU2:S	0x5001D000	US	NS	NA	No	Event generator unit 2
EGU2 : NS	0x4001D000	03	INS	INA	INO	Event generator unit 2
EGU3:S	0x5001E000	US	NS	NA	No	Event generator unit 2
EGU3: NS	0x4001E000	03	INS	INA	INO	Event generator unit 3
EGU4:S	0x5001F000	uc	NC	N/A	NI-	Format and a section with 4
EGU4 : NS	0x4001F000	US	NS N	NA	No	Event generator unit 4
EGU5: S	0x50020000	uc	NC	N/A	NI-	Format and a section with F
EGU5: NS	0x40020000	US	NS	NA	No	Event generator unit 5

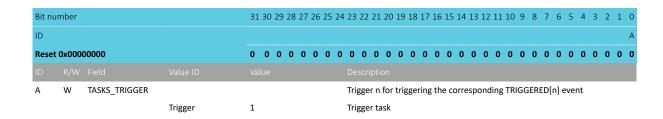
Register overview

Register	Offset	TZ	Description
TASKS_TRIGGER[n]	0x000		Trigger n for triggering the corresponding TRIGGERED[n] event
SUBSCRIBE_TRIGGER[n]	0x080		Subscribe configuration for task TRIGGER[n]
EVENTS_TRIGGERED[n]	0x100		Event number n generated by triggering the corresponding TRIGGER[n] task
PUBLISH_TRIGGERED[n]	0x180		Publish configuration for event TRIGGERED[n]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt

6.3.1.1 TASKS_TRIGGER[n] (n=0..15)

Address offset: $0x000 + (n \times 0x4)$

Trigger n for triggering the corresponding TRIGGERED[n] event

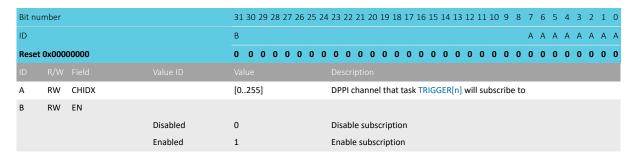




6.3.1.2 SUBSCRIBE_TRIGGER[n] (n=0..15)

Address offset: $0x080 + (n \times 0x4)$

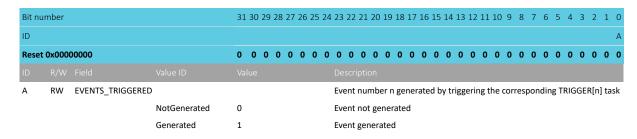
Subscribe configuration for task TRIGGER[n]



6.3.1.3 EVENTS_TRIGGERED[n] (n=0..15)

Address offset: $0x100 + (n \times 0x4)$

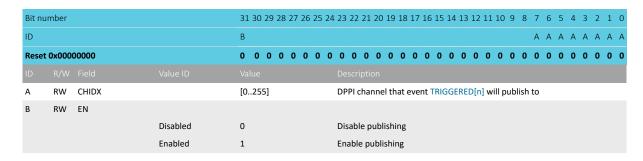
Event number n generated by triggering the corresponding TRIGGER[n] task



6.3.1.4 PUBLISH_TRIGGERED[n] (n=0..15)

Address offset: $0x180 + (n \times 0x4)$

Publish configuration for event TRIGGERED[n]

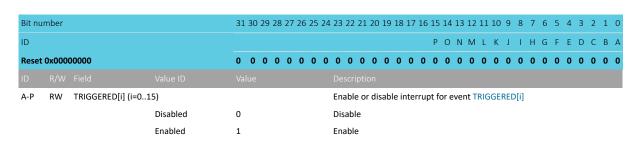


6.3.1.5 INTEN

Address offset: 0x300

Enable or disable interrupt





6.3.1.6 INTENSET

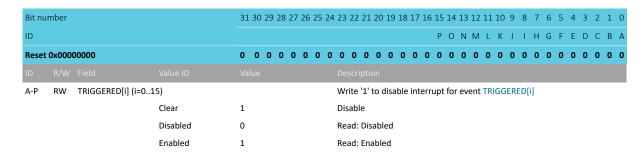
Address offset: 0x304 Enable interrupt

Bit nu	mber			31 30 29 28 27 26 25 2	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0											
ID					P O N M L K J I H G F E D C B A											
Reset 0x00000000 0 0 0 0				0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0											
ID					Description											
A-P	RW	TRIGGERED[i] (i=0	15)		Write '1' to enable interrupt for event TRIGGERED[i]											
			Set	1	Enable											
			Disabled	0	Read: Disabled											
					Read: Enabled											

6.3.1.7 INTENCLR

Address offset: 0x308

Disable interrupt



6.3.2 Electrical specification

6.3.2.1 EGU Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{EGU,EVT}	Latency between setting an EGU event flag and the system setting an		1		cycles
	interrupt				

6.4 GPIO — General purpose input/output

The general purpose input/output pins (GPIOs) are grouped as one or more ports with each port having up to 32 GPIOs.



The number of ports and GPIOs per port may vary with product variant and package. Refer to Registers on page 102 and Pin assignments on page 450 for more information about the number of GPIOs that are supported.

GPIO has the following user-configurable features:

- Up to 32 GPIO pins per GPIO port
- · Configurable output drive strength
- Internal pull-up and pull-down resistors
- Wake-up from high or low level triggers on all pins
- Trigger interrupt on state changes on any pin
- All pins can be used by the PPI task/event system
- One or more GPIO outputs can be controlled through PPI and GPIOTE channels
- · All pins can be individually mapped to interface blocks for layout flexibility
- · GPIO state changes captured on SENSE signal can be stored by LATCH register
- Support for secure and non-secure attributes for pins in conjunction with the system protection unit (SPU — System protection unit on page 257)

GPIO port and the GPIO pin details on page 98 illustrates the GPIO port containing 32 individual pins, where PINO is illustrated in more detail as a reference. All signals on the left side in the illustration are used by other peripherals in the system and therefore not directly available to the CPU.

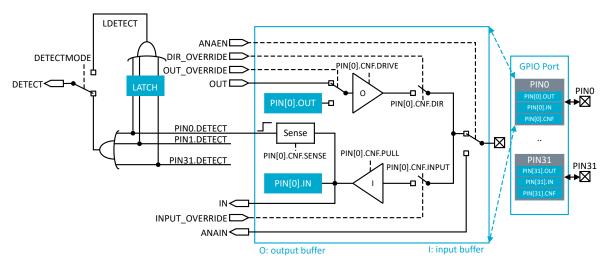


Figure 18: GPIO port and the GPIO pin details

6.4.1 Pin configuration

The GPIO port peripheral implements up to 32 pins, PIN0 through PIN31. Each of these pins can be individually configured in the PIN CNF[n] registers (n=0..31).

The following parameters can be configured through these registers:

- Direction
- Drive strength
- Enabling of pull-up and pull-down resistors
- Pin sensing
- Input buffer disconnect
- · Analog input (for selected pins)

Note: All write-capable registers are retained registers, see POWER — Power control on page 63 for more information.



The input buffer of a GPIO pin can be disconnected from the pin to enable power savings when the pin is not used as an input, see GPIO port and the GPIO pin details on page 98. Inputs must be connected to get a valid input value in the IN register, and for the sense mechanism to get access to the pin.

Other peripherals in the system can connect to GPIO pins and override their output value and configuration, or read their analog or digital input value. See GPIO port and the GPIO pin details on page 98.

Selected pins also support analog input signals, see ANAIN in GPIO port and the GPIO pin details on page 98. The assignment of the analog pins can be found in Pin assignments on page 450.

The following delays should be taken into considerations:

- There is a delay of 2 CPU clock cycles from the GPIO pad to the IN register.
- The GPIO pad must be low (or high depending on the SENSE polarity) for 3 CPU clock cycles after DETECT has gone high to generate a new DETECT signal.

Note: When a pin is configured as digital input, care has been taken to minimize increased current consumption when the input voltage is between V_{IL} and V_{IH} . However, it is a good practice to ensure that the external circuitry does not drive that pin to levels between V_{IL} and V_{IH} for a long period of time.

6.4.2 Pin sense mechanism

Pins sensitivity can be individually configured, through the SENSE field in the PIN_CNF[n] register, to detect either a high level or a low level on their input.

When the correct level is detected on any such configured pin, the sense mechanism will set the DETECT signal high. Each pin has a separate DETECT signal. Default behavior, defined by the DETECTMODE register, is that the DETECT signals from all pins in the GPIO port are combined into one common DETECT signal that is routed throughout the system, which then can be utilized by other peripherals. This mechanism is functional in both System ON and System OFF modes.

DETECTMODE and DETECTMODE_SEC are provided to handle secure and non-secure pins.

DETECTMODE_SEC register is available to control the behavior associated to pin marked as secure, while the DETECTMODE register is restricted to pin marked as non-secure. Please refer to GPIO security on page 100 for more details.

Make sure that a pin is in a level that cannot trigger the sense mechanism before enabling it. The DETECT signal will go high immediately if the SENSE condition configured in the PIN_CNF registers is met when the sense mechanism is enabled. This will trigger a PORT event if the DETECT signal was low before enabling the sense mechanism.

The DETECT signal is also used by power and clock management system to exit from System OFF mode, and by GPIOTE to generate the PORT event. In addition GPIOTE_SEC is used for PORT event related to secure pins). See POWER — Power control on page 63 and GPIOTE — GPIO tasks and events on page 107 for more information about how the DETECT signal is used.

When a pin's PINx.DETECT signal goes high, a flag will be set in the LATCH register. For example, when the PINO.DETECT signal goes high, bit 0 in the LATCH register will be set to '1'. If the CPU performs a clear operation on a bit in the LATCH register when the associated PINx.DETECT signal is high, the bit in the LATCH register will not be cleared. The LATCH register will only be cleared if the CPU explicitly clears it by writing a '1' to the bit that shall be cleared, i.e. the LATCH register will not be affected by a PINx.DETECT signal being set low.

The LDETECT signal will be set high when one or more bits in the LATCH register are '1'. The LDETECT signal will be set low when all bits in the LATCH register are successfully cleared to '0'.



If one or more bits in the LATCH register are '1' after the CPU has performed a clear operation on the LATCH registers, a rising edge will be generated on the LDETECT signal. This is illustrated in DETECT signal behavior on page 100.

Note: The CPU can read the LATCH register at any time to check if a SENSE condition has been met on one or more of the GPIO pins, even if that condition is no longer met at the time the CPU queries the LATCH register. This mechanism will work even if the LDETECT signal is not used as the DETECT signal.

The LDETECT signal is by default not connected to the GPIO port's DETECT signal, but via the DETECTMODE register it is possible to change from default behavior to DETECT signal being derived directly from the LDETECT signal instead. See GPIO port and the GPIO pin details on page 98. DETECT signal behavior on page 100 illustrates the DETECT signal behavior for these two alternatives.

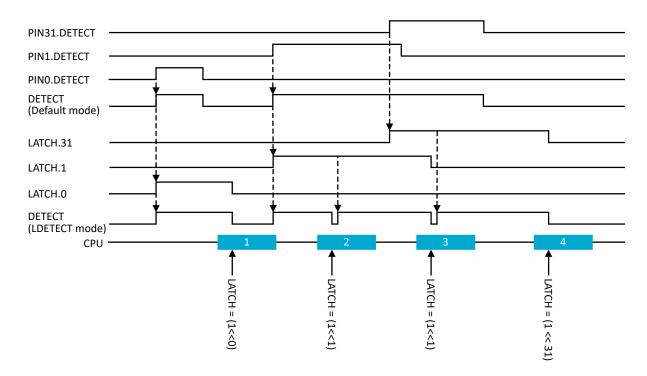


Figure 19: DETECT signal behavior

6.4.3 GPIO security

The general purpose input/output (GPIO) peripheral is implemented as a *split-security* peripheral. If marked as non-secure, it can be accessed by both secure and non-secure accesses but will behave differently depending on the access type.

A non-secure peripheral access will only be able to configure and control pins defined as non-secure in the system protection unit (SPU) GPIOPORT.PERM[] register(s).

A non-secure access to a register or a bitfield controlling a pin marked as secure in GPIO.PERM[] register(s) will be ignored. Write access will have no effect and read access will return a zero value.

No exception is triggered when a non-secure access targets a register or bitfield controlling a secure pin. For example, if the bit i is set in the SPU.GPIO.PERM[0] register (declaring Pin P0.i as secure), then

- non-secure write accesses to OUT, OUTSET, OUTCLR, DIR, DIRSET, DIRCLR and LATCH registers will not be able to write to bit i of those registers
- non-secure write accesses to registers PIN[i].OUT and PIN CNF[i] will be ignored



- non-secure read accesses to registers OUT, OUTSET, OUTCLR, IN, DIR, DIRSET, DIRCLR and LATCH will always read a '0' for the bit at position $\dot{\text{1}}$
- non-secure read accesses to registers PIN[i].OUT, PIN[i].OUT and PIN_CNF[i] will always return 0

The GPIO.DETECTMODE and GPIO.DETECTMODE_SEC registers are handled differently than the other registers mentioned before. When accessed by a secure access, the DETECTMODE_SEC register control the source for the DETECT_SEC signal for the pins marked as secure. When accessed by a non-secure access, the DETECTMODE_SEC is read as zero and write accesses are ignored. The GPIO.DETECTMODE register controls the source for the DETECT_NSEC signal for the pins defined as non-secure.

The DETECT_NSEC signal is routed to the GPIOTE peripheral, allowing generation of events and interrupts from pins marked as non-secure. The DETECT_SEC signal is routed to the GPIOTESEC peripheral, allowing generation of events and interrupts from pins marked as secure. Principle of direct pin access on page 101 illustrates how the DETECT_NSEC and DETECT_SEC signals are generated from the GPIO PIN[].DETECT signals.

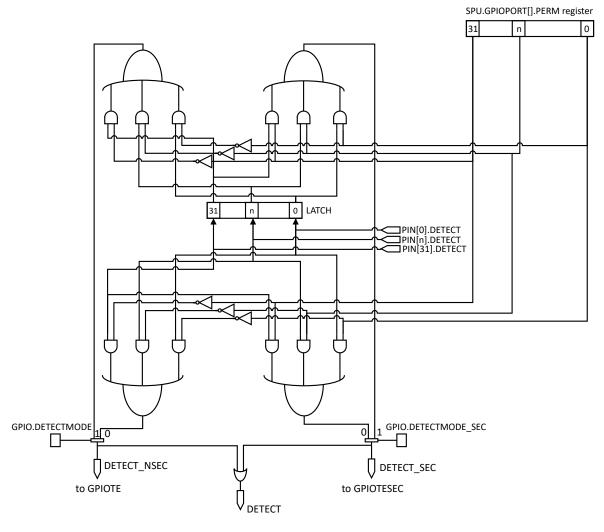


Figure 20: Principle of direct pin access



6.4.4 Registers

Instances

Instance	Base address	TrustZone		Split access	Description	
		Мар	Att	DMA		
P0 : S	0x50842500	HF	NS	NA	Yes	General purpose input and output
PO: NS	0x40842500	ПГ	INO	IVA	ies	General purpose input and output

Register overview

Register	Offset	TZ	Description
OUT	0x004		Write GPIO port
			This register is retained.
OUTSET	0x008		Set individual bits in GPIO port
OUTCLR	0x00C		Clear individual bits in GPIO port
IN	0x010		Read GPIO port
DIR	0x014		Direction of GPIO pins
			This register is retained.
DIRSET	0x018		DIR set register
DIRCLR	0x01C		DIR clear register
LATCH	0x020		Latch register indicating what GPIO pins that have met the criteria set in the
			PIN_CNF[n].SENSE registers
			This register is retained.
DETECTMODE	0x024		Select between default DETECT signal behavior and LDETECT mode (For non-secure pin only)
			This register is retained.
DETECTMODE_SEC	0x028		Select between default DETECT signal behavior and LDETECT mode (For secure pin only)
			This register is retained.
PIN_CNF[n]	0x200		Configuration of GPIO pins
			This register is retained.

6.4.4.1 OUT (Retained)

Address offset: 0x004

Write GPIO port

This register is retained.

Bit number		31	30 2	9 28	3 27	26	25	24 2	23 2	22 2	1 2	0 19	18	17	16	15	14	13 :	12 1	1 1	0 9	8	3 7	6	5	4	3	2	1	0		
ID				f	e c	l c	b	а	Z	Υ	X١	۸۱	٧ L	J T	S	R	Q	Р	0	N I	M	L F	(J	1	Н	G	F	Ε	D	С	В	Α
Reset	0x000	00000		0	0 0	0	0	0	0	0	0	0 (0 0	0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0
ID																																
A-f	RW	PIN[i] (i=031)								F	Pin	i																				
			Low	0						F	Pin	driv	er i	s lov	v																	
			High	1						F	Pin	driv	er i	s hig	gh																	

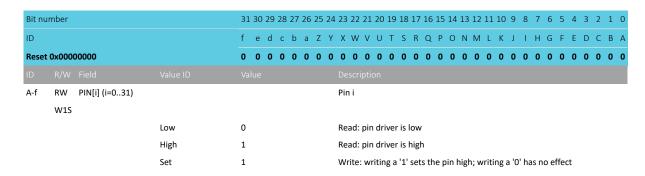
6.4.4.2 OUTSET

Address offset: 0x008

Set individual bits in GPIO port



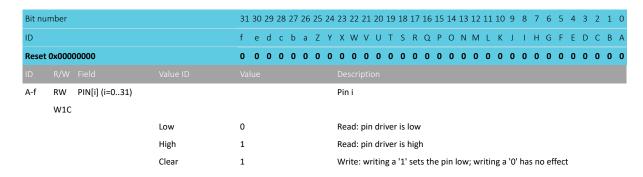
Read: reads value of OUT register.



6.4.4.3 OUTCLR

Address offset: 0x00C

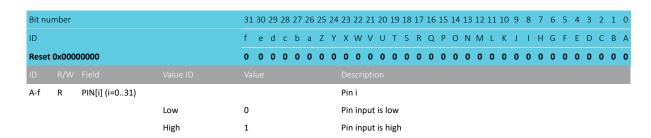
Clear individual bits in GPIO port Read: reads value of OUT register.



6.4.4.4 IN

Address offset: 0x010

Read GPIO port



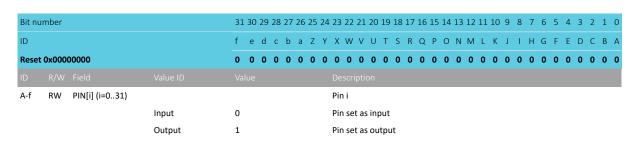
6.4.4.5 DIR (Retained)

Address offset: 0x014

Direction of GPIO pins

This register is retained.





6.4.4.6 DIRSET

Address offset: 0x018

DIR set register

Read: reads value of DIR register.

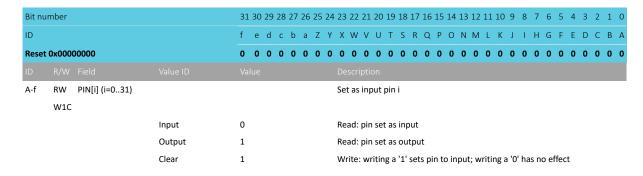
Bit nu	mber			31	30	29	28	27	26	25	24	23	22	21	20	19	18 1	L7 1	16 1	5 1	4 1	.3 1	2 1:	1 10	9	8	7	6	5	4	3	2	1 0
ID				f	e	d	С	b	а	Z	Υ	Χ	W	٧	U	Т	S	R (Q F) (1 (N N	ΛL	K	J	-1	Н	G	F	Ε	D	С	ВА
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () () (0 (0	0	0	0	0	0	0	0	0	0	0 0
ID																																	
A-f	RW	PIN[i] (i=031)										Se	tas	ou	tput	t pi	n i																
	W1S																																
			Input	0								Re	ad:	pin	set	as	inpu	ut															
			Output	1								Re	ad:	pin	set	as	out	put															
			Set	1								Wı	ite:	wr	ritin	g a	'1' s	ets	pin	to	out	put	; wr	itin	g a	'0' ŀ	nas	no	effe	ect			

6.4.4.7 DIRCLR

Address offset: 0x01C

DIR clear register

Read: reads value of DIR register.



6.4.4.8 LATCH (Retained)

Address offset: 0x020

Latch register indicating what GPIO pins that have met the criteria set in the PIN_CNF[n].SENSE registers This register is retained.



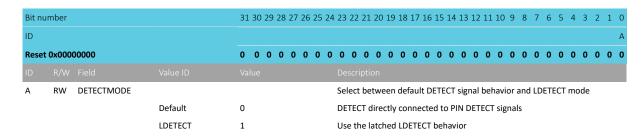
Bit nu	mber			31	L 30) 29	28	27	26	25	24	23	22	21	20 :	19 1	18 1	7 16	5 15	5 14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID				f	е	d	С	b	а	Z	Υ	Х	W	٧	U	T .	S F	R O) P	0	N	М	L	K	J	1	Н	G	F	Ε	D	С	ВА
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																	
A-f	RW	PIN[i] (i=031)										Sta	itus	on	wh	ethe	er P	IN[i]	ha	s m	et c	rite	ria	set	in F	PIN_	_CN	IF[i]].SE	NS	E re	gist	er.
												Wı	ite	'1' t	o cl	ear.																	
			NotLatched	0								Cri	teri	a ha	as n	ot b	eer	n me	et														
			Latched	1								Cri	teri	a ha	as b	een	me	t															

6.4.4.9 DETECTMODE (Retained)

Address offset: 0x024

Select between default DETECT signal behavior and LDETECT mode (For non-secure pin only)

This register is retained.

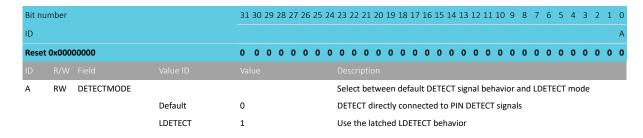


6.4.4.10 DETECTMODE_SEC (Retained)

Address offset: 0x028

Select between default DETECT signal behavior and LDETECT mode (For secure pin only)

This register is retained.

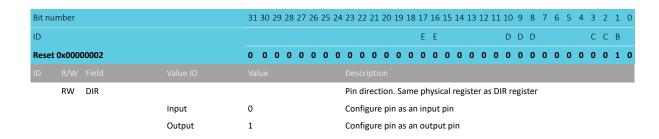


6.4.4.11 PIN_CNF[n] (n=0..31) (Retained)

Address offset: $0x200 + (n \times 0x4)$

Configuration of GPIO pins

This register is retained.





Bit nu	ımber			31	30	29 2	8 27	26	25 2	4 2	23 2	2 2	21 2	0 1	9 1	18 1	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																	E	E						D	D	D					С	С	В	
Reset	0x000	00002		0	0	0 (0 0	0	0 ()	0 (0 (0 (0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0
ID																																		
В	RW	INPUT								(Con	nec	t or	dis	co	nne	ct	inp	ut	buf	fer													
			Connect	0						(Con	nec	t in	put	: bu	ıffe	r																	
			Disconnect	1						[Disc	onn	nect	in	put	bu	ffe	r																
С	RW	PULL								F	Pull	con	nfigu	urat	tior	ı																		
			Disabled	0						1	No p	oull																						
			Pulldown	1						F	Pull	dov	wn	on	pin																			
			Pullup	3						F	Pull	up	on	pin																				
D-	RW	DRIVE								[Driv	e co	onfi	gur	atio	on																		
			S0S1	0						9	Stan	dar	rd 'C)', s	tar	ıdaı	rd '	1'																
			H0S1	1						ŀ	High	dri	ive	'0',	sta	nda	ard	'1'																
			S0H1	2						9	Stan	dar	rd 'C)', h	nigh	dr	ive	'1'																
			H0H1	3						ŀ	High	dri	ive	'0',	hig	gh 'd	driv	/e '	1"															
			DOS1	4						[Disc	onn	nect	'0'	, st	and	lar	d '1	L' (r	orı	nal	lyι	ise	d fo	r w	ired	-or	co	nne	ecti	ons)		
			D0H1	5						[Disc	onn	nect	'0'	, hi	gh	dri	ve	'1'	no	rma	ally	use	ed f	or v	wire	d-c	or c	onn	ect	ion	s)		
			SOD1	6						9	Stan	dar	rd 'C)', c	lisc	onr	nec	t '1	.' (r	ori	nal	lyι	ise	d fo	r w	ired	-ar	nd c	oni	nec	tion	ıs)		
			H0D1	7						ŀ	High	dri	ive	'0',	dis	cor	nne	ct	'1'	no	rma	ally	use	ed f	or v	wire	d-a	nd	cor	nne	ctio	ns)		
Е	RW	SENSE								F	Pin s	sens	sing	g m	ech	ani	sm	1																
			Disabled	0						[Disa	ble	d																					
			High	2						9	Sens	se fo	or h	igh	le	vel																		
			Low	3						9	Sens	se fo	or lo	ow	lev	el																		

6.4.5 Electrical specification

6.4.5.1 GPIO Electrical Specification

Note: VDD in the following table refers to VDD_GPIO.

Symbol	Description	Min.	Тур.	Max.	Units
V _{IH}	Input high voltage	0.7 x VDD		VDD	V
V_{IL}	Input low voltage	VSS		0.3 x VDD	V
$V_{OH,SD}$	Output high voltage, standard drive, 0.5 mA, VDD \geq 1.7 V	VDD-0.4		VDD	V
$V_{OH,HDH}$	Output high voltage, high drive, 5 mA, VDD \geq 2.7 V	VDD-0.4		VDD	V
$V_{OH,HDL}$	Output high voltage, high drive, 3 mA, VDD \geq 1.7 V	VDD-0.4		VDD	V
$V_{OL,SD}$	Output low voltage, standard drive, 0.5 mA, VDD \geq 1.7 V	VSS		VSS+0.4	V
$V_{OL,HDH}$	Output low voltage, high drive, 5 mA, VDD \geq 2.7 V	VSS		VSS+0.4	V
$V_{OL,HDL}$	Output low voltage, high drive, 3 mA, VDD \geq 1.7 V	VSS		VSS+0.4	V
$I_{OL,SD}$	Current at VSS + 0.4 V, output set low, standard drive, VDD \geq 1.7 V	1	2	4	mA
I _{OL,HDH}	Current at VSS + 0.4 V, output set low, high drive, VDD \geq 2.7 V	6	10	15	mA
I _{OL,HDL}	Current at VSS + 0.4 V, output set low, high drive, VDD \geq 1.7 V	3			mA
I _{OH,SD}	Current at VDD - 0.4 V, output set high, standard drive, VDD ≥1.7	1	2	4	mA
I _{OH,HDH}	Current at VDD - 0.4 V, output set high, high drive, VDD \geq 2.7 V	6	9	14	mA
I _{OH,HDL}	Current at VDD - 0.4 V, output set high, high drive, VDD \geq 1.7 V	3			mA
t _{RF,15pF}	Rise/fall time, standard drive mode, 10 to 90%, 15 pF load ¹	6	9	19	ns
t _{RF,25pF}	Rise/fall time, standard drive mode, 10 to 90%, 25 pF load ¹	10	13	30	ns
t _{RF,50pF}	Rise/fall time, standard drive mode, 10 to 90%, 50 pF load 1	18	25	61	ns
t _{HRF,15pF}	Rise/Fall time, high drive mode, 10 to 90%, 15 pF $load^1$	2	4	8	ns

¹ Rise and fall times based on simulations



Symbol	Description	Min.	Тур.	Max.	Units
t _{HRF,25pF}	Rise/Fall time, high drive mode, 10 to 90%, 25 pF load ¹	3	5	11	ns
t _{HRF,50pF}	Rise/Fall time, high drive mode, 10 to 90%, 50 pF load ¹	5	8	19	ns
R_{PU}	Pull-up resistance	11	13	16	kΩ
R _{PD}	Pull-down resistance	11	13	16	kΩ
C _{PAD}	Pad capacitance		3		pF

6.5 GPIOTE — GPIO tasks and events

The GPIO tasks and events (GPIOTE) module provides functionality for accessing GPIO pins using tasks and events. Each GPIOTE channel can be assigned to one pin.

A GPIOTE block enables GPIOs to generate events on pin state change which can be used to carry out tasks through the PPI system. A GPIO can also be driven to change state on system events using the PPI system. Tasks and events are briefly introduced in Peripheral interface on page 15, and GPIO is described in more detail in GPIO — General purpose input/output on page 97.

Low power detection of pin state changes is possible when in System ON or System OFF.

Instance	Number of GPIOTE channels
GPIOTE	8

Table 16: GPIOTE properties

Up to three tasks can be used in each GPIOTE channel for performing write operations to a pin. Two tasks are fixed (SET and CLR), and one (OUT) is configurable to perform following operations:

- Set
- Clear
- Toggle

An event can be generated in each GPIOTE channel from one of the following input conditions:

- Rising edge
- · Falling edge
- Any change

6.5.1 Pin events and tasks

The GPIOTE module has a number of tasks and events that can be configured to operate on individual GPIO pins.

The tasks SET[n], CLR[n], and OUT[n] can write to individual pins, and events IN[n] can be generated from input changes of individual pins.

The SET task will set the pin selected in GPIOTE.CONFIG[n]. PSEL to high. The CLR task will set the pin low.

The effect of the OUT task on the pin is configurable in CONFIG[n].POLARITY. It can set the pin high, set it low, or toggle it.

Tasks and events are configured using the CONFIG[n] registers. One CONFIG[n] register is associated with a set of SET[n], CLR[n], and OUT[n] tasks and IN[n] events.

As long as a SET[n], CLR[n], and OUT[n] task or an IN[n] event is configured to control pin **n**, the pin's output value will only be updated by the GPIOTE module. The pin's output value, as specified in the GPIO, will be ignored as long as the pin is controlled by GPIOTE. Attempting to write to the pin as a normal GPIO pin will have no effect. When the GPIOTE is disconnected from a pin, the associated pin gets the output and configuration values specified in the GPIO module, see MODE field in CONFIG[n] register.

NORDIC

When conflicting tasks are triggered simultaneously (i.e. during the same clock cycle) in one channel, the priority of the tasks is as described in the following table.

Priority	Task
1	оит
2	CLR
3	SET

Table 17: Task priorities

When setting the CONFIG[n] registers, MODE=Disabled does not have the same effect as MODE=Task and POLARITY=None. In the latter case, a CLR or SET task occurring at the exact same time as OUT will end up with no change on the pin, based on the priorities described in the table above.

When a GPIOTE channel is configured to operate on a pin as a task, the initial value of that pin is configured in the OUTINIT field of CONFIG[n].

6.5.2 Port event

PORT is an event that can be generated from multiple input pins using the GPIO DETECT signal.

The event will be generated on the rising edge of the DETECT signal. See GPIO — General purpose input/output on page 97 for more information about the DETECT signal.

The GPIO DETECT signal will not wake the system up again if the system is put into System ON IDLE while the DETECT signal is high. Clear all DETECT sources before entering sleep. If the LATCH register is used as a source, a new rising edge will be generated on DETECT if any bit in LATCH is still high after clearing all or part of the register. This could occur if one of the PINx.DETECT signals is still high, for example. See Pin sense mechanism on page 99 for more information.

Setting the system to System OFF while DETECT is high will cause a wakeup from System OFF reset.

This feature can be used to wake up the CPU from a WFI or WFE type sleep in System ON when all peripherals and the CPU are idle, meaning the lowest power consumption in System ON mode.

To prevent spurious interrupts from the PORT event while configuring the sources, the following steps must be performed:

- 1. Disable interrupts on the PORT event (through INTENCLR.PORT).
- 2. Configure the sources (PIN CNF[n].SENSE).
- **3.** Clear any potential event that could have occurred during configuration (write 0 to EVENTS_PORT).
- 4. Enable interrupts (through INTENSET.PORT).

6.5.3 Tasks and events pin configuration

Each GPIOTE channel is associated with one physical GPIO pin through the CONFIG.PSEL field.

When Event mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an input, overriding the DIR setting in GPIO. Similarly, when Task mode is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will be configured as an output overriding the DIR setting and OUT value in GPIO. When Disabled is selected in CONFIG.MODE, the pin specified by CONFIG.PSEL will use its configuration from the PIN[n].CNF registers in GPIO. CONFIG.MODE must be disabled in order to be able to change the value of the PSEL field.

Note: A pin can only be assigned to one GPIOTE channel at a time. Failing to do so may result in unpredictable behavior.



6.5.4 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
GPIOTE0	0x5000D000	HF	S	NA	No	Secure GPIO tasks and events
GPIOTE1	0x40031000	HF	NS	NA	No	Non Secure GPIO tasks and events

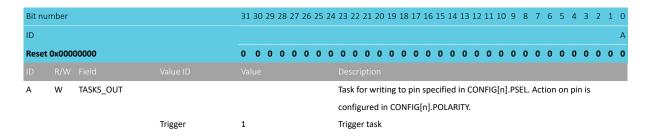
Register overview

Register	Offset	TZ	Description
TASKS_OUT[n]	0x000		Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in
			CONFIG[n].POLARITY.
TASKS_SET[n]	0x030		Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it high.
TASKS_CLR[n]	0x060		Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it low.
SUBSCRIBE_OUT[n]	0x080		Subscribe configuration for task OUT[n]
SUBSCRIBE_SET[n]	0x0B0		Subscribe configuration for task SET[n]
SUBSCRIBE_CLR[n]	0x0E0		Subscribe configuration for task CLR[n]
EVENTS_IN[n]	0x100		Event generated from pin specified in CONFIG[n].PSEL
EVENTS_PORT	0x17C		Event generated from multiple input GPIO pins with SENSE mechanism enabled
PUBLISH_IN[n]	0x180		Publish configuration for event IN[n]
PUBLISH_PORT	0x1FC		Publish configuration for event PORT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
CONFIG[n]	0x510		Configuration for OUT[n], SET[n], and CLR[n] tasks and IN[n] event

6.5.4.1 TASKS_OUT[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is configured in CONFIG[n].POLARITY.

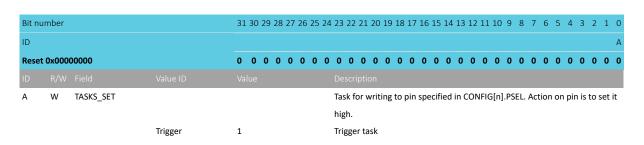


6.5.4.2 TASKS_SET[n] (n=0..7)

Address offset: $0x030 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n].PSEL. Action on pin is to set it high.





6.5.4.3 TASKS_CLR[n] (n=0..7)

Address offset: $0x060 + (n \times 0x4)$

Task for writing to pin specified in CONFIG[n]. PSEL. Action on pin is to set it low.

Bit nu	ımber			31	30 29	28	27	26 2	25 2	24 2	3 22	2 2:	1 20) 19	9 18	3 17	16	15	14	13	12	11 :	10	9	8	7 (6 !	5 4	1 3	2	1	0
ID																																Α
Reset	0x000	00000		0	0 0	0	0	0 (0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (0 (0 (0	0	0	0
ID																																
Α	W	TASKS_CLR								Ta	ask	for	wri	ting	g to	pin	spe	cifi	ed i	in C	ON	FIG	[n].	PSE	L. A	ctic	on c	on p	in is	to	set i	t
										lo	ow.																					
			Trigger	1						Tr	rigg	er t	ask																			

6.5.4.4 SUBSCRIBE_OUT[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

Subscribe configuration for task OUT[n]

Bit nu	ımber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task OUT[n] will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.5.4.5 SUBSCRIBE_SET[n] (n=0..7)

Address offset: $0x0B0 + (n \times 0x4)$

Subscribe configuration for task SET[n]

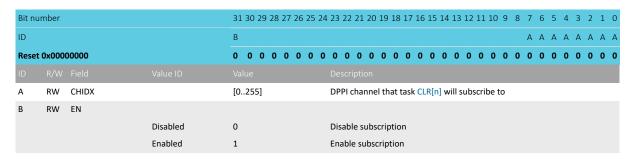
Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task SET[n] will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.5.4.6 SUBSCRIBE_CLR[n] (n=0..7)

Address offset: $0x0E0 + (n \times 0x4)$



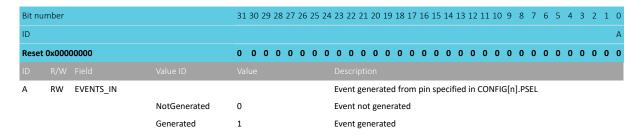
Subscribe configuration for task CLR[n]



6.5.4.7 EVENTS_IN[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

Event generated from pin specified in CONFIG[n].PSEL



6.5.4.8 EVENTS_PORT

Address offset: 0x17C

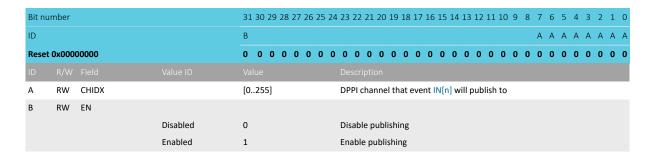
Event generated from multiple input GPIO pins with SENSE mechanism enabled

Bit nu	ımber			31 30 29 28 27 26 2	24 23 22	2 21 20	19 1	18 17	16 1	.5 14	13	12 1:	1 10	9	8 7	7 6	5	4	3 2	2 1	0
ID																					Α
Reset	0x000	00000		0 0 0 0 0 0	0 0 0	0 0	0	0 0	0 (0 0	0	0 0	0	0	0 (0	0	0	0 (0	0
ID																					
Α	RW	EVENTS_PORT			Event	t gener	ated	from	mult	iple	inpu	t GPI	O pi	ns w	ith s	SENS	SE m	nech	anis	m	
					enab	led															
			NotGenerated	0	Event	t not ge	enera	ated													
			Generated	1	Event	t gener	ated														

6.5.4.9 PUBLISH_IN[n] (n=0..7)

Address offset: 0x180 + (n × 0x4)

Publish configuration for event IN[n]





6.5.4.10 PUBLISH_PORT

Address offset: 0x1FC

Publish configuration for event PORT

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event PORT will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.5.4.11 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	mber			31 3	80 29	28 2	27 20	6 25	24	23	22 2	21 2	0 19	18	17 1	5 15	14	13	12 1	1 10	9	8	7	6	5	4 3	2	1	0
ID				1																			Н	G	F	E C) С	В	Α
Reset	0x000	00000		0	0 0	0	0 0	0	0	0	0	0 (0	0	0 0	0	0	0	0 (0	0	0	0	0	0	0 (0	0	0
ID																													
A-H	RW	IN[i] (i=07)								Wri	ite ':	1' to	ena	ble	inter	rupt	for	eve	nt IN	l[i]									
			Set	1						Ena	ble																		
			Disabled	0						Rea	ad: [Disal	bled																
			Enabled	1						Rea	ad: E	Enab	led																
1	RW	PORT								Wri	ite ':	1' to	ena	ble	inter	rupt	for	eve	nt P	ORT									
			Set	1						Ena	ble																		
			Disabled	0						Rea	ad: [Disal	bled																
			Enabled	1						Rea	d: E	Enab	led																

6.5.4.12 INTENCLR

Address offset: 0x308

Disable interrupt

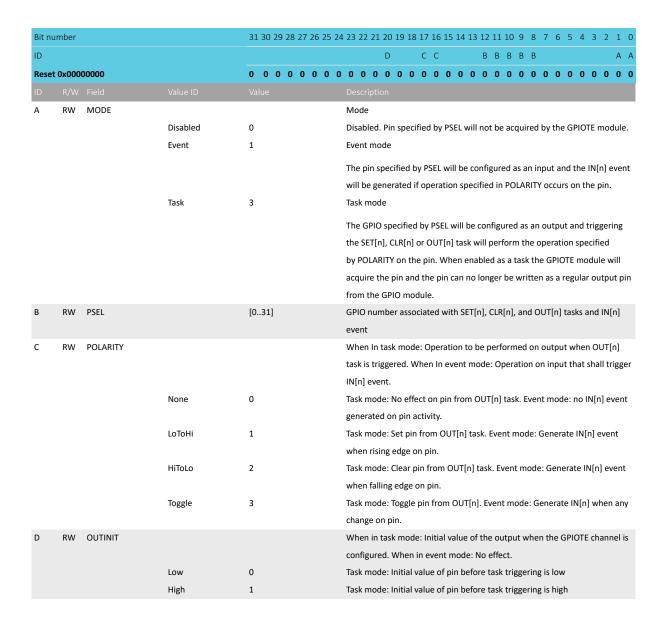
Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				T	H G F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
A-H	RW	IN[i] (i=07)			Write '1' to disable interrupt for event IN[i]
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
1	RW	PORT			Write '1' to disable interrupt for event PORT
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled



6.5.4.13 CONFIG[n] (n=0..7)

Address offset: 0x510 + (n × 0x4)

Configuration for OUT[n], SET[n], and CLR[n] tasks and IN[n] event



6.6 IPC — Interprocessor communication

The interprocessor communication (IPC) peripheral is used to send and receive events between MCUs in the system.



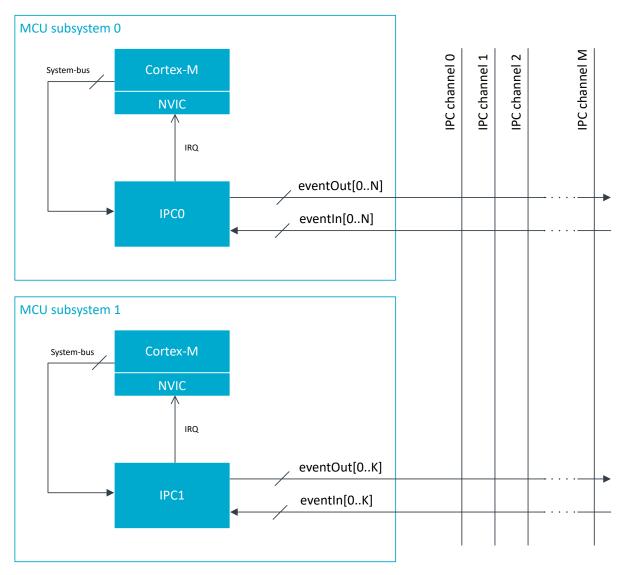


Figure 21: IPC block diagram

Functional description

IPC block diagram on page 114 illustrates the interprocessor communication (IPC) peripheral. In a multi-MCU system, each MCU has one dedicated IPC peripheral. The IPC peripheral can be used to send and receive events to and from other IPC peripherals. An instance of the IPC peripheral can have multiple SEND tasks and RECEIVE events. A single SEND task can be configured to signal an event on one or more IPC channels, and a RECEIVE event can be configured to listen on one or more IPC channels. The IPC channels that are triggered in a SEND task can be configured through the SEND_CNF registers, and the IPC channels that trigger a RECEIVE event are configured through the RECEIVE_CNF registers. The figure below illustrates how the SEND_CNF and RECEIVE_CNF registers work. Both the SEND task and the RECEIVE event can be connected to all IPC channels.



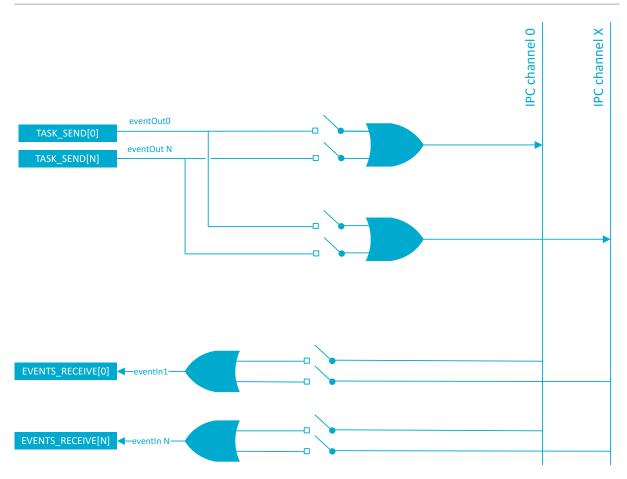


Figure 22: IPC registers SEND_CNF and RECEIVE_CNF

A SEND task can be viewed as broadcasting events onto one or more IPC channels, and a RECEIVE event can be seen as subscribing to a subset of IPC channels. It is possible for multiple IPCs to trigger events onto the same channel at the same time. When two or more events on the same channel occur within t_{IPC} , the events may be merged into a single event seen from the IPC receiver. One of the events can therefore be lost. To prevent this, the user must ensure that events on the same IPC channel do not occur within t_{IPC} of each other. When implementing firmware data structures, such as queues or mailboxes, this can be done by using one channel for acknowledgements.

An IPC event often does not contain any data itself, it is used to signal other MCUs that something has occurred. Data can be shared through shared memory, for example in the form of a software implemented mailbox, or command/event queues. It is up to software to assign a logical functionality to an IPC channel. For instance, one IPC channel can be used to signal that a command is ready to be executed, and any processor in the system can subscribe to that particular channel and decode/execute the command.

General purpose memory

The GPMEM registers can be used freely to store information. These registers are accessed like any other of the IPC peripheral's registers.

6.6.1 IPC and PPI connections

The IPC SEND tasks and RECEIVE events can be connected through PPI channels. This makes it possible to relay events from peripherals in one MCU to another, without CPU involvement.

Figure below illustrates a timer COMPARE event that is relayed from one MCU to IPC using PPI, then back into a timer CAPTURE event in another MCU.



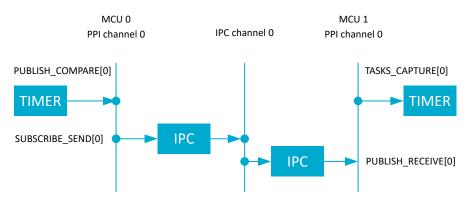


Figure 23: Example of PPI and IPC connections

6.6.2 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
IPC : S	0x5002A000	US	NS	NA	No	Interpressor communication
IPC : NS	0x4002A000	US	INO	NA	No	Interprocessor communication

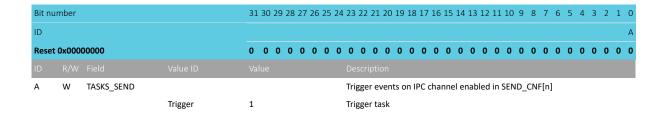
Register overview

Register	Offset	TZ	Description
TASKS_SEND[n]	0x000		Trigger events on IPC channel enabled in SEND_CNF[n]
SUBSCRIBE_SEND[n]	0x080		Subscribe configuration for task SEND[n]
EVENTS_RECEIVE[n]	0x100		Event received on one or more of the enabled IPC channels in RECEIVE_CNF[n]
PUBLISH_RECEIVE[n]	0x180		Publish configuration for event RECEIVE[n]
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
SEND_CNF[n]	0x510		Send event configuration for TASKS_SEND[n]
RECEIVE_CNF[n]	0x590		Receive event configuration for EVENTS_RECEIVE[n]
GPMEM[n]	0x610		General purpose memory

6.6.2.1 TASKS SEND[n] (n=0..7)

Address offset: $0x000 + (n \times 0x4)$

Trigger events on IPC channel enabled in SEND_CNF[n]

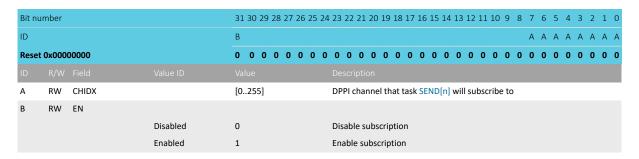




6.6.2.2 SUBSCRIBE_SEND[n] (n=0..7)

Address offset: $0x080 + (n \times 0x4)$

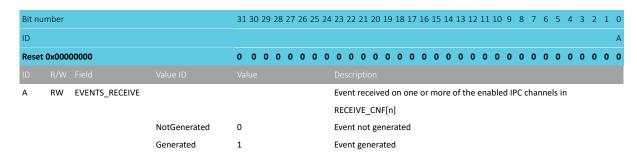
Subscribe configuration for task SEND[n]



6.6.2.3 EVENTS_RECEIVE[n] (n=0..7)

Address offset: $0x100 + (n \times 0x4)$

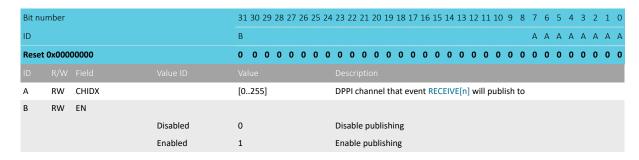
Event received on one or more of the enabled IPC channels in RECEIVE_CNF[n]



6.6.2.4 PUBLISH_RECEIVE[n] (n=0..7)

Address offset: $0x180 + (n \times 0x4)$

Publish configuration for event RECEIVE[n]



6.6.2.5 INTEN

Address offset: 0x300

Enable or disable interrupt



Bit nui	mber			31	30 29	28	27 2	6 25	24	23 2	22 2	21 20	0 19	9 18	17	16	15 1	14 1	.3 1	2 11	. 10	9	8	7	6	5 4	4 3	2	1 (
ID																								Н	G	F E	E C) С	ВА
Reset	0x000	00000		0	0 0	0	0 0	0	0	0	0 (0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0 (0	0	0 (
ID										Des																			
A-H	RW	RECEIVE[i] (i=07)							ı	Ena	ble	or d	isab	ole ii	nter	rup	t fo	r ev	ent	REC	EIVE	[i]							
			Disabled	0					ı	Disa	ble																		
			Enabled	1					ı	Ena	ble																		

6.6.2.6 INTENSET

Address offset: 0x304 Enable interrupt

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					H G F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A-H	RW	RECEIVE[i] (i=07)			Write '1' to enable interrupt for event RECEIVE[i]
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.6.2.7 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					H G F E D C B A
Reset	0x0000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
А-Н	RW	RECEIVE[i] (i=07)			Write '1' to disable interrupt for event RECEIVE[i]
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.6.2.8 INTPEND

Address offset: 0x30C Pending interrupts

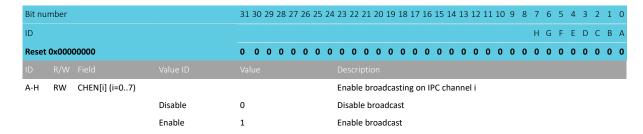
Bit nu	mber			31 30 29	28 27	26 25	24 23	3 22	21 2	0 19	18 17	7 16	15 14	4 13	12 1	1 10	9	8 7	6	5	4	3 2	1	0
ID																		Н	G	F	Е	D C	В	Α
Reset	0x000	00000		0 0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0 0	0	0	0 0	0	0	0	0 0	0	0
ID																								
A-H	R	RECEIVE[i] (i=07)					Re	ead p	oendi	ing st	atus	of int	erru	pt fo	r eve	nt RE	CEI	/E[i]						
			NotPending	0			Re	ead:	Not p	oendi	ing													
			Pending	1			Re	ead:	Pend	ling														

6.6.2.9 SEND_CNF[n] (n=0..7)

Address offset: $0x510 + (n \times 0x4)$



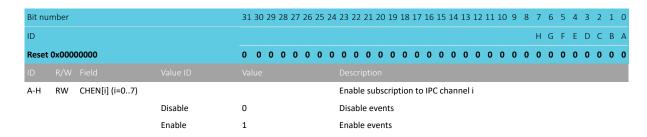
Send event configuration for TASKS_SEND[n]



6.6.2.10 RECEIVE CNF[n] (n=0..7)

Address offset: $0x590 + (n \times 0x4)$

Receive event configuration for EVENTS_RECEIVE[n]

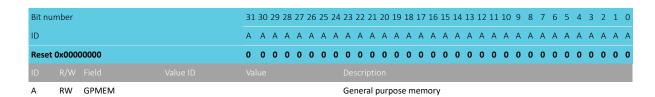


6.6.2.11 GPMEM[n] (n=0..3)

Address offset: $0x610 + (n \times 0x4)$

General purpose memory

Retained only in System ON mode



6.6.3 Electrical specification

6.6.3.1 IPC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{IPC}	Time window during which IPC events can be merged			165	μs

6.7 I2S — Inter-IC sound interface

The I2S (Inter-IC Sound) module, supports the original two-channel I2S format, and left or right-aligned formats. It implements EasyDMA for sample transfer directly to and from RAM without CPU intervention.

The I2S peripheral has the following main features:

• Master and Slave mode



- Simultaneous bi-directional (TX and RX) audio streaming
- · Original I2S and left- or right-aligned format
- 8, 16 and 24-bit sample width
- Low-jitter Master Clock generator
- Various sample rates

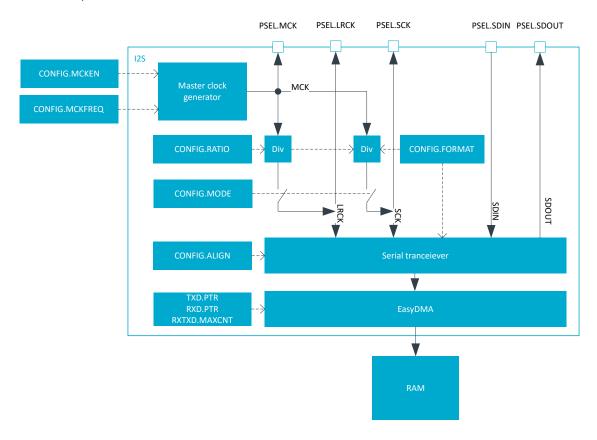


Figure 24: I2S master

6.7.1 Mode

The I2S protocol specification defines two modes of operation, Master and Slave.

The I2S mode decides which of the two sides (Master or Slave) shall provide the clock signals LRCK and SCK, and these signals are always supplied by the Master to the Slave.

6.7.2 Transmitting and receiving

The I2S module supports both transmission (TX) and reception (RX) of serial data. In both cases the serial data is shifted synchronously to the clock signals SCK and LRCK.

TX data is written to the SDOUT pin on the falling edge of SCK, and RX data is read from the SDIN pin on the rising edge of SCK. The most significant bit (MSB) is always transmitted first.

Note: When starting a transmission in master mode, two frames (two left-and-right sample pairs) of value zero will be transmitted after triggering the START task, prior to the RXTXD.MAXCNT samples specified by the TXD.PTR pointer.

TX and RX are available in both Master and Slave modes and can be enabled/disabled independently in the CONFIG.TXEN on page 134 and CONFIG.RXEN on page 134.

Transmission and/or reception is started by triggering the START task. When started and transmission is enabled (in CONFIG.TXEN on page 134), the TXPTRUPD event will be generated for every

NORDIC*
SEMICONDUCTOR

RXTXD.MAXCNT on page 137 number of transmitted data words (containing one or more samples). Similarly, when started and reception is enabled (in CONFIG.RXEN on page 134), the RXPTRUPD event will be generated for every RXTXD.MAXCNT on page 137 received data words.

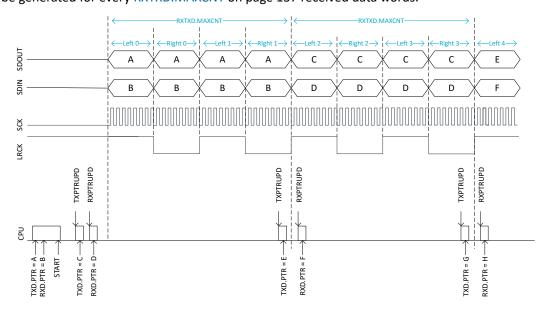


Figure 25: Transmitting and receiving. CONFIG.FORMAT = Aligned, CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo, RXTXD.MAXCNT = 1.

6.7.3 Left right clock (LRCK)

The Left Right Clock (LRCK), often referred to as "word clock", "sample clock" or "word select" in I2S context, is the clock defining the frames in the serial bit streams sent and received on SDOUT and SDIN, respectively.

In I2S mode, each frame contains one left and right sample pair, with the left sample being transferred during the low half period of LRCK followed by the right sample being transferred during the high period of LRCK.

In Aligned mode, each frame contains one left and right sample pair, with the left sample being transferred during the high half period of LRCK followed by the right sample being transferred during the low period of LRCK.

Consequently, the LRCK frequency is equivalent to the audio sample rate.

When operating in Master mode, the LRCK is generated from the MCK, and the frequency of LRCK is then given as:

```
LRCK = MCK / CONFIG.RATIO
```

LRCK always toggles around the falling edge of the serial clock SCK.

6.7.4 Serial clock (SCK)

The serial clock (SCK), often referred to as the serial bit clock, pulses once for each data bit being transferred on the serial data lines SDIN and SDOUT.

When operating in Master mode the SCK is generated from the MCK, and the frequency of SCK is then given as:

```
SCK = 2 * LRCK * CONFIG.SWIDTH
```

The falling edge of the SCK falls on the toggling edge of LRCK.



When operating in Slave mode SCK is provided by the external I2S master.

6.7.5 Master clock (MCK)

The master clock (MCK) is the clock from which LRCK and SCK are derived when operating in Master mode.

The MCK is generated by an internal MCK generator. This generator always needs to be enabled when in Master mode, but the generator can also be enabled when in Slave mode. Enabling the generator when in slave mode can be useful in the case where the external Master is not able to generate its own master clock.

The MCK generator is enabled/disabled in the register CONFIG.MCKEN on page 134, and the generator is started or stopped by the START or STOP tasks.

In Master mode the LRCK and the SCK frequencies are closely related, as both are derived from MCK and set indirectly through CONFIG.RATIO on page 135 and CONFIG.SWIDTH on page 136.

When configuring these registers, the user is responsible for fulfilling the following requirements:

1. SCK frequency can never exceed the MCK frequency, which can be formulated as:

```
CONFIG.RATIO >= 2 * CONFIG.SWIDTH
```

2. The MCK/LRCK ratio shall be a multiple of 2 * CONFIG.SWIDTH, which can be formulated as:

```
Integer = (CONFIG.RATIO / (2 * CONFIG.SWIDTH))
```

The MCK signal can be routed to an output pin (specified in PSEL.MCK) to supply external I2S devices that require the MCK to be supplied from the outside.

When operating in Slave mode, the I2S module does not use the MCK and the MCK generator does not need to be enabled.

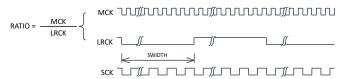


Figure 26: Relation between RATIO, MCK and LRCK.

Desired LRCK [Hz]	CONFIG.SWID	CONFIG.RATIO	CONFIG.MCKF	MCK [Hz]	LRCK [Hz]	LRCK error [%]
16000	16Bit	32X	32MDIV63	507936.5	15873.0	-0.8
16000	16Bit	64X	32MDIV31	1032258.1	16129.0	0.8
16000	16Bit	256X	32MDIV8	4000000.0	15625.0	-2.3
32000	16Bit	32X	32MDIV31	1032258.1	32258.1	0.8
32000	16Bit	64X	32MDIV16	2000000.0	31250.0	-2.3
44100	16Bit	32X	32MDIV23	1391304.3	43478.3	-1.4
44100	16Bit	64X	32MDIV11	2909090.9	45454.5	3.1

Table 18: Configuration examples



6.7.6 Width, alignment, and format

The CONFIG.SWIDTH register primarily defines the sample width of the data written to memory. In master mode, it then also sets the amount of bits per frame. In Slave mode it controls padding/trimming if required. Left, right, transmitted, and received samples always have the same width. The CONFIG.FORMAT register specifies the position of the data frames with respect to the LRCK edges in both Master and Slave modes.

When using I2S format, the first bit in a half-frame (containing one left or right sample) gets sampled on the second rising edge of the SCK after a LRCK edge. When using Aligned mode, the first bit in a half-frame gets sampled on the first rising edge of SCK following a LRCK edge.

For data being received on SDIN the sample value can be either right or left-aligned inside a half-frame, as specified in CONFIG.ALIGN on page 136. CONFIG.ALIGN on page 136 affects only the decoding of the incoming samples (SDIN), while the outgoing samples (SDOUT) are always left-aligned (or justified).

When using left-alignment, each half-frame starts with the MSB of the sample value (both for data being sent on SDOUT and received on SDIN).

When using right-alignment, each half-frame of data being received on SDIN ends with the LSB of the sample value, while each half-frame of data being sent on SDOUT starts with the MSB of the sample value (same as for left-alignment).

In Master mode, the size of a half-frame (in number of SCK periods) equals the sample width (in number of bits), and in this case the alignment setting does not care as each half-frame in any case will start with the MSB and end with the LSB of the sample value.

In slave mode, however, the sample width does not need to equal the frame size. This means you might have extra or fewer SCK pulses per half-frame than what the sample width specified in CONFIG.SWIDTH requires.

In the case where we use **left-alignment** and the number of SCK pulses per half-frame is **higher** than the sample width, the following will apply:

- For data received on SDIN, all bits after the LSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0.

In the case where we use **left-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

Data sent and received on SDOUT and SDIN will be truncated with the LSBs being removed first.

In the case where we use **right-alignment** and the number of SCK pulses per frame is **higher** than the sample width, the following will apply:

- For data received on SDIN, all bits before the MSB of the sample value will be discarded.
- For data sent on SDOUT, all bits after the LSB of the sample value will be 0 (same behavior as for left-alignment).

In the case where we use **right-alignment** and the number of SCK pulses per frame is **lower** than the sample width, the following will apply:

- Data received on SDIN will be sign-extended to "sample width" number of bits before being written to memory.
- Data sent on SDOUT will be truncated with the LSBs being removed first (same behavior as for left-alignment).

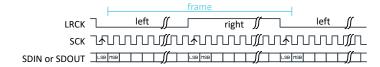


Figure 27: I2S format. CONFIG.SWIDTH equaling half-frame size.



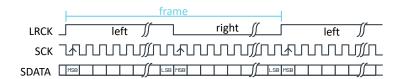


Figure 28: Aligned format. CONFIG.SWIDTH equaling half-frame size.

6.7.7 EasyDMA

The I2S module implements EasyDMA for accessing internal Data RAM without CPU intervention.

The source and destination pointers for the TX and RX data are configured in TXD.PTR on page 137 and RXD.PTR on page 137. The memory pointed to by these pointers will only be read or written when TX or RX are enabled in CONFIG.TXEN on page 134 and CONFIG.RXEN on page 134.

The addresses written to the pointer registers TXD.PTR on page 137 and RXD.PTR on page 137 are double-buffered in hardware, and these double buffers are updated for every RXTXD.MAXCNT on page 137 words (containing one or more samples) read/written from/to memory. The events TXPTRUPD and RXPTRUPD are generated whenever the TXD.PTR and RXD.PTR are transferred to these double buffers.

If TXD.PTR on page 137 is not pointing to the Data RAM region when transmission is enabled, or RXD.PTR on page 137 is not pointing to the Data RAM region when reception is enabled, an EasyDMA transfer may result in a HardFault and/or memory corruption. See Memory on page 21 for more information about the different memory regions.

Due to the nature of I2S, where the number of transmitted samples always equals the number of received samples (at least when both TX and RX are enabled), one common register RXTXD.MAXCNT on page 137 is used for specifying the sizes of these two memory buffers. The size of the buffers is specified in a number of 32-bit words. Such a 32-bit memory word can either contain four 8-bit samples, two 16-bit samples or one right-aligned 24-bit sample sign extended to 32 bit.

In stereo mode (CONFIG.CHANNELS=Stereo), the samples are stored as "left and right sample pairs" in memory. Figure Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo. on page 124, Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo. on page 125 and Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo. on page 125 show how the samples are mapped to memory in this mode. The mapping is valid for both RX and TX.

In mono mode (CONFIG.CHANNELS=Left or Right), RX sample from only one channel in the frame is stored in memory, the other channel sample is ignored. Illustrations Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left. on page 125, Memory mapping for 16 bit mono, left channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left. on page 125 and Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left. on page 126 show how RX samples are mapped to memory in this mode.

For TX, the same outgoing sample read from memory is transmitted on both left and right in a frame, resulting in a mono output stream.

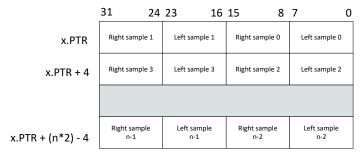


Figure 29: Memory mapping for 8 bit stereo. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Stereo.



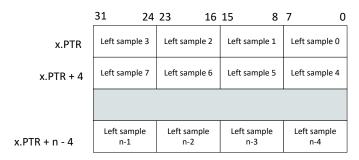


Figure 30: Memory mapping for 8 bit mono. CONFIG.SWIDTH = 8Bit, CONFIG.CHANNELS = Left.

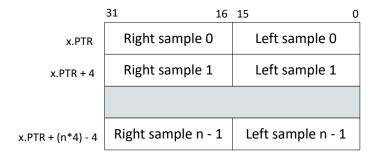


Figure 31: Memory mapping for 16 bit stereo. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Stereo.

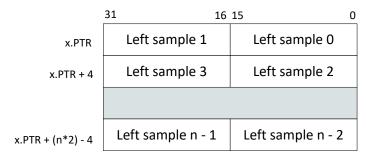


Figure 32: Memory mapping for 16 bit mono, left channel only. CONFIG.SWIDTH = 16Bit, CONFIG.CHANNELS = Left.

	31	23 0
x.PTR	Sign ext.	Left sample 0
x.PTR + 4	Sign ext.	Right sample 0
x.PTR + (n*8) - 8	Sign ext.	Left sample n - 1
x.PTR + (n*8) - 4	Sign ext.	Right sample n - 1

Figure 33: Memory mapping for 24 bit stereo. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Stereo.



	31	23 0
x.PTR	Sign ext.	Left sample 0
x.PTR + 4	Sign ext.	Left sample 1
x.PTR + (n*4) - 4	Sign ext.	Left sample n - 1

Figure 34: Memory mapping for 24 bit mono, left channel only. CONFIG.SWIDTH = 24Bit, CONFIG.CHANNELS = Left.

6.7.8 Module operation

Described here is a typical operating procedure for the I2S module.

1. Configure the I2S module using the CONFIG registers

```
// Enable reception
NRF I2S->CONFIG.RXEN = (I2S_CONFIG_RXEN_RXEN_Enabled <<
                                      I2S CONFIG RXEN RXEN Pos);
// Enable transmission
NRF I2S->CONFIG.TXEN = (I2S_CONFIG_TXEN_TXEN_Enabled <<
                                      12S_CONFIG_TXEN_TXEN_Pos);
// Enable MCK generator
NRF_I2S->CONFIG.MCKEN = (I2S_CONFIG_MCKEN_MCKEN_Enabled <<
                                      12S CONFIG MCKEN MCKEN Pos);
// MCKFREQ = 4 MHz
NRF I2S->CONFIG.MCKFREQ = I2S CONFIG MCKFREQ MCKFREQ 32MDIV8 <<
                                      12S CONFIG MCKFREQ MCKFREQ Pos;
// Ratio = 256
NRF I2S->CONFIG.RATIO = I2S CONFIG RATIO RATIO 256X <<
                                      I2S CONFIG RATIO RATIO Pos;
// MCKFREQ = 4 MHz and Ratio = 256 gives sample rate = 15.625 \text{ ks/s}
// Sample width = 16 bit
NRF I2S->CONFIG.SWIDTH = I2S CONFIG SWIDTH SWIDTH 16Bit <<
                                      12S CONFIG SWIDTH SWIDTH Pos;
// Alignment = Left
NRF I2S->CONFIG.ALIGN = I2S CONFIG ALIGN ALIGN Left <<
                                       12S_CONFIG_ALIGN_ALIGN_Pos;
// Format = I2S
NRF_I2S->CONFIG.FORMAT = I2S_CONFIG_FORMAT_FORMAT_I2S <<
                                       12S CONFIG FORMAT FORMAT Pos;
// Use stereo
NRF I2S->CONFIG.CHANNELS = I2S CONFIG CHANNELS CHANNELS Stereo <<
                                       12S CONFIG CHANNELS CHANNELS Pos;
```



2. Map IO pins using the PINSEL registers

```
// MCK routed to pin 0
NRF_I2S->PSEL.MCK = (0 << I2S_PSEL_MCK_PIN_Pos) |
                   (I2S_PSEL_MCK_CONNECT_Connected <<
                                                I2S PSEL MCK CONNECT Pos);
// SCK routed to pin 1
NRF I2S->PSEL.SCK = (1 << I2S PSEL SCK PIN Pos) |
                    (I2S PSEL SCK CONNECT Connected <<
                                                12S_PSEL_SCK_CONNECT_Pos);
// LRCK routed to pin 2
NRF I2S->PSEL.LRCK = (2 << I2S PSEL LRCK PIN Pos) |
                     (I2S PSEL LRCK CONNECT Connected <<
                                                12S_PSEL_LRCK_CONNECT_Pos);
// SDOUT routed to pin 3
NRF I2S->PSEL.SDOUT = (3 << I2S PSEL SDOUT PIN Pos) |
                     (I2S_PSEL_SDOUT_CONNECT_Connected <<
                                                12S_PSEL_SDOUT_CONNECT_Pos);
// SDIN routed on pin 4
NRF_I2S->PSEL.SDIN = (4 << I2S_PSEL_SDIN_PIN_POs) |
                     (I2S PSEL SDIN CONNECT Connected <<
                                                 12S PSEL SDIN CONNECT Pos);
```

3. Configure TX and RX data pointers using the TXD, RXD and RXTXD registers

```
NRF_I2S->TXD.PTR = my_tx_buf;
NRF_I2S->RXD.PTR = my_rx_buf;
NRF_I2S->TXD.MAXCNT = MY_BUF_SIZE;
```

4. Enable the I2S module using the ENABLE register

```
NRF_I2S->ENABLE = 1;
```

5. Start audio streaming using the START task

```
NRF_I2S->TASKS_START = 1;
```

6. Handle received and transmitted data when receiving the TXPTRUPD and RXPTRUPD events

```
if(NRF_I2S->EVENTS_TXPTRUPD != 0)
{
    NRF_I2S->TXD.PTR = my_next_tx_buf;
    NRF_I2S->EVENTS_TXPTRUPD = 0;
}

if(NRF_I2S->EVENTS_RXPTRUPD != 0)
{
    NRF_I2S->RXD.PTR = my_next_rx_buf;
    NRF_I2S->EVENTS_RXPTRUPD = 0;
}
```



6.7.9 Pin configuration

The MCK, SCK, LRCK, SDIN and SDOUT signals associated with the I2S module are mapped to physical pins according to the pin numbers specified in the PSEL.x registers.

These pins are acquired whenever the I2S module is enabled through the register ENABLE on page 133.

When a pin is acquired by the I2S module, the direction of the pin (input or output) will be configured automatically, and any pin direction setting done in the GPIO module will be overridden. The directions for the various I2S pins are shown below in GPIO configuration before enabling peripheral (master mode) on page 128 and GPIO configuration before enabling peripheral (slave mode) on page 128.

To secure correct signal levels on the pins when the system is in OFF mode, and when the I2S module is disabled, these pins must be configured in the GPIO peripheral directly.

I2S signal	I2S pin	Direction	Output value	Comment
MCK	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Output	0	
SCK	As specified in PSEL.SCK	Output	0	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 19: GPIO configuration before enabling peripheral (master mode)

I2S signal	I2S pin	Direction	Output value	Comment
МСК	As specified in PSEL.MCK	Output	0	
LRCK	As specified in PSEL.LRCK	Input	Not applicable	
SCK	As specified in PSEL.SCK	Input	Not applicable	
SDIN	As specified in PSEL.SDIN	Input	Not applicable	
SDOUT	As specified in PSEL.SDOUT	Output	0	

Table 20: GPIO configuration before enabling peripheral (slave mode)

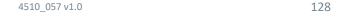
6.7.10 Registers

Instances

Instance	Base address	TrustZone	TrustZone S			Description
		Мар	Att	DMA		
12S : S	0x50028000	US	NS	SA	No	Inter-IC Sound
12S : NS	0x40028000	03	INS	SA	INO	inter-ic Sound

Register overview

Register	Offset	TZ	Description
TASKS_START	0x000		Starts continuous I2S transfer. Also starts MCK generator when this is enabled.
TASKS_STOP	0x004		Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the STOPPED
			event to be generated.
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
EVENTS_RXPTRUPD	0x104		The RXD.PTR register has been copied to internal double-buffers. When the I2S module is
			started and RX is enabled, this event will be generated for every RXTXD.MAXCNT words that
			are received on the SDIN pin.



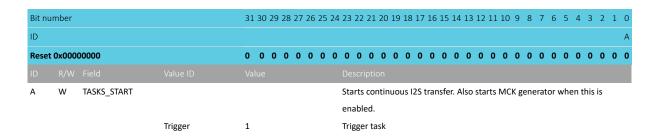


Register	Offset	TZ	Description
EVENTS_STOPPED	0x108		12S transfer stopped.
EVENTS_TXPTRUPD	0x114		The TDX.PTR register has been copied to internal double-buffers. When the I2S module is
			started and TX is enabled, this event will be generated for every RXTXD.MAXCNT words that
			are sent on the SDOUT pin.
PUBLISH_RXPTRUPD	0x184		Publish configuration for event RXPTRUPD
PUBLISH_STOPPED	0x188		Publish configuration for event STOPPED
PUBLISH_TXPTRUPD	0x194		Publish configuration for event TXPTRUPD
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		Enable I2S module.
CONFIG.MODE	0x504		I2S mode.
CONFIG.RXEN	0x508		Reception (RX) enable.
CONFIG.TXEN	0x50C		Transmission (TX) enable.
CONFIG.MCKEN	0x510		Master clock generator enable.
CONFIG.MCKFREQ	0x514		Master clock generator frequency.
CONFIG.RATIO	0x518		MCK / LRCK ratio.
CONFIG.SWIDTH	0x51C		Sample width.
CONFIG.ALIGN	0x520		Alignment of sample within a frame.
CONFIG.FORMAT	0x524		Frame format.
CONFIG.CHANNELS	0x528		Enable channels.
RXD.PTR	0x538		Receive buffer RAM start address.
TXD.PTR	0x540		Transmit buffer RAM start address.
RXTXD.MAXCNT	0x550		Size of RXD and TXD buffers.
PSEL.MCK	0x560		Pin select for MCK signal.
PSEL.SCK	0x564		Pin select for SCK signal.
PSEL.LRCK	0x568		Pin select for LRCK signal.
PSEL.SDIN	0x56C		Pin select for SDIN signal.
PSEL.SDOUT	0x570		Pin select for SDOUT signal.

6.7.10.1 TASKS_START

Address offset: 0x000

Starts continuous I2S transfer. Also starts MCK generator when this is enabled.



6.7.10.2 TASKS_STOP

Address offset: 0x004

Stops I2S transfer. Also stops MCK generator. Triggering this task will cause the STOPPED event to be generated.





Bit no	umber			31 30 29 28 27 2	26 25 24	- 23 2	2 21	20 19	9 18 1	L7 16	5 15 1	14 13	3 12	11 :	10 9	8	7	6	5	4	3	2 1	. 0
ID																							Α
Rese	t 0x000	00000		0 0 0 0 0	0 0 0	0 (0	0 0	0	0 0	0	0 0	0	0	0 0	0	0	0	0	0	0	0 0	0
Α	W	TASKS_STOP				Stop	s I2S	trans	fer. A	lso st	ops l	MCK	gen	erat	or. Tr	igge	ring	g th	is ta	ask	will	caus	se
						the S	ТОРІ	PED e	vent	to be	gen	erate	ed.										
			Trigger	1		Trigg	er ta	sk															

6.7.10.3 SUBSCRIBE_START

Address offset: 0x080

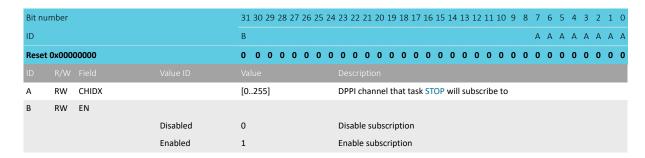
Subscribe configuration for task START

Bit nu	ımber			31 30	29 2	28 27	26 2	25 24	23	22	21	20 :	19	18 1	7 1	6 15	5 14	13	12	11	10 9	9 8	7	6	5	4	3	2	1 0
ID				В																			Α	Α	Α	Α	Α	Α.	4 A
Reset	0x000	00000		0 0	0	0 0	0 (0 0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0
ID																													
Α	RW	CHIDX		[025	55]				DP	PI c	han	nel	tha	t ta	sk S	TAR	Tw	ill s	ubs	crib	e to								
В	RW	EN																											
			Disabled	0					Dis	abl	e su	bsc	rip	ion															

6.7.10.4 SUBSCRIBE_STOP

Address offset: 0x084

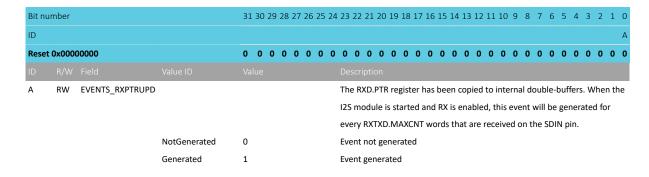
Subscribe configuration for task STOP



6.7.10.5 EVENTS_RXPTRUPD

Address offset: 0x104

The RXD.PTR register has been copied to internal double-buffers. When the I2S module is started and RX is enabled, this event will be generated for every RXTXD.MAXCNT words that are received on the SDIN pin.



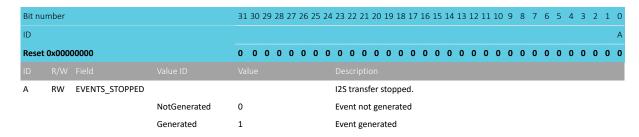




6.7.10.6 EVENTS_STOPPED

Address offset: 0x108

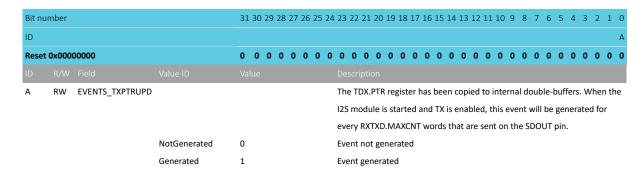
12S transfer stopped.



6.7.10.7 EVENTS TXPTRUPD

Address offset: 0x114

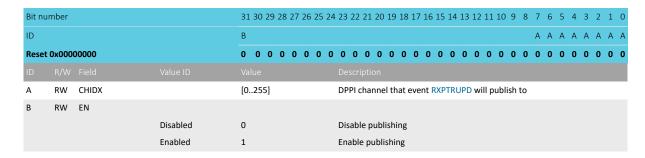
The TDX.PTR register has been copied to internal double-buffers. When the I2S module is started and TX is enabled, this event will be generated for every RXTXD.MAXCNT words that are sent on the SDOUT pin.



6.7.10.8 PUBLISH RXPTRUPD

Address offset: 0x184

Publish configuration for event RXPTRUPD



6.7.10.9 PUBLISH_STOPPED

Address offset: 0x188

Publish configuration for event STOPPED



Bit nu	mber			31 30 29	28 2	7 26	5 25 2	4 23	22 2	1 20	19	18 1	.7 16	5 15	14	13 1	.2 11	l 10	9	8	7	6	5 4	1 3	2	1 0
ID				В																	Α	Α.	4 Α	A A	Α	A A
Reset	0x000	00000		0 0 0	0	0 0	0 (0	0	0 0	0	0	0 0	0	0	0	0 0	0	0	0	0	0	0 (0	0	0 0
ID																										
Α	RW	CHIDX		[0255]				DP	PI ch	anne	el th	at ev	ent!	STO	PPE	D w	ill pu	blis	h to)						
В	RW	EN																								
			Disabled	0				Dis	able	publ	ishi	ng														
			Enabled	1				Ena	able	publi	shir	ng														

6.7.10.10 PUBLISH_TXPTRUPD

Address offset: 0x194

Publish configuration for event TXPTRUPD

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event TXPTRUPD will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.7.10.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F C B
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
В	RW	RXPTRUPD			Enable or disable interrupt for event RXPTRUPD
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
F	RW	TXPTRUPD			Enable or disable interrupt for event TXPTRUPD
			Disabled	0	Disable
			Enabled	1	Enable

6.7.10.12 INTENSET

Address offset: 0x304

Enable interrupt

Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0			
Reset 0x000000000 0 0 0 0 0 0 0 0 0 0 0 0 0		F C I	В
	000000	000000	0 0
ID R/W Field Value ID Value Description			

RW RXPTRUPD Write '1' to enable interrupt for event RXPTRUPD



Bit nu	ımber			31 30	29 2	8 27 2	6 25 2	1 23 1	22 21	20 1	9 1	18 1	7 16	15	14 :	13 1	2 1:	1 10	9	8	7	6 5	5 4	3	2	1	0
ID																						ı	=		С	В	
Reset	0x00000000			0 0	0 0	0 0	0 0	0	0 0	0 (0	0 0	0	0	0	0 (0	0	0	0	0	0 (0	0	0	0	0
ID																											
			Set	1				Ena	ble																		_
			Disabled	0				Rea	d: Di	sable	d																
			Enabled	1				Rea	d: En	abled	ł																
С	RW STOP	PED						Wri	te '1'	to en	ab	le in	terrı	ıpt i	for e	ever	t ST	OPF	ED								
			Set	1				Ena	ble																		
			Disabled	0				Rea	d: Di	sable	d																
			Enabled	1				Rea	d: En	abled	ł																
F	RW TXPT	RUPD						Wri	te '1'	to en	ab	le in	terrı	ıpt i	for e	ever	t TX	(PTR	UPI)							
			Set	1				Ena	ble																		
			Disabled	0				Rea	d: Di	sable	d																
			Enabled	1				Rea	d: En	abled	ł																

6.7.10.13 INTENCLR

Address offset: 0x308

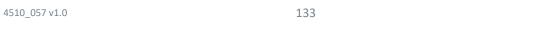
Disable interrupt

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F C B
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
В	RW	RXPTRUPD			Write '1' to disable interrupt for event RXPTRUPD
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	STOPPED			Write '1' to disable interrupt for event STOPPED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	TXPTRUPD			Write '1' to disable interrupt for event TXPTRUPD
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.7.10.14 ENABLE

Address offset: 0x500 Enable I2S module.

Bit nu	ımber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	ENABLE			Enable I2S module.
			Disabled	0	Disable
			Enabled	1	Enable

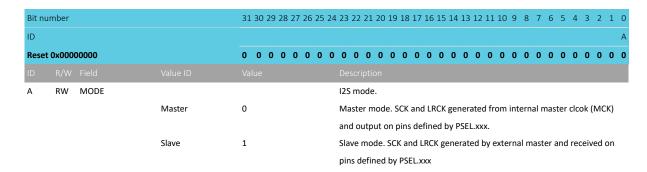




6.7.10.15 CONFIG.MODE

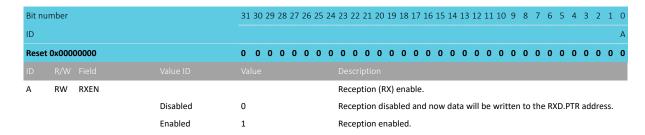
Address offset: 0x504

I2S mode.



6.7.10.16 CONFIG.RXEN

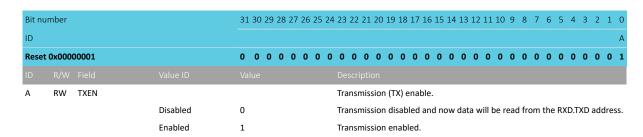
Address offset: 0x508 Reception (RX) enable.



6.7.10.17 CONFIG.TXEN

Address offset: 0x50C

Transmission (TX) enable.



6.7.10.18 CONFIG.MCKEN

Address offset: 0x510

Master clock generator enable.



Bit nu	ımber			31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Reset	0x000	00001		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	MCKEN			Master clock generator enable.
			Disabled	0	Master clock generator disabled and PSEL.MCK not connected(available as
					GPIO).
			Enabled	1	Master clock generator running and MCK output on PSEL.MCK.

6.7.10.19 CONFIG.MCKFREQ

Address offset: 0x514

Master clock generator frequency.

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				A A A A A A A	A A A A A A A A A A A A A A A A A A A
Rese	t 0x200	00000		0 0 1 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	MCKFREQ			Master clock generator frequency.
			32MDIV8	0x20000000	32 MHz / 8 = 4.0 MHz
			32MDIV10	0x18000000	32 MHz / 10 = 3.2 MHz
			32MDIV11	0x16000000	32 MHz / 11 = 2.9090909 MHz
			32MDIV15	0x11000000	32 MHz / 15 = 2.1333333 MHz
			32MDIV16	0x10000000	32 MHz / 16 = 2.0 MHz
			32MDIV21	0x0C000000	32 MHz / 21 = 1.5238095
			32MDIV23	0x0B000000	32 MHz / 23 = 1.3913043 MHz
			32MDIV30	0x08800000	32 MHz / 30 = 1.0666667 MHz
			32MDIV31	0x08400000	32 MHz / 31 = 1.0322581 MHz
			32MDIV32	0x08000000	32 MHz / 32 = 1.0 MHz
			32MDIV42	0x06000000	32 MHz / 42 = 0.7619048 MHz
			32MDIV63	0x04100000	32 MHz / 63 = 0.5079365 MHz
			32MDIV125	0x020C0000	32 MHz / 125 = 0.256 MHz

6.7.10.20 CONFIG.RATIO

Address offset: 0x518

MCK / LRCK ratio.

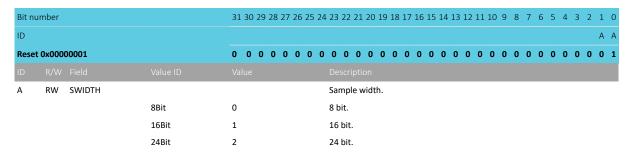
Bit nun	nber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					АААА
Reset (0x000	00006		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	RATIO			MCK / LRCK ratio.
			32X	0	LRCK = MCK / 32
			48X	1	LRCK = MCK / 48
			64X	2	LRCK = MCK / 64
			96X	3	LRCK = MCK / 96
			128X	4	LRCK = MCK / 128
			192X	5	LRCK = MCK / 192
			256X	6	LRCK = MCK / 256
			384X	7	LRCK = MCK / 384
			512X	8	LRCK = MCK / 512



6.7.10.21 CONFIG.SWIDTH

Address offset: 0x51C

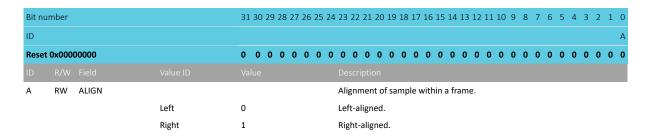
Sample width.



6.7.10.22 CONFIG.ALIGN

Address offset: 0x520

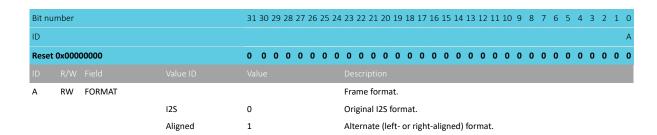
Alignment of sample within a frame.



6.7.10.23 CONFIG.FORMAT

Address offset: 0x524

Frame format.

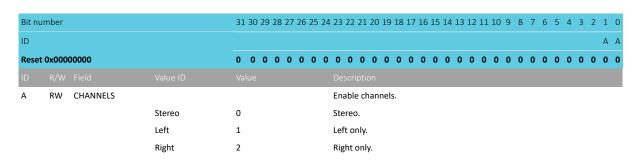


6.7.10.24 CONFIG.CHANNELS

Address offset: 0x528

Enable channels.





6.7.10.25 RXD.PTR

Address offset: 0x538

Receive buffer RAM start address.

Bit n	umber		31	30	29	28	27	26	25	24	23	22	21	L 20	0 19	9 18	8 1	7 1	6 1	5 14	4 1	3 1	2 13	10	9	8	7	6	5	4	3	2	1	0
ID			Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	. A	A	. Δ	Α Α	. 4	, Δ	Α	. 4	. Δ	ι A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
Rese	t 0x000	00000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	C	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																		
Α	RW	PTR									Re	cei	ve l	buf	ffer	Da	ta F	RAN	∕l st	art	ado	dres	ss. V	Vhe	n re	ecei	vin	g, w	vor	ds c	ont	aini	ing	
											saı	mp	les	wil	ll be	e w	ritt	en 1	to t	his	ado	lres	s. T	his	ado	Ires	s is	a w	orc	d ali	igne	d D	ata	
											RA	M	ado	dre	SS.																			

6.7.10.26 TXD.PTR

Address offset: 0x540

Transmit buffer RAM start address.

Bit n	umber		31	30	29 :	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID			Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
Rese	t 0x000	00000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																		
Α	RW	PTR									Tra	nsn	nit	buf	fer	Dat	ta R	ΑM	sta	ırt a	dd	ress	s. V	Vhe	n t	ran	sm	ittir	ng, '	woı	rds			
											cor	ntai	nin	g sa	amp	oles	wi	ll be	e fe	tch	ed 1	ron	n tł	nis a	add	Ires	s. T	his	ad	dre	ss is	a v	iow	d
											alig	ne	d D	ata	RA	Ma	add	ress	S.															

6.7.10.27 RXTXD.MAXCNT

Address offset: 0x550

Size of RXD and TXD buffers.

Α	RW	MAXCNT					Siz	e of	RXD	and	TXC	buf	fers	in n	uml	oer	of 3	2 bi	t wo	ords						
ID																										
Rese	t 0x000	00000	0 0	0 0	0 0	0 (0	0	0 0	0	0	0 0	0	0	0	0	0 (0	0	0	0	0	0	0 (0	0
ID															Α	Α	A A	A A	A	Α	Α	Α	Α	A A	A	A
Bit n	umber		31 30	29 28	3 27 26	5 25 2	4 23	22	21 2	0 19	18	17 16	5 15	14	13	12 :	111	0 9	8	7	6	5	4	3 2	2 1	0

6.7.10.28 PSEL.MCK

Address offset: 0x560
Pin select for MCK signal.



Bit nu	mber			31 30 29 28 27	26 25	24 2	3 22	21 20	19	18 1	7 16	15 1	14 13	3 12	11 1	9	8	7	6	5 4	. 3	2	1 (
ID				В																Δ	A	A	Α Α
Reset	0xFFFF	FFFF		1 1 1 1 1	1 1	1 1	l 1	1 1	1	1	1 1	1	1 1	1	1 1	. 1	1	1	1	1 1	. 1	1	1
ID																							
Α	RW	PIN		[031]		Р	in nu	mber															
В	RW	CONNECT				С	onne	ction															
			Disconnected	1		D	iscor	nect															
			Connected	0		С	onne	ct															

6.7.10.29 PSEL.SCK

Address offset: 0x564

Pin select for SCK signal.

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.7.10.30 PSEL.LRCK

Address offset: 0x568

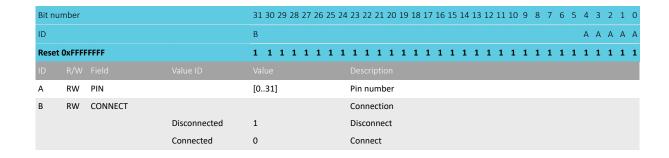
Pin select for LRCK signal.

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	ААААА
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.7.10.31 PSEL.SDIN

Address offset: 0x56C

Pin select for SDIN signal.

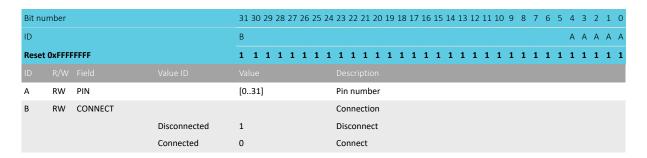




6.7.10.32 PSEL.SDOUT

Address offset: 0x570

Pin select for SDOUT signal.



6.7.11 Electrical specification

6.7.11.1 I2S timing specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{S_SDIN}	SDIN setup time before SCK rising	20			ns
t _{H_SDIN}	SDIN hold time after SCK rising	15			ns
t _{S_SDOUT}	SCK falling edge to SDOUT valid	40			ns
t _{H_SDOUT}	SDOUT hold time after SCK falling	6			ns
t _{SCK_LRCK}	SCLK falling to LRCK edge	-5	0	5	ns
f_{MCK}	MCK frequency			4000	kHz
f _{LRCK}	LRCK frequency			48	kHz
f_{SCK}	SCK frequency			2000	kHz
DC _{CK}	Clock duty cycle (MCK, LRCK, SCK)	45		55	%

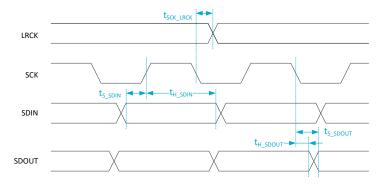


Figure 35: I2S timing diagram

6.8 KMU — Key management unit

The key management unit (KMU) enforces access policies to a subset region of user information configuration register (UICR). This subset region is used for storing cryptographic key values inside the key slots, which the CPU has no access to.

In total there are 128 key slots available, where each key slot can store one 128-bit key value together with an access policy and a destination address for the key value. Multiple key slots can be combined in order to support key sizes larger than 128 bits. The access policy of a key slot governs if and how a key value can



be used, while the destination address determines where in the memory map the KMU pushes the key value upon a request from the CPU.

Key slots can be configured to be pushed directly into write-only key registers in cryptographic accelerators, like e.g. CryptoCell, without exposing the key value itself to the CPU. This enables the CPU to use the key values stored inside the key slots for cryptographic operations without being exposed to the key value.

Access to the KMU, and the key slots in the UICR, is only allowed from secure mode.

6.8.1 Functional view

From a functional view the UICR is divided into two different regions, one-time programmable (OTP) memory and key storage.

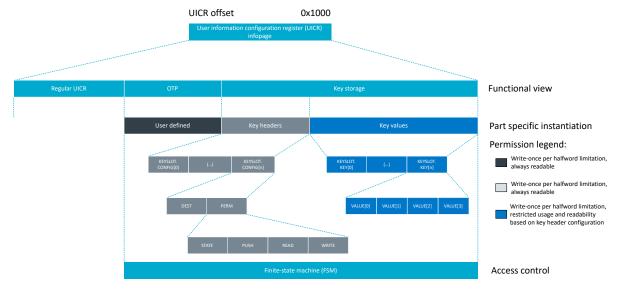


Figure 36: Memory map overview

OTP

One-time programmable (OTP) memory is typically used for holding values that are written once, and then never to be changed again throughout the product lifetime. The OTP region of UICR is emulated by placing a write-once per halfword limitation on registers defined here.

Key storage

The key storage region contains multiple key slots, where each slot consists of a key header and an associated key value. The key value is limited to 128 bits. Any key size greater than 128 bits must be divided and distributed over multiple key slot instances.

Key headers are allocated an address range of 0x400 in the UICR memory map, allowing a total of 128 keys to be addressable inside the key storage region.

Note: The use of the key storage region in UICR should be limited to keys with a certain life span, and not per-session derived keys where the CPU is involved in the key exchange.

6.8.2 Access control

Access control to the underlying UICR infopage in flash is enforced by a hardware finite-state machine (FSM). The FSM can allow or block transactions, depending both on the security of the transaction (secure or non-secure) and on the type of register being written and/or read.



Access type	Key headers	Key values
Read	Allowed	Restricted
Write	Restricted	Restricted

Table 21: Access control

Any restricted access requires an explicit key slot selection through the KMU register interface. Any illegal access to restricted key slot registers will be blocked and word <code>OxDEADDEAD</code> will be returned on the AHB.

The OTP region has individual access control behavior, while access control to the key storage region is configured on a per key slot basis. The KMU FSM operates on only one key slot instance at a time, and the permissions and the usage restriction for a key value associated with a key slot can be configured individually.

Note: Even if the KMU can be configured as non-secure, all non-secure transactions will be blocked.

6.8.3 Protecting the UICR content

The UICR content can be protected against device-internal NVMC.ERASEALL requests, in addition to device-external ERASEALL requests, through the CTRL-AP interface. This feature is useful if the firmware designers want to prevent the OTP region from being erased.

Since enabling this step will permanently disable erase for the UICR, the procedure requires an implementation defined 32-bit word to be written into the UICR's ERASEPROTECT register.

In case of a field return handling, it is still possible to erase the UICR even if the ERASEPROTECT is set. If this functionality is desired, the secure boot code must implement a secure communication channel over the CTRL-AP mailbox interface. Upon successful authentication of the external party, the secure boot code can temporarily re-enable the CTRL-AP ERASEALL functionality.

6.8.4 Usage

This section describes the specific KMU and UICR behavior in more detail, to help the reader get a better overview of KMU's features and the intended usage.

6.8.4.1 OTP

The OTP region of the UICR contains a user-defined static configuration of the device. The KMU emulates the OTP functionality by placing a write-once per halfword limitation of registers defined in this region, i.e. only halfwords containing all '1's can be written.

An OTP write transaction must consist of a full 32-bit word. Both halfwords can either be written simultaneously or one at a time. The KMU FSM will block any write to a halfword in the OTP region, if the initial value of this halfword is not 0xFFFF. When writing halfwords one at a time, the non-active halfword must be masked as 0xFFFF, otherwise the request will be blocked. For example, writing 0x1234XXXX to an OTP destination address which already contains the value 0xFFFFAABB, must be configured as 0x1234FFFF. The OTP destination address will contain the value 0x1234AABB after both write transactions have been processed.

The KMU will also only allow secure AHB write transactions into the OTP region of the UICR. Any AHB write transaction to this region that does not satisfy the above requirements will be ignored, and the STATUS.BLOCKED register will be set to '1'.

6.8.4.2 Key storage

The key storage region of the UICR can contain multiple keys of different type, including symmetrical keys, hashes, public/private key pairs and other device secrets. One of the key features of the KMU, is that these



device secrets can be installed and made available for use in cryptographic operations without revealing the actual secret values.

Keys in this region will typically have a certain life span. The region is not designed to be used for persession derived keys where the non-secure side (i.e. application) is participating in the key exchange.

All key storage is done through the concept of multiple key slots, where each key slot instance consists of one key header and an associated key value. Each key header supports the configuration of usage permissions and an optional secure destination address.

The key header secure destination address option enables the KMU to push the associated key value over a dedicated secure APB to a pre-configured secure location within the memory map. Such locations typically include a write-only key register of the hardware cryptographic accelerator, allowing the KMU to distribute keys within the system without compromising the key values.

One key slot instance can store a key value of maximum 128 bits. If a key size exceeds this limit, the key value itself must be split over multiple key slot instances.

The following usage and read permissions scheme is applicable for each key slot:

State	Push	Read	Write	Description
Active (1)	Enabled	Enabled	Enabled	Default flash erase value. Key slot cannot be pushed, write is enabled.
	(1)	(1)	(1)	
Active (1)	Enabled	Enabled	Disabled	Key slot is active, push is enabled. Key slot VALUE registers can be read, but write is disabled.
	(1)	(1)	(0)	
Active (1)	Enabled	Disabled	Disabled	Key slot is active, push is enabled. Read and write to key slot VALUE registers are disabled.
	(1)	(0)	(0)	
Active (1)	Disabled	Enabled	Disabled	Key slot is active, push is disabled. Key slot VALUE registers can be read, but write is disabled.
	(0)	(1)	(0)	
Revoked	-	-	-	Key slot is revoked. Cannot be read or pushed over secure APB regardless of the permission settings.
(0)				

Table 22: Valid key slot permission schemes

6.8.4.2.1 Selecting a key slot

The KMU FSM is designed to process only one key slot at a time, effectively operating as a memory protection unit for the key storage region. Whenever a key slot is selected, the KMU will allow access to writing, reading, and/or pushing the associated key value according to the selected slot configuration.

A key slot must be selected prior to use, by writing the key slot ID into the KMU SELECTKEYSLOT register. Because the reset value of this register is 0x00000000, there is no key slot associated with ID=0 and no slot is selected by default. All key slots are addressed using IDs from 1 to 128.

SELECTED status is set when a key slot is selected, and a read or write access to that keyslot occurs.

BLOCKED status is set when any illegal access to key slot registers is detected.

When the use of the particular key slot is stopped, the key slot selection in SELECTKEYSLOT must be set back to '0'.

By default, all KMU key slots will consist of a 128-bit key value of '1's, where the key headers have no secure destination address, or any usage and read restrictions.

6.8.4.2.2 Writing to a key slot

Writing a key slot into UICR is a five-step process.

- 1. Select which key slot the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT. The selected key slot must be empty in order to add a new entry to UICR.
- **2.** If the key value shall be pushable over secure APB, the destination address of the recipient must be configured in register KEYSLOT.CONFIG[ID-1].DEST.



- 3. Write the 128-bit key value into KEYSLOT.KEY[ID-1].VALUE[0-3].
- **4.** Write the desired key slot permissions into KEYSLOT.CONFIG[ID-1].PERM, including any applicable usage restrictions.
- **5.** Select key slot 0.

In case the total key size is greater than 128 bits, the key value itself must be split into 128-bit segments and written to multiple key slot instances. Steps 1 through 5 above must be repeated for the entire key size.

Note: If a key slot is configured as readable, and KEYSLOT.CONFIG[ID-1].DEST is not to be used, it is recommended to disable the push bit in KEYSLOT.CONFIG[ID-1].PERM when configuring key slot permissions.

Note: A key value distributed over multiple key slots should use the same key slot configuration in its key headers, but the secure destination address for each key slot instance must be incremented by 4 words (128 bits) for each key slot instance spanned.

Note: Write to flash must be enabled in NVMC->CONFIG prior to writing keys to flash, and subsequently disabled once writing is complete.

Steps 1 through 5 above will be blocked if any of the following violations are detected:

- No key slot selected
- · Non-empty key slot selected
- NVM destination address not empty
- AHB write to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot

6.8.4.2.3 Reading a key value

Key slots that are configured as readable can have their key value read directly from the UICR memory map by the CPU.

Readable keys are typically used during the secure boot sequence, where the CPU is involved in falsifying or verifying the integrity of the system. Since the CPU is involved in this decision process, it makes little sense not to trust the CPU having access to the actual key value but ultimately trust the decision of the integrity check. Another use-case for readable keys is if the key type in question does not have a HW peripheral in the platform that is able to accept such keys over secure APB.

Reading a key value from the UICR is a three-step process:

- 1. Select the key slot which the KMU shall operate on by writing the desired key slot ID into KMU->SELECTKEYSLOT.
- 2. If STATE and READ permission requirements are fulfilled as defined in KEYSLOT.CONFIG[ID-1].PERM, the key value can be read from region KEYSLOT.KEY[ID-1].VALUE[0-3] for selected key slot.
- **3.** Select key slot 0.

Step 2 will be blocked and word 0xDEADDEAD will be returned on AHB if any of the following violations are detected:

- No key slot selected
- Key slot not configured as readable
- · Key slot is revoked
- AHB read to KEYSLOT.KEY[ID-1].VALUE[0-3] registers not belonging to selected key slot



6.8.4.2.4 Push over secure APB

Key slots that are configured as non-readable cannot be read by the CPU regardless of the mode the system is in and must be pushed over secure APB in order to use the key value for cryptographic operations.

The secure APB destination address is set in the key slot configuration DEST register. Such destination addresses are typically write-only key registers in a hardware cryptographic accelerators memory map. The secure APB allows key slots to be utilized by the software side, without exposing the key value itself.

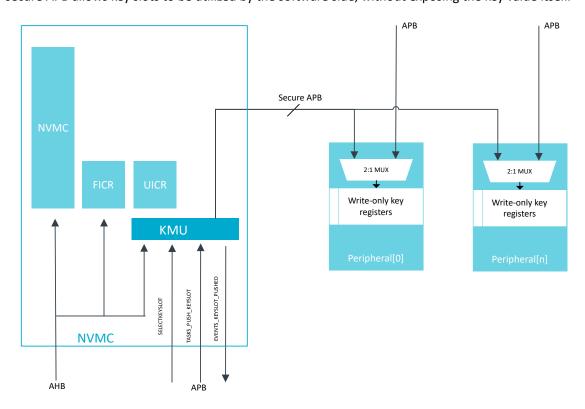


Figure 37: Tasks and events pattern for key slots

Pushing a key slot over secure APB is a four-step process:

- **1.** Select the key slot on which the KMU shall operate by writing the desired key slot ID into KMU->SELECTKEYSLOT.
- **2.** Start TASKS_PUSH_KEYSLOT to initiate a secure APB transaction, writing the 128-bit key value associated with the selected key slot into address defined in KEYSLOT.CONFIG[ID-1].DEST.
- **3.** After completing the secure APB transaction, the 128-bit key value is ready for use by the peripheral and EVENTS_KEYSLOT_PUSHED is triggered.
- 4. Select key slot 0.

Note: If a key value is distributed over multiple key slots due to its key size, exceeding the maximum 128-bit key value limitation, then each distributed key slot must be pushed individually in order to transfer the entire key value over secure APB.

Step 3 will trigger other events than EVENTS_KEYSLOT_PUSHED if the following violations are detected:

- EVENTS_KEYSLOT_ERROR:
 - If no key slot is selected
 - If a key slot has no destination address configured
 - If when pushing a key slot, flash, or peripheral returns an error
 - If pushing a key slot when push permissions are disabled

NORDIC SEMICONDUCTOR

- If attempting to push a key slot with default permissions
- EVENTS_KEYSLOT_REVOKED if a key slot is marked as revoked in its key header configuration

6.8.4.2.5 Revoking the key slots

All key slots within the key storage area can be marked as revoked.

To revoke any key slots, write to the STATE field in the KEYSLOT.CONFIG[ID-1].PERM register. The following rules apply to keys that have been revoked:

- Key slots that have the PUSH field enabled in PERM register can no longer be pushed. If a revoked key slot is selected and task TASKS_PUSH_KEYSLOT is started, the event EVENTS_KEYSLOT_REVOKED is triggered.
- 2. Key slots that have the READ field enabled in PERM register can no longer be read. Any read operation to a revoked key value will return word 0xDEADDEAD.
- **3.** Previously pushed key values stored in a peripheral write-only key register are not affected by key revocation. If secure code wants to enforce that a revoked key is no longer usable by a peripheral for cryptographic operations, the secure code should disable or reset the peripheral in question.

6.8.4.3 STATUS register

The KMU uses a STATUS register to indicate its status of operation. The SELECTED bit will be asserted whenever the currently selected key slot is successfully read from or written to.

All read or write operations to other key slots than what is currently selected in KMU->SELECTKEYSLOT will assert the BLOCKED bit. The BLOCKED bit will also be asserted if the KMU fails to select a key slot, or if a request has been blocked due to an access violation. Normal operation using the KMU should never trigger the BLOCKED bit. If this bit is triggered during the development phase, it indicates that the code is using the KMU incorrectly.

The STATUS register is reset every time register SELECTKEYSLOT is written.

6.8.5 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
KMU : S	0x50039000	HF	NS	NA	Vos	Key managament unit
KMU : NS	0x40039000	ПГ	INS	NA	Yes	Key management unit

Register overview

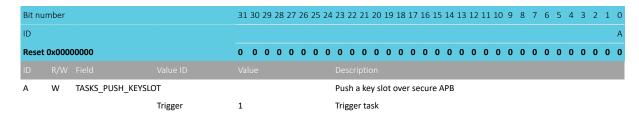
Register	Offset	TZ	Description
TASKS_PUSH_KEYSLOT	0x0000		Push a key slot over secure APB
EVENTS_KEYSLOT_PUSHED	0x100		Key slot successfully pushed over secure APB
EVENTS_KEYSLOT_REVOKED	0x104		Key slot has been revoked and cannot be tasked for selection
EVENTS_KEYSLOT_ERROR	0x108		No key slot selected, no destination address defined, or error during push operation
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
INTPEND	0x30C		Pending interrupts
STATUS	0x40C		Status bits for KMU operation
SELECTKEYSLOT	0x500		Select key slot to be read over AHB or pushed over secure APB when TASKS_PUSH_KEYSLOT
			is started



6.8.5.1 TASKS_PUSH_KEYSLOT

Address offset: 0x0000

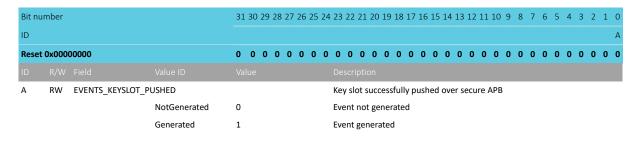
Push a key slot over secure APB



6.8.5.2 EVENTS KEYSLOT PUSHED

Address offset: 0x100

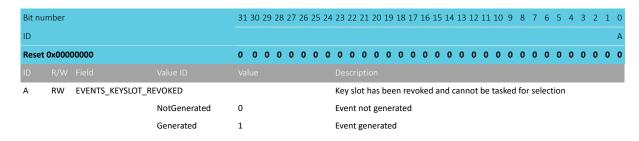
Key slot successfully pushed over secure APB



6.8.5.3 EVENTS_KEYSLOT_REVOKED

Address offset: 0x104

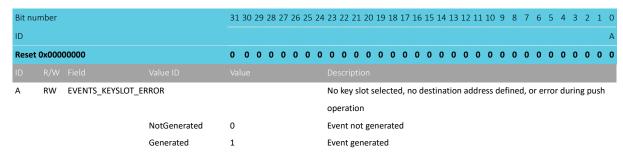
Key slot has been revoked and cannot be tasked for selection



6.8.5.4 EVENTS_KEYSLOT_ERROR

Address offset: 0x108

No key slot selected, no destination address defined, or error during push operation







6.8.5.5 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	ımber			31 3	80 29	28 27	7 26	25 2	4 23	22 2	1 20	19 1	8 17	16 1	L5 14	13	12 1	1 10	9	8	7	6	5 4	1 3	2	1	0
ID																									С	В	Α
Reset	t 0x000	00000		0 (0 0	0 0	0	0 (0	0 (0 0	0 (0 0	0	0 0	0	0 (0	0	0	0	0	0 (0	0	0	0
ID																											
Α	RW	KEYSLOT_PUSHED							Ena	able (or dis	sable	inter	rupt	for	ever	nt KE	/SLO	T_P	USF	IED						
			Disabled	0					Dis	able																	
			Enabled	1					Ena	able																	
В	RW	KEYSLOT_REVOKED							Ena	able o	or dis	sable	inter	rupt	for	ever	nt KE	/SLO	T_R	EVC	KE	D					
			Disabled	0					Dis	able																	
			Enabled	1					Ena	able																	
С	RW	KEYSLOT_ERROR							Ena	able (or dis	sable	inte	rupt	for	ever	nt KE	/SLO	T_E	RRC	R						
			Disabled	0					Dis	able																	
			Enabled	1					Ena	ble																	

6.8.5.6 INTENSET

Address offset: 0x304

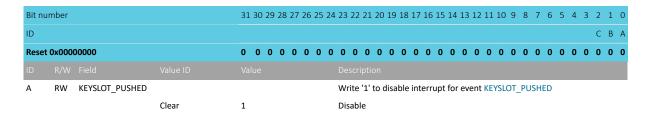
Enable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	KEYSLOT_PUSHED			Write '1' to enable interrupt for event KEYSLOT_PUSHED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	KEYSLOT_REVOKED			Write '1' to enable interrupt for event KEYSLOT_REVOKED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	KEYSLOT_ERROR			Write '1' to enable interrupt for event KEYSLOT_ERROR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.8.5.7 INTENCLR

Address offset: 0x308

Disable interrupt





Bit nu	mber			31 3	30 29 :	28 2	7 26	25 2	4 2	23 22	2 21	20 1	L9 1	18 1	7 16	15	14	13	12	11 1	0 9	8	7	6	5	4	3 2	2 1	L O
ID																											C	E	3 A
Reset	0x000	00000		0 (0 0	0	0 0	0	0 (0 0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0 0) () 0
ID																													
			Disabled	0					R	Read	: Dis	able	d																
			Enabled	1					R	Read	: En	abled	t																
В	RW	KEYSLOT_REVOKED							٧	Vrite	e '1'	to di	sab	le ir	terr	upt	for	eve	ent	KEYS	LOT	_RE	VO	KED					
			Clear	1					D	Disab	ole																		
			Disabled	0					R	Read	: Dis	able	d																
			Enabled	1					R	Read	: En	abled	t																
С	RW	KEYSLOT_ERROR							٧	Vrite	e '1'	to di	sab	le ir	terr	upt	for	eve	ent	KEYS	LOT	_EF	ROI	3					
			Clear	1					D	Disab	ole																		
			Disabled	0					R	Read	: Dis	able	d																
			Enabled	1					R	Read	: En	abled	t																

6.8.5.8 INTPEND

Address offset: 0x30C Pending interrupts

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	R	KEYSLOT_PUSHED			Read pending status of interrupt for event KEYSLOT_PUSHED
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending
В	R	KEYSLOT_REVOKED			Read pending status of interrupt for event KEYSLOT_REVOKED
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending
С	R	KEYSLOT_ERROR			Read pending status of interrupt for event KEYSLOT_ERROR
			NotPending	0	Read: Not pending
			Pending	1	Read: Pending

6.8.5.9 STATUS

Address offset: 0x40C

Status bits for KMU operation

This register is reset and re-written by the KMU whenever SELECTKEYSLOT is written

Bit nu	ımber			31	30	29 :	28	27	26	25	5 24	1 2	3 2	2 2	1 20	0 1	9 1	18 1	7	16	15	14	13	12	2 13	1 10	9	8	7	6	5	4	. 3	2	1	0
ID																																			В	Α
Reset	0x000	00000		0	0	0	0	0	0	0	0	C	0 () (0) ()	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																				
Α	R	SELECTED										K	(ey	lot	ID:	suc	ce	ssfı	ılly	sel	ec	ted	by	th.	e K	ΜL	J									
			Disabled	0								N	lo k	ey s	slot	ID	se	lect	ed	by	K٨	۱U														
			Enabled	1								K	ey s	lot	ID :	suc	ce	ssfu	ılly	sel	ec	ted	by	Κľ	ИU											
В	R	BLOCKED										٧	/iola	tio	n st	atu	IS																			
			Disabled	0								N	lo a	cce	ss v	iol	ati	on	det	ect	ed															
			Enabled	1								Α	Acce	ss \	/iola	atic	n (det	ect	ed	an	d b	loc	ke	t											

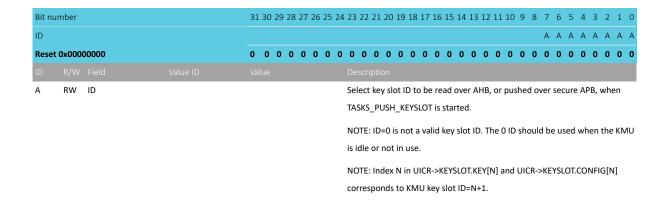




6.8.5.10 SELECTKEYSLOT

Address offset: 0x500

Select key slot to be read over AHB or pushed over secure APB when TASKS_PUSH_KEYSLOT is started



6.9 PDM — Pulse density modulation interface

The pulse density modulation (PDM) module enables input of pulse density modulated signals from external audio frontends, for example, digital microphones. The PDM module generates the PDM clock and supports single-channel or dual-channel (left and right) data input. Data is transferred directly to RAM buffers using EasyDMA.

Listed here are the main features for PDM:

- Up to two PDM microphones configured as a left/right pair using the same data input
- 16 kHz output sample rate, 16-bit samples
- EasyDMA support for sample buffering
- HW decimation filters
- Selectable ratio of 64 or 80 between PDM_CLK and output sample rate

The PDM module illustrated below is interfacing up to two digital microphones with the PDM interface. EasyDMA is implemented to relieve the real-time requirements associated with controlling of the PDM slave from a low priority CPU execution context. It also includes all the necessary digital filter elements to produce pulse code modulation (PCM) samples. The PDM module allows continuous audio streaming.

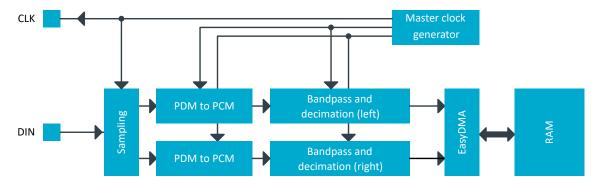


Figure 38: PDM module

6.9.1 Master clock generator

The master clock generator's PDMCLKCTRL register allows adjusting the PDM clock's frequency.

The master clock generator does not add any jitter to the HFCLK source chosen. It is recommended (but not mandatory) to use the Xtal as HFCLK source.



6.9.2 Module operation

By default, bits from the left PDM microphone are sampled on PDM_CLK falling edge, and bits for the right are sampled on the rising edge of PDM_CLK, resulting in two bitstreams. Each bitstream is fed into a digital filter which converts the PDM stream into 16-bit PCM samples, then filters and down-samples them to reach the appropriate sample rate.

The EDGE field in the MODE register allows swapping left and right, so that left will be sampled on rising edge, and right on falling.

The PDM module uses EasyDMA to store the samples coming out from the filters into one buffer in RAM. Depending on the mode chosen in the OPERATION field in the MODE register, memory either contains alternating left and right 16-bit samples (Stereo), or only left 16-bit samples (Mono). To ensure continuous PDM sampling, it is up to the application to update the EasyDMA destination address pointer as the previous buffer is filled.

The continuous transfer can be started or stopped by sending the START and STOP tasks. STOP becomes effective after the current frame has finished transferring, which will generate the STOPPED event. The STOPPED event indicates that all activity in the module is finished, and that the data is available in RAM (EasyDMA has finished transferring as well). Attempting to restart before receiving the STOPPED event may result in unpredictable behavior.

6.9.3 Decimation filter

In order to convert the incoming data stream into PCM audio samples, a decimation filter is included in the PDM interface module.

The input of the filter is the two-channel PDM serial stream (with left channel on clock high, right channel on clock low). Depending on the RATIO selected, its output is 2×16 -bit PCM samples at a sample rate either 64 times or 80 times (depending on the RATIO register) lower than the PDM clock rate.

The filter stage of each channel is followed by a digital volume control, to attenuate or amplify the output samples in a range of -20 dB to +20 dB around the default (reset) setting, defined by $G_{PDM,default}$. The gain is controlled by the GAINL and GAINR registers.

As an example, if the goal is to achieve 2500 RMS output samples (16-bit) with a 1 kHz 90 dBA signal into a -26 dBFS sensitivity PDM microphone, do the following:

- Sum the PDM module's default gain (G_{PDM,default}) and the gain introduced by the microphone and acoustic path of his implementation (an attenuation would translate into a negative gain)
- Adjust GAINL and GAINR by the above summed amount. Assuming that only the PDM module influences the gain, GAINL and GAINR must be set to -G_{PDM,default} dB to achieve the requirement.

With G_{PDM,default}=3.2 dB, and as GAINL and GAINR are expressed in 0.5 dB steps, the closest value to program would be 3.0 dB, which can be calculated as:

```
GAINL = GAINR = (DefaultGain - (2 * 3))
```

Remember to check that the resulting values programmed into GAINL and GAINR fall within MinGain and MaxGain.

6.9.4 EasyDMA

Samples will be written directly to RAM, and EasyDMA must be configured accordingly.

The address pointer for the EasyDMA channel is set in SAMPLE.PTR register. If the destination address set in SAMPLE.PTR is not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 21 for more information about the different memory regions.

DMA supports Stereo (Left+Right 16-bit samples) and Mono (Left only) data transfer, depending on the setting in the OPERATION field in the MODE register. The samples are stored little endian.



MODE.OPERATION	Bits per sample	Result stored per RAM	Physical RAM allocated	Result boundary indexes	Note
		word	(32-bit words)	in RAM	
Stereo	32 (2x16)	L+R	ceil(SAMPLE.MAXCNT/2)	R0=[31:16]; L0=[15:0]	Default
Mono	16	2xL	ceil(SAMPLE.MAXCNT/2)	L1=[31:16]; L0=[15:0]	

Table 23: DMA sample storage

The destination buffer in RAM consists of one block, the size of which is set in SAMPLE.MAXCNT register. Format is number of 16-bit samples. The physical RAM allocated is always:

```
(RAM allocation, in bytes) = SAMPLE.MAXCNT * 2;
```

(but the mapping of the samples depends on MODE.OPERATION).

If OPERATION=Stereo, RAM will contain a succession of left and right samples.

If OPERATION=Mono, RAM will contain a succession of left only samples.

For a given value of SAMPLE.MAXCNT, the buffer in RAM can contain half the stereo sampling time as compared to the mono sampling time.

The PDM acquisition can be started by the START task, after the SAMPLE.PTR and SAMPLE.MAXCNT registers have been written. When starting the module, it will take some time for the filters to start outputting valid data. Transients from the PDM microphone itself may also occur. The first few samples (typically around 50) might hence contain invalid values or transients. It is therefore advised to discard the first few samples after a PDM start.

As soon as the STARTED event is received, the firmware can write the next SAMPLE.PTR value (this register is double-buffered), to ensure continuous operation.

When the buffer in RAM is filled with samples, an END event is triggered. The firmware can start processing the data in the buffer. Meanwhile, the PDM module starts acquiring data into the new buffer pointed to by SAMPLE.PTR, and sends a new STARTED event, so that the firmware can update SAMPLE.PTR to the next buffer address.

6.9.5 Hardware example

PDM can be configured with a single microphone (mono), or with two microphones.

When a single microphone is used, connect the microphone clock to CLK, and data to DIN.

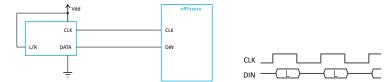


Figure 39: Example of a single PDM microphone, wired as left

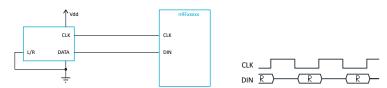


Figure 40: Example of a single PDM microphone, wired as right

Note that in a single-microphone (mono) configuration, depending on the microphone's implementation, either the left or the right channel (sampled at falling or rising CLK edge respectively) will contain reliable data.



If two microphones are used, one of them must be set as left, the other as right (L/R pin tied high or to GND on the respective microphone). It is strongly recommended to use two microphones of exactly the same brand and type so that their timings in left and right operation match.

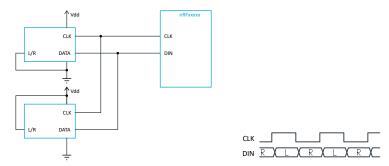


Figure 41: Example of two PDM microphones

6.9.6 Pin configuration

The CLK and DIN signals associated to the PDM module are mapped to physical pins according to the configuration specified in the PSEL.CLK and PSEL.DIN registers respectively. If the CONNECT field in any PSEL register is set to Disconnected, the associated PDM module signal will not be connected to the required physical pins and will not operate properly.

The PSEL.CLK and PSEL.DIN registers and their configurations are only used as long as the PDM module is enabled, and retained only as long as the device is in System ON mode. See POWER — Power control on page 63 for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register.

To ensure correct behavior in the PDM module, the pins used by the PDM module must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 152 before enabling the PDM module. This is to ensure that the pins used by the PDM module are driven correctly if the PDM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the PDM module is supposed to be connected to an external PDM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

PDM signal	PDM pin	Direction	Output value	Comment
CLK	As specified in PSEL.CLK	Output	0	
DIN	As specified in PSEL.DIN	Input	Not applicable	

Table 24: GPIO configuration before enabling peripheral

6.9.7 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
PDM : S	0x50026000	US	NS	SA	No	Pulse density modulation (digital
PDM: NS	0x40026000	US	CNI	ЭA	INU	microphone) interface



Register overview

Register	Offset	TZ	Description
TASKS_START	0x000		Starts continuous PDM transfer
TASKS_STOP	0x004		Stops PDM transfer
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
EVENTS_STARTED	0x100		PDM transfer has started
EVENTS_STOPPED	0x104		PDM transfer has finished
EVENTS_END	0x108		The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after
			a STOP task has been received) to Data RAM
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_END	0x188		Publish configuration for event END
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PDM module enable register
PDMCLKCTRL	0x504		PDM clock generator control
MODE	0x508		Defines the routing of the connected PDM microphones' signals
GAINL	0x518		Left output gain adjustment
GAINR	0x51C		Right output gain adjustment
RATIO	0x520		Selects the ratio between PDM_CLK and output sample rate. Change PDMCLKCTRL
			accordingly.
PSEL.CLK	0x540		Pin number configuration for PDM CLK signal
PSEL.DIN	0x544		Pin number configuration for PDM DIN signal
SAMPLE.PTR	0x560		RAM address pointer to write samples to with EasyDMA
SAMPLE.MAXCNT	0x564		Number of samples to allocate memory for in EasyDMA mode

6.9.7.1 TASKS_START

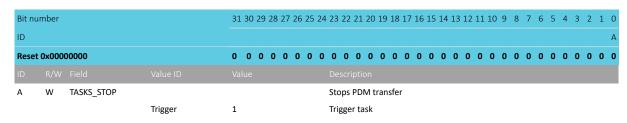
Address offset: 0x000

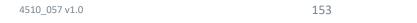
Starts continuous PDM transfer

Bit n	umber			31 30 29 28 27 26	25 24 2	23 22 2	21 20	0 19	18 1	7 16	15	14	13 1	.2 1	1 1	0 9	8	7	6	5	4	3	2	1 0
ID																								Α
Rese	t 0x000	00000		0 0 0 0 0 0	0 0	0 0	0 0	0	0 0	0	0	0	0 (0 (0	0	0	0	0	0	0	0	0 (0 0
ID																								
Α	W	TASKS_START			9	starts o	onti	nuou	s PD	M tı	ransf	er												
			Trigger	1	7	rigger	task																	

6.9.7.2 TASKS_STOP

Address offset: 0x004 Stops PDM transfer



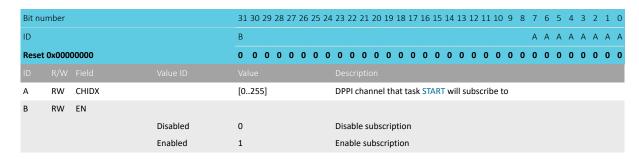




6.9.7.3 SUBSCRIBE_START

Address offset: 0x080

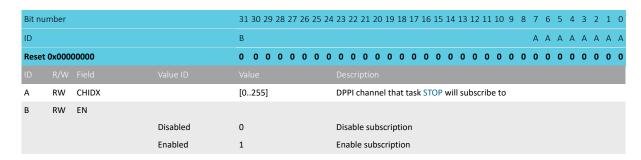
Subscribe configuration for task START



6.9.7.4 SUBSCRIBE_STOP

Address offset: 0x084

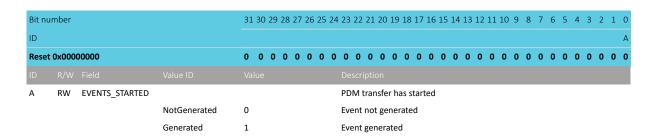
Subscribe configuration for task STOP



6.9.7.5 EVENTS STARTED

Address offset: 0x100

PDM transfer has started

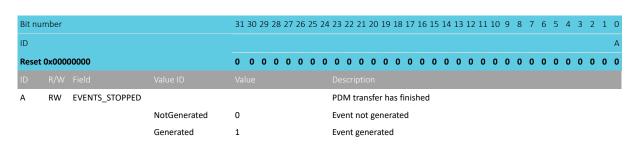


6.9.7.6 EVENTS_STOPPED

Address offset: 0x104

PDM transfer has finished

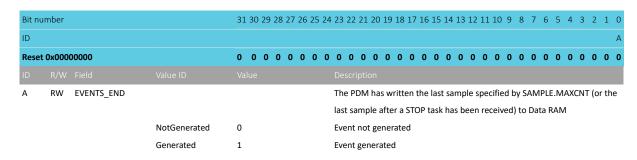




6.9.7.7 EVENTS_END

Address offset: 0x108

The PDM has written the last sample specified by SAMPLE.MAXCNT (or the last sample after a STOP task has been received) to Data RAM



6.9.7.8 PUBLISH STARTED

Address offset: 0x180

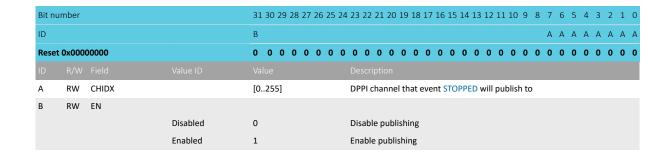
Publish configuration for event STARTED

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event STARTED will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.9.7.9 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED







6.9.7.10 PUBLISH_END

Address offset: 0x188

Publish configuration for event END

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event END will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.9.7.11 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					
Α	RW	STARTED			Enable or disable interrupt for event STARTED
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	STOPPED			Enable or disable interrupt for event STOPPED
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	END			Enable or disable interrupt for event END
			Disabled	0	Disable
			Enabled	1	Enable

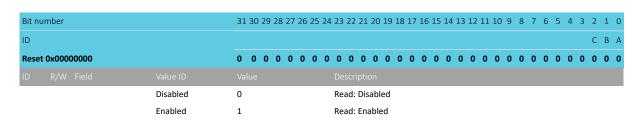
6.9.7.12 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	STARTED			Write '1' to enable interrupt for event STARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable





6.9.7.13 INTENCLR

Address offset: 0x308

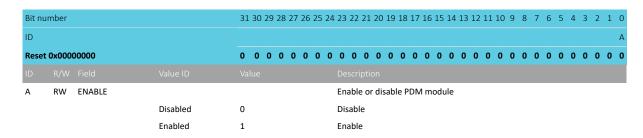
Disable interrupt

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Reset	t 0x0000	0000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	STARTED			Write '1' to disable interrupt for event STARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	STOPPED			Write '1' to disable interrupt for event STOPPED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	END			Write '1' to disable interrupt for event END
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.9.7.14 ENABLE

Address offset: 0x500

PDM module enable register

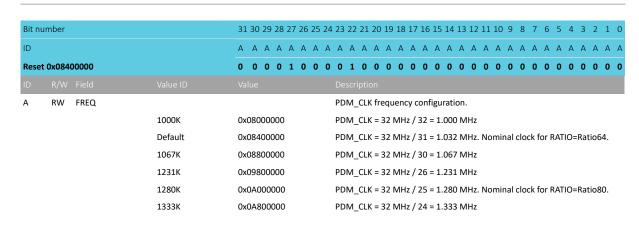


6.9.7.15 PDMCLKCTRL

Address offset: 0x504

PDM clock generator control





6.9.7.16 MODE

Address offset: 0x508

Defines the routing of the connected PDM microphones' signals

Bit nu	umber			31 30	29	28 :	27 2	6 2	5 24	1 23	22	21	20	19	18	17	16	15	14	13	12 :	11 1	.0 !	9 8	3 7	' 6	5	4	3	2	1	0
ID																															В	Α
Reset	t 0x000	00000		0 0	0	0	0 (0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 (0 0) (0	0	0	0	0	0
ID																																
Α	RW	OPERATION								M	ono	or	ster	reo	оре	erat	ion															
			Stereo	0						Sa	mp	le a	nd s	stor	e o	ne	pair	· (le	ft +	- rig	ht)	of 1	6-b	it s	amı	oles	pei	r RA	M v	vor	b	
										R=	[31	:16]]; L=	[15	:0]																	
			Mono	1						Sa	mp	le a	nd s	stor	e tı	wo:	suc	ces	sive	elet	t sa	mp	les	(16	bits	ea	ch)	per	RAI	VI W	orc	l
										L1	=[3	1:16	5]; L]=0.	15:	0]																
В	RW	EDGE								De	fine	es o	n w	hic	h P	DM	_Cl	K e	dge	e le	ft (c	or m	one	o) is	sar	npl	ed					
			LeftFalling	0						Le	ft (d	or m	non	o) is	sa	mp	led	on	fall	ing	edg	ge o	f PI	DM.	_CLI	(
			LeftRising	1						Le	ft (d	or m	non	o) is	sa	mp	led	on	risi	ng	edg	e of	PD	M_	CLK							

6.9.7.17 GAINL

Address offset: 0x518

Left output gain adjustment

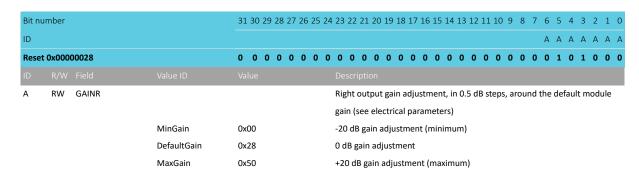


Dit	unahar			21.	20.2	0.24	0 27	7 20	י אר	24	22.5	22.2	11 20	10	10	17	10.	1 [1 /	12	17.1	1 1	2 C	C	7	C	_	1	2	2	1	0
	ımber			31 :	50 2	9 2	8 27	26	25	24	23 2	22 2	1 20	19	18	1/	16.	15	14	13	12]	111	J 9	8	/		5					
ID																										Α	Α	Α	Α	Α	Α	Α
Rese	0x0000	00028		0	0 (0 0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	1	0	1	0	0	0
ID	R/W	Field	Value ID	Valu	1e						Des	crip [.]	tion																			
Α	RW	GAINL									Left	out	tput	gair	ad	just	mei	nt,	in C).5	dB s	teps	, ar	our	nd th	ne d	defa	ult	mo	dul	e g	ain
											(see	e ele	ctric	al p	ara	me	ters))														
											0x0	0 -2	0 dB	gai	n ac	ljus	t															
											0x0	1 -1	9.5 c	dB g	ain	adj	ust															
											()																					
											0x2	7 -0	.5 dE	3 ga	in a	dju	st															
											0x2	800	dB ga	ain a	adju	ıst																
											0x2	9 +0).5 d	B ga	in a	dju	st															
											()																					
											0x4	F +1	.9.5	dB g	gain	adj	ust															
											0x5	0 +2	20 dE	3 gai	in a	djus	st															
			MinGain	0x0	0						-20	dB g	gain	adju	ıstn	nen	t (m	ini	mu	m)												
			DefaultGain	0x2	8						0 dE	B gai	in ad	djust	me	nt																
			MaxGain	0x5	0						+20	dB	gain	adj	ustr	ner	ıt (m	nax	imu	ım)												

6.9.7.18 GAINR

Address offset: 0x51C

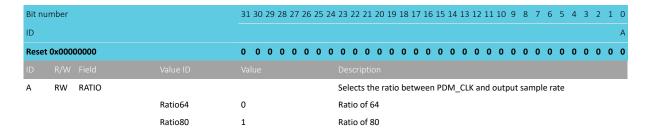
Right output gain adjustment



6.9.7.19 RATIO

Address offset: 0x520

Selects the ratio between PDM_CLK and output sample rate. Change PDMCLKCTRL accordingly.

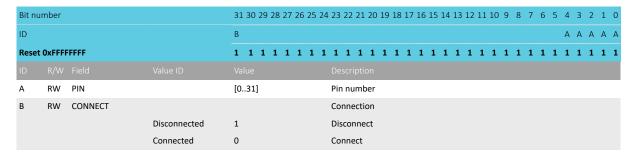


6.9.7.20 PSEL.CLK

Address offset: 0x540



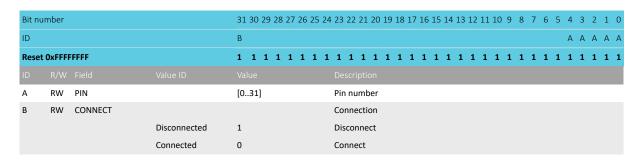
Pin number configuration for PDM CLK signal



6.9.7.21 PSEL.DIN

Address offset: 0x544

Pin number configuration for PDM DIN signal



6.9.7.22 SAMPLE.PTR

Address offset: 0x560

RAM address pointer to write samples to with EasyDMA

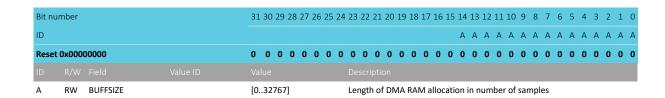


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.9.7.23 SAMPLE.MAXCNT

Address offset: 0x564

Number of samples to allocate memory for in EasyDMA mode





6.9.8 Electrical specification

6.9.8.1 PDM Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{PDM,CLK,64}	PDM clock speed. PDMCLKCTRL = Default (Setting needed for 16 MHz	sample	1.032		MHz
	frequency @ RATIO = Ratio64)				
f _{PDM,CLK,80}	PDM clock speed. PDMCLKCTRL = 1280K (Setting needed for 16 MHz	sample	1.28		MHz
	frequency @ RATIO = Ratio80)				
t _{PDM,JITTER}	Jitter in PDM clock output			20	ns
T _{dPDM,CLK}	PDM clock duty cycle	40	50	60	%
t _{PDM,DATA}	Decimation filter delay			5	ms
t _{PDM,cv}	Allowed clock edge to data valid			125	ns
t _{PDM,ci}	Allowed (other) clock edge to data invalid	0			ns
t _{PDM,s}	Data setup time at f _{PDM,CLK} =1.024 MHz or 1.280 MHz	65			ns
t _{PDM,h}	Data hold time at $f_{\text{PDM,CLK}}\text{=}1.024~\text{MHz}$ or 1.280 MHz	0			ns
G _{PDM,default}	Default (reset) absolute gain of the PDM module		3.2		dB

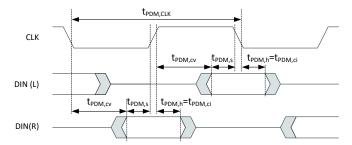


Figure 42: PDM timing diagram

6.10 PWM — Pulse width modulation

The pulse width modulation (PWM) module enables the generation of pulse width modulated signals on GPIO. The module implements an up or up-and-down counter with four PWM channels that drive assigned GPIOs.

The following are the main features of a PWM module:

- Programmable PWM frequency
- Up to four PWM channels with individual polarity and duty cycle values
- Edge or center-aligned pulses across PWM channels
- Multiple duty cycle arrays (sequences) defined in RAM
- Autonomous and glitch-free update of duty cycle values directly from memory through EasyDMA (no CPU involvement)
- Change of polarity, duty cycle, and base frequency possibly on every PWM period
- RAM sequences can be repeated or connected into loops



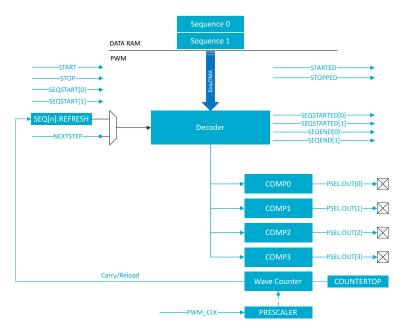


Figure 43: PWM module

6.10.1 Wave counter

The wave counter is responsible for generating the pulses, at a duty cycle that depends on the compare values and at a frequency that depends on COUNTERTOP.

There is one common 15-bit counter with four compare channels. Thus, all four channels will share the same period (PWM frequency) but can have individual duty cycle and polarity. The polarity is set by the most significant bit (MSB) of the value read from RAM (see figure Decoder memory access modes on page 165). When the MSB bit is high (FallingEdge polarity), OUT[n] starts high to become low during the given PWM cycle, whereas the inverse occurs for RisingEdge polarity. Whether the counter counts up, or up and down, is controlled by the MODE register.

The timer top value is controlled by the COUNTERTOP register. This register value, in conjunction with the selected PRESCALER of the PWM_CLK, will result in a given PWM period. A COUNTERTOP value smaller than the compare setting will result in a state where no PWM edges are generated. OUT[n] is held high, given that the polarity is set to FallingEdge. All compare registers are internal and can only be configured through decoder presented later. COUNTERTOP can be safely written at any time.

Sampling follows the START task. If DECODER.LOAD=WaveForm, the register value is ignored and taken from RAM instead (see section Decoder with EasyDMA on page 165 for more details). If DECODER.LOAD is anything else than the WaveForm, it is sampled following a STARTSEQ[n] task and when loading a new value from RAM during a sequence playback.

The following figure shows the counter operating in up mode (MODE=PWM_MODE_Up), with two PWM channels with the same frequency but different duty cycle:



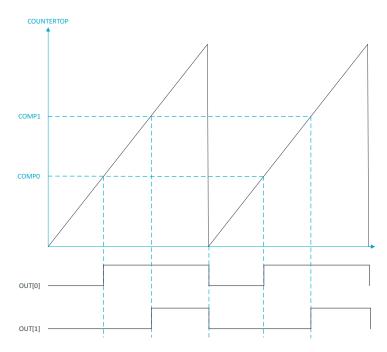


Figure 44: PWM counter in up mode example - RisingEdge polarity

The counter is automatically reset to zero when COUNTERTOP is reached and OUT[n] will invert. OUT[n] is held low if the compare value is 0 and held high if set to COUNTERTOP, given that the polarity is set to FallingEdge. Counter running in up mode results in pulse widths that are edge-aligned. The following is the code for the counter in up mode example:

```
uint16_t pwm_seq[4] = {PWM_CH0_DUTY, PWM_CH1_DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM_PSEL_OUT_CONNECT_Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                   = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);
NRF PWM0->PRESCALER = (PWM_PRESCALER_PRESCALER_DIV_1 <<
                                                PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
                     = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->LOOP
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Individual << PWM_DECODER_LOAD_Pos) |
                     (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t) (pwm seq) << PWM SEQ PTR PTR Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(pwm seq) / sizeof(uint16 t)) <<
                                                PWM SEQ CNT CNT Pos);
NRF_PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

When the counter is running in up mode, the following formula can be used to compute the PWM period and the step size:

```
PWM period: T_{PWM (Up)} = T_{PWM CLK} * COUNTERTOP
```



Step width/Resolution: $T_{\text{steps}} = T_{\text{PWM CLK}}$

The following figure shows the counter operating in up-and-down mode (MODE=PWM_MODE_UpAndDown), with two PWM channels with the same frequency but different duty cycle and output polarity:

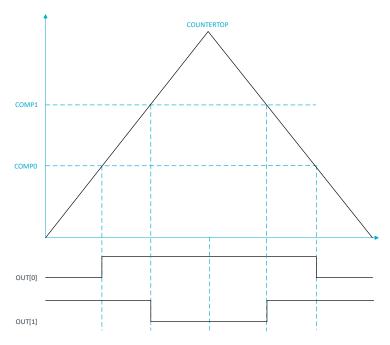


Figure 45: PWM counter in up-and-down mode example

The counter starts decrementing to zero when COUNTERTOP is reached and will invert the OUT[n] when compare value is hit for the second time. This results in a set of pulses that are center-aligned. The following is the code for the counter in up-and-down mode example:

```
uint16 t pwm seq[4] = {PWM CH0 DUTY, PWM CH1 DUTY, PWM CH2 DUTY, PWM CH3 DUTY};
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                       (PWM PSEL OUT CONNECT Connected <<
                                              PWM PSEL OUT CONNECT Pos);
NRF PWM0->PSEL.OUT[1] = (second pin << PWM PSEL OUT PIN Pos) |
                       (PWM PSEL OUT CONNECT Connected <<
                                              PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                    = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
NRF_PWM0->MODE
                    = (PWM_MODE_UPDOWN_UpAndDown << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                              PWM PRESCALER PRESCALER Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
               = (PWM LOOP CNT Disabled << PWM LOOP CNT Pos);
NRF PWM0->LOOP
NRF PWM0->DECODER = (PWM DECODER LOAD Individual << PWM DECODER LOAD Pos) |
                    (PWM_DECODER_MODE_RefreshCount << PWM_DECODER_MODE_Pos);</pre>
NRF PWM0->SEQ[0].PTR = ((uint32 t) (pwm seq) << PWM SEQ PTR PTR Pos);
PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF_PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```



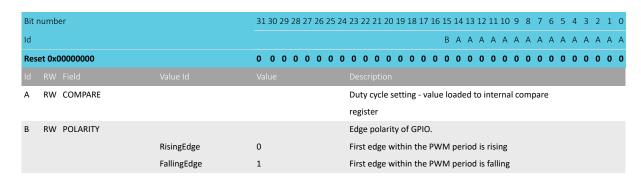
When the counter is running in up-and-down mode, the following formula can be used to compute the PWM period and the step size:

```
T_{PWM\,(Up\ And\ Down)} = T_{PWM\_CLK} * 2 * COUNTERTOP
Step width/Resolution: T_{steps} = T_{PWM\ CLK} * 2
```

6.10.2 Decoder with EasyDMA

The decoder uses EasyDMA to take PWM parameters stored in RAM and update the internal compare registers of the wave counter, based on the mode of operation.

PWM parameters are organized into a sequence containing at least one half word (16 bit). Its most significant bit[15] denotes the polarity of the OUT[n] while bit[14:0] is the 15-bit compare value.



The DECODER register controls how the RAM content is interpreted and loaded into the internal compare registers. The LOAD field controls if the RAM values are loaded to all compare channels, or to update a group or all channels with individual values. The following figure illustrates how parameters stored in RAM are organized and routed to various compare channels in different modes:

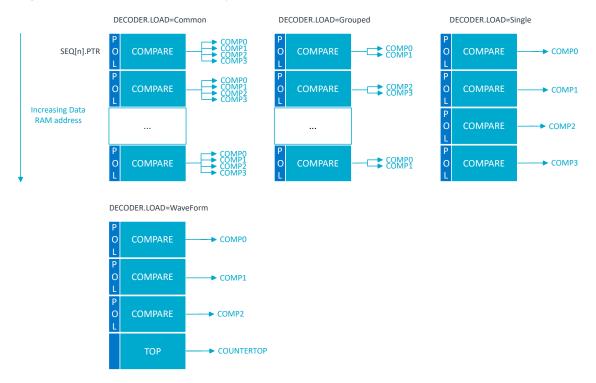


Figure 46: Decoder memory access modes

A special mode of operation is available when DECODER.LOAD is set to WaveForm. In this mode, up to three PWM channels can be enabled - OUT[0] to OUT[2]. In RAM, four values are loaded at a time: the first, second and third location are used to load the values, and the fourth RAM location is used to load



the COUNTERTOP register. This way one can have up to three PWM channels with a frequency base that changes on a per PWM period basis. This mode of operation is useful for arbitrary wave form generation in applications, such as LED lighting.

The register SEQ[n].REFRESH=N (one per sequence n=0 or 1) will instruct a new RAM stored pulse width value on every (N+1)th PWM period. Setting the register to zero will result in a new duty cycle update every PWM period, as long as the minimum PWM period is observed.

Note that registers SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored when DECODER.MODE=NextStep. The next value is loaded upon every received NEXTSTEP task.

SEQ[n].PTR is the pointer used to fetch COMPARE values from RAM. If the SEQ[n].PTR is not pointing to a RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 21 for more information about the different memory regions. After the SEQ[n].PTR is set to the desired RAM location, the SEQ[n].CNT register must be set to the number of 16-bit half words in the sequence. It is important to observe that the Grouped mode requires one half word per group, while the Single mode requires one half word per channel, thus increasing the RAM size occupation. If PWM generation is not running when the SEQSTART[n] task is triggered, the task will load the first value from RAM and then start the PWM generation. A SEQSTARTED[n] event is generated as soon as the EasyDMA has read the first PWM parameter from RAM and the wave counter has started executing it. When LOOP.CNT=0, sequence n=0 or 1 is played back once. After the last value in the sequence has been loaded and started executing, a SEQEND[n] event is generated. The PWM generation will then continue with the last loaded value. The following figure illustrates an example of a simple playback.

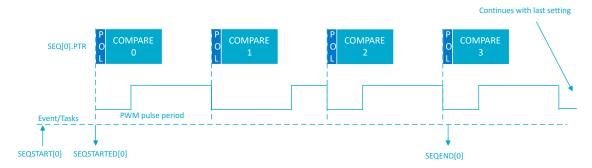


Figure 47: Simple sequence example



The following source code is used for configuration and timing details in a sequence where only sequence 0 is used and only run once with a new PWM duty cycle for each period.

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                    PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                    PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (PWM_LOOP_CNT_Disabled << PWM_LOOP_CNT_Pos);
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF PWM0->SEQ[0].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                    PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 0;
NRF PWM0->SEQ[0].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

To completely stop the PWM generation and force the associated pins to a defined state, a STOP task can be triggered at any time. A STOPPED event is generated when the PWM generation has stopped at the end of the currently running PWM period, and the pins go into their idle state as defined in GPIO OUT register. PWM generation can then only be restarted through a SEQSTART[n] task. SEQSTART[n] will resume PWM generation after having loaded the first value from the RAM buffer defined in the SEQ[n].PTR register.

The following table indicates when specific registers get sampled by the hardware. Care should be taken when updating these registers to avoid that values are applied earlier than expected.



Register	Taken into account by hardware	Recommended (safe) update
SEQ[n].PTR	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[n].CNT	When sending the SEQSTART[n] task	After having received the SEQSTARTED[n] event
SEQ[0].ENDDELAY	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	Every time a new value from sequence [0] has been loaded from	When no more value from sequence [0] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[0] event)
	PWMPERIODEND event)	At any time during sequence [1] (which starts when the
		SEQSTARTED[1] event is generated)
SEQ[1].ENDDELAY	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	When no more value from sequence [1] gets loaded from RAM
	RAM and gets applied to the Wave Counter (indicated by the	(indicated by the SEQEND[1] event)
	PWMPERIODEND event)	At any time during sequence [0] (which starts when the
		SEQSTARTED[0] event is generated)
SEQ[0].REFRESH	When sending the SEQSTART[0] task	Before starting sequence [0] through a SEQSTART[0] task
	Every time a new value from sequence [0] has been loaded from	At any time during sequence [1] (which starts when the
	RAM and gets applied to the Wave Counter (indicated by the	SEQSTARTED[1] event is generated)
	PWMPERIODEND event)	
SEQ[1].REFRESH	When sending the SEQSTART[1] task	Before starting sequence [1] through a SEQSTART[1] task
	Every time a new value from sequence [1] has been loaded from	At any time during sequence [0] (which starts when the
	RAM and gets applied to the Wave Counter (indicated by the PWMPERIODEND event)	SEQSTARTED[0] event is generated)
COUNTERTOP	In DECODER.LOAD=WaveForm: this register is ignored.	Before starting PWM generation through a SEQSTART[n] task
	In all other LOAD modes: at the end of current PWM period	After a STOP task has been triggered, and the STOPPED event has
	(indicated by the PWMPERIODEND event)	been received.
MODE	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
DECODER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PRESCALER	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
LOOP	Immediately	Before starting PWM generation through a SEQSTART[n] task
		After a STOP task has been triggered, and the STOPPED event has
		been received.
PSEL.OUT[n]	Immediately	Before enabling the PWM instance through the ENABLE register
	•	

Table 25: When to safely update PWM registers

Note: SEQ[n].REFRESH and SEQ[n].ENDDELAY are ignored at the end of a complex sequence, indicated by a LOOPSDONE event. The reason for this is that the last value loaded from RAM is maintained until further action from software (restarting a new sequence or stopping PWM generation).

The following figure shows a more complex example using the register LOOP on page 183.



Figure 48: Example using two sequences

In this case, an automated playback takes place, consisting of SEQ[0], delay 0, SEQ[1], delay 1, then again SEQ[0], etc. The user can choose to start a complex playback with SEQ[0] or SEQ[1] through sending the SEQSTART[0] or SEQSTART[1] task. The complex playback always ends with delay 1.

The two sequences 0 and 1 are defined by the addresses of value tables in RAM (pointed to by SEQ[n].PTR) and the buffer size (SEQ[n].CNT). The rate at which a new value is loaded is defined individually for each sequence by SEQ[n].REFRESH. The chaining of sequence 1 following the sequence 0 is implicit, the LOOP.CNT register allows the chaining of sequence 1 to sequence 0 for a determined number of times. In other words, it allows to repeat a complex sequence a number of times in a fully automated way.

In the following code example, sequence 0 is defined with SEQ[0].REFRESH set to 1, meaning that a new PWM duty cycle is pushed every second PWM period. This complex sequence is started with the SEQSTART[0] task, so SEQ[0] is played first. Since SEQ[0].ENDDELAY=1 there will be one PWM period delay between last period on sequence 0 and the first period on sequence 1. Since SEQ[1].ENDDELAY=0 there is no delay 1, so SEQ[0] would be started immediately after the end of SEQ[1]. However, as LOOP.CNT is



1, the playback stops after having played SEQ[1] only once, and both SEQEND[1] and LOOPSDONE are generated (their order is not guaranteed in this case).

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                         (PWM PSEL OUT CONNECT Connected <<
                                                   PWM PSEL OUT CONNECT Pos);
NRF_PWM0->ENABLE = (PWM_ENABLE_ENABLE_Enabled << PWM_ENABLE_ENABLE_Pos);
NRF_PWM0->MODE = (PWM_MODE_UPDOWN_Up << PWM_MODE_UPDOWN_Pos);</pre>
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                   PWM PRESCALER PRESCALER Pos);
NRF_PWM0->COUNTERTOP = (16000 << PWM_COUNTERTOP_COUNTERTOP_Pos); //1 msec
NRF_PWM0->LOOP = (1 << PWM_LOOP_CNT_Pos);
NRF_PWM0->DECODER = (PWM_DECODER_LOAD_Common << PWM_DECODER_LOAD_Pos) |
                       (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
NRF_PWM0->SEQ[0].PTR = ((uint32_t)(seq0_ram) << PWM_SEQ_PTR_PTR_Pos);
NRF PWM0->SEQ[0].CNT = ((sizeof(seq0 ram) / sizeof(uint16 t)) <<
                                                   PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[0].REFRESH = 1;
NRF PWM0->SEQ[0].ENDDELAY = 1;
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq1 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq1_ram) / sizeof(uint16_t)) <<
                                                  PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[1].REFRESH = 0;
NRF PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[0] = 1;
```

The decoder can also be configured to asynchronously load new PWM duty cycle. If the DECODER.MODE register is set to NextStep, then the NEXTSTEP task will cause an update of internal compare registers on the next PWM period.

The following figures provide an overview of each part of an arbitrary sequence, in various modes (LOOP.CNT=0 and LOOP.CNT>0). In particular, the following are represented:

- Initial and final duty cycle on the PWM output(s)
- Chaining of SEQ[0] and SEQ[1] if LOOP.CNT>0
- Influence of registers on the sequence
- Events generated during a sequence
- DMA activity (loading of next value and applying it to the output(s))



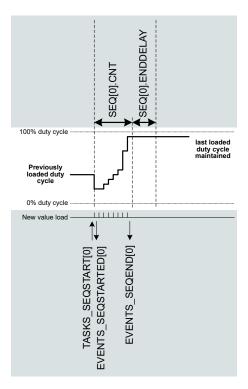


Figure 49: Single shot (LOOP.CNT=0)

Note: The single-shot example also applies to SEQ[1]. Only SEQ[0] is represented for simplicity.

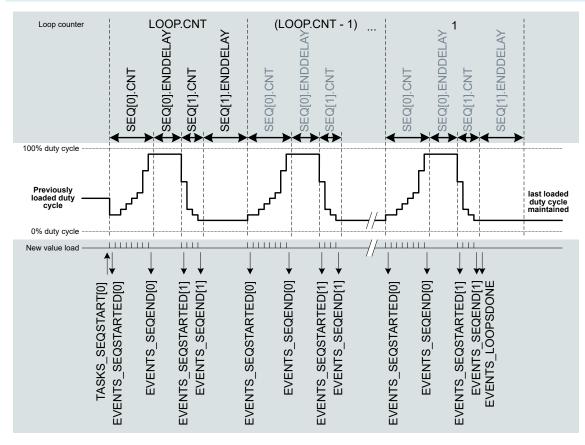


Figure 50: Complex sequence (LOOP.CNT>0) starting with SEQ[0]



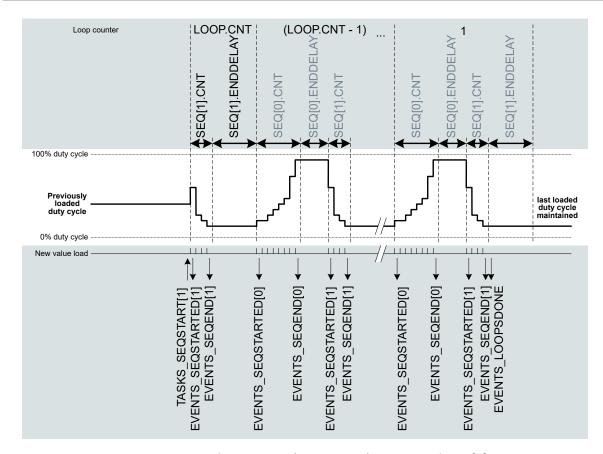


Figure 51: Complex sequence (LOOP.CNT>0) starting with SEQ[1]

Note: If a sequence is in use in a simple or complex sequence, it must have a length of SEQ[n].CNT > 0.

This example shows how the PWM module can be configured to repeat a single sequence until stopped.

```
NRF PWM0->PSEL.OUT[0] = (first pin << PWM PSEL OUT PIN Pos) |
                        (PWM PSEL OUT CONNECT Connected <<
                                                 PWM PSEL OUT CONNECT Pos);
NRF PWM0->ENABLE
                      = (PWM ENABLE ENABLE Enabled << PWM ENABLE ENABLE Pos);
                      = (PWM MODE UPDOWN Up << PWM MODE UPDOWN Pos);
NRF PWM0->MODE
NRF PWM0->PRESCALER = (PWM PRESCALER PRESCALER DIV 1 <<
                                                 PWM_PRESCALER_PRESCALER_Pos);
NRF PWM0->COUNTERTOP = (16000 << PWM COUNTERTOP COUNTERTOP Pos); //1 msec
// Enable the shortcut from LOOPSDONE event to SEQSTART1 task for infinite loop
                     = (PWM_SHORTS_LOOPSDONE_SEQSTART1_Enabled <<
NRF PWM0->SHORTS
                                          PWM SHORTS LOOPSDONE SEQSTART1 Pos);
// LOOP CNT must be greater than 0 for the LOOPSDONE event to trigger and enable looping
NRF PWM0->LOOP
                      = (1 << PWM_LOOP_CNT_Pos);
NRF PWM0->DECODER
                      = (PWM DECODER LOAD Common << PWM DECODER LOAD Pos) |
                      (PWM DECODER MODE RefreshCount << PWM DECODER MODE Pos);
// To repeat a single sequence until stopped, it must be configured in SEQ[1]
NRF PWM0->SEQ[1].PTR = ((uint32 t)(seq0 ram) << PWM SEQ PTR PTR Pos);
NRF_PWM0->SEQ[1].CNT = ((sizeof(seq0_ram) / sizeof(uint16_t)) <<
                                                 PWM SEQ CNT CNT Pos);
NRF PWM0->SEQ[1].REFRESH = 0;
NRF PWM0->SEQ[1].ENDDELAY = 0;
NRF PWM0->TASKS SEQSTART[1] = 1;
```



6.10.3 Limitations

The previous compare value is repeated if the PWM period is shorter than the time it takes for the EasyDMA to retrieve from RAM and update the internal compare registers. This is to ensure a glitch-free operation even for very short PWM periods.

Only SEQ[1] can trigger the LOOPSDONE event upon completion, not SEQ[0]. This requires looping to be enabled (LOOP > 0) and SEQ[1].CNT > 0 when sequence playback starts.

6.10.4 Pin configuration

The OUT[n] (n=0..3) signals associated with each PWM channel are mapped to physical pins according to the configuration of PSEL.OUT[n] registers. If PSEL.OUT[n].CONNECT is set to Disconnected, the associated PWM module signal will not be connected to any physical pins.

The PSEL.OUT[n] registers and their configurations are used as long as the PWM module is enabled and the PWM generation active (wave counter started). They are retained only as long as the device is in System ON mode (see the POWER section for more information about power modes).

To ensure correct behavior in the PWM module, the pins that are used must be configured in the GPIO peripheral in the following way before the PWM module is enabled:

PWM signal	PWM pin	Direction	Output value	Comment
OUT[n]	As specified in PSEL.OUT[n]	Output	0	Idle state defined in GPIO OUT
	(n=03)			register

Table 26: Recommended GPIO configuration before starting PWM generation

The idle state of a pin is defined by the OUT register in the GPIO module, to ensure that the pins used by the PWM module are driven correctly. If PWM generation is stopped by triggering a STOP task, the PWM module itself is temporarily disabled or the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected pins (I/Os) for as long as the PWM module is supposed to be connected to an external PWM circuit.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

6.10.5 Registers

Instances

Instance	Base address	TrustZone			Split access	Description				
		Мар	Att	DMA						
PWM0:S	0x50021000	US	NS	SA	No	Pulse width modulation unit 0				
PWM0 : NS	0x40021000	03	INS	ЗА	INO	ruise width modulation unit o				
PWM1:S	0x50022000	US	NS	SA	No	Pulse width modulation unit 1				
PWM1:NS	0x40022000	03	NS	3 A	NO	r disc width modulation diff. I				
PWM2:S	0x50023000	US	NS	SA	No	Pulse width modulation unit 2				
PWM2:NS	0x40023000	03	113	371	110	raise water modulation and 2				
PWM3:S	0x50024000	US	NS	SA	No	Pulse width modulation unit 3				
PWM3:NS	0x40024000	03	NS	3 A	NO	r disc width modulation diff. 5				



Register overview

Register	Offset	TZ	Description
TASKS_STOP	0x004		Stops PWM pulse generation on all channels at the end of current PWM period, and stops
			sequence playback
TASKS_SEQSTART[n]	0x008		Loads the first PWM value on all enabled channels from sequence n, and starts playing
			that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM
			generation to start if not running.
TASKS_NEXTSTEP	0x010		Steps by one value in the current sequence on all enabled channels if
			DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_SEQSTART[n]	0x088		Subscribe configuration for task SEQSTART[n]
SUBSCRIBE_NEXTSTEP	0x090		Subscribe configuration for task NEXTSTEP
EVENTS_STOPPED	0x104		Response to STOP task, emitted when PWM pulses are no longer generated
EVENTS_SEQSTARTED[n]	0x108		First PWM period started on sequence n
EVENTS_SEQEND[n]	0x110		Emitted at end of every sequence n, when last value from RAM has been applied to wave
			counter
EVENTS_PWMPERIODEND	0x118		Emitted at the end of each PWM period
EVENTS_LOOPSDONE	0x11C		Concatenated sequences have been played the amount of times defined in LOOP.CNT
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_SEQSTARTED[n]	0x188		Publish configuration for event SEQSTARTED[n]
PUBLISH_SEQEND[n]	0x190		Publish configuration for event SEQEND[n]
PUBLISH_PWMPERIODEND	0x198		Publish configuration for event PWMPERIODEND
PUBLISH_LOOPSDONE	0x19C		Publish configuration for event LOOPSDONE
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		PWM module enable register
MODE	0x504		Selects operating mode of the wave counter
COUNTERTOP	0x508		Value up to which the pulse generator counter counts
PRESCALER	0x50C		Configuration for PWM_CLK
DECODER	0x510		Configuration of the decoder
LOOP	0x514		Number of playbacks of a loop
SEQ[n].PTR	0x520		Beginning address in RAM of this sequence
SEQ[n].CNT	0x524		Number of values (duty cycles) in this sequence
SEQ[n].REFRESH	0x528		Number of additional PWM periods between samples loaded into compare register
SEQ[n].ENDDELAY	0x52C		Time added after the sequence
PSEL.OUT[n]	0x560		Output pin select for PWM channel n

6.10.5.1 TASKS_STOP

Address offset: 0x004

Stops PWM pulse generation on all channels at the end of current PWM period, and stops sequence playback

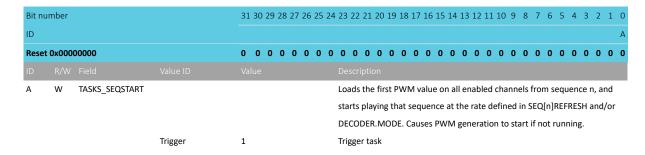
Bit nu	umber			31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_STOP			Stops PWM pulse generation on all channels at the end of current PWM
					period, and stops sequence playback
			Trigger	1	Trigger task



6.10.5.2 TASKS_SEQSTART[n] (n=0..1)

Address offset: $0x008 + (n \times 0x4)$

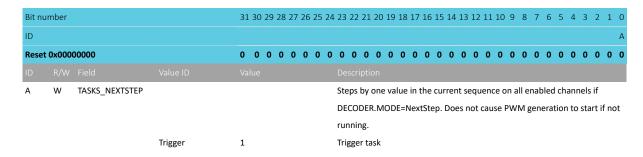
Loads the first PWM value on all enabled channels from sequence n, and starts playing that sequence at the rate defined in SEQ[n]REFRESH and/or DECODER.MODE. Causes PWM generation to start if not running.



6.10.5.3 TASKS_NEXTSTEP

Address offset: 0x010

Steps by one value in the current sequence on all enabled channels if DECODER.MODE=NextStep. Does not cause PWM generation to start if not running.



6.10.5.4 SUBSCRIBE STOP

Address offset: 0x084

Subscribe configuration for task STOP

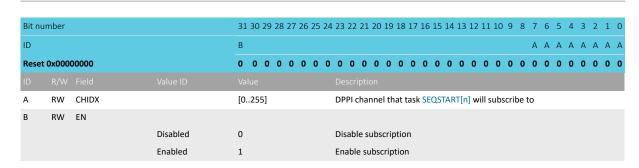
Bit nu	ımber			31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.10.5.5 SUBSCRIBE_SEQSTART[n] (n=0..1)

Address offset: $0x088 + (n \times 0x4)$

Subscribe configuration for task SEQSTART[n]

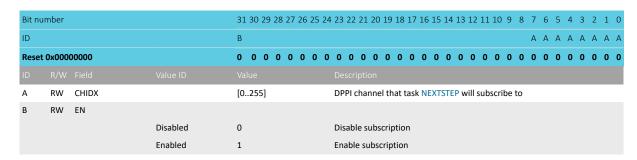




6.10.5.6 SUBSCRIBE NEXTSTEP

Address offset: 0x090

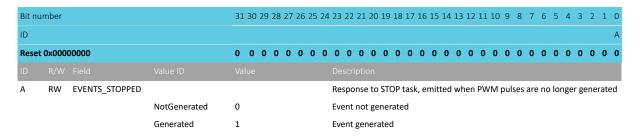
Subscribe configuration for task NEXTSTEP



6.10.5.7 EVENTS STOPPED

Address offset: 0x104

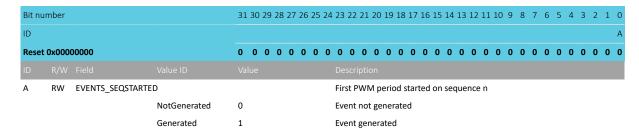
Response to STOP task, emitted when PWM pulses are no longer generated



6.10.5.8 EVENTS_SEQSTARTED[n] (n=0..1)

Address offset: $0x108 + (n \times 0x4)$

First PWM period started on sequence n

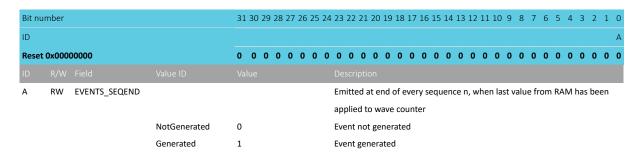


6.10.5.9 EVENTS_SEQEND[n] (n=0..1)

Address offset: $0x110 + (n \times 0x4)$



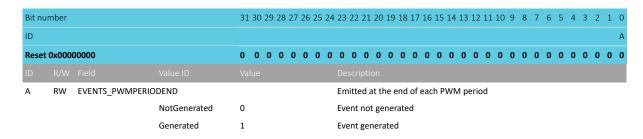
Emitted at end of every sequence n, when last value from RAM has been applied to wave counter



6.10.5.10 EVENTS PWMPERIODEND

Address offset: 0x118

Emitted at the end of each PWM period

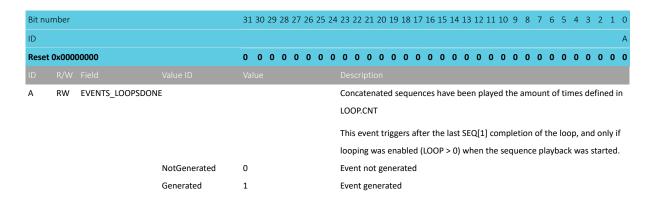


6.10.5.11 EVENTS_LOOPSDONE

Address offset: 0x11C

Concatenated sequences have been played the amount of times defined in LOOP.CNT

This event triggers after the last SEQ[1] completion of the loop, and only if looping was enabled (LOOP > 0) when the sequence playback was started.



6.10.5.12 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED



Bit nu	mber			31 30 29	28 27	26 25	24 2	23 22	21 2	20 19	9 18	17 1	6 15	5 14	13 1	.2 11	. 10	9	8	7 6	5 5	4	3	2	1 0
ID				В															,	Δ Α	A A	Α	Α	Α	А А
Reset	0x0000	00000		0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 (0	0	0 (0 0	0	0	0 () (0	0	0	0	0 0
ID																									
Α	RW	CHIDX		[0255]			[DPPI	chan	nel tl	hat e	vent	STO	OPPE	D wi	ill pu	blisl	ı to							
В	RW	EN																							
			Disabled	0 Dis					le pu	blish	ing														
			Enabled	1	Enabl	e pul	blishi	ing																	

6.10.5.13 PUBLISH_SEQSTARTED[n] (n=0..1)

Address offset: $0x188 + (n \times 0x4)$

Publish configuration for event SEQSTARTED[n]

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event SEQSTARTED[n] will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.10.5.14 PUBLISH_SEQEND[n] (n=0..1)

Address offset: $0x190 + (n \times 0x4)$

Publish configuration for event SEQEND[n]

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event SEQEND[n] will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.10.5.15 PUBLISH_PWMPERIODEND

Address offset: 0x198

Publish configuration for event PWMPERIODEND

Bit no	umber			31 30 29 28 27 26 25 24	$23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event PWMPERIODEND will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing



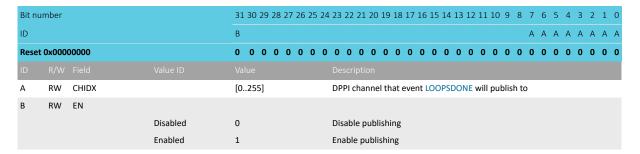


6.10.5.16 PUBLISH_LOOPSDONE

Address offset: 0x19C

Publish configuration for event LOOPSDONE

This event triggers after the last SEQ[1] completion of the loop, and only if looping was enabled (LOOP > 0) when the sequence playback was started.



6.10.5.17 SHORTS

Address offset: 0x200

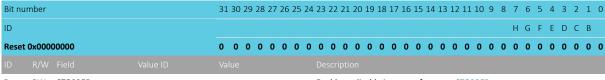
Shortcuts between local events and tasks

Bit nu	ımber			31 3	30 29	9 28	3 27 :	26 2	25 24	4 23	3 2	2 21	20	19	18 1	17 1	16 1	5 1	4 1	3 1	2 1:	10	9	8	7	6	5	4	3	2 1	L O	
ID																												Е	D (C E	3 A	
Reset	0x000	00000		0	0 0	0	0	0	0 0	0) (0 0	0	0	0	0	0 () (0 () (0	0	0	0	0	0	0	0	0) (0	
ID																																ĺ
Α	RW	SEQENDO_STOP								Sł	nor	tcut	bet	wee	n e	ven	t SE	QE	ND[0] a	and	tasl	c ST	OP								
			Disabled	0						Di	isal	ble s	hor	tcut																		
			Enabled	1						Er	nab	ole sh	ort	cut																		
В	RW	SEQEND1_STOP								Sł	nor	tcut	bet	wee	n e	ven	t SE	QE	ND[1] a	and	tasl	k ST	OP								
			Disabled	0						Di	isal	ble s	hor	tcut																		
			Enabled	1						Er	nab	ole sh	nort	cut																		
С	RW	LOOPSDONE_SEQST	ARTO							Sł	nor	tcut	bet	wee	n e	ven	t LC	ОР	SDO	ONE	an	d ta	sk S	EQS	TAI	RT[(0]					
			Disabled	0						Di	isal	ble s	hor	tcut																		
			Enabled	1						Er	nab	ole sh	nort	cut																		
D	RW	LOOPSDONE_SEQST	ART1							Sł	nor	tcut	bet	wee	n e	ven	t LC	OP	SDO	ONE	an	d ta	sk S	EQS	TAI	RT[:	1]					
			Disabled	0						Di	isal	ble s	hor	tcut																		
			Enabled	1						Er	nab	ole sh	nort	cut																		
E	RW	LOOPSDONE_STOP								Sł	nor	tcut	bet	wee	n e	ven	t LC	OP	SDO	ONE	an	d ta	sk S	TOF)							
			Disabled	0						Di	isal	ble s	hor	tcut																		
			Enabled	1						Er	nab	ole sh	nort	cut																		

6.10.5.18 INTEN

Address offset: 0x300

Enable or disable interrupt



B RW STOPPED Enable or disable interrupt for event STOPPED



Bit nu	ımber			31 3	30 29	28	27 2	6 2	5 24	- 23	22	21 2	20 1	9 1	8 1	7 16	15	14	13	12 :	11 10	9	8	7	6	5	4	3	2	1	0
ID																								Н	G	F	Ε	D	С	В	
Reset	0x000	00000		0	0 0	0	0 (0 0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0
ID																															
			Disabled	0						Dis	abl	e																			
			Enabled	1						Ena	able	9																			
C-D	RW	SEQSTARTED[i] (i=0.	1)							Ena	able	e or	disa	ble	inte	erru	pt f	or e	ven	t SE	QST	ART	ED[i]							
			Disabled	0						Dis	abl	e																			
			Enabled	1						Ena	able	e																			
E-F	RW	SEQEND[i] (i=01)					Ena	able	e or	disa	ble	inte	erru	pt f	or e	ven	t SE	QEN	D[i]												
			Disabled	0						Dis	abl	е																			
			Enabled	1						Ena	able	9																			
G	RW	PWMPERIODEND								Ena	able	e or	disa	ble	inte	erru	pt f	or e	ven	t PV	VMP	ERI	ODI	END)						
			Disabled	0						Dis	abl	е																			
			Enabled	1						Ena	able	9																			
Н	RW	LOOPSDONE								Ena	able	e or	disa	ble	inte	erru	pt f	or e	ven	t LC	OPS	DO	NE								
										Thi	s ev	vent	trig	ger	s af	ter 1	the	last	SEC	Ղ[1]	com	ple	tior	n of	the	loc	р, а	and	onl	y if	
										loo	pin	ıg wa	as e	nab	led	(LO	OP :	> 0)	wh	en t	he s	equ	enc	e p	layl	bacl	k wa	as si	art	ed.	
			Disabled	0						Dis	abl	e																			
			Enabled	1						Ena	able	9																			

6.10.5.19 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	mber			31	30 2	29 2	8 27	7 26	5 25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																											Н	G	F	Е	D	С	В	
Reset	0x000	00000		0	0	0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
В	RW	STOPPED									Wri	ite	'1' t	to e	enal	ble	int	errı	ıpt	for	eve	nt S	STC	PP	ED									
			Set	1							Ena	able	e																					
			Disabled	0							Rea	ad:	Dis	abl	ed																			
			Enabled	1							Rea	ad:	Ena	able	ed																			
C-D	RW	SEQSTARTED[i] (i=0.	.1)								Wri	ite	'1' t	to e	enal	ble	int	errı	ıpt	for	eve	nt S	SEC	QST/	ART	ED[i]							
			Set	1							Ena	able	e																					
			Disabled	0							Rea	ad:	Dis	abl	ed																			
			Enabled	1							Rea	ad:	Ena	able	ed																			
E-F	RW	SEQEND[i] (i=01)									Wri	ite	'1' t	to e	enal	ble	int	errı	ıpt	for	eve	nt S	SEC)EN	D[i]								
			Set	1							Ena	able	e																					
			Disabled	0							Rea	ad:	Dis	abl	ed																			
			Enabled	1							Rea	ad:	Ena	able	ed																			
G	RW	PWMPERIODEND									Wri	ite	'1' t	to e	enal	ble	int	errı	ıpt	for	eve	nt F	PW	MP	ERI	IOD	ENI	D						
			Set	1							Ena	able	e																					
			Disabled	0							Rea	ad:	Dis	abl	ed																			
			Enabled	1							Rea	ad:	Ena	able	ed																			
Н	RW	LOOPSDONE									Wri	ite	'1' t	to e	enal	ble	int	errı	ıpt	for	eve	nt l	.00	OPS	DO	NE								
											This	s e	ven	t tr	igg	ers	aft	er t	he	last	SEC	Ղ[1]	со	mp	leti	ion	of t	the	loo	p, a	nd	onl	y if	
											loo	pin	ng w	/as	ena	able	ed (LOC	OP :	> 0)	wh	en 1	the	se	que	ence	pl	ayb	ack	k wa	ıs st	arte	ed.	
			Set	1							Ena	able	e																					
			Disabled	0							Rea	ad:	Dis	abl	ed																			
			Enabled	1							Rea	ad:	Ena	able	ed																			



6.10.5.20 INTENCLR

Address offset: 0x308

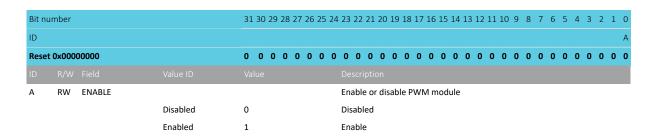
Disable interrupt

Bit nu	mber			31	30	29 2	28 2	27 2	6 2	25 2	4 2	23 2	22 2	21	20	19	18	3 17	16	5 15	14	1 13	3 12	2 11	10	9	8	7	6	5	4	3	2	1	0
ID																												Н	G	F	Ε	D	С	В	
Reset	0x000	00000		0	0	0 (0 (0 0	0	0 (ס	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																			
В	RW	STOPPED									١	Writ	te '	'1' t	:o c	disa	ble	e in	teri	up	t fo	r ev	/en	t ST	ОРІ	PED									_
			Clear	1							[Disa	ble	е																					
			Disabled	0							F	Rea	d: [Disa	abl	ed																			
			Enabled	1							F	Rea	d: E	Ena	ble	ed																			
C-D	RW	SEQSTARTED[i] (i=0.	.1)								١	Writ	te '	'1' t	0 0	disa	ble	e in	teri	up	t fo	r ev	/en	t SE	QS	TAR	TED	[i]							
			Clear	1							[Disa	ble	е																					
			Disabled	0							F	Rea	d: [Disa	abl	ed																			
			Enabled	1							F	Rea	d: E	Ena	ble	ed																			
E-F	RW	SEQEND[i] (i=01)									١	Writ	te '	'1' t	0 0	disa	ble	e in	teri	up	t fo	r ev	/en	t SE	QEI	ND[i]								
			Clear	1							[Disa	ble	е																					
			Disabled	0							F	Rea	d: [Disa	abl	ed																			
			Enabled	1							F	Rea	d: E	Ena	ble	ed																			
G	RW	PWMPERIODEND									١	Writ	te '	'1' t	0 0	disa	ble	e in	teri	up	t fo	r ev	/en	t P\	٧M	PEF	RIOE	EN	D						
			Clear	1							[Disa	ble	е																					
			Disabled	0							F	Rea	d: [Disa	abl	ed																			
			Enabled	1							F	Rea	d: E	Ena	ble	ed																			
Н	RW	LOOPSDONE									١	Writ	te '	'1' t	:o c	disa	ble	e in	teri	up	t fo	r ev	/en	t LC	ОР	SDO	ONE								
											1	This	ev	en!	t tr	igg	ers	aft	er	the	las	t SE	Q[1] c	om	plet	ion	of :	the	loc	p, a	and	on	ly if	
											ı	oop	oing	g w	as	ena	able	ed	(LO	OP	> 0) w	her	n th	e se	qu	enc	e pl	ayb	ack	· wa	as st	art	ed.	
			Clear	1							1	Disa	ble	е																					
			Disabled	0							ı	Rea	d: [Disa	abl	ed																			
			Enabled	1							ı	Rea	d: E	Ena	ble	ed																			

6.10.5.21 ENABLE

Address offset: 0x500

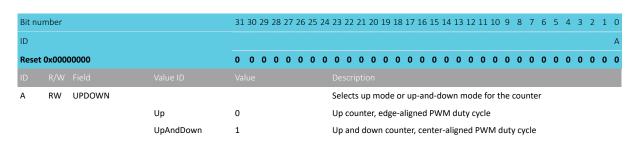
PWM module enable register



6.10.5.22 MODE

Address offset: 0x504

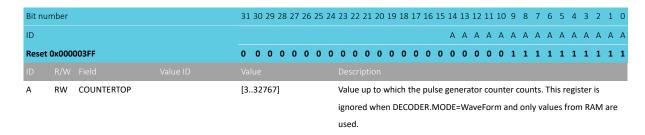
Selects operating mode of the wave counter



6.10.5.23 COUNTERTOP

Address offset: 0x508

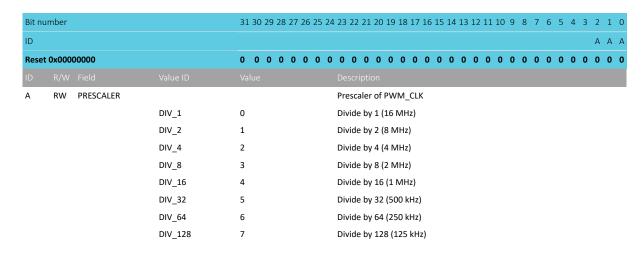
Value up to which the pulse generator counter counts



6.10.5.24 PRESCALER

Address offset: 0x50C

Configuration for PWM CLK



6.10.5.25 DECODER

Address offset: 0x510

Configuration of the decoder



Bit nu	ımber			31 3	30 29	28 27	26	25 2	4 23	3 22	2 21	. 20	19	18	17	16 1	15 :	14 1	13 1	2 1	1 10	9	8	7	6	5	4	3	2 :	1	0
ID																							В						,	Α	Α
Reset	0x000	00000		0	0 0	0 0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 () (0	0
ID																															I
Α	RW	LOAD							Н	ow a	a se	eque	ence	e is ı	rea	d fro	om	RAI	VI a	nd s	pre	ad t	o th	ie c	om	pare	e re	gist	er		
			Common	0					15	t ha	alf v	vord	d (1	6-bi	t) u	ısed	l in	all I	wi	∕l cl	nanr	els	03	3							
			Grouped	1					15	t ha	alf v	vord	d (1	6-bi	t) u	ısed	l in	cha	nne	10.	.1; 2	nd '	wor	d in	ch	ann	el 2	3			
			Individual	2					15	t ha	alf v	vord	d (1	6-bi	t) ii	n ch	.0;	2nc	lin	ch.1	L;;	4th	n in	ch.	3						
			WaveForm	3					15	t ha	alf v	vord	d (1	6-bi	t) ii	n ch	.0;	2nc	lin	ch.1	L;;	4th	n in	CO	JNT	ΓER	ГОР	,			
В	RW	MODE							Se	elect	ts s	our	e f	or a	dva	ncii	ng t	he	acti	ve s	equ	enc	e								
			RefreshCount	0					SE	Q[r	n].R	EFR	ESH	l is u	ıse	d to	de	teri	nin	e lo	adin	g in	iteri	nal (com	npar	e r	egis	ters	S	
			NextStep	1					N	EXT:	STE	P ta	sk	caus	es	a ne	w	valu	e to	be	loa	ded	to	nte	rna	l co	mp	are			
									re	gist	ers																				

6.10.5.26 LOOP

Address offset: 0x514

Number of playbacks of a loop

Bit nu	ımber			31	30 2	29 2	8 2	7 26	5 25	24	23	22 2	21 2	0 19	18	17	16	15 1	.4 1	.3 12	2 11	. 10	9	8	7	6	5	4	3 2	2 1	0
ID																		A	Δ.	А А	Α	Α	Α	Α	Α	Α	Α	Α	A A	, Δ	Α
Reset	0x000	00000		0	0	0 (0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0 (0	0
ID																															
Α	RW	CNT									Nu	mbe	r of	play	/bac	ks o	f pa	itte	rn d	ycle	s										
			Disabled	0							Loc	ping	g di:	sable	ed (s	stop	at t	he	enc	l of t	hes	sequ	ıen	ce)							

6.10.5.27 SEQ[n].PTR (n=0..1)

Address offset: $0x520 + (n \times 0x20)$

Beginning address in RAM of this sequence

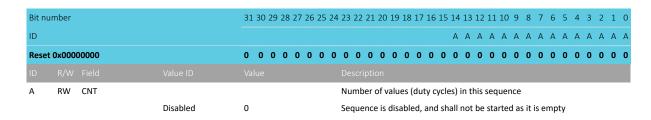
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 ID A A A A A A A A A A A A A A A A A A A	A RW PTR	Beginning address in RAM of this sequence	
ID A A A A A A A A A A A A A A A A A A A			
	Reset 0x00000000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2	D	A A A A A A A A A A A A A A A A A A A	A A A A A
	Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5	5 4 3 2 1 0

Note: See the memory chapter for details about which memories are available for EasyDMA.

6.10.5.28 SEQ[n].CNT (n=0..1)

Address offset: $0x524 + (n \times 0x20)$

Number of values (duty cycles) in this sequence



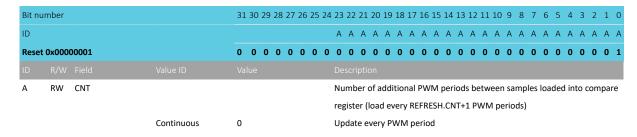




6.10.5.29 SEQ[n].REFRESH (n=0..1)

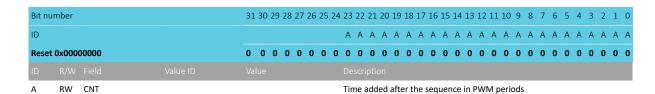
Address offset: $0x528 + (n \times 0x20)$

Number of additional PWM periods between samples loaded into compare register



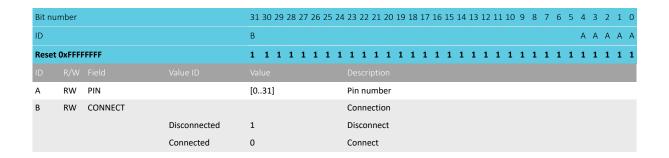
6.10.5.30 SEQ[n].ENDDELAY (n=0..1)

Address offset: $0x52C + (n \times 0x20)$ Time added after the sequence



6.10.5.31 PSEL.OUT[n] (n=0..3)

Address offset: $0x560 + (n \times 0x4)$ Output pin select for PWM channel n



6.11 RTC — Real-time counter

The real-time counter (RTC) module provides a generic, low-power timer on the low frequency clock source (LFCLK).



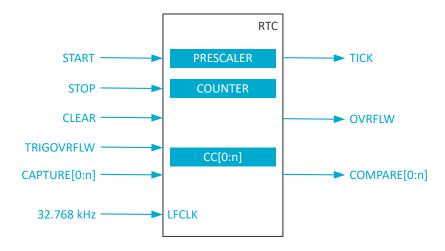


Figure 52: RTC block diagram

The RTC module features a 24-bit COUNTER, a 12-bit (1/X) prescaler, compare registers, and a tick event generator.

6.11.1 Clock source

The RTC will run off the LFCLK.

When started, the RTC will automatically request the LFCLK source with RC oscillator if the LFCLK is not already running.

See CLOCK — Clock control on page 70 for more information about clock sources.

6.11.2 Resolution versus overflow and the prescaler

The relationship between the prescaler, counter resolution, and overflow is summarized in the following table.

Prescaler	Counter resolution	Overflow
0	30.517 μs	512 seconds
2 ⁸ -1	7812.5 μs	131072 seconds
2 ¹² -1	125 ms	582.542 hours

Table 27: RTC resolution versus overflow

The counter increment frequency is given by the following equation:

```
f_{RTC} [kHz] = 32.768 / (PRESCALER + 1 )
```

The PRESCALER register can only be written when the RTC is stopped.

The prescaler is restarted on tasks START, CLEAR and TRIGOVRFLW. That is, the prescaler value is latched to an internal register (<<PRESC>>) on these tasks.

Examples:

1. Desired COUNTER frequency 100 Hz (10 ms counter period)

```
PRESCALER = round(32.768 kHz / 100 Hz) - 1 = 327 f_{RTC} = 99.9 Hz
```

10009.576 µs counter period

NORDIC*

2. Desired COUNTER frequency 8 Hz (125 ms counter period)

PRESCALER = round(32.768 kHz / 8 Hz) - 1 = 4095

 $f_{RTC} = 8 Hz$

125 ms counter period

6.11.3 Counter register

The internal <<COUNTER>> register increments on LFCLK when the internal PRESCALER register (<<PRESC>>) is 0x00. <<PRESC>> is reloaded from the PRESCALER register. If enabled, the TICK event occurs on each increment of the COUNTER.

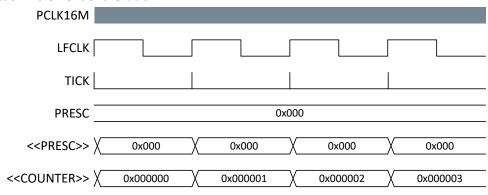


Figure 53: Timing diagram - COUNTER PRESCALER 0

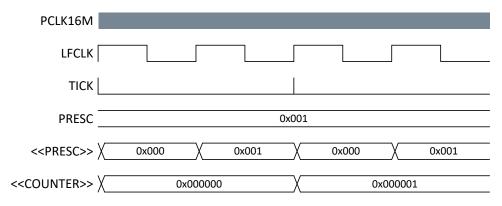


Figure 54: Timing diagram - COUNTER_PRESCALER_1

6.11.3.1 Reading the counter register

To read the COUNTER register, the internal <<COUNTER>> value is sampled.

To ensure that the <<COUNTER>> is safely sampled (considering that an LFCLK transition may occur during a read), the CPU and core memory bus are halted for PCLK16M cycles. In addition, the read takes the CPU two PCLK16M cycles, resulting in the COUNTER register read taking maximum six PCLK16M clock cycles.

6.11.4 Overflow

An OVRFLW event is generated on COUNTER register overflow (overflowing from 0xFFFFFF to 0).

The TRIGOVRFLW task will set the COUNTER value to 0xFFFFF0, to allow software test of the overflow condition.

Note: The OVRFLW event is disabled by default.



6.11.5 Tick event

The TICK event enables low-power tickless RTOS implementation, as it optionally provides a regular interrupt source for an RTOS with no need for use of the ARM SysTick feature.

Using the TICK event, rather than the SysTick, allows the CPU to be powered down while keeping RTOS scheduling active.

Note: The TICK event is disabled by default.

6.11.6 Event control

To optimize the RTC power consumption, events in the RTC can be individually disabled to prevent PCLK16M and HFCLK from being requested when those events are triggered. This is managed using the EVTEN register.

This means that the RTC implements a slightly different task and event system compared to the standard system described in Peripheral interface on page 15. The RTC task and event system is illustrated in the following figure.

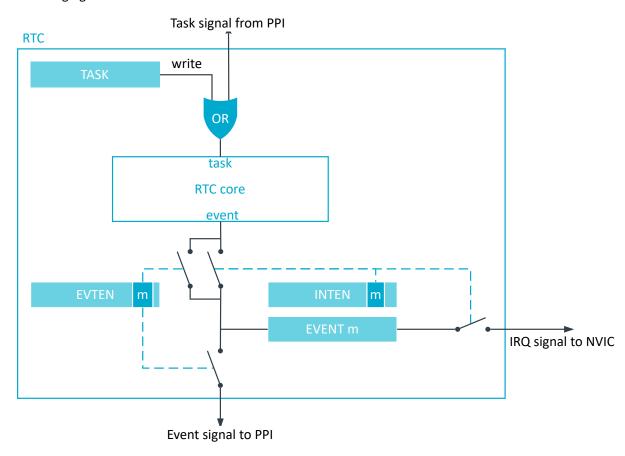


Figure 55: Tasks, events, and interrupts in the RTC

6.11.7 Compare

The RTC implements one COMPARE event for every available compare register.

When the COUNTER is incremented and then becomes equal to the value specified in the register CC[n], the corresponding compare event COMPARE[n] is generated.

When writing a CC[n] register, the RTC COMPARE event exhibits several behaviors. See the following figures for more information.

If a CC value is 0 when a CLEAR task is set, this will not trigger a COMPARE event.



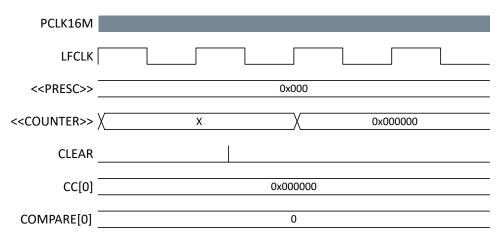


Figure 56: Timing diagram - COMPARE_CLEAR

If a CC value is N and the COUNTER value is N when the START task is set, this will not trigger a COMPARE event.

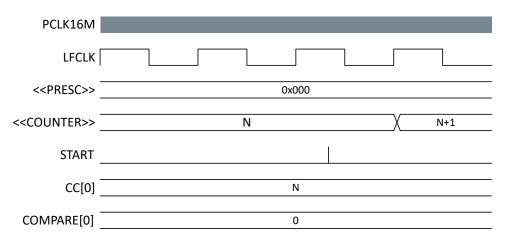


Figure 57: Timing diagram - COMPARE_START

A COMPARE event occurs when a CC value is N, and the COUNTER value transitions from N-1 to N.

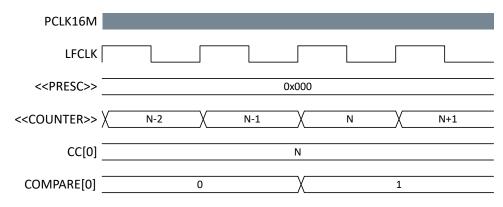


Figure 58: Timing diagram - COMPARE

If the COUNTER value is N, writing N+2 to a CC register is guaranteed to trigger a COMPARE event at N+2.



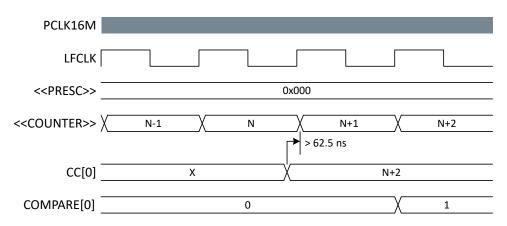


Figure 59: Timing diagram - COMPARE_N+2

If the COUNTER value is N, writing N or N+1 to a CC register may not trigger a COMPARE event.

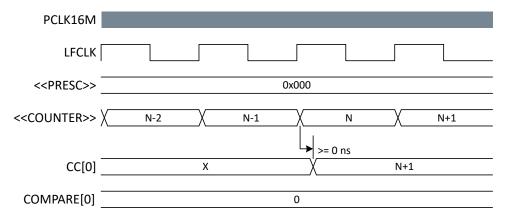


Figure 60: Timing diagram - COMPARE_N+1

If the COUNTER value is N, and the current CC value is N+1 or N+2 when a new CC value is written, a match may trigger on the previous CC value before the new value takes effect. If the current CC value is greater than N+2 when the new value is written, there will be no event due to the old value.

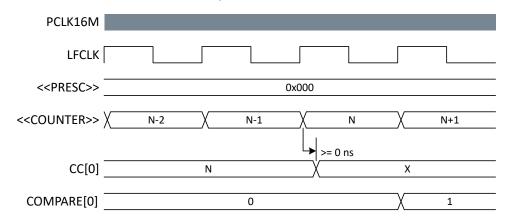


Figure 61: Timing diagram - COMPARE_N-1

6.11.8 Task and event jitter/delay

Jitter or delay in the RTC is due to the peripheral clock being a low frequency clock (LFCLK), which is not synchronous to the faster PCLK16M.

Registers in the peripheral interface that are part of the PCLK16M domain, have a set of mirrored registers in the LFCLK domain. For example, the COUNTER value accessible from the CPU is in the PCLK16M domain and is latched on a read from an internal COUNTER register in the LFCLK domain. The COUNTER register

189 NORDIC*

is modified each time the RTC ticks. The registers are synchronised between the two clock domains (PCLK16M and LFCLK).

CLEAR and STOP (and TRIGOVRFLW, which is not shown) will be delayed as long as it takes for the peripheral to clock a falling edge and a rising edge of the LFCLK. This is between 15.2585 μ s and 45.7755 μ s – rounded to 15 μ s and 46 μ s for the remainder of the section.

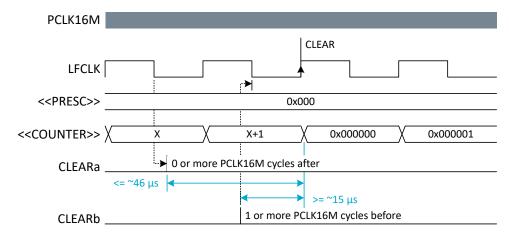


Figure 62: Timing diagram - DELAY CLEAR

When a STOP task is triggered, the PCLK16M domain will immediately prevent the generation of any EVENTS from the RTC. However, as seen in the following figure, the COUNTER value can still increment one final time.

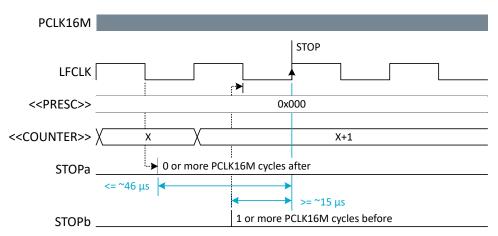


Figure 63: Timing diagram - DELAY_STOP

The START task will start the RTC. Assuming that the LFCLK was previously running and stable, the first increment of COUNTER (and instance of TICK event) will be typically after 30.5 μ s +/-15 μ s. Additional delay will occur if the RTC is started before the LFCLK is running, see CLOCK — Clock control on page 70 for LFLK startup times. The software should therefore wait for the first TICK if it has to make sure that the RTC is running. Sending a TRIGOVRFLW task sets the COUNTER to a value close to overflow. However, since the update of COUNTER relies on a stable LFCLK, sending this task while LFCLK is not running will also add additional delay as previously described. The figures show the smallest and largest delays on the START task, appearing as a +/-15 μ s jitter on the first COUNTER increment.



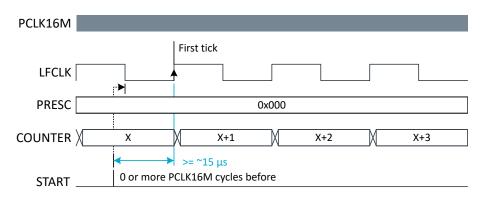


Figure 64: Timing diagram - JITTER_START-

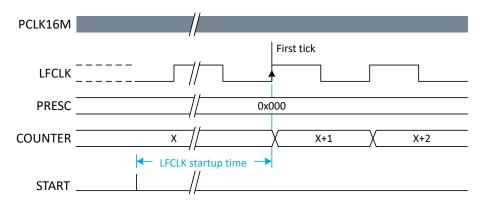


Figure 65: Timing diagram - JITTER_START+

The following tables summarize jitter introduced for tasks and events. Any 32.768 kHz clock jitter will come in addition to these numbers.

Task	Delay
CLEAR, START, STOP, TRIGOVRFLOW	+15 to 46 μs

Table 28: RTC jitter magnitudes on tasks

Operation/Function	Jitter
START to COUNTER increment	± 15 μs
COMPARE to COMPARE ¹⁴	± 62.5 ns

Table 29: RTC jitter magnitudes on events

6.11.9 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
RTC0: S	0x50014000	US	NS	NA	No	Real time counter 0
RTC0 : NS	0x40014000	03	INS	INA	NO	real time counter o
RTC1:S	0x50015000	US	NS	NA	No	Real time counter 1
RTC1: NS	0x40015000	US	CVI	INA	INU	real time counter 1

191

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¹⁴ Assumes RTC runs continuously between these events.

Register overview

Register	Offset	TZ	Description
TASKS_START	0x000		Start RTC counter
TASKS_STOP	0x004		Stop RTC counter
TASKS_CLEAR	0x008		Clear RTC counter
TASKS_TRIGOVRFLW	0x00C		Set counter to 0xFFFFF0
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_CLEAR	0x088		Subscribe configuration for task CLEAR
SUBSCRIBE_TRIGOVRFLW	0x08C		Subscribe configuration for task TRIGOVRFLW
EVENTS_TICK	0x100		Event on counter increment
EVENTS_OVRFLW	0x104		Event on counter overflow
EVENTS_COMPARE[n]	0x140		Compare event on CC[n] match
PUBLISH_TICK	0x180		Publish configuration for event TICK
PUBLISH_OVRFLW	0x184		Publish configuration for event OVRFLW
PUBLISH_COMPARE[n]	0x1C0		Publish configuration for event COMPARE[n]
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
EVTEN	0x340		Enable or disable event routing
EVTENSET	0x344		Enable event routing
EVTENCLR	0x348		Disable event routing
COUNTER	0x504		Current counter value
PRESCALER	0x508		12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written when RTC is
			stopped.
CC[n]	0x540		Compare register n

6.11.9.1 TASKS_START

Address offset: 0x000

Start RTC counter

Bit no	umber			31 30 29 28 27 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1	0
ID						Α
Rese	t 0x000	00000		0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$	0
ID						
Α	W	TASKS_START			Start RTC counter	
			Trigger	1	Trigger task	

6.11.9.2 TASKS_STOP

Address offset: 0x004 Stop RTC counter

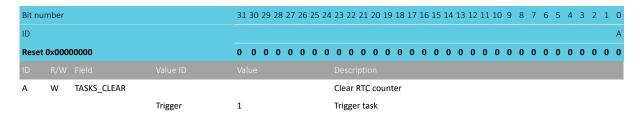
Bit nu	mber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_STOP			Stop RTC counter
			Trigger	1	Trigger task



6.11.9.3 TASKS_CLEAR

Address offset: 0x008

Clear RTC counter



6.11.9.4 TASKS_TRIGOVRFLW

Address offset: 0x00C Set counter to 0xFFFFF0

Bit no	umber			31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	W	TASKS_TRIGO	VRFLW		Set counter to 0xFFFFF0
			Trigger		Trigger task

6.11.9.5 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task START will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.11.9.6 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x0000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

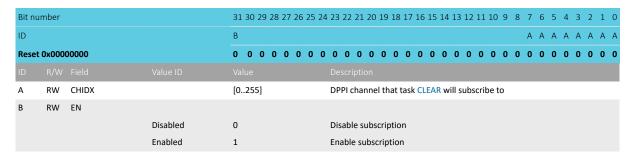
193



6.11.9.7 SUBSCRIBE_CLEAR

Address offset: 0x088

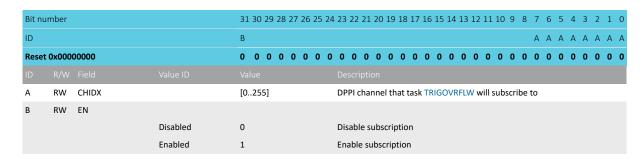
Subscribe configuration for task CLEAR



6.11.9.8 SUBSCRIBE_TRIGOVRFLW

Address offset: 0x08C

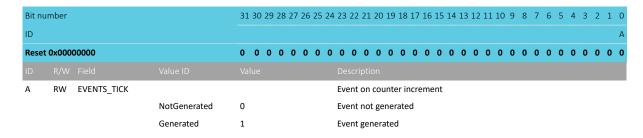
Subscribe configuration for task TRIGOVRFLW



6.11.9.9 EVENTS TICK

Address offset: 0x100

Event on counter increment



6.11.9.10 EVENTS OVRFLW

Address offset: 0x104

Event on counter overflow



Bit nu	umber			31 3	0 29	28	27 2	26 25	5 24	- 23	22 2	21 2	0 19	9 18	17 1	l6 1	5 14	13	12 1	11 1	0 9	8	7	6	5	4	3 2	2 1	0
ID																													Α
Rese	t 0x000	00000		0 (0 0	0	0	0 0	0	0	0	0 (0 0	0	0	0 (0	0	0	0 (0	0	0	0	0	0	0 (0	0
ID																													
Α	RW	EVENTS_OVRFLW								Eve	nt c	n co	ount	er o	verfl	low													
			NotGenerated	0						Eve	nt n	ot g	gene	rate	d														
			Generated	1						Eve	nt g	ene	rate	d															

6.11.9.11 EVENTS_COMPARE[n] (n=0..3)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

Bit nu	ımber			31	30 29	9 28	3 27 :	26 2	25 2	24 2	23 2:	2 21	L 20	19	18	17 1	16 1	5 14	1 13	12	11	10	9 8	3 7	7 (5 5	5 4	3	2	1 0
ID																														А
Reset	0x000	00000		0	0 0	0	0	0	0	0 (0 0	0	0	0	0	0	0 (0	0	0	0	0	0 (0 () (0 0	0	0	0	0 0
ID																														
Α	RW	EVENTS_COMPARE								C	Com	pare	e ev	ent	on (CC[r	n] m	atch	1											
			NotGenerated	0						Е	ven	t no	t ge	ener	ate	t														
			Generated	1						E	ven	t ge	ner	ated	t															

6.11.9.12 PUBLISH_TICK

Address offset: 0x180

Publish configuration for event TICK

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x0000	00000		0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event TICK will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.11.9.13 PUBLISH_OVRFLW

Address offset: 0x184

Publish configuration for event OVRFLW

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event OVRFLW will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.11.9.14 PUBLISH_COMPARE[n] (n=0..3)

Address offset: $0x1C0 + (n \times 0x4)$



Publish configuration for event COMPARE[n]

Bit no	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event COMPARE[n] will publish to
В	RW	EN			
			Disabled	0	Disable publishing

6.11.9.15 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31 30 29 2	8 27 26	25 24	23 22	2 21 2	0 19	18	17 1	16 15	14	13	12 1	1 1	9	8	7	6	5	4 3	2	1	0
ID									F	Ε	D	С												В	Α
Reset	0x000	00000		0 0 0 0	0 0 0	0 0	0 0	0 (0	0	0	0 0	0	0	0 () (0	0	0	0	0	0 0	0	0	0
ID																									
Α	RW	TICK					Write	e '1' to	ena	ble	inte	rrupt	for	eve	nt T	CK									
			Set	1			Enab	le																	
			Disabled	0			Read	: Disal	oled																
			Enabled	1			Read	: Enab	led																
В	RW	OVRFLW					Write	e '1' to	ena	ble	inte	rrupt	for	eve	nt O	VRF	LW								
			Set	1			Enab	le																	
			Disabled	0			Read	: Disal	oled																
			Enabled	1			Read	: Enab	led																
C-F	RW	COMPARE[i] (i=03)					Write	e '1' to	ena	ble	inte	rrupt	for	eve	nt C	DM	PAR	E[i]							
			Set	1			Enab	le																	
			Disabled	0			Read	: Disal	oled																
			Enabled	1			Read	: Enab	led																

6.11.9.16 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	1 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	TICK			Write '1' to disable interrupt for event TICK
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	OVRFLW			Write '1' to disable interrupt for event OVRFLW
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
C-F	RW	COMPARE[i] (i=03)			Write '1' to disable interrupt for event COMPARE[i]
			Clear	1	Disable





Bit number		31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			F E D C
Reset 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field			
	Disabled	0	Read: Disabled
	Enabled	1	Read: Enabled

6.11.9.17 EVTEN

Address offset: 0x340

Enable or disable event routing

D.1				24 :	20.20	20	27.2		- 24	22	22.	24.2	20.4	0.4	0 4:	7.40	4.5		4.0	42.				_	_	_		_	_	4	_
BIT NU	ımber			31 :	30 29	28	2/ 2	6 25	5 24	- 23	22 .	21 2	20 1	9 1	81.	/ 16	15	14	13	12 .	ιι.	10 9	8 (/	6	5	4	3	2	1	J
ID													F	E	D	С														В	Д
Reset	0x000	00000		0	0 0	0	0 (0 0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0
ID																															I
Α	RW	TICK								Ena	able	or o	disa	ble	eve	nt r	out	ing	for	ever	nt T	ICK									
			Disabled	0						Dis	able	9																			
			Enabled	1						Ena	able																				
В	RW	OVRFLW								Ena	able	or o	disa	ble	eve	nt r	outi	ing	for	ever	nt C	OVRI	LW								
			Disabled	0						Dis	able	9																			
			Enabled	1						Ena	able																				
C-F	RW	COMPARE[i] (i=03)								Ena	able	or o	disa	ble	eve	nt r	out	ing	for	ever	nt C	OM	PAR	E[i]							
			Disabled	0						Dis	able	9																			
			Enabled	1						Ena	able																				

6.11.9.18 EVTENSET

Address offset: 0x344 Enable event routing

Rit nı	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
	mber			31 30 23 20 27 20 23 2	
ID					F E D C
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	TICK			Write '1' to enable event routing for event TICK
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable
В	RW	OVRFLW			Write '1' to enable event routing for event OVRFLW
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable
C-F	RW	COMPARE[i] (i=03)			Write '1' to enable event routing for event COMPARE[i]
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Set	1	Enable

6.11.9.19 EVTENCLR

Address offset: 0x348

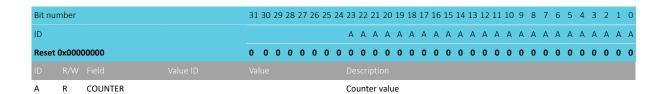
Disable event routing



Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TICK			Write '1' to disable event routing for event TICK
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable
В	RW	OVRFLW			Write '1' to disable event routing for event OVRFLW
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable
C-F	RW	COMPARE[i] (i=03)			Write '1' to disable event routing for event COMPARE[i]
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
			Clear	1	Disable

6.11.9.20 COUNTER

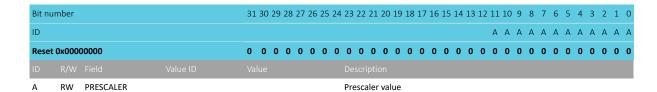
Address offset: 0x504 Current counter value



6.11.9.21 PRESCALER

Address offset: 0x508

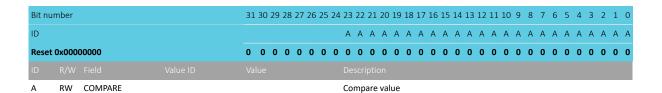
12-bit prescaler for counter frequency (32768/(PRESCALER+1)). Must be written when RTC is stopped.



6.11.9.22 CC[n] (n=0..3)

Address offset: $0x540 + (n \times 0x4)$

Compare register n





6.12 SAADC — Successive approximation analog-to-digital converter

The SAADC is a differential successive approximation register (SAR) analog-to-digital converter.

Listed here are the main features of SAADC:

- 8/10/12-bit resolution, 14-bit resolution with oversampling
- Multiple analog inputs:
 - AINO to AIN7 pins
 - VDD GPIO pin
- Up to eight input channels:
 - One channel per single-ended input and two channels per differential input
 - Scan mode can be configured with both single-ended channels and differential channels
 - Each channel can be configured to select any of the above analog inputs
- Full scale input range (0 to VDD GPIO)
- Sampling triggered via a task from software or a PPI channel for full flexibility on sample frequency source from low-power 32.768 kHz RTC or more accurate 1/16 MHz timers
- One-shot conversion mode to sample a single channel
- Scan mode to sample a series of channels in sequence with configurable sample delay
- Support for direct sample transfer to RAM using EasyDMA
- Interrupts on single sample and full buffer events
- Samples stored as 16-bit two's complement values for differential and single-ended sampling
- · Continuous sampling without the need of an external timer
- Internal resistor string
- · On-the-fly limit checking

6.12.1 Overview

The ADC supports up to eight external analog input channels. It can be operated in One-shot mode with sampling under software control, or Continuous mode with a programmable sampling rate.

The analog inputs can be configured as eight single-ended inputs, four differential inputs or a combination of these. Each channel can be configured to select:

- AINO to AIN7 pins
- VDD GPIO pin

Channels can be sampled individually in one-shot or continuous sampling modes, or, using scan mode, multiple channels can be sampled in sequence. Channels can also be oversampled to improve noise performance.



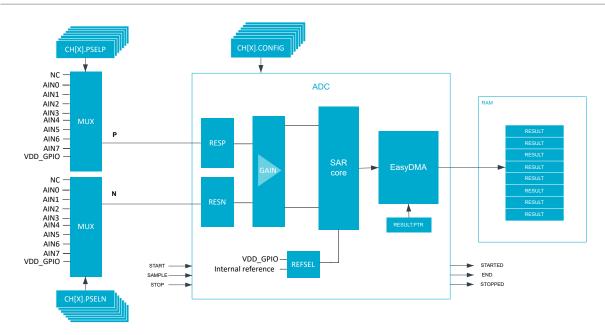


Figure 66: Simplified ADC block diagram

Internally, the ADC is always a differential analog-to-digital converter, but by default it is configured with single-ended input in the MODE field of the CH[n].CONFIG register. In single-ended mode, the negative input will be shorted to ground internally.

The assumption in single-ended mode is that the internal ground of the ADC is the same as the external ground that the measured voltage is referred to. The ADC is thus sensitive to ground bounce on the PCB in single-ended mode. If this is a concern, we recommend using differential measurement.

6.12.2 Digital output

The output result of the ADC depends on the settings in the CH[n].CONFIG and RESOLUTION registers as follows:

```
RESULT = [V(P) - V(N)] * GAIN/REFERENCE * 2 (RESOLUTION - m)
```

where

V(P)

is the voltage at input P

V(N)

is the voltage at input N

GAIN

is the selected gain setting

m

is the mode setting. Use m=0 if CONFIG.MODE=SE, or m=1 if CONFIG.MODE=Diff

REFERENCE

is the selected reference voltage

The result generated by the ADC will deviate from the expected due DC errors like offset, gain, differential non-linearity (DNL), and integral non-linearity (INL). See Electrical specification for details on these parameters. The result can also vary due to AC errors like non-linearities in the GAIN block, settling errors



due to high source impedance and sampling jitter. For battery measurement, the DC errors are most noticeable.

The ADC has a wide selection of gains controlled in the GAIN field of the CH[n].CONFIG register. If CH[n].CONFIG.REFSEL=0, the input range of the ADC core is nominally ±0.6 V differential and the input must be scaled accordingly.

Calibration

The ADC has a temperature dependent offset. If the ADC is to operate over a large temperature range, we recommend running TASKS_CALIBRATEOFFSET at regular intervals.

The DONE, RESULTDONE, and CALIBRATEDONE events are fired when the calibration has been completed.

The offset calibration must be run when the SAADC is stopped. If the TASKS_CALIBRATEOFFSET is run when the SAADC is started, then RAM may contain values not related to the ADC input.

6.12.3 Analog inputs and channels

Up to eight analog input channels, CH[n](n=0..7), can be configured.

Any one of the available channels can be enabled for the ADC to operate in one-shot mode. If more than one CH[n] is configured, the ADC enters scan mode.

An analog input is selected as a positive converter input if CH[n].PSELP is set, setting CH[n].PSELP also enables the particular channel.

An analog input is selected as a negative converter input if CH[n].PSELN is set. The CH[n].PSELN register will have no effect unless differential mode is enabled, see MODE field in CH[n].CONFIG register.

If more than one of the CH[n].PSELP registers is set, the device enters scan mode. Input selections in scan mode are controlled by the CH[n].PSELP and CH[n].PSELN registers, where CH[n].PSELN is only used if the particular scan channel is specified as differential, see MODE field in CH[n].CONFIG register.

6.12.4 Operation modes

The ADC input configuration supports one-shot mode, continuous mode, and scan mode.

Note: Scan mode and oversampling cannot be combined.

The ADC indicates a single ongoing conversion via the register STATUS on page 220. During scan mode, oversampling, or continuous modes, more than a single conversion take place in the ADC. As consequence, the value reflected in STATUS register will toggle at the end of each single conversion.

6.12.4.1 One-shot mode

One-shot operation is configured by enabling only one of the available channels defined by CH[n].PSELP, CH[n].PSELN, and CH[n].CONFIG registers.

Upon a SAMPLE task, the ADC starts to sample the input voltage. The CH[n].CONFIG.TACQ controls the acquisition time.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA. For more information, see EasyDMA on page 203.

6.12.4.2 Continuous mode

Continuous sampling can be achieved by using the internal timer in the ADC, or triggering the SAMPLE task from one of the general purpose timers through the PPI system.



Care shall be taken to ensure that the sample rate fulfils the following criteria, depending on how many channels are active:

```
f<sub>SAMPLE</sub> < 1/(t<sub>ACQ</sub> + t<sub>conv</sub>)
```

The SAMPLERATE register can be used as a local timer instead of triggering individual SAMPLE tasks. When SAMPLERATE.MODE is set to Timers, it is sufficient to trigger SAMPLE task only once in order to start the SAADC and triggering the STOP task will stop sampling. The SAMPLERATE.CC field controls the sample rate.

The SAMPLERATE timer mode cannot be combined with SCAN mode, and only one channel can be enabled in this mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.4.3 Oversampling

An accumulator in the ADC can be used to average noise on the analog input. In general, oversampling improves the signal-to-noise ratio (SNR). However, oversampling does not improve the integral non-linearity (INL) nor the differential non-linearity (DNL).

Oversampling and scan should not be combined, since oversampling and scan will average over input channels.

The accumulator is controlled in the OVERSAMPLE register. The SAMPLE task must be set 2^{OVERSAMPLE} number of times before the result is written to RAM. This can be achieved by:

- Configuring a fixed sampling rate using the local timer or a general purpose timer and the PPI system to trigger a SAMPLE task
- Triggering SAMPLE 2^{OVERSAMPLE} times from software
- Enabling BURST mode

CH[n].CONFIG.BURST can be enabled to avoid setting SAMPLE task $2^{\text{OVERSAMPLE}}$ times. With BURST = 1 the ADC will sample the input $2^{\text{OVERSAMPLE}}$ times as fast as it can (actual timing: $<(t_{ACQ}+t_{CONV})\times 2^{\text{OVERSAMPLE}}$). Thus, for the user it will just appear like the conversion took a bit longer time, but other than that, it is similar to one-shot mode.

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals that enough conversions have taken place for an oversampled result to get transferred into RAM. Note that both events may occur before the actual value has been transferred into RAM by EasyDMA.

6.12.4.4 Scan mode

A channel is considered enabled if CH[n].PSELP is set. If more than one channel, CH[n], is enabled, the ADC enters scan mode.

In scan mode, one SAMPLE task will trigger one conversion per enabled channel. The time it takes to sample all channels is:

```
Total time < Sum(CH[x].t_{ACQ}+t_{CONV}), x=0..enabled channels
```

A DONE event signals that one sample has been taken.

In this mode, the RESULTDONE event signals has the same meaning as DONE when no oversampling takes place. Note that both events may occur before the actual values have been transferred into RAM by EasyDMA.



The following figure shows an example of results placement in Data RAM, with an even RESULT.MAXCNT. In this example, channels 1, 2, and 5 are enabled, all others are disabled.

	31 16	15 0
RESULT.PTR	CH[2] 1 st result	CH[1] 1 st result
RESULT.PTR + 4	CH[1] 2 nd result	CH[5] 1 st result
RESULT.PTR + 8	CH[5] 2 nd result	CH[2] 2 nd result
	()
RESULT.PTR + 2*(RESULT.MAXCNT – 2)	CH[5] last result	CH[2] last result

Figure 67: Example of RAM placement (even RESULT.MAXCNT), channels 1, 2 and 5 enabled

The following figure shows an example of results placement in Data RAM, with an odd RESULT.MAXCNT. In this example, channels 1, 2, and 5 are enabled, all others are disabled. The last 32-bit word is populated only with one 16-bit result.

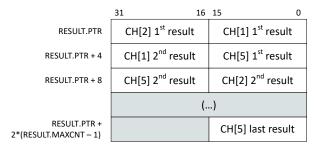


Figure 68: Example of RAM placement (odd RESULT.MAXCNT), channels 1, 2 and 5 enabled

6.12.5 EasyDMA

After configuring RESULT.PTR and RESULT.MAXCNT, the ADC resources are started by triggering the START task. The ADC is using EasyDMA to store results in a Result buffer in RAM.

The Result buffer is located at the address specified in the RESULT.PTR register. The RESULT.PTR register is double-buffered and it can be updated and prepared for the next START task immediately after the STARTED event is generated. The size of the Result buffer is specified in the RESULT.MAXCNT register and the ADC will generate an END event when it has filled up the Result buffer, see ADC on page 204. Results are stored in little-endian byte order in Data RAM. Every sample will be sign extended to 16 bit before stored in the Result buffer.

The ADC is stopped by triggering the STOP task. The STOP task will terminate an ongoing sampling. The ADC will generate a STOPPED event when it has stopped. If the ADC is already stopped when the STOP task is triggered, the STOPPED event will still be generated.



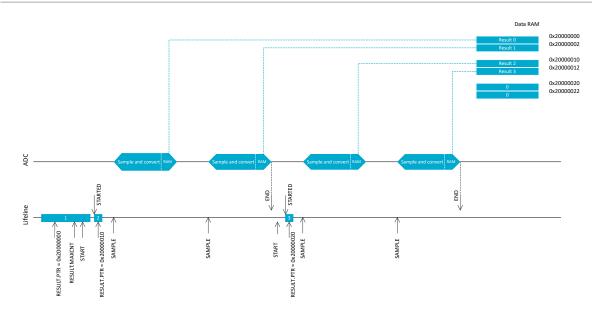


Figure 69: ADC

If the RESULT.PTR is not pointing to a RAM region accessible from the peripheral, an EasyDMA transfer may result in a HardFault and/or memory corruption. See Memory on page 21 for more information about the different memory regions.

The EasyDMA will have finished accessing the RAM when the END or STOPPED event has been generated.

The RESULT.AMOUNT register can be read following an END event or a STOPPED event to see how many results have been transferred to the Result buffer in RAM since the START task was triggered.

In scan mode, SAMPLE tasks can be triggered once the START task is triggered. The END event is generated when the number of samples transferred to memory reaches the value specified by RESULT.MAXCNT.

After an END event, the START task needs to be triggered again before new samples can be taken. Also make sure that the size of the Result buffer is large enough to have space for minimum one result from each of the enabled channels, by specifying RESULT.MAXCNT >= number of channels enabled. For more information about the scan mode, see Scan mode on page 202.

6.12.6 Resistor ladder

The ADC has an internal resistor string for positive and negative input.

See Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP) on page 205. The resistors are controlled in the CH[n].CONFIG.RESP and CH[n].CONFIG.RESN registers.



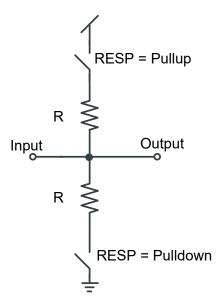


Figure 70: Resistor ladder for positive input (negative input is equivalent, using RESN instead of RESP)

6.12.7 Reference

The ADC can use two different references, controlled in the REFSEL field of the CH[n].CONFIG register.

These are:

- Internal reference
- VDD_GPIO as reference

The internal reference results in an input range of ± 0.6 V on the ADC core. VDD_GPIO as reference results in an input range of $\pm VDD_GPIO/4$ on the ADC core. The gain block can be used to change the effective input range of the ADC.

```
Input range = (± 0.6 V or ±VDD_GPIO/4)/Gain
```

For example, choosing VDD_GPIO as reference, single ended input (grounded negative input), and a gain of 1/4 the input range will be:

```
Input range = (VDD_GPIO/4)/(1/4) = VDD_GPIO
```

With internal reference, single ended input (grounded negative input), and a gain of 1/6 the input range will be:

```
Input range = (0.6 \text{ V})/(1/6) = 3.6 \text{ V}
```

The AINO-AIN7 inputs cannot exceed VDD_GPIO, or be lower than VSS.

6.12.8 Acquisition time

To sample the input voltage, the ADC connects a capacitor to the input.

For illustration, see Simplified ADC sample network on page 206. The acquisition time indicates how long the capacitor is connected, see TACQ field in CH[n].CONFIG register. The required acquisition time depends on the source (R_{source}) resistance. For high source resistance the acquisition time should be increased, see Acquisition time on page 206.



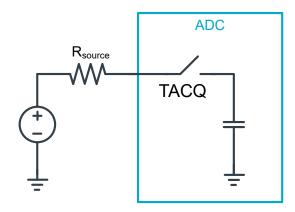


Figure 71: Simplified ADC sample network

TACQ [µs]	Maximum source resistance [kOhm]
3	10
5	40
10	100
15	200
20	400
40	800

Table 30: Acquisition time

6.12.9 Limits event monitoring

A channel can be event monitored by configuring limit register CH[n].LIMIT.

If the conversion result is higher than the defined high limit, or lower than the defined low limit, the appropriate event will get fired.

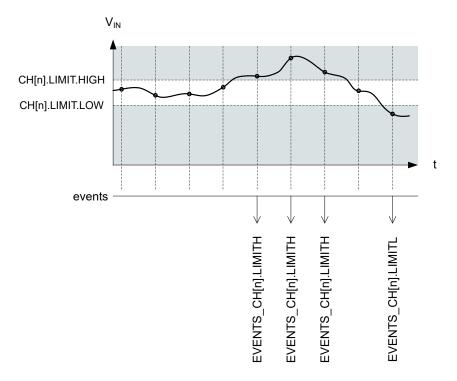


Figure 72: Example of limits monitoring on channel 'n'



Note that when setting the limits, CH[n].LIMIT.HIGH shall always be higher than or equal to CH[n].LIMIT.LOW . In other words, an event can be fired only when the input signal has been sampled outside of the defined limits. It is not possible to fire an event when the input signal is inside a defined range by swapping high and low limits.

The comparison to limits always takes place, there is no need to enable it. If comparison is not required on a channel, the software shall simply ignore the related events. In that situation, the value of the limits registers is irrelevant, so it does not matter if CH[n].LIMIT.LOW is lower than CH[n].LIMIT.HIGH or not.

6.12.10 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
SAADC : S	0x5000E000	US	NS	C A	No	Analog to digital convertor
SAADC : NS	0x4000E000	03	INS	SA	No	Analog to digital converter

Register overview

Register	Offset	TZ	Description
TASKS_START	0x000		Start the ADC and prepare the result buffer in RAM
TASKS_SAMPLE	0x004		Take one ADC sample, if scan is enabled all channels are sampled
TASKS_STOP	0x008		Stop the ADC and terminate any on-going conversion
TASKS_CALIBRATEOFFSET	0x00C		Starts offset auto-calibration
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_SAMPLE	0x084		Subscribe configuration for task SAMPLE
SUBSCRIBE_STOP	0x088		Subscribe configuration for task STOP
SUBSCRIBE_CALIBRATEOFFSET	0x08C		Subscribe configuration for task CALIBRATEOFFSET
EVENTS_STARTED	0x100		The ADC has started
EVENTS_END	0x104		The ADC has filled up the Result buffer
EVENTS_DONE	0x108		A conversion task has been completed. Depending on the mode, multiple conversions might
			be needed for a result to be transferred to RAM.
EVENTS_RESULTDONE	0x10C		A result is ready to get transferred to RAM.
EVENTS_CALIBRATEDONE	0x110		Calibration is complete
EVENTS_STOPPED	0x114		The ADC has stopped
EVENTS_CH[n].LIMITH	0x118		Last results is equal or above CH[n].LIMIT.HIGH
EVENTS_CH[n].LIMITL	0x11C		Last results is equal or below CH[n].LIMIT.LOW
PUBLISH_STARTED	0x180		Publish configuration for event STARTED
PUBLISH_END	0x184		Publish configuration for event END
PUBLISH_DONE	0x188		Publish configuration for event DONE
PUBLISH_RESULTDONE	0x18C		Publish configuration for event RESULTDONE
PUBLISH_CALIBRATEDONE	0x190		Publish configuration for event CALIBRATEDONE
PUBLISH_STOPPED	0x194		Publish configuration for event STOPPED
PUBLISH_CH[n].LIMITH	0x198		Publish configuration for event CH[n].LIMITH
PUBLISH_CH[n].LIMITL	0x19C		Publish configuration for event CH[n].LIMITL
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
STATUS	0x400		Status
ENABLE	0x500		Enable or disable ADC
CH[n].PSELP	0x510		Input positive pin selection for CH[n]
CH[n].PSELN	0x514		Input negative pin selection for CH[n]

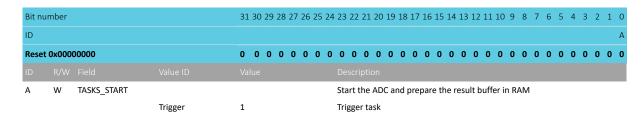


Register	Offset	TZ	Description
CH[n].CONFIG	0x518		Input configuration for CH[n]
CH[n].LIMIT	0x51C		High/low limits for event monitoring a channel
RESOLUTION	0x5F0		Resolution configuration
OVERSAMPLE	0x5F4		Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The
			RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION
			should be used.
SAMPLERATE	0x5F8		Controls normal or continuous sample rate
RESULT.PTR	0x62C		Data pointer
RESULT.MAXCNT	0x630		Maximum number of buffer words to transfer
RESULT.AMOUNT	0x634		Number of buffer words transferred since last START

6.12.10.1 TASKS_START

Address offset: 0x000

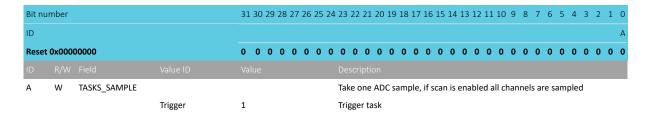
Start the ADC and prepare the result buffer in RAM



6.12.10.2 TASKS_SAMPLE

Address offset: 0x004

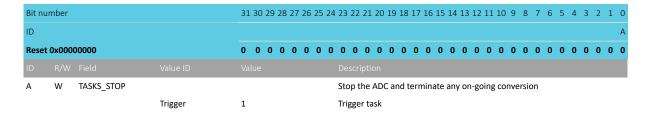
Take one ADC sample, if scan is enabled all channels are sampled



6.12.10.3 TASKS STOP

Address offset: 0x008

Stop the ADC and terminate any on-going conversion



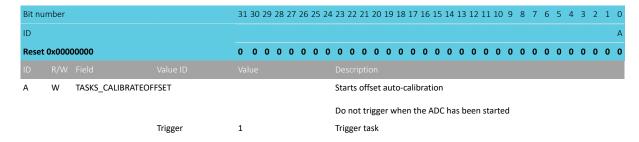
6.12.10.4 TASKS CALIBRATEOFFSET

Address offset: 0x00C

Starts offset auto-calibration



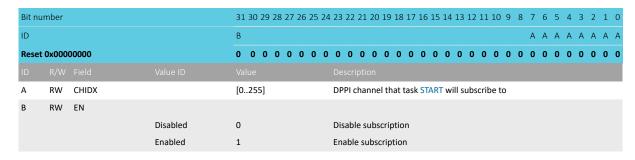
Do not trigger when the ADC has been started



6.12.10.5 SUBSCRIBE_START

Address offset: 0x080

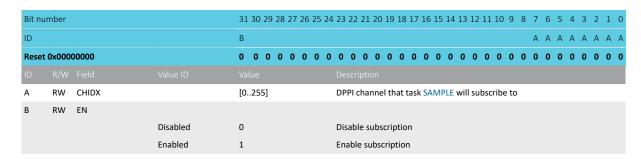
Subscribe configuration for task START



6.12.10.6 SUBSCRIBE_SAMPLE

Address offset: 0x084

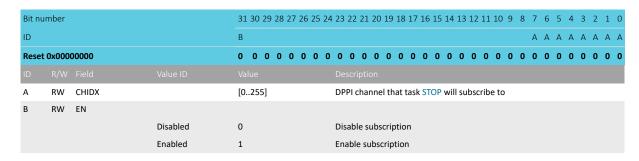
Subscribe configuration for task SAMPLE



6.12.10.7 SUBSCRIBE STOP

Address offset: 0x088

Subscribe configuration for task STOP



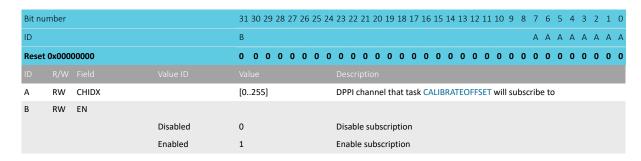


6.12.10.8 SUBSCRIBE_CALIBRATEOFFSET

Address offset: 0x08C

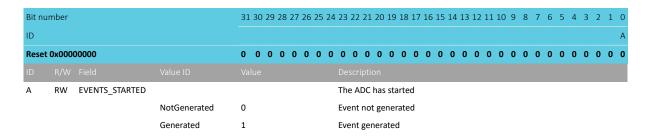
Subscribe configuration for task CALIBRATEOFFSET

Do not trigger when the ADC has been started



6.12.10.9 EVENTS STARTED

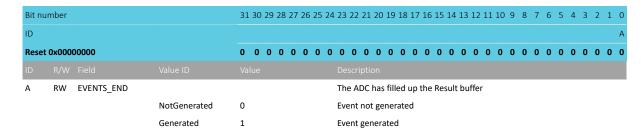
Address offset: 0x100
The ADC has started



6.12.10.10 EVENTS_END

Address offset: 0x104

The ADC has filled up the Result buffer



6.12.10.11 EVENTS_DONE

Address offset: 0x108

A conversion task has been completed. Depending on the mode, multiple conversions might be needed for a result to be transferred to RAM.



Bit nu	ımber			31 3	30 2	9 2	8 27	' 26	25	24	23	22	21 2	20 1	.9 1	8 1	7 16	5 15	5 14	13	12	11	10	9	8	7	6	5	4	3 2	2 :	L O
ID																																Α
Reset	0x000	00000		0	0 (0 (0	0	0	0	0	0	0	0 (0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 (0 0
ID																																
Α	RW	EVENTS_DONE									A c	onv	ersi	on t	task	has	be	en	con	nple	eted	l. De	epe	ndiı	ng c	n t	he	mo	de,	mul	ltipl	e
											cor	nver	sior	ns m	nigh	t be	ne	ede	d fo	or a	res	ult	to b	e tı	rans	fer	red	to	RAI	M.		
			NotGenerated	0							Eve	ent r	not	gen	era	ted																
			Generated	1							Eve	ent g	gene	erat	ed																	

6.12.10.12 EVENTS_RESULTDONE

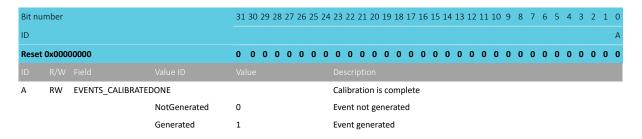
Address offset: 0x10C

A result is ready to get transferred to RAM.

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23	22 2	21 20	19 :	18 17	7 16	15 1	4 13	3 12	11 1	10 9	8	7	6	5	4 3	3 2	1	0
ID																							Α
Rese	0x000	00000		0 0 0 0 0 0 0 0	0	0 (0 0	0	0 0	0	0 (0 0	0	0	0 (0	0	0	0	0 (0	0	0
ID																							
Α	RW	EVENTS_RESULTDO	NE		A r	esult	t is re	ady	to ge	t tra	nsfe	rred	to F	RAM									
			NotGenerated	0	Eve	nt n	ot ge	enera	ited														
			Generated	1	Eve	nt g	ener	ated															

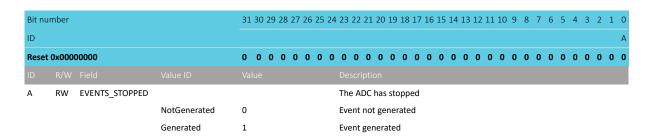
6.12.10.13 EVENTS_CALIBRATEDONE

Address offset: 0x110
Calibration is complete



6.12.10.14 EVENTS STOPPED

Address offset: 0x114
The ADC has stopped



6.12.10.15 EVENTS_CH[n] (n=0..7)

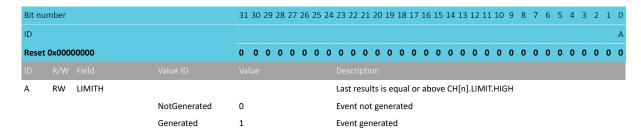
Peripheral events.



6.12.10.15.1 EVENTS_CH[n].LIMITH (n=0..7)

Address offset: $0x118 + (n \times 0x8)$

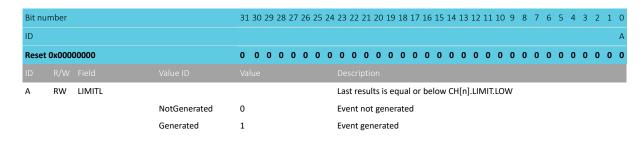
Last results is equal or above CH[n].LIMIT.HIGH



6.12.10.15.2 EVENTS_CH[n].LIMITL (n=0..7)

Address offset: 0x11C + (n × 0x8)

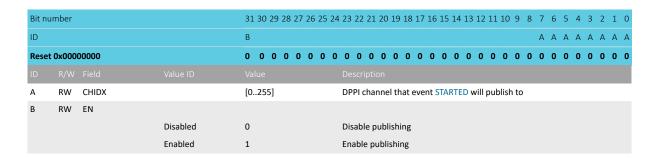
Last results is equal or below CH[n].LIMIT.LOW



6.12.10.16 PUBLISH_STARTED

Address offset: 0x180

Publish configuration for event STARTED



6.12.10.17 PUBLISH_END

Address offset: 0x184

Publish configuration for event END



Bit nu	mber			31 30 29	28 27	26 25	24	23 22	21 2	20 19	9 18	17 1	6 15	5 14	13 1	2 11	. 10	9	8 7	' 6	5	4	3	2	1 0
ID				В															A	, Δ	A	Α	Α	Α	А А
Reset	0x0000	00000		0 0 0	0 0	0 0	0	0 0	0	0 0	0	0 (0	0	0 (0	0	0	0 (0	0	0	0	0	0 0
ID																									
Α	RW	CHIDX		[0255]			ı	DPPI	chan	nel tl	hat e	vent	ENI	D wil	l pul	olish	to								
В	RW	EN																							
			Disabled	0				Disab	le pu	blish	ing														
			Enabled	1			- 1	Enabl	e pul	blishi	ing														

6.12.10.18 PUBLISH_DONE

Address offset: 0x188

Publish configuration for event DONE

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event DONE will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.19 PUBLISH_RESULTDONE

Address offset: 0x18C

Publish configuration for event RESULTDONE

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event RESULTDONE will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.20 PUBLISH_CALIBRATEDONE

Address offset: 0x190

Publish configuration for event CALIBRATEDONE

Bit no	umber			31 30 29 28 27 26 25 24	$23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID				В	A A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event CALIBRATEDONE will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

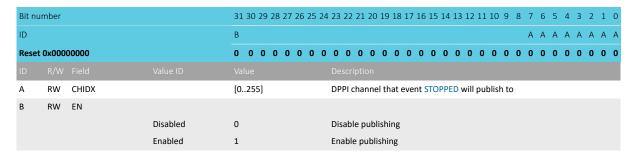




6.12.10.21 PUBLISH_STOPPED

Address offset: 0x194

Publish configuration for event STOPPED



6.12.10.22 PUBLISH_CH[n] (n=0..7)

Publish configuration for events

6.12.10.22.1 PUBLISH_CH[n].LIMITH (n=0..7)

Address offset: $0x198 + (n \times 0x8)$

Publish configuration for event CH[n].LIMITH

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event CH[n].LIMITH will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.22.2 PUBLISH_CH[n].LIMITL (n=0..7)

Address offset: $0x19C + (n \times 0x8)$

Publish configuration for event CH[n].LIMITL

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event CH[n].LIMITL will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.12.10.23 INTEN

Address offset: 0x300

4510_057 v1.0

Enable or disable interrupt



Bit no	umber			31 30	29 2	8 27	26	25	24 2	3 2:	2 21	L 20	0 1	.9 1	8 :	17	16	15	14	13	12	13	1 10	9)	3 7	, ,	6 !	5	4	3	2	1	0
ID											٧	U	٠ ر	T 5	ŝ	R	Q	Р	0	N	М	L	K	J		l F	(G 1	F	E	D	С	В	Α
Rese	t 0x000	0 0	0 (0 0	0	0	0 (0 0	0 (0)	0 (0	0	0	0	0	0	0	0	0	0) (0) () (0	0	0	0	0	0		
ID			Value ID						C																									
A	RW	STARTED									le o			ble	in	ter	rup	t fo	or e	vei	nt S	TA	RTE	D										
			Disabled	0						isak																								
			Enabled	1						nab																								
В	RW	END							Е	nab	le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt E	NE)											
			Disabled	0						isak																								
			Enabled	1						nab																								
С	RW	DONE		_							le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt D	001	NE											
			Disabled	0						isak																								
			Enabled	1						nab																								
D	RW	RESULTDONE	Litabica	-							ile oi	ır d	lisa	hle	in	ter	run	t fa	or e	VAI	nt R	eFS	LIIT	חר	ואכ									
D	11.00	RESOLIDONE	Disabled	0						isak		ı u	1136	ibic		LC11	ир		J1 C	VCI	10 10	LJ	OLI	DC	/141									
			Enabled	1						nab																								
E	RW	CALIBRATEDONE	Ellableu	1							ile oi	r d	lica	hlo	in	tor	run	+ f.	ar o		a+ C	١٨:	IDD	ΛТΙ	ED	ONI								
_	NVV	CALIBRATEDONE	Disabled	0)isak		ıı u	1150	ibie		ten	up		JI E	vei	it C	AL	IDN	AII	יט	OINE								
_	DIA	CTORRED	Enabled	1						nab			l:	L. I.								т.	DD1											
F	RW	STOPPED	Division I								le o	ır a	IISa	Bidi	ını	ter	rup	t I	or e	vei	1t 5	ilu	PPI	ט:										
			Disabled	0						isak																								
_	D) 4 /	CLIQUIA ALTILI	Enabled	1						nab								. ,																
G	RW	CHOLIMITH	· · · ·								le o	r a	IISa	ıbie	ın	ter	rup	T TO	or e	vei	nt C	.HC	LIIN	111	Н									
			Disabled	0						isat																								
			Enabled	1						nab																								
Н	RW	CHOLIMITL		_							le o	r d	lisa	ible	ın	ter	rup	t fo	or e	vei	nt C	HC)LIN	111	L									
			Disabled	0						oisak																								
			Enabled	1						nab								. ,																
I	RW	CH1LIMITH		_							le o	r d	lisa	ible	ın	ter	rup	t fo	or e	vei	nt C	.H3	LLIN	111	Н									
			Disabled	0						isat																								
			Enabled	1						nab																								
J	RW	CH1LIMITL		_							le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	:H1	LIN	1IT	L									
			Disabled	0						isak																								
			Enabled	1						nab																								
K	RW	CH2LIMITH		_							le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	:H2	LIN	1IT	Н									
			Disabled	0						isak																								
			Enabled	1						nab																								
L	RW	CH2LIMITL									le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	:H2	LIN	1IT	L									
			Disabled	0						isak																								
			Enabled	1						nab																								
M	RW	CH3LIMITH									le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	CH3	BLIN	1IT	Н									
			Disabled	0						isak																								
			Enabled	1					E	nab	le																							
N	RW	CH3LIMITL							Е	nab	le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	CH3	BLIN	1IT	L									
			Disabled	0						isak																								
			Enabled	1					E	nab	le																							
0	RW	CH4LIMITH									le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	H4	LIN	1IT	Н									
			Disabled	0						isak																								
			Enabled	1					E	nab	le																							
Р	RW	CH4LIMITL							Е	nab	le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	CH4	LIN	1IT	L									
			Disabled	0					C	isak	ble																							
			Enabled	1					E	nab	le																							
Q	RW	CH5LIMITH							E	nab	le o	r d	lisa	ble	in	ter	rup	t fo	or e	vei	nt C	CH5	LIN	1IT	Н									
			Disabled	0					C	isal	ble																							





Bit nu	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
			Enabled	1	Enable
R	RW	CH5LIMITL			Enable or disable interrupt for event CH5LIMITL
			Disabled	0	Disable
			Enabled	1	Enable
S	RW	CH6LIMITH			Enable or disable interrupt for event CH6LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
Т	RW	CH6LIMITL			Enable or disable interrupt for event CH6LIMITL
			Disabled	0	Disable
			Enabled	1	Enable
U	RW	CH7LIMITH			Enable or disable interrupt for event CH7LIMITH
			Disabled	0	Disable
			Enabled	1	Enable
٧	RW	CH7LIMITL			Enable or disable interrupt for event CH7LIMITL
			Disabled	0	Disable
			Enabled	1	Enable

6.12.10.24 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	STARTED			Write '1' to enable interrupt for event STARTED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	DONE			Write '1' to enable interrupt for event DONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	RESULTDONE			Write '1' to enable interrupt for event RESULTDONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
E	RW	CALIBRATEDONE			Write '1' to enable interrupt for event CALIBRATEDONE
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
F	RW	STOPPED			Write '1' to enable interrupt for event STOPPED
			Set	1	Enable
			Disabled	0	Read: Disabled



Bit n	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Enabled	1	Read: Enabled
G	RW	CHOLIMITH			Write '1' to enable interrupt for event CH0LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	CHOLIMITL			Write '1' to enable interrupt for event CHOLIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
I	RW	CH1LIMITH			Write '1' to enable interrupt for event CH1LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW	CH1LIMITL			Write '1' to enable interrupt for event CH1LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
K	RW	CH2LIMITH			Write '1' to enable interrupt for event CH2LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
L	RW	CH2LIMITL			Write '1' to enable interrupt for event CH2LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
М	RW	CH3LIMITH			Write '1' to enable interrupt for event CH3LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
N	RW	CH3LIMITL			Write '1' to enable interrupt for event CH3LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
0	RW	CH4LIMITH			Write '1' to enable interrupt for event CH4LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Р	RW	CH4LIMITL			Write '1' to enable interrupt for event CH4LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Q	RW	CH5LIMITH	6.1		Write '1' to enable interrupt for event CH5LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
		CUELL TO THE	Enabled	1	Read: Enabled
R	RW	CH5LIMITL	6.		Write '1' to enable interrupt for event CH5LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
S	RW	CH6LIMITH			Write '1' to enable interrupt for event CH6LIMITH





Bit nu	mber			31 30 29 28 27 26 25 24	¹ 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Т	RW	CH6LIMITL			Write '1' to enable interrupt for event CH6LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
U	RW	CH7LIMITH			Write '1' to enable interrupt for event CH7LIMITH
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
٧	RW	CH7LIMITL			Write '1' to enable interrupt for event CH7LIMITL
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.12.10.25 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber			31	30 2	29 2	28 :	27 2	26 :	25 2	24	23	3 22	2	1 2	0 1	.9	18	17	16	15	14	13	12	11	1 10	9		8 7	7	6	5	4	3	2	1	0
ID														١	/ l	J .	Т	S	R	Q	Р	0	N	М	L	K	J		l F	1	G	F	E	D	С	В	Α
Reset	0x000	00000		0	0	0 (0	0	0	0	0	0	0	C) ()	0	0	0	0	0	0	0	0	0	0	0	(0 ()	0	0	0	0	0	0	0
Α	RW	STARTED										W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	ST	AR	ΓED										
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	ł																				
В	RW	END									,	W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	ΕN	ND											
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	i																				
С	RW	DONE									,	W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	D	ONE											
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	ł																				
D	RW	RESULTDONE									,	W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	RE	SU	LTD	0	NE								
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	i																				
E	RW	CALIBRATEDONE									,	W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	C/	ALIE	RA	TE	DO	NE							
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	t																				
F	RW	STOPPED									,	W	rite	'1	' to	di	sal	ole	int	err	upt	fo	rev	ent	ST	ОР	PEC)									
			Clear	1								Di	sab	le																							
			Disabled	0								Re	ead:	D	isal	ble	d																				
			Enabled	1								Re	ead:	E	nab	lec	ł																				



Bit n	umber			31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
					Description
G	RW	CHOLIMITH			Write '1' to disable interrupt for event CHOLIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Н	RW	CHOLIMITL			Write '1' to disable interrupt for event CHOLIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
I	RW	CH1LIMITH			Write '1' to disable interrupt for event CH1LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
J	RW	CH1LIMITL			Write '1' to disable interrupt for event CH1LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
K	RW	CH2LIMITH			Write '1' to disable interrupt for event CH2LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
L	RW	CH2LIMITL			Write '1' to disable interrupt for event CH2LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
М	RW	CH3LIMITH			Write '1' to disable interrupt for event CH3LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
N	D\A/	CHALIMITI	Enabled	1	Read: Enabled
N	RW	CH3LIMITL	Class	1	Write '1' to disable interrupt for event CH3LIMITL
			Clear Disabled	0	Disable Read: Disabled
			Enabled	1	Read: Enabled
0	RW	CH4LIMITH	Ellableu	1	Write '1' to disable interrupt for event CH4LIMITH
U	IVV	CH4LIMITH	Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Р	RW	CH4LIMITL	2.102.100	-	Write '1' to disable interrupt for event CH4LIMITL
		•	Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Q	RW	CH5LIMITH			Write '1' to disable interrupt for event CH5LIMITH
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
R	RW	CH5LIMITL			Write '1' to disable interrupt for event CH5LIMITL
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
S	RW	CH6LIMITH			Write '1' to disable interrupt for event CH6LIMITH
			Clear	1	Disable



Bit n	umber		31 30 29 28 2	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				V U T S R Q P O N M L K J I H G F E D C B A
Rese	t 0x0000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Т	RW CH6LIMITL			Write '1' to disable interrupt for event CH6LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
U	RW CH7LIMITH			Write '1' to disable interrupt for event CH7LIMITH
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
V	RW CH7LIMITL			Write '1' to disable interrupt for event CH7LIMITL
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.12.10.26 STATUS

Address offset: 0x400

Status

Bit n	umber			31 30	29 2	8 27	26	25 2	24 2	3 22	21	20	19	18 1	7 1	6 15	5 14	13	12	11	10	9 8	3 7	7 6	5 5	4	3	2	1 ()
ID																													,	A
Rese	t 0x000	00000		0 0	0 (0 0	0	0	0 (0	0	0	0	0 (0	0	0	0	0	0	0	0 (0 () (0	0	0	0	0 (כ
ID																														
Α	R	STATUS							S	tatus	5																			
			Ready	0					Α	DC i	s re	ady.	No	on-	goir	ng c	onv	ersi	on.											
			Busy	1					Α	DC i	s bu	ısy. S	Sing	le c	onve	ersi	on i	n pr	ogr	ess.										

6.12.10.27 ENABLE

Address offset: 0x500 Enable or disable ADC

Bit nu	ımber			31	30 2	9 28	3 27 :	26 2	25 24	23	22 2	21 2	0 19	9 18	8 17	16	15	14	13 :	12 1	1 10	9	8	7	6	5	4	3 2	. 1	0
ID																														Α
Reset	0x000	00000		0	0 (0	0	0 (0 0	0	0	0 (0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 0	0	0
ID																														
Α	RW	ENABLE								Ena	able	or c	disal	ble .	ADC															
			Disabled	0						Dis	able	AD	C																	
			Enabled	1						Ena	able	ADO	С																	
										Wh	nen e	enak	bled	l, th	e Al	OC v	vill a	acqı	uire	acc	ess 1	o th	ne a	nalo	og i	npu	ıt pi	ns		
										spe	cifie	d ir	n the	e Ch	H[n]	.PSE	LP a	and	СН	[n].F	SEL	N re	gist	ers						

6.12.10.28 CH[n].PSELP (n=0..7)

Address offset: $0x510 + (n \times 0x10)$ Input positive pin selection for CH[n]



Bit nu	ımber			31 3	80 29 2	28 27	26 2	25 24	23 22	2 21 2	0 19	18 1	7 16	15	14	13	12 1	1 10	9	8	7	6	5 4	3	2	1	0
ID																							Δ	A	Α	Α	Α
Reset	0x000	00000		0	0 0	0 0	0	0 0	0 0	0 (0 0	0	0 0	0	0	0	0 0	0	0	0	0	0	0 0	0	0	0	0
ID																											
Α	RW	PSELP							Analo	og pos	itive	inpu	t cha	anne	el												
			NC	0					Not c	onne	cted																
			AnalogInput0	1					AIN0																		
			AnalogInput1	2					AIN1																		
			AnalogInput2	3					AIN2																		
			AnalogInput3	4					AIN3																		
			AnalogInput4	5					AIN4																		
			AnalogInput5	6					AIN5																		
			AnalogInput6	7					AIN6																		
			AnalogInput7	8					AIN7																		
			VDDGPIO	9					VDD_	_GPIO																	

6.12.10.29 CH[n].PSELN (n=0..7)

Address offset: $0x514 + (n \times 0x10)$ Input negative pin selection for CH[n]

Bit no	umber				31	30	29 2	8 27	26 2	5 24	23 2	22 21	20 1	9 18	17 1	16 15	5 14	13	12 1:	1 10	9	8	7	6	5 4	1 3	2	1	0
ID																									A	A A	Α	Α	Α
Rese	t 0x000	00000			0	0	0 0	0	0 0	0	0	0 0	0 (0	0	0 0	0	0	0 0	0	0	0	0	0	0 (0	0	0	0
ID				D																									
Α	RW	PSELN									Ana	log ne	egativ	ve inp	out,	enab	les c	diffe	erenti	al cl	nan	nel							
			NC		0						Not	conn	ected	ł															
			Analog	Input0	1						AIN	0																	
			Analog	Input1	2						AIN	1																	
			Analog	Input2	3						AIN	2																	
			Analog	Input3	4						AIN	3																	
			Analog	Input4	5						AIN	4																	
			Analog	Input5	6						AIN	5																	
			Analog	Input6	7						AIN	6																	
			Analog	Input7	8						AIN	7																	
			VDD_0	PIO	9						VDE	_GPI	0																

6.12.10.30 CH[n].CONFIG (n=0..7)

Address offset: $0x518 + (n \times 0x10)$ Input configuration for CH[n]

Bit nu	ımber			31 30	0 29 :	28 2	27 26	5 25	24	23	22 2	1 20	19	18	17	16	15 1	4 13	3 12	11	10	9	8	7	6	5	4	3 2	1	0
ID									G			F		Е	Ε	Ε			D		С	С	С			В	В		Α	Α
Reset	0x000	20000		0 0	0	0	0 0	0	0	0	0 (0	0	0	1	0	0	0 0	0	0	0	0	0	0	0	0	0	0 0	0	0
ID																														
Α	RW	RESP								Pos	itive	cha	nne	l res	isto	or c	onti	ol												
			Bypass	0						Вур	oass i	resis	tor l	add	ler															
			Pulldown	1						Pul	l-dov	vn to	o GN	ID																
			Pullup	2						Pul	l-up	to V	DD_	GPI	0															
			VDD1_2	3						Set	inpu	ıt at	VDE	o_G	PIO	/2														
В	RW	RESN								Ne	gativ	e ch	ann	el re	sis	tor	con	trol												
			Bypass	0						Вур	oass i	resis	tor l	add	ler															



Bit n	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				G	F E E E D C C C B B A A
Rese	t 0x000	20000		0 0 0 0 0 0 0 0	0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
			Pulldown	1	Pull-down to GND
			Pullup	2	Pull-up to VDD_GPIO
			VDD1_2	3	Set input at VDD_GPIO/2
С	RW	GAIN			Gain control
			Gain1_6	0	1/6
			Gain1_5	1	1/5
			Gain1_4	2	1/4
			Gain1_3	3	1/3
			Gain1_2	4	1/2
			Gain1	5	1
			Gain2	6	2
			Gain4	7	4
D-	RW	REFSEL			Reference control
			Internal	0	Internal reference (0.6 V)
			VDD1_4	1	VDD_GPIO/4 as reference
E	RW	TACQ			Acquisition time, the time the ADC uses to sample the input voltage
			3us	0	3 us
			5us	1	5 us
			10us	2	10 us
			15us	3	15 us
			20us	4	20 us
			40us	5	40 us
F	RW	MODE			Enable differential mode
			SE	0	Single ended, PSELN will be ignored, negative input to ADC shorted to GND
			Diff	1	Differential
G	RW	BURST			Enable burst mode
			Disabled	0	Burst mode is disabled (normal operation)
			Enabled	1	Burst mode is enabled. SAADC takes 2^OVERSAMPLE number of samples as
					fast as it can, and sends the average to Data RAM.

6.12.10.31 CH[n].LIMIT (n=0..7)

Address offset: 0x51C + (n × 0x10)

High/low limits for event monitoring a channel

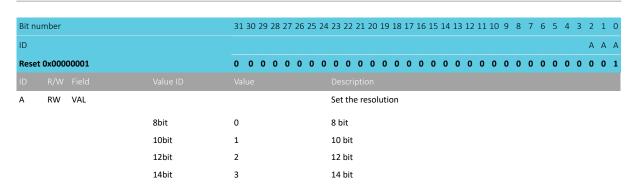
Bit nu	ımber	31	30 2	9 28	3 27	26	25 2	24 2	3 22	2 2 1	20	19 1	8 17	7 16	15	14	13 :	12 1:	1 10	9	8	7	6	5	4	3 2	2 1	. 0
ID		В	ВЕ	3 B	В	В	В	ВЕ	3 B	В	В	В	ВВ	В	Α	Α	Α	А А	Α	Α	Α	Α	Α	Α	Α	A A	Α Α	A
Reset	0x7FFF8000	0	1 1	1	1	1	1	1 :	1 1	1	1	1	1 1	1	1	0	0	0 0	0	0	0	0	0	0	0	0 0	0	0
ID																												
Α	RW LOW	[-3	2768	to +	-327	67]		L	ow l	evel	lim	it																
В	RW HIGH	[-3	2768	to +	-327	67]		Н	ligh	leve	l lim	it																

6.12.10.32 RESOLUTION

Address offset: 0x5F0
Resolution configuration



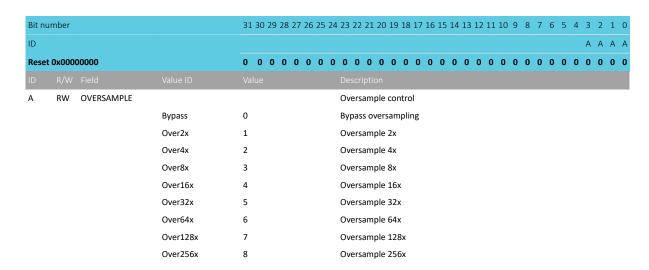




6.12.10.33 OVERSAMPLE

Address offset: 0x5F4

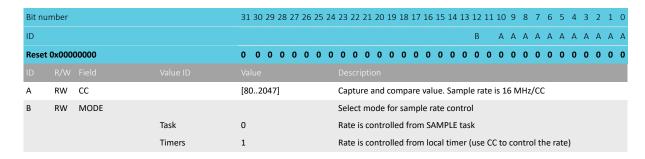
Oversampling configuration. OVERSAMPLE should not be combined with SCAN. The RESOLUTION is applied before averaging, thus for high OVERSAMPLE a higher RESOLUTION should be used.



6.12.10.34 SAMPLERATE

Address offset: 0x5F8

Controls normal or continuous sample rate



6.12.10.35 RESULT

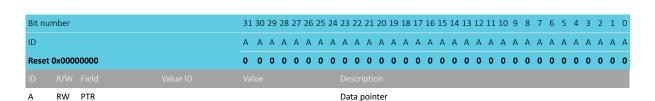
RESULT EasyDMA channel

6.12.10.35.1 RESULT.PTR

Address offset: 0x62C

Data pointer



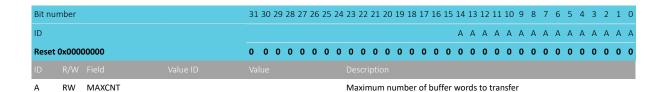


Note: See the memory chapter for details about which memories are available for EasyDMA.

6.12.10.35.2 RESULT.MAXCNT

Address offset: 0x630

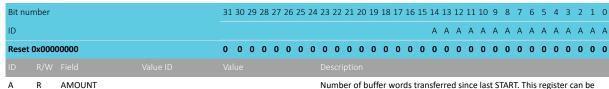
Maximum number of buffer words to transfer



6.12.10.35.3 RESULT.AMOUNT

Address offset: 0x634

Number of buffer words transferred since last START



Number of buffer words transferred since last START. This register can be read after an END or STOPPED event.

6.12.11 Electrical specification

6.12.11.1 SAADC Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
DNL ₁₀	Differential non-linearity, 10-bit resolution	-0.95	<1		LSB10b
INL ₁₀	Integral non-linearity, 10-bit resolution		1		LSB10b
Vos	Differential offset error (calibrated), 10-bit resolution ^a		±2		LSB10b
C _{EG}	Gain error temperature coefficient	-0.05	0.02	0.05	%/°C
f _{SAMPLE}	Maximum sampling rate			200	kHz
t _{ACQ,10k}	Acquisition time (configurable), source Resistance <= 10 kOhm		3		μs
t _{ACQ,40k}	Acquisition time (configurable), source Resistance <= 40 kOhm		5		μs
t _{ACQ,100k}	Acquisition time (configurable), source Resistance <= 100 kOhm		10		μs
t _{ACQ,200k}	Acquisition time (configurable), source Resistance <= 200 kOhm		15		μs
t _{ACQ,400k}	Acquisition time (configurable), source Resistance <= 400 kOhm		20		μs
t _{ACQ,800k}	Acquisition time (configurable), source Resistance <= 800 kOhm		40		μs
t _{CONV}	Conversion time		<2		μs

^a Digital output code at zero volt differential input.



Symbol	Description	Min.	Тур.	Max.	Units
E _{G1/6}	Error ^b for Gain = 1/6	-3		3	%
E _{G1/4}	Error ^b for Gain = 1/4	-3		3	%
E _{G1/2}	Error ^b for Gain = 1/2. Internal reference	-3		4	%
E _{G1}	Error ^b for Gain = 1. Internal reference	-3		4	%
E _{G1/2_VDD_GPIO}	Error ^b for Gain = 1/2. VDD_GPIO as reference	-4		4	%
E _{G1_VDD_GPIO}	Error ^b for Gain = 1. VDD_GPIO as reference	-4		4	%
C _{SAMPLE}	Sample and hold capacitance at maximum gain ¹⁵		2.5		pF
R _{INPUT}	Input resistance		>1		ΜΩ
E _{NOB}	Effective number of bits, differential mode, 12-bit resolution, 1/1 gain, 3 μs		9		Bit
	acquisition time, HFXO, 200 ksps				
S _{NDR}	Peak signal to noise and distortion ratio, differential mode, 12-bit resolution,		56		dB
	1/1 gain, 3 μs acquisition time, HFXO, 200 ksps				
S _{FDR}	Spurious free dynamic range, differential mode, 12-bit resolution, 1/1 gain, 3		70		dBc
	μs acquisition time, HFXO, 200 ksps				
R _{LADDER}	Ladder resistance		160		kΩ

6.12.12 Performance factors

Clock jitter, affecting sample timing accuracy, and circuit noise can affect ADC performance.

Jitter can be between START tasks or from START task to acquisition. START timer accuracy and startup times of regulators and references will contribute to variability. Sources of circuit noise may include CPU activity and the DC/DC regulator. Best ADC performance is achieved using START timing based on the TIMER module, HFXO clock source, and Constant Latency mode.

6.13 SPIM — Serial peripheral interface master with EasyDMA

The SPI master can communicate with multiple slaves using individual chip select signals for each of the slave devices attached to a bus.

Listed here are the main features for the SPIM

- SPI mode 0-3
- EasyDMA direct transfer to/from RAM for both SPI Slave and SPI Master
- Individual selection of IO pin for each SPI signal



^b Does not include temperature drift

¹⁵ Maximum gain corresponds to highest capacitance.

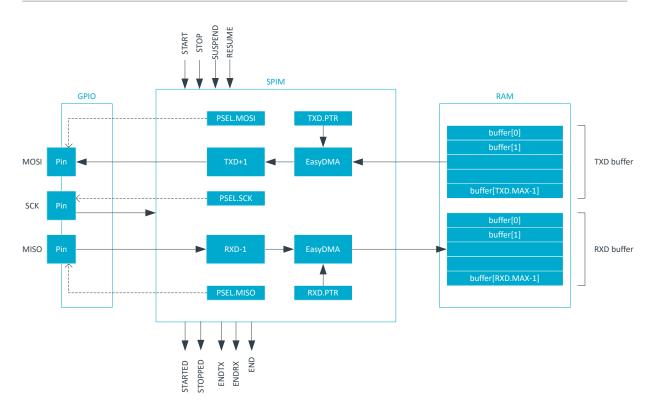


Figure 73: SPIM — SPI master with EasyDMA

The SPIM does not implement support for chip select directly. Therefore, the CPU must use available GPIOs to select the correct slave and control this independently of the SPI master. The SPIM supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.

Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Leading)
SPI_MODE1	0 (Active High)	1 (Trailing)
SPI_MODE2	1 (Active Low)	0 (Leading)
SPI_MODE3	1 (Active Low)	1 (Trailing)

Table 31: SPI modes

6.13.1 SPI master transaction sequence

An SPI master transaction consists of a sequence started by the START task followed by a number of events, and finally the STOP task.

An SPI master transaction is started by triggering the START task. The ENDTX event will be generated when the transmitter has transmitted all bytes in the TXD buffer as specified in the TXD.MAXCNT register. The ENDRX event will be generated when the receiver has filled the RXD buffer, i.e. received the last possible byte as specified in the RXD.MAXCNT register.

Following a START task, the SPI master will generate an END event when both ENDRX and ENDTX have been generated.

The SPI master is stopped by triggering the STOP task. A STOPPED event is generated when the SPI master has stopped.

If the ENDRX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDRX event explicitly even though the RX buffer is not full.

NORDIC*

If the ENDTX event has not already been generated when the SPI master has come to a stop, the SPI master will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

The SPI master is a synchronous interface, and for every byte that is sent, a different byte will be received at the same time; this is illustrated in SPI master transaction on page 227.

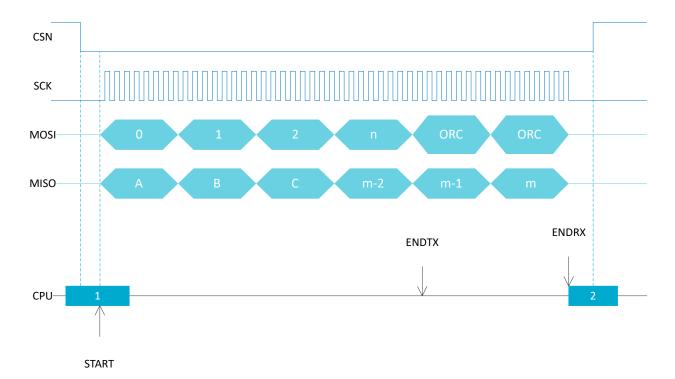


Figure 74: SPI master transaction

6.13.2 Master mode pin configuration

The SCK, MOSI, and MISO signals associated with the SPI master are mapped to physical pins according to the configuration specified in the PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively.

The PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI master is enabled, and retained only as long as the device is in ON mode. PSEL.SCK, PSEL.MOSI and PSEL.MISO must only be configured when the SPI master is disabled.

To secure correct behavior in the SPI, the pins used by the SPI must be configured in the GPIO peripheral as described in GPIO configuration on page 227 prior to enabling the SPI. This configuration must be retained in the GPIO for the selected IOs as long as the SPI is enabled.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI master signal	SPI master pin	Direction	Output value
SCK	As specified in PSEL.SCK	Output	Same as CONFIG.CPOL
MOSI	As specified in PSEL.MOSI	Output	0
MISO	As specified in PSEL.MISO	Input	Not applicable

Table 32: GPIO configuration



6.13.3 Shared resources

The SPI shares registers and other resources with other peripherals that have the same ID as the SPI. Therefore, the user must disable all peripherals that have the same ID as the SPI before the SPI can be configured and used.

Disabling a peripheral that has the same ID as the SPI will not reset any of the registers that are shared with the SPI. It is therefore important to configure all relevant SPI registers explicitly to secure that it operates correctly.

See the Instantiation table in Instantiation on page 25 for details on peripherals and their IDs.

6.13.4 EasyDMA

The SPIM implements EasyDMA for accessing RAM without CPU involvement.

The SPIM peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 33: SPIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 43.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next transmission immediately after having received the STARTED event.

The SPI master will automatically stop transmitting after TXD.MAXCNT bytes have been transmitted and RXD.MAXCNT bytes have been received. If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register. If TXD.MAXCNT is larger than RXD.MAXCNT, the superfluous received bytes will be discarded.

The ENDRX/ENDTX event indicate that EasyDMA has finished accessing respectively the RX/TX buffer in RAM. The END event gets generated when both RX and TX are finished accessing the buffers in RAM.

In the case of bus congestion as described in AHB multilayer interconnect on page 46, data loss may occur.

6.13.5 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.



6.13.6 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
SPIM0 : S	0x50008000	US	NS	SA	No	SPI master 0
SPIM0 : NS	0x40008000	03	INS	ЭА	NO	SFI IIIastei U
SPIM1:S	0x50009000	US	NS	SA	No	SPI master 1
SPIM1: NS	0x40009000	03	INS	ЭА	NO	SFITHASIEI I
SPIM2 : S	0x5000A000	US	NS	SA	No	SPI master 2
SPIM2 : NS	0x4000A000	03	INS	ЭА	NO	SFITHASLEI Z
SPIM3:S	0x5000B000	US	NS	SA	No	SPI master 3
SPIM3 : NS	0x4000B000	US	INO	ЭА	INU	SFI IIIdStel S

Register overview

		_	
Register	Offset	TZ	Description
TASKS_START	0x010		Start SPI transaction
TASKS_STOP	0x014		Stop SPI transaction
TASKS_SUSPEND	0x01C		Suspend SPI transaction
TASKS_RESUME	0x020		Resume SPI transaction
SUBSCRIBE_START	0x090		Subscribe configuration for task START
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_STOPPED	0x104		SPI transaction has stopped
EVENTS_ENDRX	0x110		End of RXD buffer reached
EVENTS_END	0x118		End of RXD buffer and TXD buffer reached
EVENTS_ENDTX	0x120		End of TXD buffer reached
EVENTS_STARTED	0x14C		Transaction started
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_END	0x198		Publish configuration for event END
PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
PUBLISH_STARTED	0x1CC		Publish configuration for event STARTED
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ENABLE	0x500		Enable SPIM
PSEL.SCK	0x508		Pin select for SCK
PSEL.MOSI	0x50C		Pin select for MOSI signal
PSEL.MISO	0x510		Pin select for MISO signal
FREQUENCY	0x524		SPI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
TXD.LIST	0x550		EasyDMA list type



Register	Offset	TZ	Description
CONFIG	0x554		Configuration register
ORC	0x5C0		Over-read character. Character clocked out in case an over-read of the TXD buffer.

6.13.6.1 TASKS_START

Address offset: 0x010 Start SPI transaction

			Trigger	1			ger ta			•														
Α	W	TASKS START				Sta	rt SPI	rans	acti	on														
ID																								
Rese	t 0x000	00000		0 0 0 0 0 0	0 0	0	0 0	0	0 0	0	0	0 0	0	0	0	0	0 (0	0	0	0	0	0	0 0
ID																								Α
Bit n	umber			31 30 29 28 27 26	25 24	1 23	22 21	20 1	19 18	3 17	16 1	.5 1	4 13	3 12	11	10	9 8	3 7	6	5	4	3	2	1 0

6.13.6.2 TASKS_STOP

Address offset: 0x014
Stop SPI transaction

Bit nu	ımber			31 30 29 28 27 26	5 25 24	4 23	22 2	1 20	19	18 1	7 16	15	14	13 13	2 11	10	9	8	7	6	5	4	3 2	1	0
ID																									Α
Reset	0x000	00000		0 0 0 0 0 0	0 0	0	0 (0 0	0	0 0	0	0	0	0 0	0	0	0	0	0	0	0	0	0 (0	0
ID																									
Α	W	TASKS_STOP				Sto	p SP	l tra	nsac	tion															
			Trigger	1		Tri	gger	task																	

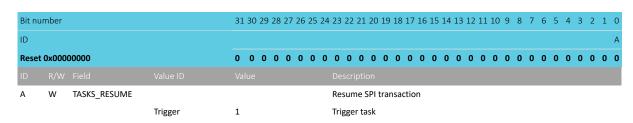
6.13.6.3 TASKS_SUSPEND

Address offset: 0x01C Suspend SPI transaction

Bit no	umber			31 30 29 28 27 26 2	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	W	TASKS_SUSPEND			Suspend SPI transaction
			Trigger	1	Trigger task

6.13.6.4 TASKS_RESUME

Address offset: 0x020 Resume SPI transaction



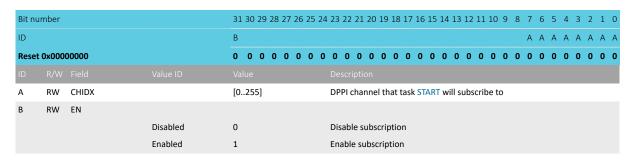




6.13.6.5 SUBSCRIBE_START

Address offset: 0x090

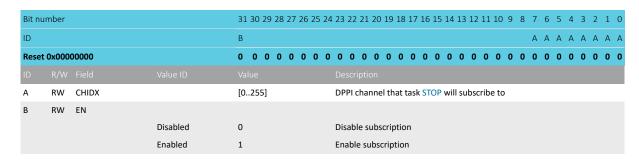
Subscribe configuration for task START



6.13.6.6 SUBSCRIBE_STOP

Address offset: 0x094

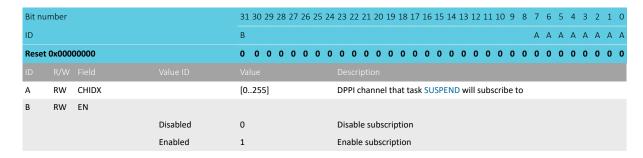
Subscribe configuration for task STOP



6.13.6.7 SUBSCRIBE SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND



6.13.6.8 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME



Bit nu	mber			31 30 2	9 28	27 2	26 25	24 2	23 2	2 21	. 20	19 1	8 17	' 16	15	14 1	3 12	11	10	9 8	3 7	6	5	4	3 2	. 1	0
ID				В																	Α	Α	Α	Α	АА	A	Α
Reset	0x000	00000		0 0 0	0	0 (0 0	0	0 (0 0	0	0 (0	0	0	0 (0	0	0	0 (0	0	0	0	0 0	0	0
ID																											
Α	RW	CHIDX		[0255]				[DPPI	I cha	nnel	that	tas	k RE	SUN	ΛE v	ill s	ubsc	ribe	to							
В	RW	EN																									
			Disabled	0				ı	Disa	ble s	ubsc	ripti	on														
			Enabled	1				1	Enat	ole s	ubsc	riptio	on														

6.13.6.9 EVENTS_STOPPED

Address offset: 0x104

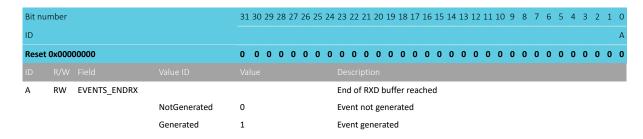
SPI transaction has stopped

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 2	2 21 2	20 19	18 1	7 16	15 1	4 13	12	11 10	9	8	7	6	5	4 3	2	1	0
ID																						Α
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0	0	0 0	0 0	0	0 (0	0	0 0	0	0	0	0	0	0 (0	0	0
ID																						
Α	RW	EVENTS_STOPPED			SPI t	ransad	tion	has st	topp	ed												
			NotGenerated	0	Even	t not	gener	rated														
			Generated	1	Even	t gene	erated	d														

6.13.6.10 EVENTS_ENDRX

Address offset: 0x110

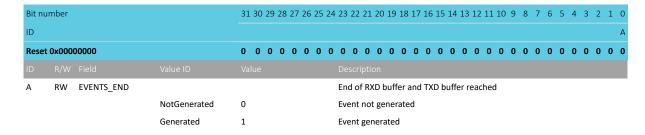
End of RXD buffer reached



6.13.6.11 EVENTS END

Address offset: 0x118

End of RXD buffer and TXD buffer reached



6.13.6.12 EVENTS_ENDTX

Address offset: 0x120

End of TXD buffer reached



Bit nui	mber			31 30 29 28 27 2	6 25 24	1 23 :	22 21 :	20 19	18 17	7 16 1	.5 14	13 1	2 11	10 9	8	7	6	5	4	3 2	. 1	0
ID																						Α
Reset	0x000	00000		0 0 0 0 0	0 0	0	0 0	0 0	0 0	0	0 0	0 0	0	0 0	0	0	0	0	0	0 0	0	0
ID																						
Α	RW	EVENTS_ENDTX				End	of TXI) buff	er rea	ched												
			NotGenerated	0		Eve	nt not	gener	ated													
			Generated	1		Eve	nt gen	erated	t													

6.13.6.13 EVENTS_STARTED

Address offset: 0x14C
Transaction started

Bit nu	mber			31 30	29 2	8 27 :	26 25	5 24	23 2	22 2	1 20	19	18	17 1	6 15	14	13	12 1	1 10	9	8	7	6	5 4	4 3	3 2	1	0
ID																												Α
Reset	0x000	00000		0 0	0 0	0	0 0	0	0	0 (0 0	0	0	0 (0	0	0	0 0	0	0	0	0	0	0 (0 (0 0	0	0
ID																												
Α	RW	EVENTS_STARTED							Trar	ısac	tion	star	rted															
			NotGenerated	0					Eve	nt n	ot ge	ener	rated	ł														
			Generated	1					Eve	nt g	ener	ated	b															

6.13.6.14 PUBLISH_STOPPED

Address offset: 0x184

Publish configuration for event STOPPED

Bit nu	ımber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event STOPPED will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.13.6.15 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

Bit nu	ımber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event ENDRX will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

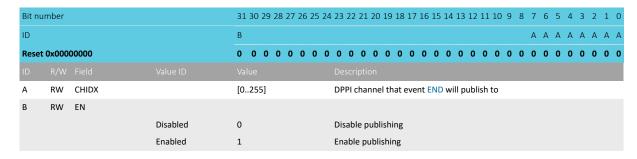
6.13.6.16 PUBLISH_END

Address offset: 0x198





Publish configuration for event END



6.13.6.17 PUBLISH_ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event ENDTX will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.13.6.18 PUBLISH_STARTED

Address offset: 0x1CC

Publish configuration for event STARTED

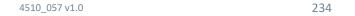
Bit nu	umber			31 30 29 28	27 26 25 2	24 23 2	22 21 2	20 19	18 17	16 1	5 14	13 12	2 11	10	9 8	7	6	5	4	3 2	1	0
ID				В												Α	Α	Α	Α .	4 А	Α	Α
Reset	t 0x000	00000		0 0 0 0	0 0 0	0 0	0 0	0 0	0 0	0 (0 0	0 0	0	0	0 0	0	0	0	0	0 0	0	0
ID																						
Α	RW	CHIDX		[0255]		DPP	l chan	nel th	at eve	ent ST	ARTE	D will	pub	olish	to							
В	RW	EN																				
			Disabled	0		Disa	able pu	blishii	ng													
			Enabled	1		Ena	ble pul	blishir	ng													

6.13.6.19 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit no	umber		31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				А
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID	R/W Field	Value ID	Value	Description
Α	RW END_START			Shortcut between event END and task START
		Disabled	0	Disable shortcut
		Enabled	1	Enable shortcut





6.13.6.20 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			3	31 3	0 29	28	27 2	26 2	25 24	1 2	3 22	2 2:	1 20	0 19	9 18	8 1	7 1	6 1	5 1	4 1	3 1	2 1	1 1	10 9) ;	8 7	6	5 5	4	3	2	1	0
ID															E											ı	D	(2	В			Α	
Reset	0x000	00000		0) (0	0	0	0	0 0	(0 0	0	0	0	0) (0 () () () () () ()	0 0) (0 0	(0 0	0	0	0	0	0
ID																																		
Α	RW	STOPPED									٧	Vrite	e '1	' to	en	able	e ir	nter	rup	t fo	r e	ver	it S	ΓΟΙ	PPE)								
			Set	1	L						Ε	nab	le																					
			Disabled	0)						R	lead	: Di	isab	led	ł																		
			Enabled	1	L						R	lead	: Er	nab	led																			
В	RW	ENDRX									٧	Vrite	e '1	' to	en	able	e ir	nter	rup	t fo	r e	ver	it El	ND	RX									
			Set	1	L						Ε	nab	le																					
			Disabled	0)						R	lead	: Di	isab	led	i																		
			Enabled	1	L						R	lead	: Er	nab	led																			
С	RW	END									٧	Vrite	e '1	' to	en	able	e ir	nter	rup	t fo	r e	ver	it El	ND										
			Set	1	L						Ε	nab	le																					
			Disabled	0)						R	lead	: Di	isab	led	i																		
			Enabled	1	L						R	lead	: Er	nab	led																			
D	RW	ENDTX									٧	Vrite	e '1	' to	en	able	e ir	nter	rup	t fo	r e	ver	it El	ND	TX									
			Set	1	L						Ε	nab	le																					
			Disabled	0)						R	lead	: Di	isab	led	i																		
			Enabled	1	L						R	lead	: Er	nab	led																			
E	RW	STARTED									٧	Vrite	e '1	' to	en	able	e ir	nter	rup	t fo	r e	ver	it Si	TAF	RTED)								
			Set	1	L						Ε	nab	le																					
			Disabled	0)						R	lead	: Di	isab	led	ł																		
			Enabled	1	L						R	lead	: Er	nab	led																			

6.13.6.21 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber			31 3	30 2	9 28	3 27	26	25 2	4 2	23 2:	2 2	1 20	19	18	3 17	16	15	14	13	12	11	10	9	8 7	' 6	5 5	4	3	2	1 0
ID														Ε											D	(2	В			Α
Reset	0x000	00000		0	0 0	0	0	0	0 (0	0 0) (0	0	0	0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0 0
ID																															
Α	RW	STOPPED								١	Write	e '1	' to	disa	ble	e int	err	upt	for	eve	ent S	STC	PPE	D							
			Clear	1						[Disab	ble																			
			Disabled	0						F	Read	l: D	isabl	ed																	
			Enabled	1						F	Read	l: Er	nable	ed																	
В	RW	ENDRX								١	Write	e '1	' to	disa	ble	e int	err	upt	for	eve	ent l	ENI	ORX								
			Clear	1						[Disab	ble																			
			Disabled	0						F	Read	l: D	isabl	ed																	
			Enabled	1						F	Read	d: Er	nable	ed																	
С	RW	END								١	Write	e '1	' to	disa	ble	e int	err	upt	for	eve	ent l	ENI)								
			Clear	1						[Disab	ble																			
			Disabled	0						F	Read	l: D	isabl	ed																	
			Enabled	1						F	Read	d: Er	nable	ed																	
D	RW	ENDTX								١	Write	e '1	' to	disa	ble	e int	err	upt	for	eve	ent l	ENI	XTC								
			Clear	1						[Disab	ble																			



Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
Е	RW	STARTED			Write '1' to disable interrupt for event STARTED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.13.6.22 ENABLE

Address offset: 0x500

Enable SPIM

Bit nu	ımber			31 30 2	9 28 27	7 26 25	24 23	3 22 2	21 20	19 1	8 17 1	.6 15	14	13 12	11 :	10 9	8	7	6	5	4	3 2	1	0
ID																						A A	A	Α
Reset	0x000	00000		0 0 0	0 0	0 0	0 0	0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0	0	0	0	0 0	0	0
ID																								
Α	RW	ENABLE					Er	able	or dis	able	SPIM													
			Disabled	0			Di	sable	SPIM															
			Enabled	7			Er	able	SPIM															

6.13.6.23 PSEL.SCK

Address offset: 0x508

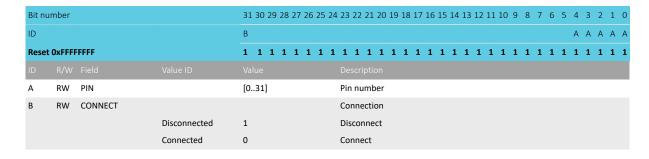
Pin select for SCK

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.13.6.24 PSEL.MOSI

Address offset: 0x50C

Pin select for MOSI signal



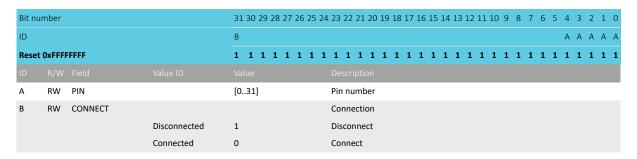




6.13.6.25 PSEL.MISO

Address offset: 0x510

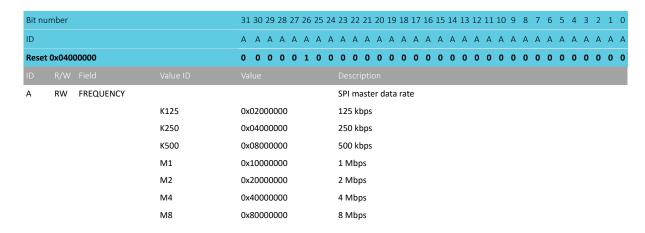
Pin select for MISO signal



6.13.6.26 FREQUENCY

Address offset: 0x524

SPI frequency. Accuracy depends on the HFCLK source selected.



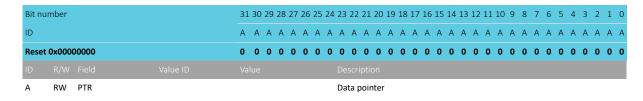
6.13.6.27 RXD

RXD EasyDMA channel

6.13.6.27.1 RXD.PTR

Address offset: 0x534

Data pointer



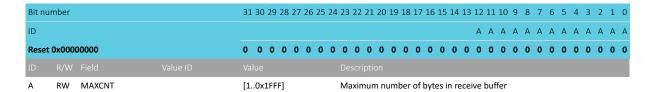
Note: See the memory chapter for details about which memories are available for EasyDMA.

6.13.6.27.2 RXD.MAXCNT

Address offset: 0x538



Maximum number of bytes in receive buffer



6.13.6.27.3 RXD.AMOUNT

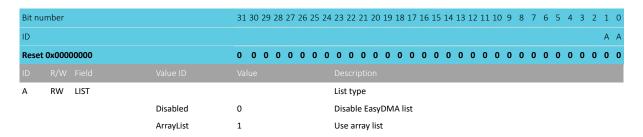
Address offset: 0x53C

Number of bytes transferred in the last transaction

Δ	R	AMOUNT	[10x1FFF]	Number of bytes transferred in the last transaction											
ID															
Reset 0x00000000			0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0											
ID				A A A A A A A A A A A A A A A A A A A											
Bit nu	ımber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1											

6.13.6.27.4 RXD.LIST

Address offset: 0x540 EasyDMA list type



6.13.6.28 TXD

TXD EasyDMA channel

6.13.6.28.1 TXD.PTR

Address offset: 0x544

Data pointer



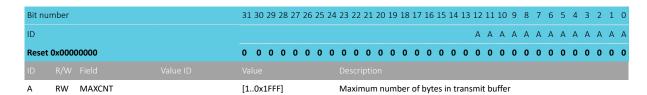
Note: See the memory chapter for details about which memories are available for EasyDMA.



6.13.6.28.2 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



6.13.6.28.3 TXD.AMOUNT

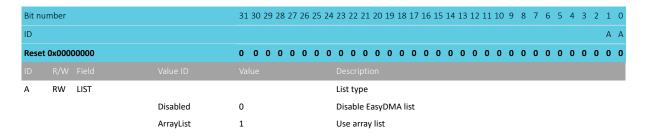
Address offset: 0x54C

Number of bytes transferred in the last transaction

Δ	R	AMOUNT		[1 Ox1FFF]	Number of bytes transferred in the last transaction											
ID																
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0											
ID					A A A A A A A A A A A A A A A A A A A											
Bit number				31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0											

6.13.6.28.4 TXD.LIST

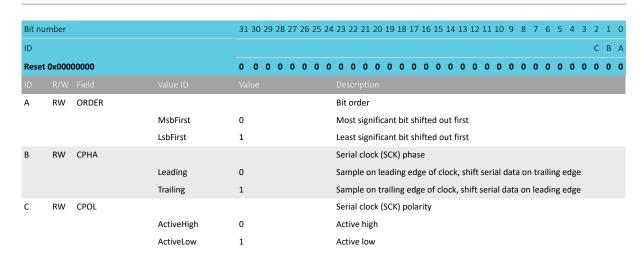
Address offset: 0x550 EasyDMA list type



6.13.6.29 CONFIG

Address offset: 0x554 Configuration register

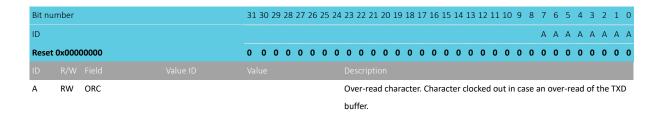




6.13.6.30 ORC

Address offset: 0x5C0

Over-read character. Character clocked out in case an over-read of the TXD buffer.



6.13.7 Electrical specification

6.13.7.1 SPIM master interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIM}	Bit rates for SPIM ¹⁶			8	Mbps
t _{SPIM,START}	Time from START task to transmission started		1		μs

6.13.7.2 Serial Peripheral Interface Master (SPIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIM,CSCK}	SCK period		125		ns
t _{SPIM,RSCK,LD}	SCK rise time, standard drive ^a			t _{RF,25pF}	
t _{SPIM,RSCK,HD}	SCK rise time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,FSCK,LD}	SCK fall time, standard drive ^a			t _{RF,25pF}	
t _{SPIM,FSCK,HD}	SCK fall time, high drive ^a			t _{HRF,25pF}	
t _{SPIM,WHSCK}	SCK high time ^a	(0.5*t _{CSCK})			
		- t _{RSCK}			
t _{SPIM,WLSCK}	SCK low time ^a	(0.5*t _{CSCK})			
		$-t_{FSCK}$			
t _{SPIM,SUMI}	MISO to CLK edge setup time	19			ns
t _{SPIM,HMI}	CLK edge to MISO hold time	18			ns

¹⁶ High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.



^a At 25pF load, including GPIO pin capacitance, see GPIO spec.

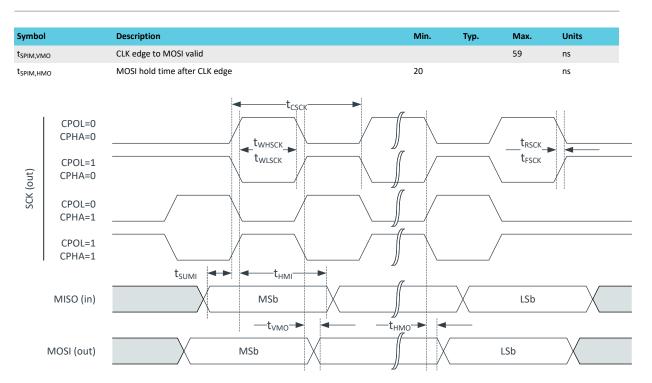


Figure 75: SPIM timing diagram

6.14 SPIS — Serial peripheral interface slave with EasyDMA

SPI slave (SPIS) is implemented with EasyDMA support for ultra low power serial communication from an external SPI master. EasyDMA in conjunction with hardware-based semaphore mechanisms removes all real-time requirements associated with controlling the SPI slave from a low priority CPU execution context.

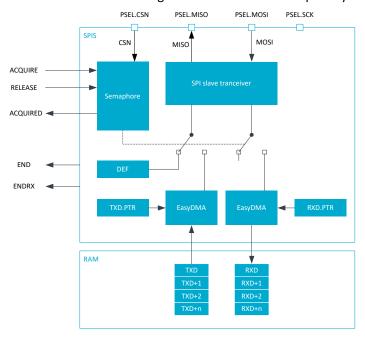


Figure 76: SPI slave

The SPIS supports SPI modes 0 through 3. The CONFIG register allows setting CPOL and CPHA appropriately.



Mode	Clock polarity	Clock phase
	CPOL	СРНА
SPI_MODE0	0 (Active High)	0 (Sample on Leading)
SPI_MODE1	0 (Active High)	1 (Sample on Trailing)
SPI_MODE2	1 (Active Low)	0 (Sample on Leading)
SPI_MODE3	1 (Active Low)	1 (Sample on Trailing)

Table 34: SPI modes

6.14.1 Shared resources

The SPI slave shares registers and other resources with other peripherals that have the same ID as the SPI slave. Therefore, you must disable all peripherals that have the same ID as the SPI slave before the SPI slave can be configured and used.

Disabling a peripheral that has the same ID as the SPI slave will not reset any of the registers that are shared with the SPI slave. It is important to configure all relevant SPI slave registers explicitly to secure that it operates correctly.

The Instantiation table in Instantiation on page 25 shows which peripherals have the same ID as the SPI slave.

6.14.2 EasyDMA

The SPIS implements EasyDMA for accessing RAM without CPU involvement.

The SPIS peripheral implements the following EasyDMA channels:

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 35: SPIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 43.

If RXD.MAXCNT is larger than TXD.MAXCNT, the remaining transmitted bytes will contain the value defined in the ORC register.

The END event indicates that EasyDMA has finished accessing the buffer in RAM.

6.14.3 SPI slave operation

SPI slave uses two memory pointers, RXD.PTR and TXD.PTR, that point to the RXD buffer (receive buffer) and TXD buffer (transmit buffer) respectively. Since these buffers are located in RAM, which can be accessed by both the SPI slave and the CPU, a hardware based semaphore mechanism is implemented to enable safe sharing.

Before the CPU can safely update the RXD.PTR and TXD.PTR pointers it must first acquire the SPI semaphore. The CPU can acquire the semaphore by triggering the ACQUIRE task and then receiving the ACQUIRED event. When the CPU has updated the RXD.PTR and TXD.PTR pointers the CPU must release the semaphore before the SPI slave will be able to acquire it.

The CPU releases the semaphore by triggering the RELEASE task, this is illustrated in SPI transaction when shortcut between END and ACQUIRE is enabled on page 243. Triggering the RELEASE task when the semaphore is not granted to the CPU will have no effect. See Semaphore operation on page 244 for more information



If the CPU is not able to reconfigure the TXD.PTR and RXD.PTR between granted transactions, the same TX data will be clocked out and the RX buffers will be overwritten. To prevent this from happening, the END_ACQUIRE shortcut can be used. With this shortcut enabled the semaphore will be handed over to the CPU automatically after the granted transaction has completed, giving the CPU the ability to update the TXPTR and RXPTR between every granted transaction.

The ENDRX event is generated when the RX buffer has been filled.

The RXD.MAXCNT register specifies the maximum number of bytes the SPI slave can receive in one granted transaction. If the SPI slave receives more than RXD.MAXCNT number of bytes, an OVERFLOW will be indicated in the STATUS register and the incoming bytes will be discarded.

The TXD.MAXCNT parameter specifies the maximum number of bytes the SPI slave can transmit in one granted transaction. If the SPI slave is forced to transmit more than TXD.MAXCNT number of bytes, an OVERREAD will be indicated in the STATUS register and the ORC character will be clocked out.

The RXD.AMOUNT and TXD.AMOUNT registers are updated when a granted transaction is completed. The TXD.AMOUNT register indicates how many bytes were read from the TX buffer in the last transaction, that is, ORC (over-read) characters are not included in this number. Similarly, the RXD.AMOUNT register indicates how many bytes were written into the RX buffer in the last transaction.

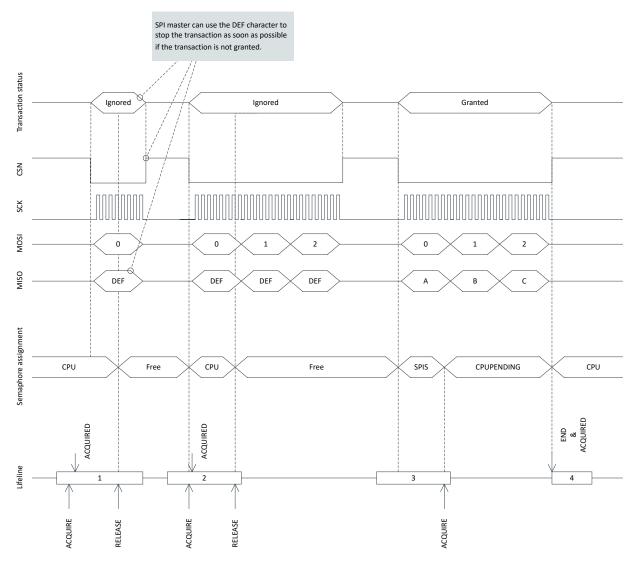


Figure 77: SPI transaction when shortcut between END and ACQUIRE is enabled



6.14.4 Semaphore operation

The semaphore is a mechanism implemented inside the SPI slave that prevents simultaneous access to the data buffers by the SPI slave and CPU.

The semaphore is by default assigned to the CPU after the SPI slave is enabled. No ACQUIRED event will be generated for this initial semaphore handover. An ACQUIRED event will be generated immediately if the ACQUIRE task is triggered while the semaphore is assigned to the CPU. The figure SPI semaphore FSM on page 244 illustrates the transitions between states in the semaphore based on the relevant tasks and events.

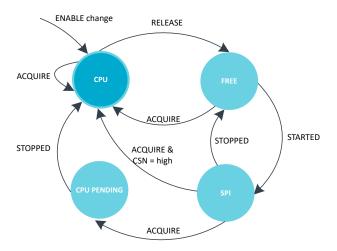


Figure 78: SPI semaphore FSM

Note: The semaphore mechanism does not, at any time, prevent the CPU from performing read or write access to the RXD.PTR register, the TXD.PTR registers, or the RAM that these pointers are pointing to. The semaphore is only telling when these can be updated by the CPU so that safe sharing is achieved.

The SPI slave will try to acquire the semaphore when STARTED event is detected, the event also indicates that CSN is currently low. If the SPI slave does not manage to acquire the semaphore at this point (i.e., it is under CPU's control), the transaction will be ignored. This means that all incoming data on MOSI will be discarded, and the DEF (default) character will be clocked out on the MISO line throughout the whole transaction. This will also be the case even if the semaphore is released by the CPU during the transaction. In case of a race condition where the CPU and the SPI slave try to acquire the semaphore at the same time, as illustrated in lifeline item 2 in figure SPI transaction when shortcut between END and ACQUIRE is enabled on page 243, the semaphore will be granted to the CPU.

If the SPI slave acquires the semaphore, the transaction will be granted. The incoming data on MOSI will be stored in the RXD buffer and the data in the TXD buffer will be clocked out on MISO.

When a granted transaction is completed and CSN goes high, the SPI slave will automatically release the semaphore and generate the END event.

As long as the semaphore is available, the SPI slave can be granted multiple transactions one after the other.

If the CPU tries to acquire the semaphore while it is assigned to the SPI slave, an immediate handover will not be granted. However, the semaphore will be handed over to the CPU as soon as the SPI slave has released the semaphore after the granted transaction is completed. If the END_ACQUIRE shortcut is enabled and the CPU has triggered the ACQUIRE task during a granted transaction, only one ACQUIRE request will be served following the END event.



6.14.5 Pin configuration

The CSN, SCK, MOSI, and MISO signals associated with the SPI slave are mapped to physical pins according to the configuration specified in the PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers respectively. If the CONNECT field of any of these registers is set to Disconnected, the associated SPI slave signal will not be connected to any physical pins.

The PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO registers and their configurations are only used as long as the SPI slave is enabled, and retained only as long as the device is in System ON mode, see POWER — Power control on page 63 chapter for more information about power modes. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.CSN, PSEL.SCK, PSEL.MOSI, and PSEL.MISO must only be configured when the SPI slave is disabled.

To secure correct behavior in the SPI slave, the pins used by the SPI slave must be configured in the GPIO peripheral as described in GPIO configuration before enabling peripheral on page 245 before enabling the SPI slave. This is to secure that the pins used by the SPI slave are driven correctly if the SPI slave itself is temporarily disabled, or if the device temporarily enters System OFF. This configuration must be retained in the GPIO for the selected I/Os as long as the SPI slave is to be recognized by an external SPI master.

The MISO line is set in high impedance as long as the SPI slave is not selected with CSN.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

SPI signal	SPI pin	Direction	Output value Comment
CSN	As specified in PSEL.CSN	Input	Not applicable
SCK	As specified in PSEL.SCK	Input	Not applicable
MOSI	As specified in PSEL.MOSI	Input	Not applicable
MISO	As specified in PSEL.MISO	Input	Not applicable Emulates that the SPI slave is not selected.

Table 36: GPIO configuration before enabling peripheral

6.14.6 Registers

Instances

Instance	Base address	TrustZone			Split access	Description				
		Мар	Att	DMA						
SPISO : S	0x50008000	US	NS	SA	No	SPI slave 0				
SPISO : NS	0x40008000	US	INS	SA	NO	SPI Slave U				
SPIS1:S	0x50009000	US	NS	SA	No	SPI slave 1				
SPIS1 : NS	0x40009000	03	INS	3A	INO	SPI Slave 1				
SPIS2 : S	0x5000A000	US	NS	SA	No	SPI slave 2				
SPIS2 : NS	0x4000A000	US	INS	SA	NO	SPI Slave 2				
SPIS3 : S	0x5000B000	US	NS	SA	No	SPI slave 3				
SPIS3 : NS	0x4000B000	US	CNI	SA	INO	ori siave o				

Register overview

Register	Offset	TZ	Description
TASKS_ACQUIRE	0x024		Acquire SPI semaphore
TASKS_RELEASE	0x028		Release SPI semaphore, enabling the SPI slave to acquire it
SUBSCRIBE_ACQUIRE	0x0A4		Subscribe configuration for task ACQUIRE



Register	Offset	TZ	Description
SUBSCRIBE_RELEASE	0x0A8		Subscribe configuration for task RELEASE
EVENTS_END	0x104		Granted transaction completed
EVENTS_ENDRX	0x110		End of RXD buffer reached
EVENTS_ACQUIRED	0x128		Semaphore acquired
PUBLISH_END	0x184		Publish configuration for event END
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_ACQUIRED	0x1A8		Publish configuration for event ACQUIRED
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
SEMSTAT	0x400		Semaphore status register
STATUS	0x440		Status from last transaction
ENABLE	0x500		Enable SPI slave
PSEL.SCK	0x508		Pin select for SCK
PSEL.MISO	0x50C		Pin select for MISO signal
PSEL.MOSI	0x510		Pin select for MOSI signal
PSEL.CSN	0x514		Pin select for CSN signal
RXD.PTR	0x534		RXD data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes received in last granted transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		TXD data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transmitted in last granted transaction
TXD.LIST	0x550		EasyDMA list type
CONFIG	0x554		Configuration register
DEF	0x55C		Default character. Character clocked out in case of an ignored transaction.
ORC	0x5C0		Over-read character

6.14.6.1 TASKS_ACQUIRE

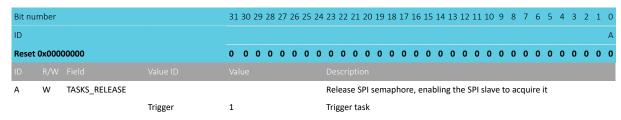
Address offset: 0x024 Acquire SPI semaphore

Bit no	umber			31	30 2	29 2	8 2	7 20	6 25	24	- 23	22	21 2	20 1	9 1	8 17	16	15	14	13 1	.2 1	1 1	0 9	8	7	6	5	4	3	2 1	1 0
ID																															Α
Rese	Reset 0x00000000				0	0 (0 (0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 () (0 0
ID																															
Α	W	TASKS_ACQUIRE							Acquire SPI semaphore																						
			Trigger	1					Trigger task																						

6.14.6.2 TASKS_RELEASE

Address offset: 0x028

Release SPI semaphore, enabling the SPI slave to acquire it



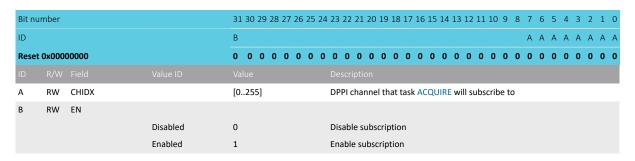




6.14.6.3 SUBSCRIBE_ACQUIRE

Address offset: 0x0A4

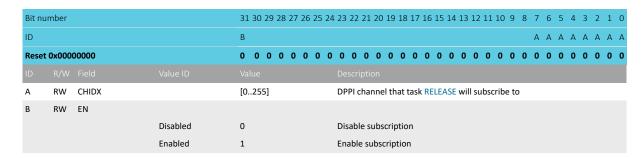
Subscribe configuration for task ACQUIRE



6.14.6.4 SUBSCRIBE_RELEASE

Address offset: 0x0A8

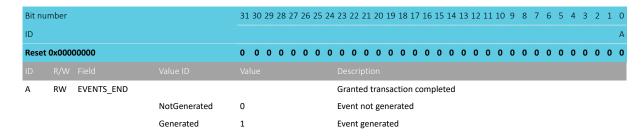
Subscribe configuration for task RELEASE



6.14.6.5 EVENTS END

Address offset: 0x104

Granted transaction completed



6.14.6.6 EVENTS ENDRX

Address offset: 0x110

End of RXD buffer reached



Bit nun	mber			31 30 2	9 28 27	' 26 25	24 2	23 22	2 21 2	0 19	18 17	7 16 1	15 14	13 1	2 11	10 !	9 8	7	6	5	4	3 2	1 ()
ID																							A	
Reset (0x0000	00000		0 0 0	0 0	0 0	0 (0 0	0 (0 0	0 0	0	0 0	0 (0	0	0 0	0	0	0	0	0 0	0 ()
ID																								
Α	RW	EVENTS_ENDRX					Е	nd o	f RXD	buff	er rea	ched												
			NotGenerated	0			Е	vent	not g	gener	ated													
			Generated	1			Е	vent	gene	rated	i													

6.14.6.7 EVENTS_ACQUIRED

Address offset: 0x128 Semaphore acquired

Bit nu	mber			31 30 29	28 27 2	26 25 2	4 23	22 21	. 20 1	.9 18	17 1	6 15	14	13 12	11 1	0 9	8	7	6	5 4	1 3	2	1 0
ID																							А
Reset	0x000	00000		0 0 0	0 0	0 0	0 0	0 0	0 (0 0	0	0 0	0	0 0	0	0	0	0	0	0 (0	0	0 0
ID																							
Α	RW	EVENTS_ACQUIRED					Ser	napho	ore ac	quire	ed												
			NotGenerated	0			Eve	nt no	t gen	erate	d												
			Generated	1			Eve	nt ge	nerat	ed													

6.14.6.8 PUBLISH_END

Address offset: 0x184

Publish configuration for event END

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event END will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.14.6.9 PUBLISH_ENDRX

Address offset: 0x190

Publish configuration for event ENDRX

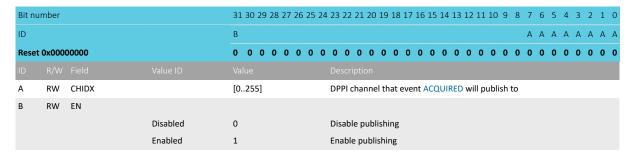
Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event ENDRX will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.14.6.10 PUBLISH_ACQUIRED

Address offset: 0x1A8



Publish configuration for event ACQUIRED



6.14.6.11 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit no	umber			31 30 29 28 27 26 25 24	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID					А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	END_ACQUIRE			Shortcut between event END and task ACQUIRE
			Disabled	0	Disable shortcut
			Enabled	1	Enable shortcut

6.14.6.12 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	END			Write '1' to enable interrupt for event END
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to enable interrupt for event ENDRX
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	ACQUIRED			Write '1' to enable interrupt for event ACQUIRED
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.14.6.13 INTENCLR

Address offset: 0x308

Disable interrupt



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					C B A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
					Description
Α	RW	END			Write '1' to disable interrupt for event END
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	ENDRX			Write '1' to disable interrupt for event ENDRX
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	ACQUIRED			Write '1' to disable interrupt for event ACQUIRED
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.14.6.14 SEMSTAT

Address offset: 0x400 Semaphore status register

Bit n	umber			31 30 29 28 27 26	5 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A A
Rese	t 0x000	00001		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	R	SEMSTAT			Semaphore status
			Free	0	Semaphore is free
			CPU	1	Semaphore is assigned to CPU
			SPIS	2	Semaphore is assigned to SPI slave
			CPUPending	3	Semaphore is assigned to SPI but a handover to the CPU is pending

6.14.6.15 STATUS

Address offset: 0x440

Status from last transaction

Note: Individual bits are cleared by writing a '1' to the bits that shall be cleared

Bit nu	ımber			31 3	0 29 :	28 27	7 26	25 2	4 23	3 22	21	20 1	19 18	8 17	16 3	l5 1	4 13	12	11 :	10 9	8	7	6	5	4	3 2	2 1	1 0
ID																											E	ВА
Reset	t 0x000	00000		0 (0	0 0	0	0 0	0	0	0	0	0 0	0	0	0 0	0	0	0	0 0	0	0	0	0	0	0 0) (0 0
ID																												
Α	RW	OVERREAD							TX	(but	ffer	ove	r-rea	ad de	etect	ed,	and	prev	ent	ed								
			NotPresent	0					Re	ad:	err	or no	ot pr	reser	nt													
			Present	1					Re	ad:	err	or pr	rese	nt														
			Clear	1					W	rite:	: cle	ar e	rror	on v	vritir	ng '1	'											
В	RW	OVERFLOW							RX	(but	ffer	ove	rflov	v de	tecte	d, a	nd p	reve	ente	d								
			NotPresent	0					Re	ad:	err	or no	ot pr	reser	nt													
			Present	1					Re	ad:	err	or pr	rese	nt														
			Clear	1					W	rite:	: cle	ar e	rror	on v	vritir	ng '1												

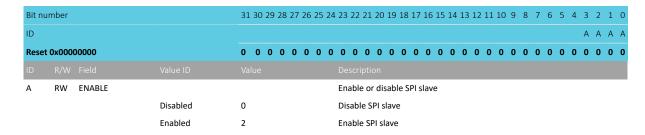




6.14.6.16 ENABLE

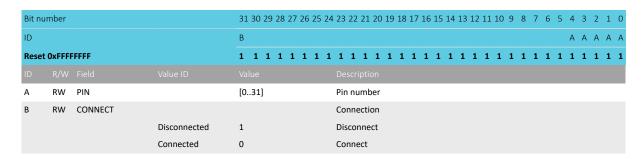
Address offset: 0x500

Enable SPI slave



6.14.6.17 PSEL.SCK

Address offset: 0x508
Pin select for SCK



6.14.6.18 PSEL.MISO

Address offset: 0x50C

Pin select for MISO signal

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	ААААА
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.14.6.19 PSEL.MOSI

Address offset: 0x510

Pin select for MOSI signal



Bit nu	mber			31 3	0 29 :	28 27	7 26	25 2	4 23	3 22	21 20	0 19	18	17	16 1	5 14	1 13	12	11 1	.0 !	9 8	7	6	5	4	3 2	. 1	0
ID				В																					Α	A A	A	Α
Reset	0xFFFI	FFFF		1 1	l 1	1 1	1	1	1 1	1	1 1	. 1	1	1	1 :	1 1	1	1	1	1	L 1	1	1	1	1	1 1	1	1
ID																												
Α	RW	PIN		[03	1]				Pii	n nı	ımber	r																
В	RW	CONNECT							Co	onne	ection																	
			Disconnected	1					Di	scoi	nnect																	
			Connected	0					Co	onne	ect																	

6.14.6.20 PSEL.CSN

Address offset: 0x514

Pin select for CSN signal

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.14.6.21 RXD.PTR

Address offset: 0x534

RXD data pointer

Bit nu	mber			31	30	29	28	27 2	26 2	5 2	24 2	23 2	22 :	21	20 :	19 1	l8 1	7 16	5 15	14	13	12	11	10	9	8	7	6	5 -	4 3	2	1	0
ID				Α	Α	Α	Α	Α	A A	4	Α.	Α	Α	Α	Α	Α.	A A	A A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α.	Α,	Д А	Α	Α	Α
Reset	0x000	00000		0	0	0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0	0
ID																																	
Α	RW	PTR									F	RXE) da	ta	poiı	nter																	

See the Memory chapter for details about which memories are available for EasyDMA.

6.14.6.22 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer

Bit nu	umber	31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A A A A A A A A A A A A A
Reset	t 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			
Α	RW MAXCNT	[10x1FFF]	Maximum number of bytes in receive buffer

6.14.6.23 RXD.AMOUNT

Address offset: 0x53C

Number of bytes received in last granted transaction

ID A A A A A A A A A A A A A A A A A A A
ID A A A A A A A A A A A A A A A A A A A
St 30 29 20 27 20 23 24 23 22 21 20 19 10 17 10 13 14 13 12 11 10 9 6 7 0 3 4 3 2 1
Bit number 31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.14.6.24 RXD.LIST

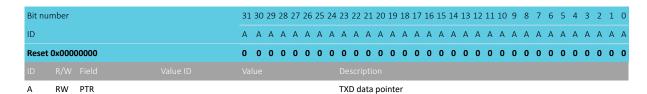
Address offset: 0x540 EasyDMA list type

Bit nu	umber			31 30 29	28 27	26 25	24 23	22 2	1 20	19 1	8 17	16 15	5 14	13 13	2 11	10	9	8	7 6	5 5	4	3	2	1 0
ID																								А А
Reset	t 0x000	00000		0 0 0	0 0	0 0	0 0	0 (0	0 0	0	0 0	0	0 0	0	0	0	0 () (0	0	0	0	0 0
ID																								
Α	RW	LIST					Lis	t type	9															
			Disabled	0			Di	sable	Easy	OMA	list													
			ArrayList	1			Us	e arra	ay list															

6.14.6.25 TXD.PTR

Address offset: 0x544

TXD data pointer

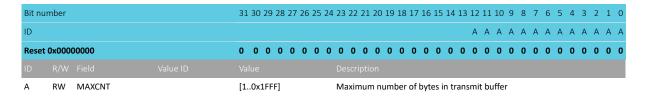


See the Memory chapter for details about which memories are available for EasyDMA.

6.14.6.26 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



6.14.6.27 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transmitted in last granted transaction



Reset	กรดดด	00000		0 0				_				_		_		_	_		_	_	_	_	0 0	0 0
· · · · · · · · · · · · · · · · · · ·	. UNUUU	00000		0 0	0 0	0 0	0 0	U	0 0	, 0	0 0	U	0 0	U	0 0	U	U	U U	U	U	U	U	0 0	0 0
ID		Field	Value ID	Value	0 0	0 0	0 0		script		0 0	Ü	0 0	U	0 0	U	U	0 0	U	U	Ü	Ü	0 0	

6.14.6.28 TXD.LIST

Address offset: 0x550 EasyDMA list type

Bit n	umber		31 30 29 28 27 2	6 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				АА
Rese	t 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW LIST			List type
		Disabled	0	Disable EasyDMA list
		ArrayList	1	Use array list

6.14.6.29 CONFIG

Address offset: 0x554 Configuration register

Bit nu				31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	
ID					СВА	
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID					Description	
Α	RW	ORDER			Bit order	
			MsbFirst	0	Most significant bit shifted out first	
			LsbFirst	1	Least significant bit shifted out first	
В	RW	СРНА			Serial clock (SCK) phase	
			Leading	0	Sample on leading edge of clock, shift serial data on trailing edge	
			Trailing	1	Sample on trailing edge of clock, shift serial data on leading edge	
С	RW	CPOL		Serial clock (SCK) polarity		
			ActiveHigh	0 Active high		
			ActiveLow	1	Active low	

6.14.6.30 DEF

Address offset: 0x55C

Default character. Character clocked out in case of an ignored transaction.

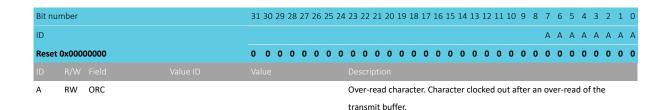
Bit n	umber	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A A A A A A
Rese	t 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			Description
Α	RW DEF		Default character. Character clocked out in case of an ignored transaction.

6.14.6.31 ORC

Address offset: 0x5C0



Over-read character



6.14.7 Electrical specification

6.14.7.1 SPIS slave interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{SPIS}	Bit rates for SPIS ¹⁷			8 ¹⁸	Mbps
t _{SPIS,START}	Time from RELEASE task to receive/transmit (CSN active)		0.125		μs

6.14.7.2 Serial Peripheral Interface Slave (SPIS) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{SPIS,CSCKIN}	SCK input period	125			ns
t _{SPIS,RFSCKIN}	SCK input rise/fall time			30	ns
t _{SPIS,WHSCKIN}	SCK input high time	30			ns
t _{SPIS,WLSCKIN}	SCK input low time	30			ns
t _{SPIS,SUCSN}	CSN to CLK setup time	1000			ns
t _{SPIS,HCSN}	CLK to CSN hold time	2000			ns
t _{SPIS,ASA}	CSN to MISO driven	0			ns
t _{SPIS,ASO}	CSN to MISO valid ^a			1000	ns
t _{SPIS,DISSO}	CSN to MISO disabled ^a			68	ns
t _{SPIS,CWH}	CSN inactive time	300			ns
t _{SPIS,VSO}	CLK edge to MISO valid			59	ns
t _{SPIS,HSO}	MISO hold time after CLK edge	20 ¹⁹			ns
t _{SPIS,SUSI}	MOSI to CLK edge setup time	19			ns
t _{SPIS,HSI}	CLK edge to MOSI hold time	18			ns

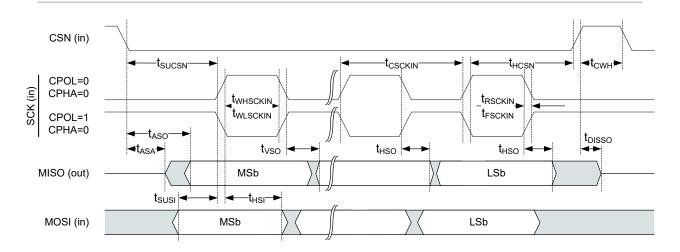


 $^{^{17}\,}$ High bit rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

The actual maximum data rate depends on the master's CLK to MISO and MOSI setup and hold timings

^a At 25pF load, including GPIO capacitance, see GPIO spec.

¹⁹ This is to ensure compatibility to SPI masters sampling MISO on the same edge as MOSI is output



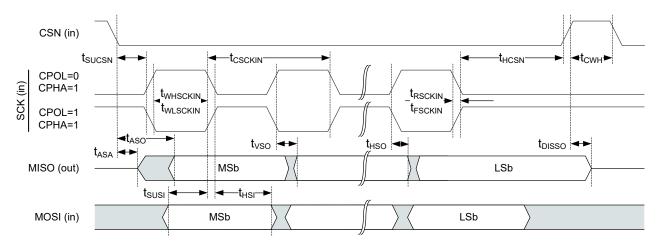


Figure 79: SPIS timing diagram

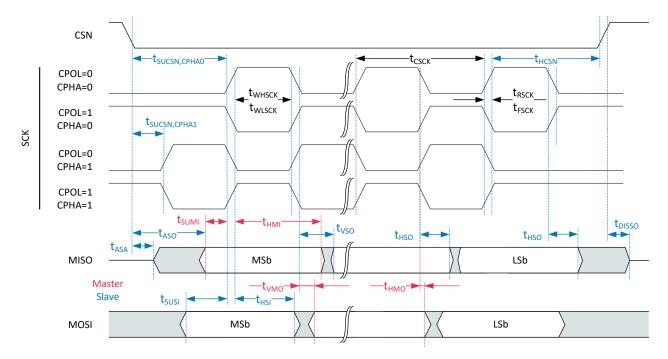


Figure 80: Common SPIM and SPIS timing diagram



6.15 SPU — System protection unit

SPU is the central point in the system to control access to memories, peripherals and other resources.

Listed here are the main features of the SPU:

- ARM TrustZone support, allowing definition of secure, non-secure and non-secure callable memory regions
- Extended ARMTrustZone, protecting memory regions and peripherals from non-CPU devices like EasyDMA transfer
- Pin access protection, preventing non-secure code and peripherals from accessing secure pin resources
- DPPI access protection, realized by preventing non-secure code and peripherals to publish from or subscribe to secured DPPI channels
- External domain access protection, controlling access rights from other MCUs

6.15.1 General concepts

SPU provides a register interface to control the various internal logic blocks that monitor access to memory-mapped slave devices (RAM, flash, peripherals, etc) and other resources (device pins, DPPI channels, etc).

For memory-mapped devices like RAM, flash and peripherals, the internal logic checks the address and attributes (e.g. read, write, execute, secure) of the incoming transfer to block it if necessary. Whether a secure resource can be accessed by a given master is defined:

For a CPU-type master

By the security state of the CPU and the security state reported by the SPU, for the address in the bus transfer

For a non-CPU master

By the security attribute of the master that initiates the transfer, defined by a SPU register The Simplified view of the protection of RAM, flash and peripherals using SPU on page 257 shows a simplified view of the SPU registers controlling several internal modules.

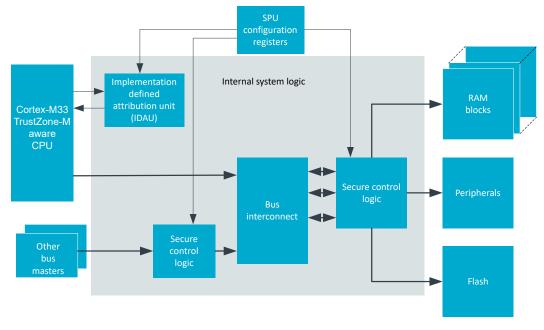


Figure 81: Simplified view of the protection of RAM, flash and peripherals using SPU

The protection logic implements a read-as-zero/write-ignore (RAZ/WI) policy:



- A blocked read operation will always return a zero value on the bus, preventing information leak
- A write operation to a forbidden region or peripheral will be ignored

An error is reported through dedicated error signals. For security state violations from an M33 master this will be a SecureFault exception, for other violations this will be an SPU event. The SPU event can be configured to generate an interrupt towards the CPU.

Other resources like pins and DPPI channels are protected by comparing the security attributes of the protected resource with the security attribute of the peripheral that wants to access it. The SPU is the only place where those security attributes can be configured.

6.15.1.1 Special considerations for ARM TrustZone for Cortex-M enabled system

For a ARM TrustZone for Cortex-M enabled CPU, the SPU also controls custom logic.

Custom logic is shown as the implementation defined attribution unit (IDAU) in figure Simplified view of the protection of RAM, flash and peripherals using SPU on page 257. Full support is provided for:

- ARM TrustZone for Cortex-M related instructions, like test target (TT) for reporting the security attributes of a region
- Non-secure callable (NSC) regions, to implement secure entry points from non-secure code

The SPU provides the necessary registers to configure the security attributes for memory regions and peripherals. However, as a requirement to use the SPU, the secure attribution unit (SAU) needs to be disabled and all memory set as non-secure in the ARM core. This will allow the SPU to control the IDAU and set the security attribution of all addresses as originally intended.

6.15.2 Flash access control

The flash memory space is divided in regions, each of them with configurable permissions settings.

The flash memory space is divided into 32 regions of 32 KiB.

For each region, four different types of permissions can be configured:

Read

Allows data read access to the region. Note that code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write or page erase access to the region

Execute

Allows code fetch from this region, even if data read is disabled

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a flash region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked by using the FLASHREGION[n].PERM.LOCK bit, to prevent subsequent modifications.

Note that the debugger is able to step through execute-protected memory regions.

The following figure shows the flash memory space and the divided regions:



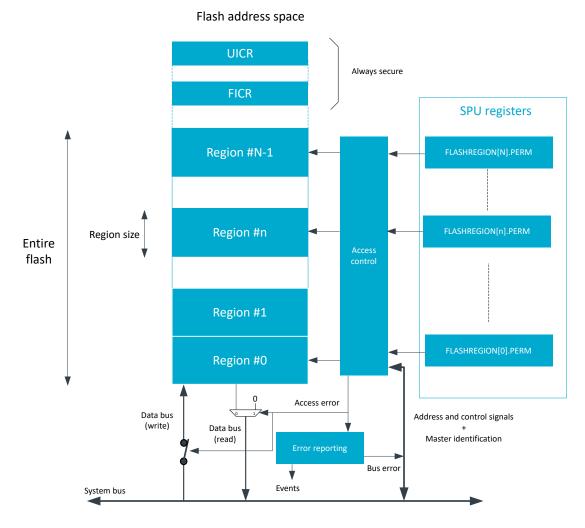


Figure 82: Definition of the N=32 regions, each of 32 KiB, in the flash memory space

6.15.2.1 Non-secure callable (NSC) region definition in flash

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- FLASHNSC[n].REGION, used to select the secure region that will contain the NSC sub-region
- FLASHNSC[n].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



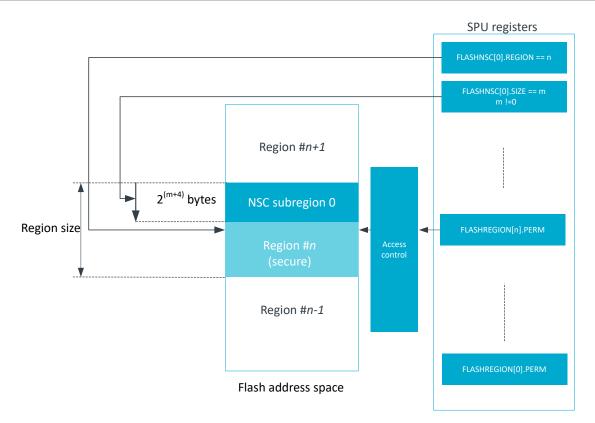


Figure 83: Non-secure callable region definition in the flash memory space

The NSC sub-region will only be defined if:

- FLASHNSC[i].SIZE value is non zero
- FLASHNSC[i].REGION defines a secure region

If FLASHNSC[i].REGION and FLASHNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of FLASHNSC[i].SIZE and FLASHNSC[j].SIZE.

If FLASHNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.2.2 Flash access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the flash ports:

- · The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the
 master. Moreover, the SPU will receive an event that can optionally trigger an interrupt towards the
 CPU.
- SecureFault exception will be triggered if security violation is detected for access from Cortex-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex-M33
- FLASHACCERR event will be triggered if any access violations are detected for all master types except for Cortex-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:

NORDIC

Master type	Security violation	Read/Write/Execute protection violation
Cortex-M33	SecureFault exception	BusFault exception, FLASHACCERR event
EasyDMA	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event
Other masters	RAZ/WI, FLASHACCERR event	RAZ/WI, FLASHACCERR event

Table 37: Error reporting for flash access errors

For a Cortex-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.2.3 UICR and FICR protections

The user information configuration registers (UICR) and factory information configuration registers (FICR) are always considered as secure. FICR registers are read-only. UICR registers can be read and written by secure code only.

Writing new values to user information configuration registers must follow the procedure described in NVMC — Non-volatile memory controller on page 29. Code execution from FICR and UICR address spaces will always be reported as access violation, an exception to this rule applies during a debug session.

6.15.3 RAM access control

The RAM memory space is divided in regions, each of them with configurable permissions settings.

The RAM memory space is divided into 32 regions of 8 KiB.

For each region, four different types of permissions can be configured:

Read

Allows data read access to the region. Code fetch from this region is not controlled by the read permission but by the execute permission described below.

Write

Allows write access to the region

Execute

Allows code fetch from this region

Secure

Allows only bus accesses with the security attribute set to access the region

Permissions can be set independently. For example, it is possible to configure a RAM region to be accessible only through secure transfer, being read-only (no write allowed) and non-executable (no code fetch allowed). For each region, permissions can be set and then locked to prevent subsequent modifications by using the RAMREGION[n].PERM.LOCK bit.

The following figure shows the RAM memory space and the devided regions:



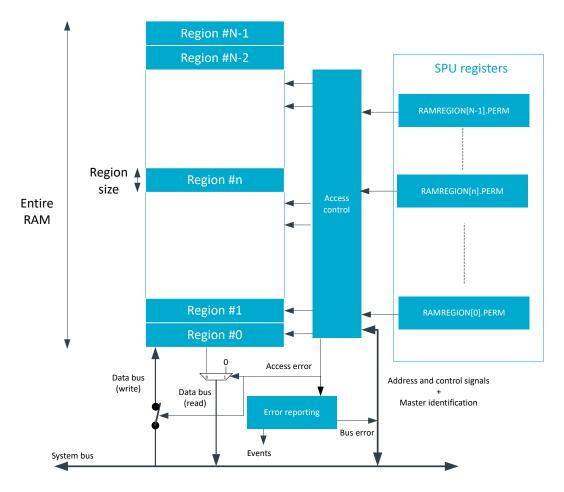


Figure 84: Definition of the N=32 regions, each of 8 KiB, in the RAM memory space

6.15.3.1 Non-secure callable (NSC) region definition in RAM

The SPU provides support for the definition of non-secure callable (NSC) sub-regions to allow non-secure to secure function calls.

A non-secure callable sub-region can only exist within an existing secure region and its definition is done using two registers:

- RAMNSC[n].REGION, used to select the secure region that will contain the NSC sub-region
- RAMNSC[n].SIZE, used to define the size of the NSC sub-region within the secure region

The NSC sub-region will be defined from the highest address in that region, going downwards. Figure below illustrates the NSC sub-regions and the registers used for their definition:



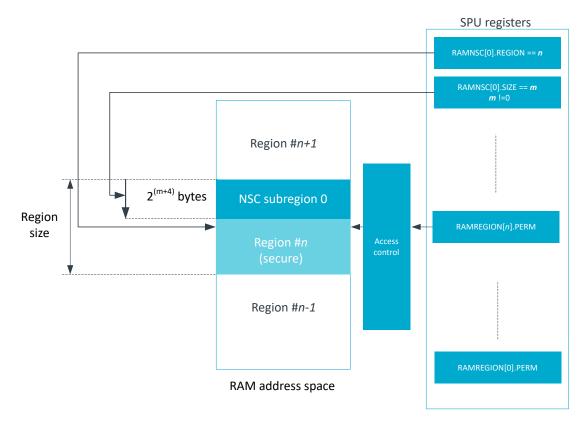


Figure 85: Non-secure callable region definition in the RAM memory space

The NSC sub-region will only be defined if:

- RAMNSC[i].SIZE value is non zero
- RAMNSC[i].REGION defines a secure region

If RAMNSC[i].REGION and RAMNSC[j].REGION have the same value, there is only one sub-region defined as NSC, with the size given by the maximum of RAMNSC[i].SIZE and RAMNSC[j].SIZE.

If RAMNSC[i].REGION defines a non-secure region, then there is no non-secure callable region defined and the selected region stays non-secure.

6.15.3.2 RAM access error reporting

The SPU and the logic controlled by it will respond with a certain behavior once an access violation is detected.

The following will happen once the logic controlled by the SPU detects an access violation on one of the RAM ports:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero
- Feedback will be sent to the master through specific bus error signals, if this is supported by the master
- · SecureFault exception will be triggered if security violation is detected for access from Cortex-M33
- BusFault exception will be triggered when read/write/execute protection violation is detected for Cortex-M33. The SPU will also generate an event that can optionally trigger an interrupt towards the CPU.
- RAMACCERR event will be triggered if any access violations are detected for all master types but for Cortex-M33 security violation

The following table summarizes the SPU behavior based on the type of initiator and access violation:



Master type	Security violation	Read/Write/Execute protection violation
Cortex-M33	SecureFault exception	BusFault exception, RAMACCERR event
EasyDMA	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event
Other masters	RAZ/WI, RAMACCERR event	RAZ/WI, RAMACCERR event

Table 38: Error reporting for RAM access errors

For a Cortex-M33 master, the SecureFault exception will take precedence over the BusFault exception if a security violation occurs simultaneously with another type of violation.

6.15.4 Peripheral access control

Access controls are defined by the characteristics of the peripheral.

Peripherals can have their security attribute set as:

Always secure

For a peripheral related to system control

Always non-secure

For some general-purpose peripherals

Configurable

For general-purpose peripherals that may be configured for secure only access

The full list of peripherals and their corresponding security attributes can be found in Memory map on page 23. For each peripheral with ID n, PERIPHID[n]. PERM will show whether the security attribute for this peripheral is configurable or not.

If not hardcoded, the security attribute can configured using the PERIPHID[id].PERM.

At reset, all user-selectable and split security peripherals are set to be secure, with secure DMA where present.

Secure code can access both secure peripherals and non-secure peripherals.

The nRF9161 does not support runtime security configuration of peripherals. It is thus, advisable that all security settings on peripherals are set during boot time. Doing so will ensure the desired system security configuration is deployed simultaneously system-wide.

6.15.4.1 Peripherals with split security

Peripherals with split security are defined to handle use-cases when both secure and non-secure code needs to control the same resource.

When peripherals with split security have their security attribute set to non-secure, access to specific registers and bitfields within some registers is dependent on the security attribute of the bus transfer. For example, some registers will not be accessible for a non-secure transfer.

When peripherals with split security have their security attribute set to secure, then only secure transfers can access their registers.

See Instantiation on page 25 for an overview of split security peripherals. Respective peripheral chapters explain the specific security behavior of each peripheral.

6.15.4.2 Peripheral address mapping

Peripherals that have non-secure security mapping have their address starting with 0x4XXX_XXXX. Peripherals that have secure security mapping have their address starting with 0x5XXX_XXXX.

NORDIC*

Peripherals with a user-selectable security mapping are available at an address starting with:

- 0x4XXX XXXX, if the peripheral security attribute is set to non-secure
- 0x5XXX_XXXX, if the peripheral security attribute is set to secure

Note: Accesses to the 0x4XXX_XXXX address range from secure or non-secure code for a peripheral marked as secure will result in a bus-error.

Secure code accessing the 0x5XXX_XXXX address range of a peripheral marked as non-secure will also result in a bus-error.

Peripherals with a split security mapping are available at an address starting with:

- 0x4XXX_XXXX for non-secure access and 0x5XXX_XXXX for secure access, if the peripheral security attribute is set to non-secure
 - Secure registers in the 0x4XXX_XXXX range are not visible for secure or non-secure code, and an attempt to access such a register will result in write-ignore, read-as-zero behavior
 - Secure code can access both non-secure and secure registers in the 0x5XXX XXXX range
- 0x5XXX_XXXX, if the peripheral security attribute is set to secure

Any attempt to access the 0x5000_0000-0x5FFF_FFFF address range from non-secure code will be ignored and generate a SecureFault exception.

The table below illustrates the address mapping for the three peripheral types, in all possible configurations

Security-features and configuration	Is mapped at 0x4XXX_XXXX?	Is mapped at 0x5XXX_XXXX?
Secure peripheral	No	Yes
Non-secure peripheral	Yes	No
Split-security peripheral, with attribute=secure	No	Yes
Split-security peripheral, with attribute=non-secure	Yes, restricted functionality	Yes

Table 39: Peripheral's address mapping in relation to its security-features and configuration

6.15.4.3 Special considerations for peripherals with DMA master

Peripherals containing a DMA master can be configured so the security attribute of the DMA transfers is different from the security attribute of the peripheral itself. This allows a secure peripheral to do non-secure data transfers to or from the system memories.

The following conditions must be met:

- The DMA field of PERIPHID[n].PERM.SECURITYMAPPING should read as "SeparateAttribute"
- The peripheral itself should be secure (PERIPHID[n].PERM.SECATTR == 1)

Then it is possible to select the security attribute of the DMA transfers using the field DMASEC (PERIPHID[n].PERM.DMASEC == Secure and PERIPHID[n].PERM.DMASEC == NonSecure) in PERIPHID[n].PERM.

6.15.4.4 Peripheral access error reporting

Peripherals send error reports once access violation is detected.

The following will happen if the logic controlled by the SPU detects an access violation on one of the peripherals:

- The faulty transfer will be blocked
- In case of a read transfer, the bus will be driven to zero



- Feedback is sent to the master through specific bus error signals, if this is supported by the master. If the master is a processor supporting ARM TrustZone for Cortex-M, a SecureFault exception will be generated for security related errors.
- · The PERIPHACCERR event will be triggered

6.15.5 Pin access control

Access to device pins can be controlled by the SPU. A pin can be declared as secure so that only secure peripherals or secure code can access it. Pins declared as non-secure can be accessed by both secure and non-secure peripherals or code.

The security attribute of each pin can be individually configured in SPU's GPIOPORT[n].PERM register. When the secure attribute is set for a pin, only peripherals that have the secure attribute set will be able to read the value of the pin or change it.

Peripherals can select the pin(s) they need access to through their PSEL register(s). If a peripheral has its attribute set to non-secure, but one of its PSEL registers selects a pin with the attribute set to secure, the SPU controlled logic will ensure that the pin selection is not propagated. In addition, the pin value will always be read as zero, to prevent a non-secure peripheral from obtaining a value from a secure pin. Whereas access to other pins with attribute set as non-secure will not be blocked.

Pins can be assigned to other domains than the application domain by changing the MCUSEL value in the GPIO PIN_CNF[n] register. Domains that do not have a pin assigned to them can neither control that pin nor read its status. Any pin configuration set in a domain that doesn't have ownership of that pin will not take effect until the MCUSEL is updated to assign that pin to the domain. Within each domain, pin access is controlled by that domain's local security configuration and peripheral PSEL registers. This is illustrated in the following figure:

Note: The SPU setting will still count when the APP domain accesses its local GPIO peripheral, as local registers are still writable even though MCUSEL is set to a different domain. Any changes in the APP GPIO peripheral done to a GPIO controlled by another domain will not affect the GPIO pad until MCUSEL is changed to APP.

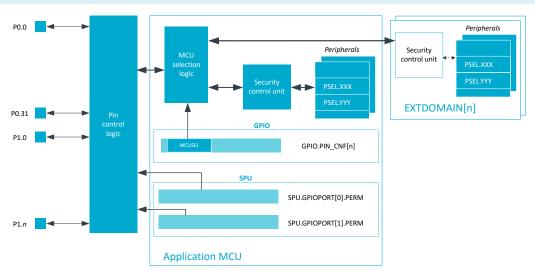


Figure 86: Pin access for domains other than the application domain

6.15.6 DPPI access control

Access to DPPI channels can be restricted. A channel can be declared as secure so that only secure peripherals can access it.



The security attribute of a DPPI channel is configured in DPPI[n].PERM (n=0..0) on page 274. When the secure attribute is set for a channel, only peripherals that have the secure attribute set will be able to publish events to this channel or subscribe to this channel to receive tasks.

The DPPI controller peripheral (DPPIC) is a split security peripheral, i.e., its security behavior depends on the security attributes of both the DPPIC and the accessing party. See Special considerations regarding the DPPIC configuration registers on page 267 for more information about the DPPIC security behavior.

If a non-secure peripheral wants to publish an event on a secure DPPI channel, the channel will ignore the event. If a non-secure peripheral subscribes to a secure DPPI channel, it will not receive any events from this channel. The following figure illustrates the principle of operation of the security logic for a subscribed channel:

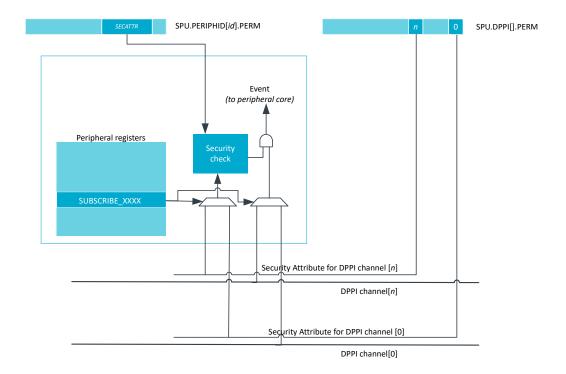


Figure 87: Subscribed channel security concept

No error reporting mechanism is associated with the DPPI access control logic.

6.15.6.1 Special considerations regarding the DPPIC configuration registers

DPPI channels can be enabled, disabled and grouped through the DPPI controller (DPPIC). The DPPIC is a split-security peripheral, and handles both secure and non-secure accesses.

A non-secure peripheral access will only be able to configure and control DPPI channels defined as non-secure in SPU's DPPI[n].PERM register(s). A secure peripheral access can control all DPPI channels, independently of the configuration in the DPPI[n].PERM register(s).

The DPPIC allows the creation of group of channels to be able to enable or disable all channels within a group simultaneously. The security attribute of a group of channels (secure or non-secure) is defined as follows:

- If all channels (enabled or not) in the group are non-secure, then the group is considered non-secure
- If at least one of the channels (enabled or not) in the group is secure, then the group is considered

A non-secure access to a DPPIC register, or a bitfield controlling a channel marked as secure in DPPI[n].PERM register(s), will be ignored:

Write accesses will have no effect



Read will always return a zero value

No exceptions are thrown when a non-secure access targets a register or bitfield controlling a secure channel. For example, if the bit i is set in the DPPI[n].PERM register (declaring the DPPI channel i as secure), then:

- Non-secure write accesses to registers CHEN, CHENSET and CHENCLR will not be able to write to bit i of those registers
- Non-secure write accesses to registers TASK_CHG[j].EN and TASK_CHG[j].DIS will be ignored if the channel group j contains at least one channel defined as secure (it can be the channel i itself or any channel declared as secured)
- Non-secure read accesses to registers CHEN, CHENSET and CHENCLR will always read zero for the bit at position i

For the channel configuration registers (DPPIC.CHG[n]), access from non-secure code is only possible if the included channels are all non-secure, whether the channels are enabled or not. If a DPPIC.CHG[g] register included one or more secure channels, then the group gis considered as secure and only a secure transfer can read or write DPPIC.CHG[g]. A non-secure write will be ignored and a non-secure read will return zero.

The DPPIC can subscribe to secure or non-secure channels through SUBSCRIBE_CHG[n] registers in order to trigger task for enabling or disabling groups of channels. But an event from a non-secure channel will be ignored if the group subscribing to this channel is secure. An event from a secure channel can trigger both secure and non-secure tasks.

6.15.7 External domain access control

Other domains with their own CPUs can access peripherals, flash, and RAM memories. The SPU allows controlling accesses from those bus masters.

The external domains can access application MCU memories and peripherals. External domains are assigned security attributes as described in register EXTDOMAIN[n].PERM.

Domain	Capability register	Permission register				
LTE modem	Modem is always a non-secure domain	Not applicable				

Table 40: Register mapping for external domains

The figure below illustrates how the security control units are used to assign security attributes to transfers initiated by the external domains:



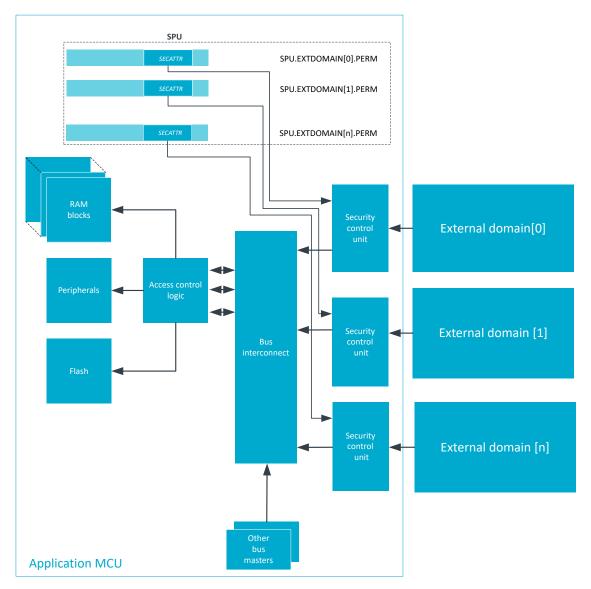


Figure 88: Access control from external domains

6.15.8 TrustZone for Cortex-M ID allocation

Flash and RAM regions, as well as non-secure and secure peripherals, are assigned unique TrustZone IDs.

Note: TrustZone ID should not be confounded with the peripheral ID used to identify peripherals.

The table below shows the TrustZone ID allocation:

Regions	TrustZone Cortex-M ID
Flash regions 031	031
RAM regions 015	6479
Non-secure peripherals	253
Secure peripherals	254

Table 41: TrustZone ID allocation



6.15.9 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
SPU	0x50003000	HF	S	NA	No	System Protection Unit

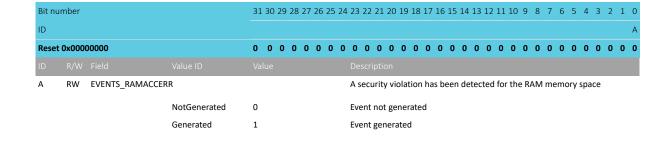
Register overview

Register	Offset	TZ	Description
EVENTS_RAMACCERR	0x100		A security violation has been detected for the RAM memory space
EVENTS_FLASHACCERR	0x104		A security violation has been detected for the flash memory space
EVENTS_PERIPHACCERR	0x108		A security violation has been detected on one or several peripherals
PUBLISH_RAMACCERR	0x180		Publish configuration for event RAMACCERR
PUBLISH_FLASHACCERR	0x184		Publish configuration for event FLASHACCERR
PUBLISH_PERIPHACCERR	0x188		Publish configuration for event PERIPHACCERR
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
CAP	0x400		Show implemented features for the current device
EXTDOMAIN[n].PERM	0x440		Access for bus access generated from the external domain n
			List capabilities of the external domain n
DPPI[n].PERM	0x480		Select between secure and non-secure attribute for the DPPI channels.
DPPI[n].LOCK	0x484		Prevent further modification of the corresponding PERM register
GPIOPORT[n].PERM	0x4C0		Select between secure and non-secure attribute for pins 0 to 31 of port n.
			This register is retained.
GPIOPORT[n].LOCK	0x4C4		Prevent further modification of the corresponding PERM register
FLASHNSC[n].REGION	0x500		Define which flash region can contain the non-secure callable (NSC) region n
FLASHNSC[n].SIZE	0x504		Define the size of the non-secure callable (NSC) region n
RAMNSC[n].REGION	0x540		Define which RAM region can contain the non-secure callable (NSC) region n
RAMNSC[n].SIZE	0x544		Define the size of the non-secure callable (NSC) region n
FLASHREGION[n].PERM	0x600		Access permissions for flash region n
RAMREGION[n].PERM	0x700		Access permissions for RAM region n
PERIPHID[n].PERM	0x800		List capabilities and access permissions for the peripheral with ID n

6.15.9.1 EVENTS_RAMACCERR

Address offset: 0x100

A security violation has been detected for the RAM memory space



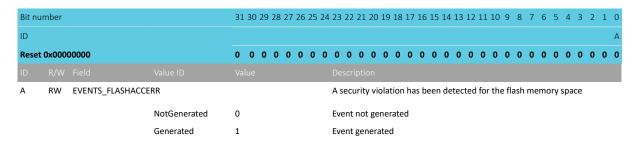




6.15.9.2 EVENTS_FLASHACCERR

Address offset: 0x104

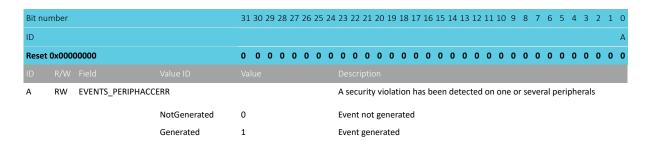
A security violation has been detected for the flash memory space



6.15.9.3 EVENTS_PERIPHACCERR

Address offset: 0x108

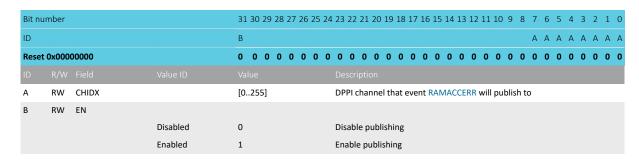
A security violation has been detected on one or several peripherals



6.15.9.4 PUBLISH RAMACCERR

Address offset: 0x180

Publish configuration for event RAMACCERR



6.15.9.5 PUBLISH FLASHACCERR

Address offset: 0x184

Publish configuration for event FLASHACCERR



Bit nu	mber			31 30 29	28 27	7 26	25 24	4 23	22 2	21 20	0 19	18	17 1	16 1	5 14	13	12	11 1	0 9	8	7	6	5	4	3	2 :	L O
ID				В																	Α	Α	Α	Α	Α .	Δ ,	4 A
Reset	0x000	00000		0 0 0	0 0	0	0 0	0	0	0 0	0	0	0	0 (0	0	0	0 (0	0	0	0	0	0	0	0 (0
ID																											
Α	RW	CHIDX		[0255] DPPI							el th	nat e	even	t FL	ASH	ACC	ERR	will	pub	lish	to						
В	RW	EN																									
			Disabled	0				Dis	able	pub	olish	ing															
			Enabled	1				Ena	able	pub	lishi	ng															

6.15.9.6 PUBLISH_PERIPHACCERR

Address offset: 0x188

Publish configuration for event PERIPHACCERR

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event PERIPHACCERR will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.15.9.7 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	RAMACCERR			Enable or disable interrupt for event RAMACCERR
			Disabled	0	Disable
			Enabled	1	Enable
В	RW	FLASHACCERR			Enable or disable interrupt for event FLASHACCERR
			Disabled	0	Disable
			Enabled	1	Enable
С	RW	PERIPHACCERR			Enable or disable interrupt for event PERIPHACCERR
			Disabled	0	Disable
			Enabled	1	Enable

6.15.9.8 INTENSET

Address offset: 0x304

Enable interrupt



Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	RAMACCERR			Write '1' to enable interrupt for event RAMACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	FLASHACCERR			Write '1' to enable interrupt for event FLASHACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	PERIPHACCERR			Write '1' to enable interrupt for event PERIPHACCERR
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.15.9.9 INTENCLR

Address offset: 0x308

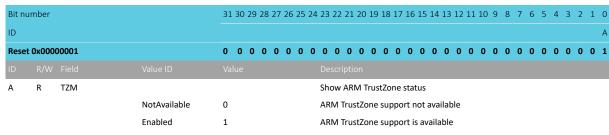
Disable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	RAMACCERR			Write '1' to disable interrupt for event RAMACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	FLASHACCERR			Write '1' to disable interrupt for event FLASHACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	PERIPHACCERR			Write '1' to disable interrupt for event PERIPHACCERR
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.15.9.10 CAP

Address offset: 0x400

Show implemented features for the current device





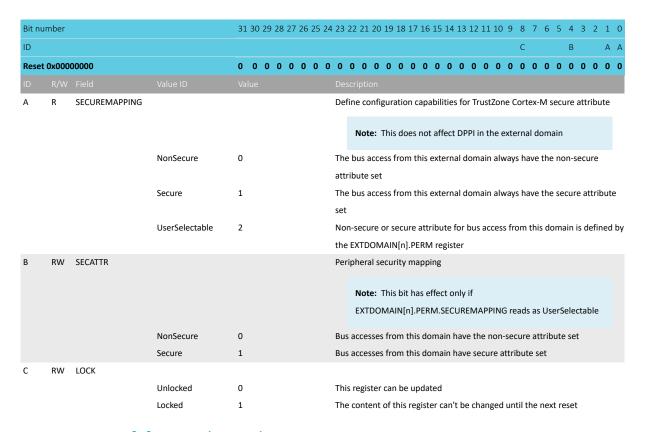


6.15.9.11 EXTDOMAIN[n].PERM (n=0..0)

Address offset: $0x440 + (n \times 0x4)$

Access for bus access generated from the external domain n

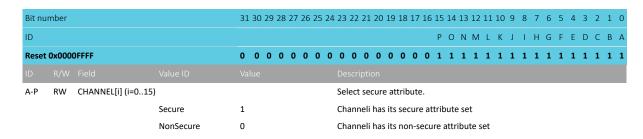
List capabilities of the external domain n



6.15.9.12 DPPI[n].PERM (n=0..0)

Address offset: $0x480 + (n \times 0x8)$

Select between secure and non-secure attribute for the DPPI channels.

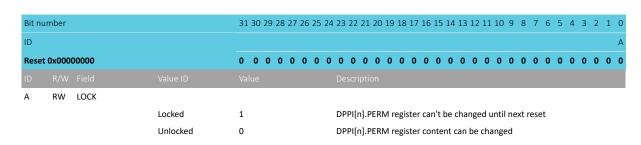


6.15.9.13 DPPI[n].LOCK (n=0..0)

Address offset: 0x484 + (n × 0x8)

Prevent further modification of the corresponding PERM register



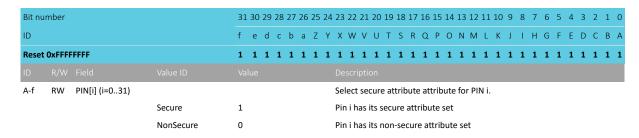


6.15.9.14 GPIOPORT[n].PERM (n=0..0) (Retained)

Address offset: $0x4C0 + (n \times 0x8)$

Select between secure and non-secure attribute for pins 0 to 31 of port n.

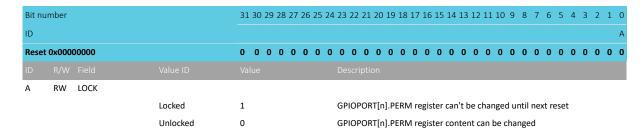
This register is retained.



6.15.9.15 GPIOPORT[n].LOCK (n=0..0)

Address offset: $0x4C4 + (n \times 0x8)$

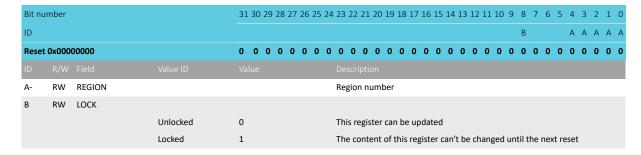
Prevent further modification of the corresponding PERM register



6.15.9.16 FLASHNSC[n].REGION (n=0..1)

Address offset: $0x500 + (n \times 0x8)$

Define which flash region can contain the non-secure callable (NSC) region n



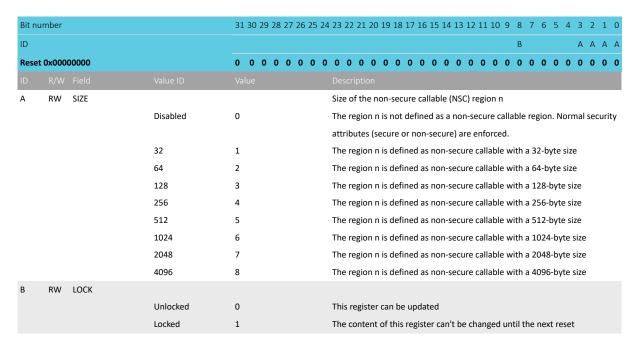
6.15.9.17 FLASHNSC[n].SIZE (n=0..1)

Address offset: $0x504 + (n \times 0x8)$





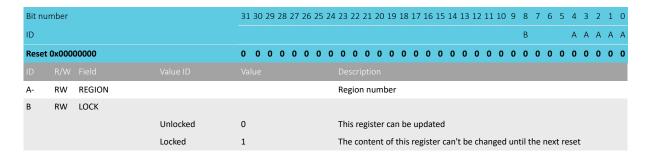
Define the size of the non-secure callable (NSC) region n



6.15.9.18 RAMNSC[n].REGION (n=0..1)

Address offset: $0x540 + (n \times 0x8)$

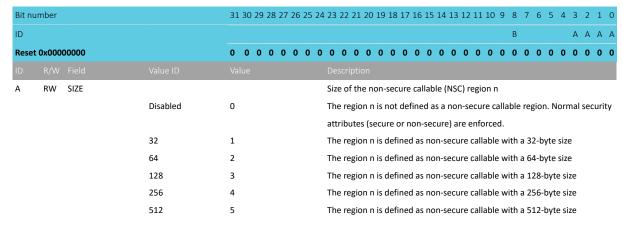
Define which RAM region can contain the non-secure callable (NSC) region n



6.15.9.19 RAMNSC[n].SIZE (n=0..1)

Address offset: $0x544 + (n \times 0x8)$

Define the size of the non-secure callable (NSC) region n





Bit number		31 30 29 28 27	7 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			B AAAA
Reset 0x00000000		0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field			Description
	1024	6	The region n is defined as non-secure callable with a 1024-byte size
	2048	7	The region n is defined as non-secure callable with a 2048-byte size
	4096	8	The region n is defined as non-secure callable with a 4096-byte size
B RW LOCK			
	Unlocked	0	This register can be updated
	Locked	1	The content of this register can't be changed until the next reset

6.15.9.20 FLASHREGION[n].PERM (n=0..31)

Address offset: $0x600 + (n \times 0x4)$ Access permissions for flash region n

Rit n	umber			31 :	30 2	9 2	g 27	26	25.2) / ·	י או	2 2	21 2	o∩ 1	19 1	Q 1 ⁻	7 16	15	1/1	13	12 1	1 1	n 9	8	7	6	5	1	2 2	1	Λ
	umber			51.	JO 2	J 21	0 27	20	25 2		2J Z.		21 2	10 1		.0 1	, 10	13	17	13	12 1		.0 5	_		-	<i>J</i>				^
ID																								Ε				D	(: B	Α
Rese	t 0x0000	00017		0	0 (0	0	0	0	0	0 0) (0	0 (0 (0	0	0	0	0	0 () (0 0	0	0	0	0	1) 1	. 1	1
ID																															
Α	RW	EXECUTE								(Conf	figu	ure	inst	ruc	tion	fet	ch p	erm	nissi	ons	fro	m fla	sh	regi	on r	n				
			Enable	1						1	Allov	w ir	nstr	uct	ion	feto	hes	fro	m fl	ash	regi	on	n								
			Disable	0						E	Blocl	k in	nstr	ucti	ion	fetc	hes	froi	n fl	ash	regi	on	n								
В	RW	WRITE								(Conf	figu	ure	writ	te p	erm	issi	on f	or f	lash	reg	ion	n								
			Enable	1						,	Allov	w w	write	e op	pera	ation	ı to	reg	on	n											
			Disable	0						1	3locl	k w	vrite	е ор	oera	tior	to	regi	on i	า											
С	RW	READ								(Conf	figu	ure	read	d pe	ermi	issic	ns f	or f	lasł	n reg	ion	n								
			Enable	1						1	Allov	w re	ead	Іор	era	tion	fro	m fl	ash	reg	ion i	ı									
			Disable	0						E	Blocl	k re	ead	оре	era	tion	froi	n fl	ash	reg	ion r	1									
D	RW	SECATTR								9	Secu	ırity	y at	trib	ute	for	flas	h re	gio	n n											
			Non_Secure	0						ı	lash	n re	egio	n n	sec	curit	y at	trib	ute	is n	on-s	eci	ure								
			Secure	1						ı	lash	n re	egio	n n	sec	curit	y at	trib	ute	is s	ecur	е									
E	RW	LOCK																													
			Unlocked	0						1	Γhis	reg	giste	er c	an l	be u	pda	ted													
			Locked	1						1	Γhe (cor	nter	nt o	f th	is re	gist	er c	an't	: be	cha	nge	ed ur	ntil 1	he	next	t re	set			

6.15.9.21 RAMREGION[n].PERM (n=0..31)

Address offset: $0x700 + (n \times 0x4)$ Access permissions for RAM region n

Bit nu	umber			31	30 29	28	27	26	25 2	24 2	3 2	2 2	1 20	0 19	9 18	8 17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																									Ε				D		С	В А
Reset	t 0x000	00017		0	0 0	0	0	0	0	0 0) (0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	1 1
ID																																
Α	RW	EXECUTE								С	ont	figu	re ii	nstr	uct	ion	feto	ch p	err	nis	sior	ıs fr	om	RA	Мr	egi	on I	n				
			Enable	1						Α	llo	w in	ıstrı	ucti	on	fetc	hes	fro	m f	RAN	∕l r∈	gio	n n									
			Disable	0						В	loc	k in	stru	ıctio	on 1	fetc	hes	fro	m F	RAN	∕l re	gio	n n									
В	RW	WRITE								С	ont	figu	re v	vrite	e p	erm	issi	on 1	for	RAI	VI re	egic	n n									
			Enable	1						Α	llo	w w	rite	ор	era	tior	to	RA	M r	egi	on i	า										
			Disable	0						В	loc	k w	rite	ор	era	tion	to	RAI	M r	egio	on r	1										
С	RW	READ								С	ont	figu	re r	ead	l pe	rmi	ssio	ns	for	RAI	M r	egio	on n	1								
			Enable	1						Α	llo	w re	ead	оре	erat	ion	fro	n R	AN	1 re	gio	n n										



Bit nu	ımber			31	30	29 2	8 2	27 2	6 2	5 24	23	22	21 2	20 1	19 1	l8 1	7 1	6 1	5 1	4 1	.3 :	12	11	10	9	8	7	6	5	4	3	2	1	0
ID																										Ε				D		С	В	Α
Reset	0x000	00017		0	0	0 (0	0 (0	0	0	0	0	0	0	0 () () () () (0	0	0	0	0	0	0	0	0	1	0	1	1	1
ID																																		
			Disable	0							Blo	ock r	ead	Іор	era	tion	fro	m	RAI	Иr	egi	on	n											
D	RW	SECATTR									Sec	curit	y at	ttrib	oute	e for	RA	M	reg	ion	n													
			Non_Secure	0							RA	M re	egic	n n	sec	curi	ty a	ttri	but	e is	s no	on-	sec	ure	2									
			Secure	1							RA	M re	egic	n n	sec	curi	ty a	ttri	but	e is	s se	cu	re											
E	RW	LOCK																																
			Unlocked	0							Thi	is re	gist	er c	an	be ι	pdı	ate	d															
			Locked	1							The	е со	nte	nt o	f th	nis r	egis	ter	cai	n't	be	cha	ang	ed	unt	til tl	he i	next	t re	eset				

6.15.9.22 PERIPHID[n].PERM (n=0..66)

Address offset: $0x800 + (n \times 0x4)$

List capabilities and access permissions for the peripheral with ID n

Note: Reset values are unique per peripheral instantiation. Please refer to the peripheral instantiation table. Entries not listed in the instantiation table are undefined.

Bit nu	ımber			31	30 29	9 28	3 27 2	26	25 2	24	23 2	2 2:	1 20	0 19	18	17	16	15	14 1	13 :	12 1	1 1	10 9	9 :	8 .	7	6	5	4	3	2	1	0
ID				F																					E			D	С	В	В	A	Α
Reset	0x000	00012		0	0 0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0 ()	0 () (0 (0	0	0	1	0	0	1	0
											Desc																						
Α	R	SECUREMAPPING						Т		Т	Defi	ne c	onf	igur	atio	n c	apal	oilit	ties	for	Tru	stZ	one	Со	rte	x-N	∕l se	cu	re a	ttri	but	e	
			NonSecure	0							This	per	iphe	eral	is al	lwa	ys a	cce	ssib	le a	as a	no	n-se	cu	re p	er	iphe	era	ıl				
			Secure	1							This	per	iphe	eral	is al	lwa	ys a	cce	ssib	le a	as a	se	cure	ре	eripl	he	ral						
			UserSelectable	2							Non	-sec	ure	ors	ecu	ire	attri	bu	te fo	or t	his p	er	iphe	eral	l is c	def	ine	d b	y tł	ne			
											PERI	IPHI	D[n].PE	RM	reg	giste	r															
			Split	3							This	per	iphe	eral	imp	len	nent	s t	he s	plit	sec	uri	ty n	nec	har	nisı	n. N	Vor	n-se	cur	e o	r	
											secu	ıre a	ttri	bute	for	th	is pe	erip	her	al i	s de	fin	ed b	y t	he I	PE	RIPH	HID	[n]	.PEI	RM		
											regis	ster.																					
В	R	DMA									Indi	cate	if t	he p	erip	he	ral h	as	DM	A c	apa	bili	ties	an	d if	Ν	MA 1	tra	nsf	er c	an l	be	
											assig	gnec	d to	a di	ffer	ent	sec	uri	ty a	ttril	oute	th	an 1	the	pe	rip	hera	al i	tsel	f			
			NoDMA	0							Peri	phei	ral h	has r	no D	M	A ca	pak	oility	1													
			NoSeparateAttribute	1							Peri	phei	ral h	has [OM/	A aı	nd D	MA	A tra	nst	ers	alv	vays	ha	ive 1	the	sar	me	se	curi	ty		
											attri	bute	e as	assi	gne	d t	o th	e p	erip	he	ral												
			SeparateAttribute	2							Peri	phei	ral h	has [)MA	A aı	nd D	MA	\ tra	nsi	ers	car	n ha	ve	a di	ffe	ren	t s	ecu	rity			
											attri	bute	e th	an t	he c	one	ass	ign	ed t	o t	he p	eri	phe	ral									
С	RW	SECATTR									Peri	phei	ral s	secu	rity	ma	ippir	ng															
												No	te.	Thi	s hit	ha	ıs ef	fec	t on	lv i	f												
														HID[NG	rea	ds i	as l	Jse	rSe	lec	tab	le c	r		
												Spl																					
												- "																					
			Secure	1										s ma																			
			NonSecure	0										1APP				erS	elec	tab	le: I	er	iphe	era	lisı	ma	ppe	ed i	in n	on-	sec	ure	!
											peri	phe	ral a	addr	ess	spa	ice.																
											If SE	CUR	REM	1APP	ING	; ==	Spl	it: I	Peri	phe	erali	is n	nap	peo	d in	nc	n-s	ecı	ure	and	l se	cur	e
											peri	phei	ral a	addr	ess	spa	ice.																



Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				F	E DCBBAA
Reset	0x000	00012		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
D	RW	DMASEC			Security attribution for the DMA transfer
					Note: This bit has effect only if PERIPHID[n].PERM.SECATTR is set to secure
			Secure	1	DMA transfers initiated by this peripheral have the secure attribute set
			NonSecure	0	DMA transfers initiated by this peripheral have the non-secure attribute set
E	RW	LOCK			
			Unlocked	0	This register can be updated
			Locked	1	The content of this register can't be changed until the next reset
F	R	PRESENT			Indicate if a peripheral is present with ID n
			NotPresent	0	Peripheral is not present
			IsPresent	1	Peripheral is present

6.16 TIMER — Timer/counter

This peripheral is a general purpose timer designed to keep track of time in user-selective time intervals, it can operate in two modes: timer and counter.

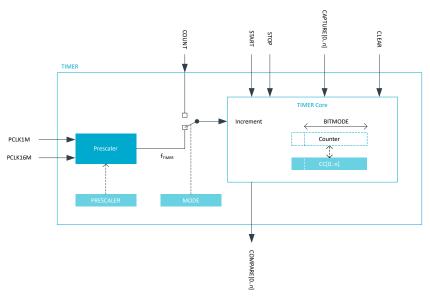


Figure 89: Block schematic for timer/counter

The timer/counter runs on the high-frequency clock source (HFCLK) and includes a four-bit (1/2X) prescaler that can divide the timer input clock from the HFCLK controller. Clock source selection between PCLK16M and PCLK1M is automatic according to TIMER base frequency set by the prescaler. The TIMER base frequency is always given as 16 MHz divided by the prescaler value.

The PPI system allows a TIMER event to trigger a task of any other system peripheral of the device. The PPI system also enables the TIMER task/event features to generate periodic output and PWM signals to any GPIO. The number of input/outputs used at the same time is limited by the number of GPIOTE channels.

TIMER can operate in two modes: Timer mode and Counter mode. In both modes, TIMER is started by triggering the START task, and stopped by triggering the STOP task. After the timer is stopped the timer can resume timing/counting by triggering the START task again. When timing/counting is resumed, the timer will continue from the value it had prior to being stopped.

NOPDIC

In Timer mode, the TIMER's internal Counter register is incremented by one for every tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 279. The timer frequency is derived from PCLK16M as shown in the following example, using the values specified in the PRESCALER register.

```
f_{\text{TIMER}} = 16 \text{ MHz} / (2^{\text{PRESCALER}})
```

When $f_{TIMER} \le 1$ MHz, TIMER will use PCLK1M instead of PCLK16M for reduced power consumption.

In counter mode, the TIMER's internal Counter register is incremented by one each time the COUNT task is triggered, meaning the timer frequency and the prescaler are not utilized in counter mode. Similarly, the COUNT task has no effect in Timer mode.

The TIMER's maximum value is configured by changing the bit-width of the timer in register BITMODE on page 286.

PRESCALER on page 287 and BITMODE on page 286 must only be updated when the timer is stopped. If these registers are updated while the timer is started, unpredictable behavior may occur.

When the timer is incremented beyond its maximum value, the Counter register will overflow and the timer will automatically start over from zero.

The Counter register can be cleared by triggering the CLEAR task. This will explicitly set the internal value to zero.

TIMER implements multiple capture/compare registers.

Independent of prescaler setting, the accuracy of TIMER is equivalent to one tick of the timer frequency f_{TIMER} as illustrated in Block schematic for timer/counter on page 279.

6.16.1 Capture

TIMER implements one capture task for every available capture/compare register.

Every time the CAPTURE[n] task is triggered, the Counter value is copied to the CC[n] register.

6.16.2 Compare

TIMER implements one COMPARE event for every available capture/compare register.

A COMPARE event is generated when the Counter is incremented and then becomes equal to the value specified in one of the capture compare registers. When the Counter value becomes equal to the value specified in a capture compare register CC[n], the corresponding compare event COMPARE[n] is generated.

BITMODE on page 286 specifies how many bits of the Counter register and the capture/compare register that are used when the comparison is performed. Other bits will be ignored.

The COMPARE event can be configured to operate in one-shot mode by configuring the corresponding ONESHOTEN[n] register. COMPARE[n] event is generated the first time the Counter matches CC[n] after CC[n] has been written.

6.16.3 Task delays

After TIMER is started, the CLEAR, COUNT, and STOP tasks are guaranteed to take effect within one clock cycle of the PCLK16M.

6.16.4 Task priority



If the START task and the STOP task are triggered at the same time, meaning within the same period of PCLK16M, the STOP task will be prioritized.

If one or more of the CAPTURE tasks and the CLEAR task is triggered at the same time, that is, within the same period of PCLK16M, the CLEAR task will be prioritized. This means that the CC register for the relevant CAPTURE task will be set to 0.

6.16.5 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
TIMER0 : S	0x5000F000	LIC	NS	NA	No	Timer 0
TIMER0 : NS	0x4000F000	US	INS	NA	NO	Timer 0
TIMER1: S	0x50010000	LIC	NS	NA	No	Timer 1
TIMER1: NS	0x40010000	US	INS	NA	NO	Timer 1
TIMER2 : S	0x50011000	LIC	NS	NA	No	Timer 2
TIMER2 : NS	0x40011000	US	CVI	INA	INU	Timer Z

Register overview

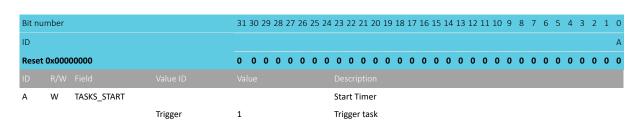
Register	Offset	TZ	Description
TASKS_START	0x000		Start Timer
TASKS_STOP	0x004		Stop Timer
TASKS_COUNT	0x008		Increment Timer (Counter mode only)
TASKS_CLEAR	0x00C		Clear time
TASKS_SHUTDOWN	0x010		Shut down timer
			This register is deprecated.
TASKS_CAPTURE[n]	0x040		Capture Timer value to CC[n] register
SUBSCRIBE_START	0x080		Subscribe configuration for task START
SUBSCRIBE_STOP	0x084		Subscribe configuration for task STOP
SUBSCRIBE_COUNT	0x088		Subscribe configuration for task COUNT
SUBSCRIBE_CLEAR	0x08C		Subscribe configuration for task CLEAR
SUBSCRIBE_SHUTDOWN	0x090		Subscribe configuration for task SHUTDOWN
			This register is deprecated.
SUBSCRIBE_CAPTURE[n]	0x0C0		Subscribe configuration for task CAPTURE[n]
EVENTS_COMPARE[n]	0x140		Compare event on CC[n] match
PUBLISH_COMPARE[n]	0x1C0		Publish configuration for event COMPARE[n]
SHORTS	0x200		Shortcuts between local events and tasks
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
MODE	0x504		Timer mode selection
BITMODE	0x508		Configure the number of bits used by the TIMER
PRESCALER	0x510		Timer prescaler register
ONESHOTEN[n]	0x514		Enable one-shot operation for Capture/Compare channel n
CC[n]	0x540		Capture/Compare register n

6.16.5.1 TASKS_START

Address offset: 0x000

Start Timer

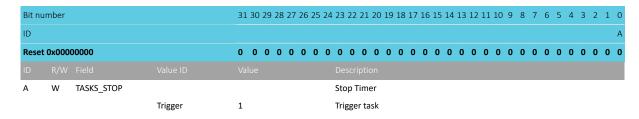




6.16.5.2 TASKS STOP

Address offset: 0x004

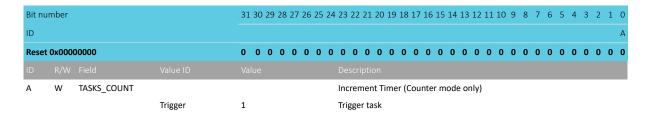
Stop Timer



6.16.5.3 TASKS COUNT

Address offset: 0x008

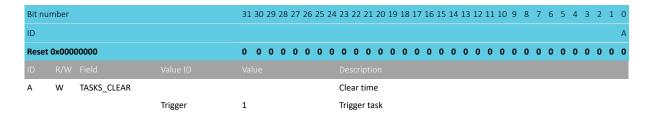
Increment Timer (Counter mode only)



6.16.5.4 TASKS CLEAR

Address offset: 0x00C

Clear time



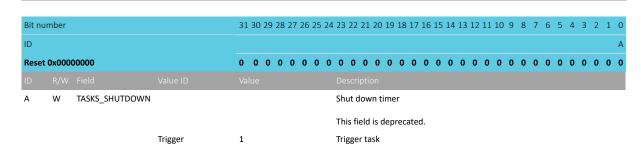
6.16.5.5 TASKS_SHUTDOWN (Deprecated)

Address offset: 0x010

Shut down timer

This register is deprecated.





6.16.5.6 TASKS_CAPTURE[n] (n=0..5)

Address offset: $0x040 + (n \times 0x4)$

Capture Timer value to CC[n] register

Bit nu	ımber			31	30	29	28	27	26 2	25 2	24 2	23 2	22 2	1 2	0 1	9 1	8 17	7 16	5 15	14	13	12	11 :	10 !	9 8	3 7	6	5	4	3	2	1 0
ID																																Α
Reset	t 0x000	00000		0	0	0	0	0	0	0	0	0	0 () () (0 0	0	0	0	0	0	0	0	0 (0 0) (0	0	0	0	0	0 0
ID																																
Α	W	TASKS_CAPTURE									C	Cap	ture	Tir	ner	r val	ue t	to C	C[n] re	gist	er										
			Trigger	1							Т	rig	ger 1	tasl	<																	

6.16.5.7 SUBSCRIBE_START

Address offset: 0x080

Subscribe configuration for task START

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task START will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.16.5.8 SUBSCRIBE_STOP

Address offset: 0x084

Subscribe configuration for task STOP

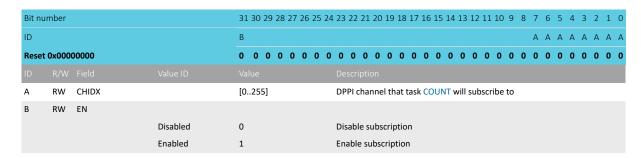
Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.16.5.9 SUBSCRIBE_COUNT

Address offset: 0x088



Subscribe configuration for task COUNT



6.16.5.10 SUBSCRIBE_CLEAR

Address offset: 0x08C

Subscribe configuration for task CLEAR

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task CLEAR will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.16.5.11 SUBSCRIBE_SHUTDOWN (Deprecated)

Address offset: 0x090

Subscribe configuration for task SHUTDOWN

This register is deprecated.

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task SHUTDOWN will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.16.5.12 SUBSCRIBE_CAPTURE[n] (n=0..5)

Address offset: $0x0C0 + (n \times 0x4)$

Subscribe configuration for task ${\sf CAPTURE}[n]$



Bit nu	mber			31 30 29	28 27	26	25 24	- 23 2	22 21	20	19 1	8 17	' 16	15 1	4 1	3 12	11	10 9	8	7	6	5	4	3 2	. 1	0
ID				В																Α	Α	Α	Α	A A	A	Α
Reset	0x0000	00000		0 0 0	0 0	0	0 0	0	0 0	0	0 (0	0	0	0 0	0	0	0 (0	0	0	0	0	0 0	0	0
ID																										
Α	RW	CHIDX		[0255]				DPP	I cha	nnel	that	t tas	k CA	PTU	RE[r	ı] wi	ll su	bscr	ibe t	0						
В	RW	EN																								
			Disabled	0				Disa	ble s	ubso	ripti	ion														
			Enabled	1				Enal	ble s	ubsc	riptio	on														

6.16.5.13 EVENTS_COMPARE[n] (n=0..5)

Address offset: $0x140 + (n \times 0x4)$ Compare event on CC[n] match

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 2	21 20	19 1	.8 17	16 15	5 14	13 1	2 11	10	9 8	7	6	5	4	3 2	2 1	0
ID																					Α
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0	0 0	0 (0 0	0 0	0	0 (0 0	0	0 0	0	0	0	0	0 (0	0
ID																					
Α	RW	EVENTS_COMPARE			Compa	re eve	ent o	n CC[n] ma	atch											
			NotGenerated	0	Event n	not ge	nera	ted													
			Generated	1	Event g	genera	ited														

6.16.5.14 PUBLISH_COMPARE[n] (n=0..5)

Address offset: $0x1C0 + (n \times 0x4)$

Publish configuration for event COMPARE[n]

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event COMPARE[n] will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.16.5.15 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

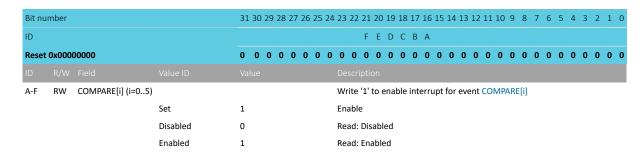
Bit nu	mber			31 3	30	29 2	28	27 2	26	25 2	4 2	23 2	2 2:	1 20	19	9 18	3 17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																					L	K	J	1	Н	G			F	Е	D (С	ВА
Reset	0x000	00000		0	0	0	0	0	0	0 (0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0 0
ID												Description																					
A-F	A-F RW COMPARE[i]_CLEAR (i=05)															een	eve	ent	COI	MPA	ARE	[i] a	nd	task	(CL	EAF	3						
			Disabled	0							[Disal	ole	shoi	rtcı	ut																	
			Enabled	0 D								Enab	le s	hor	tcu	ıt																	
G-L	RW	COMPARE[i]_STOP (i	=05)								9	Shor	tcu	t be	tw	een	eve	ent	COI	MPA	ARE	[i] a	nd	task	ST	OP							
			Disabled	0							[Disal	ole:	shoi	rtcı	ut																	
			Enabled	1							E	Enab	le s	hor	tcu	ıt																	



6.16.5.16 INTENSET

Address offset: 0x304

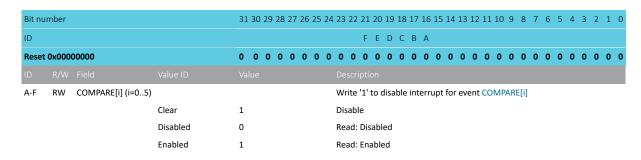
Enable interrupt



6.16.5.17 INTENCLR

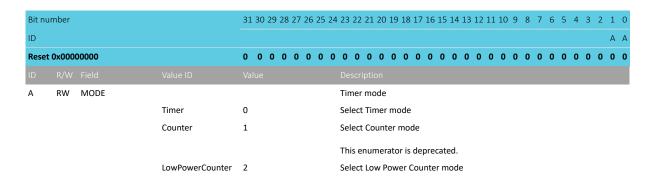
Address offset: 0x308

Disable interrupt



6.16.5.18 MODE

Address offset: 0x504
Timer mode selection



6.16.5.19 BITMODE

Address offset: 0x508

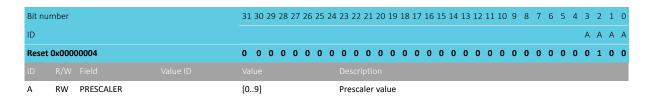
Configure the number of bits used by the TIMER



Bit n	umber			31 30 29 28 27	26 25 24 2	23 22 21 20	19 18 1	7 16 1	5 14	13 12	2 11	10 9	8	7	6	5	4	3 2	1	0
ID																			Α	Α
Rese	t 0x000	00000		0 0 0 0 0	0 0 0	0 0 0 0	0 0 0	0 (0 0	0 0	0	0 0	0	0	0	0	0	0 0	0	0
ID																				
Α	RW	BITMODE			1	Timer bit wi	dth													
			16Bit	0	1	L6 bit timer	bit width	1												
			08Bit	1	8	B bit timer b	it width													
			24Bit	2	2	24 bit timer	bit width	1												
			32Bit	3	3	32 bit timer	bit width	1												

6.16.5.20 PRESCALER

Address offset: 0x510
Timer prescaler register



6.16.5.21 ONESHOTEN[n] (n=0..5)

Address offset: $0x514 + (n \times 0x4)$

Enable one-shot operation for Capture/Compare channel n

Bit nu	ımber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					А
Reset	0x000	00000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	ONESHOTEN			Enable one-shot operation
					Configures the corresponding compare-channel for one-shot operation
			Disable	0	Disable one-shot operation
					Compare event is generated every time the Counter matches CC[n]
			Enable	1	Enable one-shot operation
					Compare event is generated the first time the Counter matches CC[n] after
					CC[n] has been written

6.16.5.22 CC[n] (n=0..5)

Address offset: $0x540 + (n \times 0x4)$ Capture/Compare register n

Bit number 3			31	30	29	28 :	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0	
ID .				Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α.	Α.	А А
Reset 0x00000000				0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																		
Α	RW CC								Capture/Compare value																									

Only the number of bits indicated by BITMODE will be used by the TIMER.



$6.17 \text{ TWIM} - I^2 \text{C}$ compatible two-wire interface master with EasyDMA

TWI master with EasyDMA (TWIM) is a two-wire half-duplex master which can communicate with multiple slave devices connected to the same bus.

Listed here are the main features for TWIM:

- I²C compatible
- Supported baud rates: 100, 250, 400 kbps
- Support for clock stretching (non I²C compliant)
- EasyDMA

The two-wire interface can communicate with a bi-directional wired-AND bus with two lines (SCL, SDA). The protocol makes it possible to interconnect up to 127 individually addressable devices. TWIM is not compatible with CBUS.

The GPIOs used for each two-wire interface line can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

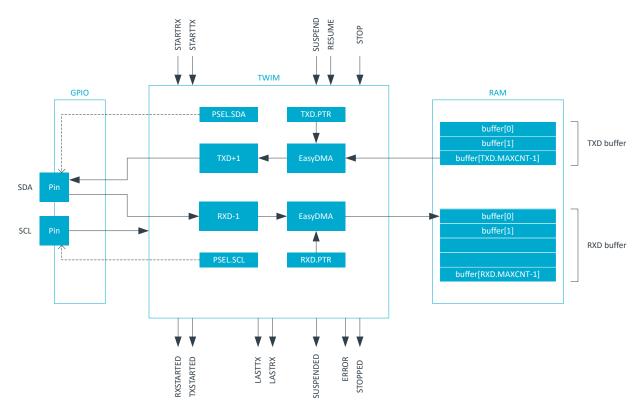


Figure 90: TWI master with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see the following figure. This TWIM is only able to operate as a single master on the TWI bus. Multi-master bus configuration is not supported.



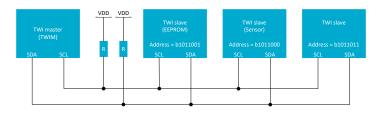


Figure 91: A typical TWI setup comprising one master and three slaves

This TWI master supports clock stretching performed by the slaves. The SCK pulse following a stretched clock cycle may be shorter than specified by the I2C specification.

The TWI master is started by triggering the STARTTX or STARTRX tasks and stopped by triggering the STOP task. The TWI master will generate a STOPPED event when it has stopped following a STOP task.

After the TWI master is started, the STARTTX or STARTRX tasks should not be triggered again until the TWI master has issued a LASTRX, LASTTX, or STOPPED event.

The TWI master can be suspended using the SUSPEND task, this can be used when using the TWI master in a low priority interrupt context. When the TWIM enters suspend state, will automatically issue a SUSPENDED event while performing a continuous clock stretching until it is instructed to resume operation via a RESUME task. The TWI master cannot be stopped while it is suspended, thus the STOP task must be issued after the TWI master has been resumed.

Note: Any ongoing byte transfer will be allowed to complete before the suspend is enforced. A SUSPEND task has no effect unless the TWI master is actively involved in a transfer.

If a NACK is clocked in from the slave, the TWI master will generate an ERROR event.

6.17.1 Shared resources

The TWI master shares registers and other resources with other peripherals that have the same ID as the TWI master. Therefore, you must disable all peripherals that have the same ID as the TWI master before the TWI master can be configured and used.

Disabling a peripheral that has the same ID as the TWI master will not reset any of the registers that are shared with the TWI master. It is therefore important to configure all relevant registers explicitly to secure that the TWI master operates correctly.

The Instantiation table in Instantiation on page 25 shows which peripherals have the same ID as the TWI.

6.17.2 EasyDMA

The TWIM implements EasyDMA for accessing RAM without CPU involvement.

The TWIM peripheral implements the EasyDMA channels found in the following table.

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 42: TWIM EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 43.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.



6.17.3 Master write sequence

A TWI master write sequence is started by triggering the STARTTX task. After the STARTTX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1).

The address must match the address of the slave device that the master wants to write to. The READ/ WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) generated by the slave.

After receiving the ACK bit, the TWI master will clock out the data bytes found in the transmit buffer located in RAM at the address specified in the TXD.PTR register. Each byte clocked out from the master will be followed by an ACK/NACK bit clocked in from the slave.

A typical TWI master write sequence is shown in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect. This event can be used to synchronize the software.

The TWI master will generate a LASTTX event when it starts to transmit the last byte, this is shown in the following figure.

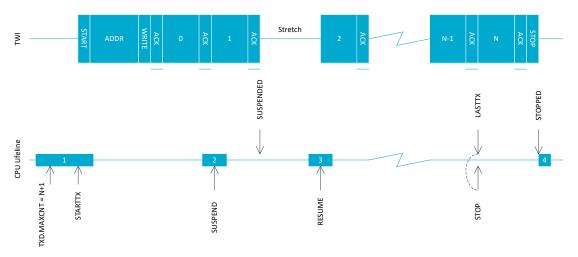


Figure 92: TWI master writing data to a slave

The TWI master is stopped by triggering the STOP task. This task should be triggered during the transmission of the last byte to secure that the TWI master will stop as fast as possible after sending the last byte. The shortcut between LASTTX and STOP can alternatively be used to accomplish this.

Note: The TWI master does not stop by itself when the entire RAM buffer has been sent, or when an error occurs. The STOP task must be issued, using a local or PPI shortcut, or in software as part of the error handler.

6.17.4 Master read sequence

A TWI master read sequence is started by triggering the STARTRX task. After the STARTRX task has been triggered, the TWI master will generate a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE = 0, READ = 1). The address must match the address of the slave device that the master wants to read from. The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK = 1) generated by the slave.

After sending the ACK bit, the TWI slave will send data to the master using the clock generated by the master.



Data received will be stored in RAM at the address specified in the RXD.PTR register. The TWI master will generate an ACK after all but the last byte have been received from the slave. The TWI master will generate a NACK after the last byte received to indicate that the read sequence shall stop.

A typical TWI master read sequence is illustrated in The TWI master reading data from a slave on page 291. Occurrence 2 in the figure illustrates clock stretching performed by the TWI master following a SUSPEND task.

A SUSPENDED event indicates that the SUSPEND task has taken effect. This event can be used to synchronize the software.

The TWI master will generate a LASTRX event when it is ready to receive the last byte, as shown in The TWI master reading data from a slave on page 291. If RXD.MAXCNT > 1, the LASTRX event is generated after sending the ACK of the previously received byte. If RXD.MAXCNT = 1, the LASTRX event is generated after receiving the ACK following the address and READ bit.

The TWI master is stopped by triggering the STOP task. This task must be triggered before the NACK bit is supposed to be transmitted. The STOP task can be triggered at any time during the reception of the last byte. It is recommended to use the shortcut between LASTRX and STOP to accomplish this.

The TWI master does not stop by itself when the RAM buffer is full, or when an error occurs. The STOP task must be issued, using a local or PPI shortcut, or in software as part of the error handler.

The TWI master cannot be stopped while suspended, so the STOP task must be issued after the TWI master has been resumed.

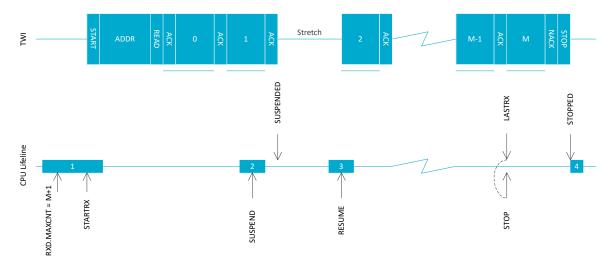


Figure 93: The TWI master reading data from a slave

6.17.5 Master repeated start sequence

A typical repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave. This example uses shortcuts to perform the simplest type of repeated start sequence, i.e. one write followed by one read. The same approach can be used to perform a repeated start sequence where the sequence is read followed by write.

The following figure shows an example of a repeated start sequence where the TWI master writes two bytes followed by reading four bytes from the slave.



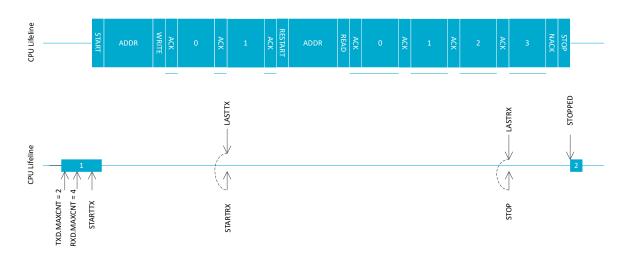


Figure 94: Master repeated start sequence

If a more complex repeated start sequence is needed, and the TWI firmware drive is serviced in a low priority interrupt, it may be necessary to use the SUSPEND task and SUSPENDED event to guarantee that the correct tasks are generated at the correct time. A double repeated start sequence using the SUSPEND task to secure safe operation in low priority interrupts is shown in the following figure.

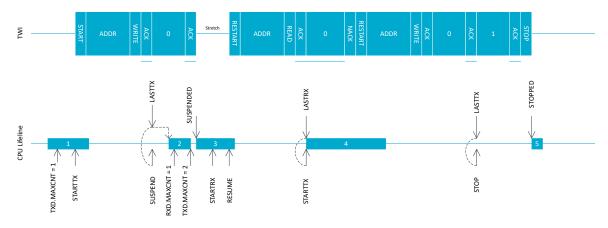


Figure 95: Double repeated start sequence

6.17.6 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

When the STOP task is sent, the software shall wait until the STOPPED event is received as a response before disabling the peripheral through the ENABLE register. If the peripheral is already stopped, the STOP task is not required.

6.17.7 Master mode pin configuration

The SCL and SDA signals associated with the TWI master are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI master is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL, PSEL.SDA must only be configured when the TWI master is disabled.



To secure correct signal levels on the pins used by the TWI master when the system is in OFF mode, and when the TWI master is disabled, these pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI master signal	TWI master pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 43: GPIO configuration before enabling peripheral

6.17.8 Registers

Instances

Instance	Base address	TrustZone			Split access	Description				
		Мар	Att	DMA						
TWIM0 : S	0x50008000	US	NS	SA	No	Two-wire interface master 0				
TWIM0 : NS	0x40008000	03	NS	3A	NO	Two-wife interface master o				
TWIM1:S	0x50009000	US	NS	SA	No	Two-wire interface master 1				
TWIM1: NS	0x40009000	03	NS	JA	NO	Two-wife interface master 1				
TWIM2 : S	0x5000A000	US	NS	SA	No	Two-wire interface master 2				
TWIM2 : NS	0x4000A000	03	145	3A	140	Two wife interface master 2				
TWIM3 : S	0x5000B000	US	NS	SA	No	Two-wire interface master 3				
TWIM3: NS	0x4000B000	03	NS	3A	140	Two wife interface master 5				

Register overview

Register	Offset	TZ	Description
TASKS_STARTRX	0x000		Start TWI receive sequence
TASKS_STARTTX	0x008		Start TWI transmit sequence
TASKS_STOP	0x014		Stop TWI transaction. Must be issued while the TWI master is not suspended.
TASKS_SUSPEND	0x01C		Suspend TWI transaction
TASKS_RESUME	0x020		Resume TWI transaction
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
EVENTS_STOPPED	0x104		TWI stopped
EVENTS_ERROR	0x124		TWI error
EVENTS_SUSPENDED	0x148		SUSPEND task has been issued, TWI traffic is now suspended.
EVENTS_RXSTARTED	0x14C		Receive sequence started
EVENTS_TXSTARTED	0x150		Transmit sequence started
EVENTS_LASTRX	0x15C		Byte boundary, starting to receive the last byte
EVENTS_LASTTX	0x160		Byte boundary, starting to transmit the last byte
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_SUSPENDED	0x1C8		Publish configuration for event SUSPENDED
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED

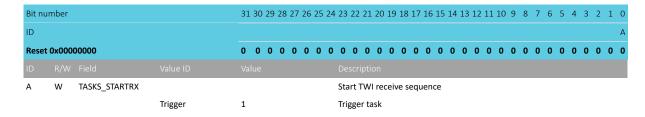


Register	Offset	TZ	Description
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_LASTRX	0x1DC		Publish configuration for event LASTRX
PUBLISH_LASTTX	0x1E0		Publish configuration for event LASTTX
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x4C4		Error source
ENABLE	0x500		Enable TWIM
PSEL.SCL	0x508		Pin select for SCL signal
PSEL.SDA	0x50C		Pin select for SDA signal
FREQUENCY	0x524		TWI frequency. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
TXD.LIST	0x550		EasyDMA list type
ADDRESS	0x588		Address used in the TWI transfer

6.17.8.1 TASKS_STARTRX

Address offset: 0x000

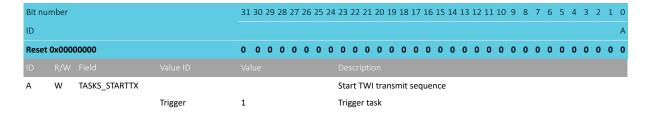
Start TWI receive sequence



6.17.8.2 TASKS_STARTTX

Address offset: 0x008

Start TWI transmit sequence



6.17.8.3 TASKS_STOP

Address offset: 0x014

Stop TWI transaction. Must be issued while the TWI master is not suspended.



Bit nu	mber			31	30 29	28	27	26 2	25 2	4 2	3 2	2 2	1 20	0 19	9 18	3 17	16	15	14	13	12 :	111	0 9	8	7	6	5	4	3 2	2 1	. 0
ID																															Α
Reset	0x000	00000		0	0 0	0	0	0	0 (0 0) () (0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0 (0	0
ID																															
Α	W	TASKS_STOP								St	top	TW	/I tr	ans	acti	on.	Mu	ist k	oe is	sue	ed w	hile	the	TW	/I m	ast	er is	no	t		
										SI	usp	enc	ded.																		
			Trigger	1						Ti	rigg	er 1	task																		

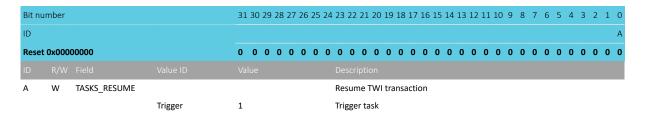
6.17.8.4 TASKS_SUSPEND

Address offset: 0x01C Suspend TWI transaction

Bit nu	ımber			31	30	29	28	27	26 2	25 :	24 2	23 2	22 2	1 2	0 1	9 1	8 17	7 16	15	14	13	12 1	11 1	0 9	8	7	6	5	4	3 2	2 1	0
ID																																Α
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0 (0 (0 0) (0	0	0	0	0	0	0 (0	0	0	0	0	0	0 (0	0
ID																																
Α	W	TASKS_SUSPEND									9	Sus	pen	d T	WI t	ran	isac	tion														
			Trigger	1							٦	Γrig	ger	tas	k																	

6.17.8.5 TASKS_RESUME

Address offset: 0x020
Resume TWI transaction



6.17.8.6 SUBSCRIBE_STARTRX

Address offset: 0x080

Subscribe configuration for task STARTRX

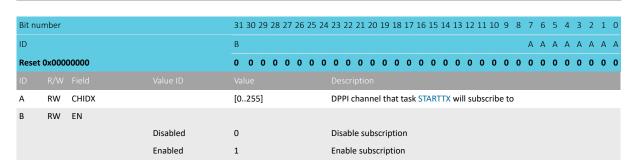
Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 1	13 12 11 10 9	8 7	7 6	5	4	3 2	1 0
ID				В			Δ	A A	Α	Α	А А	A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0	0 0	0	0	0	0 0	0 0
ID												
Α	RW	CHIDX		[0255]	DPPI channel that task STARTRX v	will subscribe to)					
В	RW	EN										
В	RW	EN	Disabled	0	Disable subscription							

6.17.8.7 SUBSCRIBE_STARTTX

Address offset: 0x088

Subscribe configuration for task STARTTX





6.17.8.8 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.17.8.9 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task SUSPEND will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled		Enable subscription

6.17.8.10 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

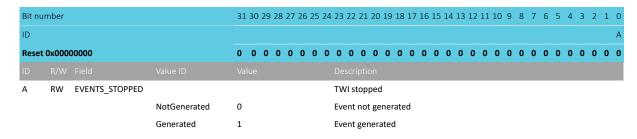
Bit no	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task RESUME will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription



6.17.8.11 EVENTS_STOPPED

Address offset: 0x104

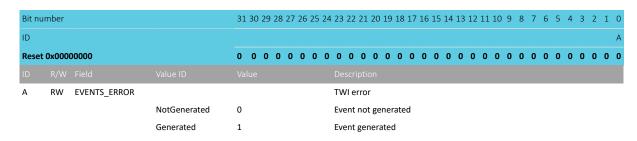
TWI stopped



6.17.8.12 EVENTS ERROR

Address offset: 0x124

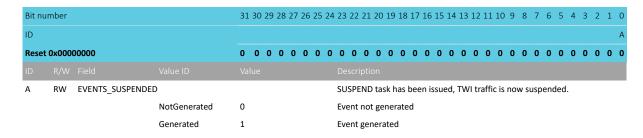
TWI error



6.17.8.13 EVENTS SUSPENDED

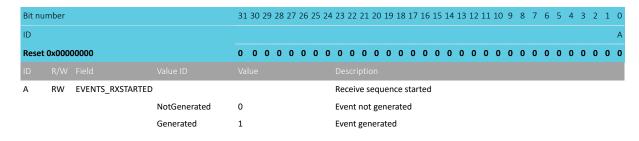
Address offset: 0x148

SUSPEND task has been issued, TWI traffic is now suspended.



6.17.8.14 EVENTS RXSTARTED

Address offset: 0x14C Receive sequence started

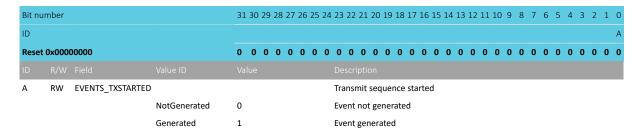




6.17.8.15 EVENTS_TXSTARTED

Address offset: 0x150

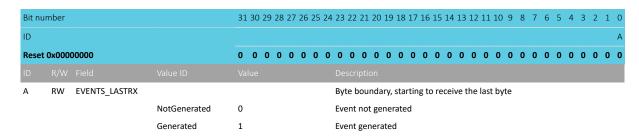
Transmit sequence started



6.17.8.16 EVENTS LASTRX

Address offset: 0x15C

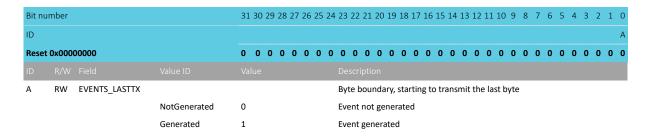
Byte boundary, starting to receive the last byte



6.17.8.17 EVENTS LASTTX

Address offset: 0x160

Byte boundary, starting to transmit the last byte

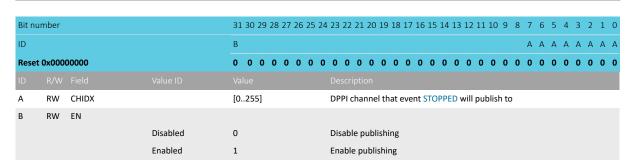


6.17.8.18 PUBLISH STOPPED

Address offset: 0x184

Publish configuration for event STOPPED





6.17.8.19 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event ERROR will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.17.8.20 PUBLISH_SUSPENDED

Address offset: 0x1C8

Publish configuration for event SUSPENDED

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event SUSPENDED will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.17.8.21 PUBLISH_RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED

Bit no	umber			31 30 29 28 27 26 25 24	$23\ 22\ 21\ 20\ 19\ 18\ 17\ 16\ 15\ 14\ 13\ 12\ 11\ 10\ 9\ 8\ 7\ 6\ 5\ 4\ 3\ 2\ 1\ 0$
ID				В	A A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event RXSTARTED will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

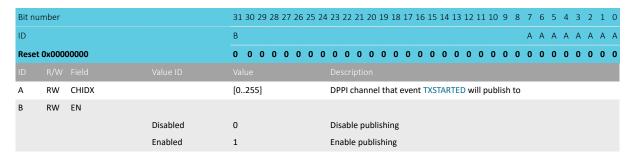




6.17.8.22 PUBLISH_TXSTARTED

Address offset: 0x1D0

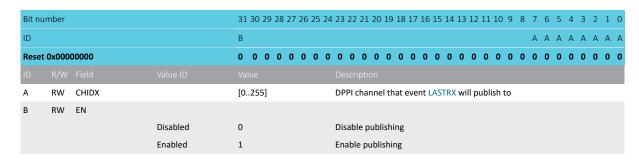
Publish configuration for event TXSTARTED



6.17.8.23 PUBLISH_LASTRX

Address offset: 0x1DC

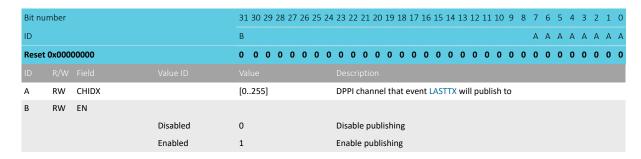
Publish configuration for event LASTRX



6.17.8.24 PUBLISH LASTTX

Address offset: 0x1E0

Publish configuration for event LASTTX



6.17.8.25 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks



Bit nu	ımber			31	30	29 2	8 2	7 20	6 2	5 24	1 2	3 2	2 2	21 2	0 1	9 1	8 17	7 16	5 15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 ()
ID																						F		D	С	В	Α							
Reset	0x000	00000		0	0	0 (0 (0 0) C	0	C	0 0) (0 () () (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 ()
ID																																		
Α	RW	LASTTX_STARTRX									S	hor	tcu	ıt be	etw	eer	ev	ent	LAS	TT)	(ar	ıd t	ask	STA	ART	RX								
			Disabled	0							D	isab	ble	sho	ortc	ut																		
			Enabled	1							Ε	nab	le:	sho	rtcı	ıt																		
В	RW	LASTTX_SUSPEND									S	hor	tcu	ıt be	etw	eer	ev	ent	LAS	TT)	(ar	nd t	ask	SU	SPE	ND								
			Disabled	0							D	isab	ble	sho	ortc	ut																		
			Enabled	1							Ε	nab	le:	sho	rtcı	ıt																		
С	RW	LASTTX_STOP									S	hor	tcu	ıt be	etw	eer	ev	ent	LAS	(TT	(ar	ıd t	ask	STO	OP									
			Disabled	0							D	isal	ble	sho	ortc	ut																		
			Enabled	1							Е	nab	le:	sho	rtcı	ıt																		
D	RW	LASTRX_STARTTX									S	hor	tcu	ıt be	etw	eer	ev	ent	LAS	TR	(ar	nd t	ask	STA	ART	TX								
			Disabled	0							D	isal	ble	sho	ortc	ut																		
			Enabled	1							Е	nab	le:	sho	rtcı	ıt																		
F	RW	LASTRX_STOP									S	hor	tcu	ıt be	etw	eer	ev	ent	LAS	TR	(ar	nd t	ask	STO	OP									
			Disabled	0							D	isak	ble	sho	ortc	ut																		
			Enabled	1							Е	nab	le:	sho	rtcı	ut																		

6.17.8.26 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	mber			31	30	29 2	8 27	7 26	25	24	23	22	2 21	20	19	18	17	16	15	14	13 :	12 1	11:	10 !	9	8	7	6 5	5 4	1 3	2	1	0
ID										J	1			Н	G	F								- 1	D							Α	
Reset	0x000	00000		0	0	0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0 (0	0 (0	0 () (0	0	0	0
Α	RW	STOPPED									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t ST	OPI	PED									
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
D	RW	ERROR									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t ER	RO	R									
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
F	RW	SUSPENDED									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t SU	SPI	END	ED								
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
G	RW	RXSTARTED									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t RX	STA	ARTI	ED								
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
Н	RW	TXSTARTED									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t TX	STA	RTE	ED								
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
1	RW	LASTRX									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t LA	STF	RX									
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				
J	RW	LASTTX									Ena	abl	le or	dis	abl	e in	iter	rup	t fo	r ev	/en	t LA	STI	Χ									
			Disabled	0							Disa	ab	le																				
			Enabled	1							Ena	abl	le																				

6.17.8.27 INTENSET

Address offset: 0x304



Enable interrupt

Bit nu	mber			31	30	29 2	28 :	27 2	26 2	25 2	24 2	23 2	22 2	21 2	0 :	19	18	17 1	6 1	5 14	13	12	11	10	9	8	7	6	5	4	3 2	2 1	1 (O
ID											J I	L		ŀ	+	G	F								D							A	4	
Reset	0x000	00000		0	0	0	0	0	0	0	0 (0 (0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () () (D
ID																																		
Α	RW	STOPPED									٧	Vrit	e '	1' to	e	nab	le i	ntei	rup	t for	ev	ent	STO	OPP	ED									
			Set	1							Ε	nat	ble																					
			Disabled	0							R	Read	d: [Disal	ble	ed																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
D	RW	ERROR									٧	Vrit	e '	1' to	eı	nab	le i	ntei	rup	t for	ev	ent	ERI	ROF	l									
			Set	1							Ε	nat	ble																					
			Disabled	0							R	Read	d: [Disal	ble	d																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
F	RW	SUSPENDED									٧	Vrit	e '	1' to	e	nab	le i	ntei	rup	t for	ev	ent	SU	SPE	NDI	ED								
			Set	1							Ε	nak	ble																					
			Disabled	0							R	Read	d: [Disal	ble	ed																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
G	RW	RXSTARTED									٧	Vrit	e '	1' to	eı	nab	le i	ntei	rup	for	ev	ent	RX:	STA	RTE	D								
			Set	1							Е	nak	ble																					
			Disabled	0							R	Read	d: [Disal	ble	ed																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
Н	RW	TXSTARTED									٧	Vrit	e '	1' to	e	nab	le i	ntei	rup	for	ev	ent	TXS	STAI	RTE	D								
			Set	1							Ε	nak	ble																					
			Disabled	0							R	Read	d: [Disal	ble	d																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
1	RW	LASTRX									٧	Vrit	e '	1' to	e e	nab	le i	ntei	rup	t for	ev	ent	LAS	STR	K									
			Set	1							Ε	nak	ble																					
			Disabled	0							R	Read	d: [Disal	ble	d																		
			Enabled	1							R	Read	d: E	Enab	ole	d																		
J	RW	LASTTX									٧	Vrit	e '	1' to	e	nab	le i	ntei	rup	t for	ev	ent	LAS	STT	(
			Set	1							Е	nat	ble																					
			Disabled	0							R	Read	d: [Disal	ble	d																		
			Enabled	1							R	Read	d: E	nab	ole	d																		

6.17.8.28 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				JI H G F D A
Reset	0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW STOPPED			Write '1' to disable interrupt for event STOPPED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
D	RW ERROR			Write '1' to disable interrupt for event ERROR
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
F	RW SUSPENDED			Write '1' to disable interrupt for event SUSPENDED



Bit nu	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				JI HGF D A
Reset	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
G	RW RXSTARTED			Write '1' to disable interrupt for event RXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
Н	RW TXSTARTED			Write '1' to disable interrupt for event TXSTARTED
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
1	RW LASTRX			Write '1' to disable interrupt for event LASTRX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled
J	RW LASTTX			Write '1' to disable interrupt for event LASTTX
		Clear	1	Disable
		Disabled	0	Read: Disabled
		Enabled	1	Read: Enabled

6.17.8.29 ERRORSRC

Address offset: 0x4C4

Error source

Bit nu	umber		31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				СВА
Rese	t 0x00000000		0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID				
Α	RW OVERRUN			Overrun error
	W1C			A new byte was received before previous byte got transferred into RXD
				buffer. (Previous data is lost)
		NotReceived	0	Error did not occur
		Received	1	Error occurred
В	RW ANACK			NACK received after sending the address (write '1' to clear)
	W1C			
		NotReceived	0	Error did not occur
		Received	1	Error occurred
С	RW DNACK			NACK received after sending a data byte (write '1' to clear)
	W1C			
		NotReceived	0	Error did not occur
		Received	1	Error occurred

6.17.8.30 ENABLE

Address offset: 0x500

Enable TWIM



Bit nu	ımber			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID					A A A
Rese	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	ENABLE			Enable or disable TWIM
			Disabled	0	Disable TWIM
			Enabled	6	Enable TWIM

6.17.8.31 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.17.8.32 PSEL.SDA

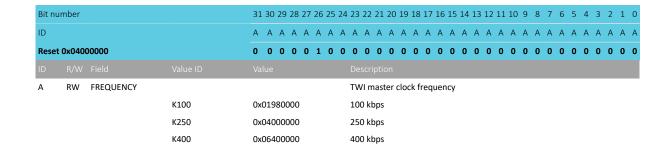
Address offset: 0x50C Pin select for SDA signal

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.17.8.33 FREQUENCY

Address offset: 0x524

TWI frequency. Accuracy depends on the HFCLK source selected.





6.17.8.34 RXD

RXD EasyDMA channel

6.17.8.34.1 RXD.PTR

Address offset: 0x534

Data pointer

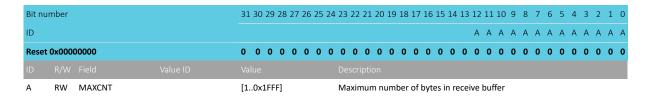
Bit nu	ımber		31	30	29 :	28 2	27 :	26 2	25	24	23	22	21	20	19	18 1	L7 1	6 1	5 14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
ID			Α	Α	Α	Α.	Α	Α /	Д	Α	Α	Α	Α	Α	Α	Α	A A	\ <i>A</i>	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α
Reset	0x000	00000	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0 0) (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID											De:																						
Α	RW	PTR									Dat	ta p	oin	ter																			

See the memory chapter for details about which memories are available for EasyDMA.

6.17.8.34.2 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer



6.17.8.34.3 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction

Bit nu	ımber		31 30 2	9 28 2	27 26	25 2	4 23	22	21 2	0 19	18	17 1	6 15	14	13 1	2 11	. 10	9	8	7	6	5 4	1 3	2	1	0
ID															,	4 A	Α	Α	Α	Α	Α	A A	Α Α	A	Α	Α
Reset	0x000	00000	0 0 0	0 0	0 0	0 (0 0	0	0 (0	0	0 (0 0	0	0 (0	0	0	0	0	0	0 (0	0	0	0
ID																										
Α	R	AMOUNT	[10x1F	FF]			Νι	ımb	er of	byte	es tra	ansfe	erred	d in	the la	st t	rans	act	ion.	. In o	case	e of	NAC	K er	ror,	
							inc	clude	es th	e NA	ACK'e	ed by	∕te.													

6.17.8.34.4 RXD.LIST

Address offset: 0x540 EasyDMA list type

Bit nu	ımber			31 30	29 2	28 27	26 2	5 24	1 23	22 2	21 2	0 19	18 1	17 16	5 15	14	13 13	2 11	10	9 8	3 7	6	5	4	3	2	1 0
ID																											А А
Reset	0x000	00000		0 0	0	0 0	0 (0	0	0	0 (0 0	0	0 0	0	0	0 0	0	0	0 (0	0	0	0	0	0	0 0
ID																											
Α	RW	LIST							List	t typ	e																
			Disabled	0					Dis	able	e Eas	yDM	IA lis	t													
			ArrayList	1					Us	e arr	ray li	ist															





6.17.8.35 TXD

TXD EasyDMA channel

6.17.8.35.1 TXD.PTR

Address offset: 0x544

Data pointer

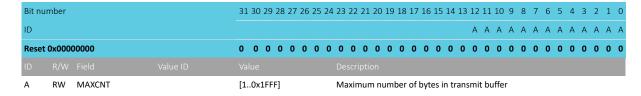
Α	RW		PTR											Dat	ta p	oin	ter																		
ID																																			
Rese	t 0x00	00	0000			0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID						Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A	4 Α	A	. A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A A
Bit n	umber					31	L 30	29	28	27	26	25	24	23	22	21	20	19	18 1	7 1	6 15	5 14	13	12	11	10	9	8	7	6	5	4	3	2	1 0

See the memory chapter for details about which memories are available for FasyDMA

6.17.8.35.2 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer



6.17.8.35.3 TXD.AMOUNT

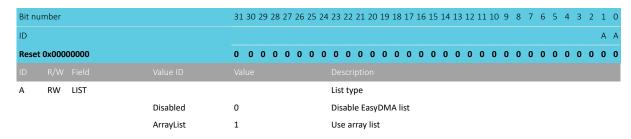
Address offset: 0x54C

Number of bytes transferred in the last transaction

Bit n	umber		31 30 29 28 27 26 2	24 :	23 2	2 21	20 19	18	17	16 1	5 14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID													Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	А А
Rese	t 0x000	00000	0 0 0 0 0 0	0	0 (0 0	0 0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																								
Α	R	AMOUNT	[10x1FFF]	ı	Num	ber c	f byt	es tı	ransf	ferre	d in	the	las	t tra	ans	act	ion	. In	cas	e o	f N	4CK	err	or,
				i	nclu	ides t	he NA	ACK'	ed b	vte.														

6.17.8.35.4 TXD.LIST

Address offset: 0x550 EasyDMA list type

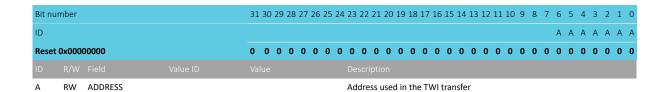




6.17.8.36 ADDRESS

Address offset: 0x588

Address used in the TWI transfer



6.17.9 Electrical specification

6.17.9.1 TWIM interface electrical specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIM,SCL}	Bit rates for TWIM ²⁰	100		400	kbps
t _{TWIM,START}	Time from STARTRX/STARTTX task to transmission started		1.615		μs

6.17.9.2 Two Wire Interface Master (TWIM) timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
t _{TWIM,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIM,HD_DAT}	Data hold time after negative edge on SCL – 100, 250 and 400 kbps	500			ns
t _{TWIM,HD_STA,100kbps}	TWIM master hold time for START and repeated START condition, 100 kbps	10000			ns
t _{TWIM,HD_STA,250kbps}	TWIM master hold time for START and repeated START condition, 250 kbps	4000			ns
$t_{TWIM,HD_STA,400kbps}$	TWIM master hold time for START and repeated START condition, 400 kbps	2500			ns
t _{TWIM,SU_STO,100kbps}	TWIM master setup time from SCL high to STOP condition, 100 kbps	5000			ns
t _{TWIM,SU_STO,250kbps}	TWIM master setup time from SCL high to STOP condition, 250 kbps	2000			ns
t _{TWIM,SU_STO,400kbps}	TWIM master setup time from SCL high to STOP condition, 400 kbps	1250			ns
t _{TWIM,BUF,100kbps}	TWIM master bus free time between STOP and START conditions, 100 kbps $$	5800			ns
t _{TWIM,BUF,250kbps}	TWIM master bus free time between STOP and START conditions, 250 kbps	2700			ns
t _{TWIM,BUF,400kbps}	TWIM master bus free time between STOP and START conditions, 400 kbps	2100			ns

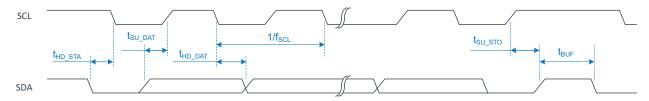


Figure 96: TWIM timing diagram, 1 byte transaction



High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO — General purpose input/output on page 97 for more details.

6.17.10 Pullup resistor

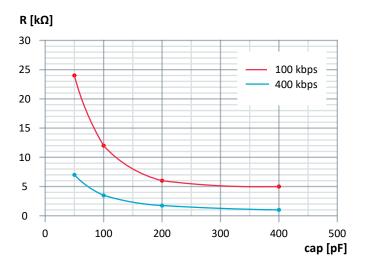


Figure 97: Recommended TWIM pullup value vs. line capacitance

- The I2C specification allows a line capacitance of 400 pF at most.
- The value of internal pullup resistor (R_{PU}) for nRF9161 can be found in GPIO General purpose input/output on page 97.

$6.18 \text{ TWIS} - I^2 \text{C}$ compatible two-wire interface slave with EasyDMA

TWI slave with EasyDMA (TWIS) is compatible with I^2C operating at 100 kHz and 400 kHz. The TWI transmitter and receiver implement EasyDMA.

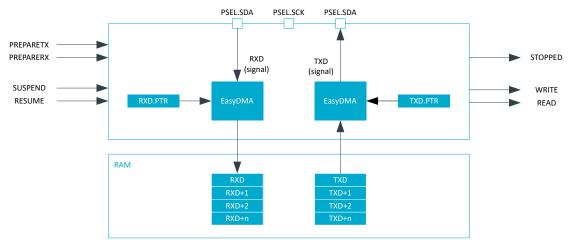


Figure 98: TWI slave with EasyDMA

A typical TWI setup consists of one master and one or more slaves. For an example, see the following figure. TWIS is only able to operate with a single master on the TWI bus.



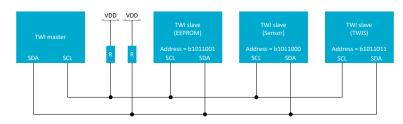


Figure 99: A typical TWI setup comprising one master and three slaves

The following figure shows the TWI slave state machine.

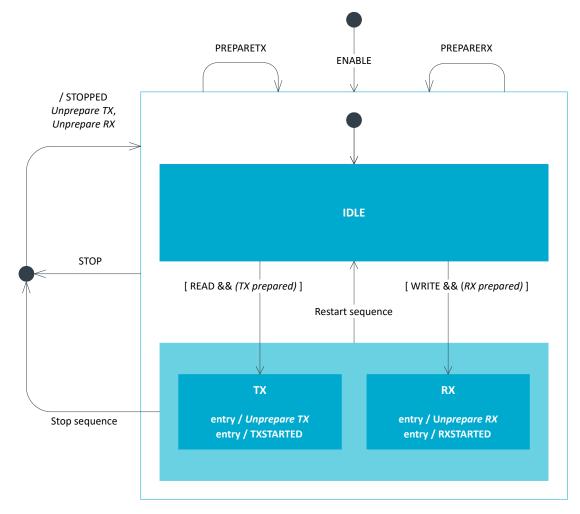


Figure 100: TWI slave state machine

The following table contains descriptions of the symbols used in the state machine.



Symbol	Туре	Description
ENABLE	Register	The TWI slave has been enabled via the ENABLE register.
PREPARETX	Task	The TASKS_PREPARETX task has been triggered.
STOP	Task	The TASKS_STOP task has been triggered.
PREPARERX	Task	The TASKS_PREPARERX task has been triggered.
STOPPED	Event	The EVENTS_STOPPED event was generated.
RXSTARTED	Event	The EVENTS_RXSTARTED event was generated.
TXSTARTED	Event	The EVENTS_TXSTARTED event was generated.
TX prepared	Internal	Internal flag indicating that a TASKS_PREPARETX task has been triggered. This flag is not visible to the
		user.
RX prepared	Internal	Internal flag indicating that a TASKS_PREPARERX task has been triggered. This flag is not visible to the
		user.
Unprepare TX	Internal	Clears the internal 'TX prepared' flag until next TASKS_PREPARETX task.
Unprepare RX	Internal	Clears the internal 'RX prepared' flag until next TASKS_PREPARERX task.
Stop condition	TWI protocol	A TWI stop condition was detected.
Restart condition	TWI protocol	A TWI restart condition was detected.

Table 44: TWI slave state machine symbols

The TWI slave can perform clock stretching, with the premise that the master is able to support it.

The TWI slave operates in a low power mode while waiting for a TWI master to initiate a transfer. As long as the TWI slave is not addressed, it will remain in this low power mode.

To secure correct behavior of the TWI slave, PSEL.SDA, CONFIG, and the ADDRESS[n] registers must be configured prior to enabling the TWI slave through the ENABLE register. Similarly, changing these settings must be performed while the TWI slave is disabled. Failing to do so may result in unpredictable behavior.

6.18.1 Shared resources

The TWI slave shares registers and other resources with other peripherals that have the same ID as the TWI slave.

Therefore, you must disable all peripherals that have the same ID as the TWI slave before the TWI slave can be configured and used. Disabling a peripheral that has the same ID as the TWI slave will not reset any of the registers that are shared with the TWI slave. It is therefore important to configure all relevant registers explicitly to secure that the TWI slave operates correctly.

The Instantiation table in Instantiation on page 25 shows which peripherals have the same ID as the TWI slave.

6.18.2 EasyDMA

The TWIS implements EasyDMA for accessing RAM without CPU involvement.

The following table shows the Easy DMA channels that the TWIS peripheral implements.

Channel	Туре	Register Cluster
TXD	READER	TXD
RXD	WRITER	RXD

Table 45: TWIS EasyDMA Channels

For detailed information regarding the use of EasyDMA, see EasyDMA on page 43.

The STOPPED event indicates that EasyDMA has finished accessing the buffer in RAM.



6.18.3 TWI slave responding to a read command

Before the TWI slave can respond to a read command, the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled, the TWI slave will be in its IDLE state. .

A read command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 1 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the TWI slave.

The TWI slave can listen for up to two addresses at the same time. This is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the read command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a READ event when it acknowledges the read command.

The TWI slave can only detect a read command from the IDLE state.

The TWI slave will set an internal 'TX prepared' flag when the PREPARETX task is triggered.

When the read command is received, the TWI slave will enter the TX state if the internal 'TX prepared' flag is set.

If the internal 'TX prepared' flag is not set when the read command is received, the TWI slave will stretch the master's clock until the PREPARETX task is triggered and the internal 'TX prepared' flag is set.

The TWI slave will generate the TXSTARTED event and clear the 'TX prepared' flag ('unprepare TX') when it enters the TX state. In this state the TWI slave will send the data bytes found in the transmit buffer to the master using the master's clock.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the TX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the 'TX prepared' flag ('unprepare TX') and go back to the IDLE state when it has stopped.

The transmit buffer is located in RAM at the address specified in the TXD.PTR register. The TWI slave will only be able to send TXD.MAXCNT bytes from the transmit buffer for each transaction. If the TWI master forces the slave to send more than TXD.MAXCNT bytes, the slave will send the byte specified in the ORC register to the master instead. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see TXD.PTR etc., are latched when the TXSTARTED event is generated.

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the 'TX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 314.

Each byte sent from the slave will be followed by an ACK/NACK bit sent from the master. The TWI master will generate a NACK following the last byte that it wants to receive to tell the slave to release the bus so that the TWI master can generate the stop condition. The TXD.AMOUNT register can be queried after a transaction to see how many bytes were sent.

A typical TWI slave read command response is shown in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.



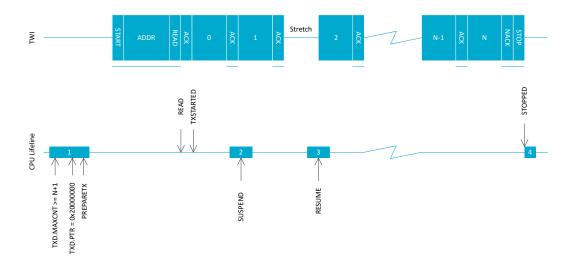


Figure 101: The TWI slave responding to a read command

6.18.4 TWI slave responding to a write command

Before the TWI slave can respond to a write command, the TWI slave must be configured correctly and enabled via the ENABLE register. When enabled, the TWI slave will be in its IDLE state.

A write command is started when the TWI master generates a start condition on the TWI bus, followed by clocking out the address and the READ/WRITE bit set to 0 (WRITE=0, READ=1). The READ/WRITE bit is followed by an ACK/NACK bit (ACK=0 or NACK=1) response from the slave.

The TWI slave can listen for up to two addresses at the same time. This is configured in the ADDRESS registers and the CONFIG register.

The TWI slave will only acknowledge (ACK) the write command if the address presented by the master matches one of the addresses the slave is configured to listen for. The TWI slave will generate a WRITE event if it acknowledges the write command.

The TWI slave can only detect a write command from the IDLE state.

The TWI slave will set an internal 'RX prepared' flag when the PREPARERX task is triggered.

When the write command is received, the TWI slave will enter the RX state if the internal 'RX prepared' flag is set.

If the internal 'RX prepared' flag is not set when the write command is received, the TWI slave will stretch the master's clock until the PREPARERX task is triggered and the internal 'RX prepared' flag is set.

The TWI slave will generate the RXSTARTED event and clear the internal 'RX prepared' flag ('unprepare RX') when it enters the RX state. In this state, the TWI slave will be able to receive the bytes sent by the TWI master.

The TWI slave will go back to the IDLE state if the TWI slave receives a restart command when it is in the RX state.

The TWI slave is stopped when it receives the stop condition from the TWI master. A STOPPED event will be generated when the transaction has stopped. The TWI slave will clear the internal 'RX prepared' flag ('unprepare RX') and go back to the IDLE state when it has stopped.

The receive buffer is located in RAM at the address specified in the RXD.PTR register. The TWI slave will only be able to receive as many bytes as specified in the RXD.MAXCNT register. If the TWI master tries to send more bytes to the slave than it can receive, the extra bytes are discarded and NACKed by the slave. If this happens, an ERROR event will be generated.

The EasyDMA configuration registers, see RXD.PTR etc., are latched when the RXSTARTED event is generated.

NORDIC

The TWI slave can be forced to stop by triggering the STOP task. A STOPPED event will be generated when the TWI slave has stopped. The TWI slave will clear the internal 'RX prepared' flag and go back to the IDLE state when it has stopped, see also Terminating an ongoing TWI transaction on page 314.

The TWI slave will generate an ACK after every byte received from the master. The RXD.AMOUNT register can be queried after a transaction to see how many bytes were received.

A typical TWI slave write command response is show in the following figure. Occurrence 2 in the figure illustrates clock stretching performed by the TWI slave following a SUSPEND task.

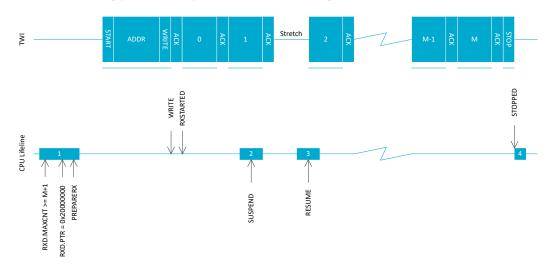


Figure 102: The TWI slave responding to a write command

6.18.5 Master repeated start sequence

An example of a repeated start sequence is one in which the TWI master writes two bytes to the slave followed by reading four bytes from the slave.

This is illustrated in the following figure.

In this example, the receiver does not know what the master wants to read in advance. This information is in the first two received bytes of the write in the repeated start sequence. To guarantee that the CPU is able to process the received data before the TWI slave starts to reply to the read command, the SUSPEND task is triggered via a shortcut from the READ event generated when the read command is received. When the CPU has processed the incoming data and prepared the correct data response, the CPU will resume the transaction by triggering the RESUME task.

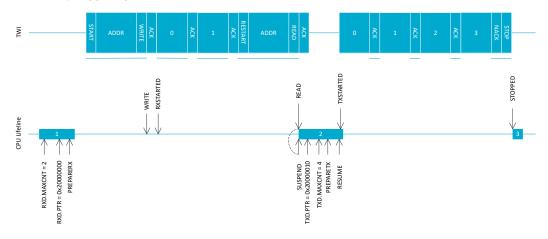


Figure 103: Repeated start sequence



6.18.6 Terminating an ongoing TWI transaction

In some situations, e.g. if the external TWI master is not responding correctly, it may be required to terminate an ongoing transaction.

This can be achieved by triggering the STOP task. In this situation, a STOPPED event will be generated when the TWI has stopped independent of whether or not a STOP condition has been generated on the TWI bus. The TWI slave will release the bus when it has stopped and go back to its IDLE state.

6.18.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOP task may not be always needed (the peripheral might already be stopped), but if it is sent, software shall wait until the STOPPED event was received as a response before disabling the peripheral through the ENABLE register.

6.18.8 Slave mode pin configuration

The SCL and SDA signals associated with the TWI slave are mapped to physical pins according to the configuration specified in the PSEL.SCL and PSEL.SDA registers respectively.

The PSEL.SCL and PSEL.SDA registers and their configurations are only used as long as the TWI slave is enabled, and retained only as long as the device is in ON mode. When the peripheral is disabled, the pins will behave as regular GPIOs, and use the configuration in their respective OUT bit field and PIN_CNF[n] register. PSEL.SCL and PSEL.SDA must only be configured when the TWI slave is disabled.

To secure correct signal levels on the pins used by the TWI slave when the system is in OFF mode, and when the TWI slave is disabled, these pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

TWI slave signal	TWI slave pin	Direction	Output value	Drive strength
SCL	As specified in PSEL.SCL	Input	Not applicable	SOD1
SDA	As specified in PSEL.SDA	Input	Not applicable	SOD1

Table 46: GPIO configuration before enabling peripheral

6.18.9 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
TWIS0 : S	0x50008000	US	NS	SA	No	Two-wire interface slave 0
TWIS0 : NS	0x40008000	03	NS	JA	NO	Two-wife interface slave o
TWIS1: S	0x50009000	US	NS	SA	No	Two-wire interface slave 1
TWIS1: NS	0x40009000	03	NS	JA	NO	Two wife interface slave 1
TWIS2 : S	0x5000A000	US	NS	SA	No	Two-wire interface slave 2
TWIS2 : NS	0x4000A000	03	NS	JA	NO	Two-wife interface slave 2
TWIS3: S	0x5000B000	US	NS	SA	No	Two-wire interface slave 3
TWIS3: NS	0x4000B000	03	143	JA	140	Two wife interface slave 5





Register overview

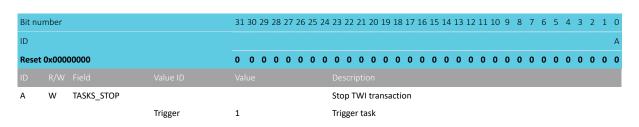
Register	Offset	TZ	Description
TASKS_STOP	0x014		Stop TWI transaction
TASKS_SUSPEND	0x01C		Suspend TWI transaction
TASKS_RESUME	0x020		Resume TWI transaction
TASKS_PREPARERX	0x030		Prepare the TWI slave to respond to a write command
TASKS_PREPARETX	0x034		Prepare the TWI slave to respond to a read command
SUBSCRIBE_STOP	0x094		Subscribe configuration for task STOP
SUBSCRIBE_SUSPEND	0x09C		Subscribe configuration for task SUSPEND
SUBSCRIBE_RESUME	0x0A0		Subscribe configuration for task RESUME
SUBSCRIBE_PREPARERX	0x0B0		Subscribe configuration for task PREPARERX
SUBSCRIBE_PREPARETX	0x0B4		Subscribe configuration for task PREPARETX
EVENTS_STOPPED	0x104		TWI stopped
EVENTS_ERROR	0x124		TWI error
EVENTS_RXSTARTED	0x14C		Receive sequence started
EVENTS_TXSTARTED	0x150		Transmit sequence started
EVENTS_WRITE	0x164		Write command received
EVENTS_READ	0x168		Read command received
PUBLISH_STOPPED	0x184		Publish configuration for event STOPPED
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_WRITE	0x1E4		Publish configuration for event WRITE
PUBLISH_READ	0x1E8		Publish configuration for event READ
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x4D0		Error source
MATCH	0x4D4		Status register indicating which address had a match
ENABLE	0x500		Enable TWIS
PSEL.SCL PSEL.SCL	0x508		Pin select for SCL signal
PSEL.SDA	0x50C		Pin select for SDA signal
RXD.PTR	0x534		RXD Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in RXD buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last RXD transaction
RXD.LIST	0x540		EasyDMA list type
TXD.PTR	0x544		TXD Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in TXD buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last TXD transaction
TXD.LIST	0x550		EasyDMA list type
ADDRESS[n]	0x588		TWI slave address n
CONFIG	0x594		Configuration register for the address match mechanism
ORC	0x5C0		Over-read character. Character sent out in case of an over-read of the transmit buffer.

6.18.9.1 TASKS_STOP

Address offset: 0x014

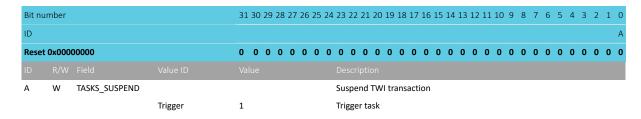
Stop TWI transaction





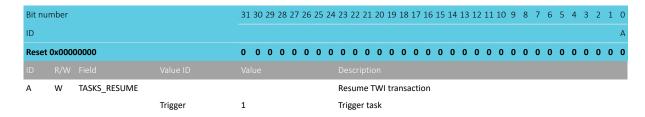
6.18.9.2 TASKS SUSPEND

Address offset: 0x01C
Suspend TWI transaction



6.18.9.3 TASKS_RESUME

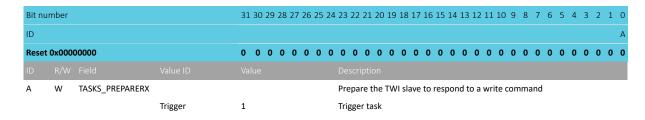
Address offset: 0x020
Resume TWI transaction



6.18.9.4 TASKS PREPARERX

Address offset: 0x030

Prepare the TWI slave to respond to a write command

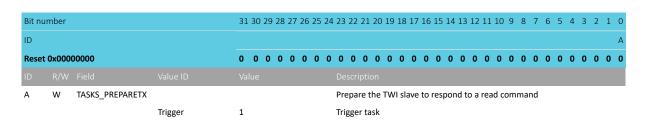


6.18.9.5 TASKS_PREPARETX

Address offset: 0x034

Prepare the TWI slave to respond to a read command





6.18.9.6 SUBSCRIBE_STOP

Address offset: 0x094

Subscribe configuration for task STOP

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task STOP will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.7 SUBSCRIBE_SUSPEND

Address offset: 0x09C

Subscribe configuration for task SUSPEND

Bit nu	ımber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task SUSPEND will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.8 SUBSCRIBE_RESUME

Address offset: 0x0A0

Subscribe configuration for task RESUME

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task RESUME will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

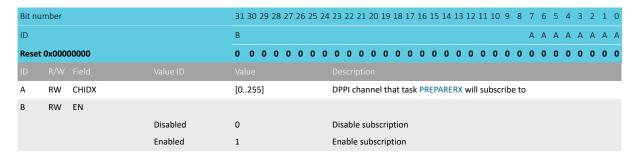
6.18.9.9 SUBSCRIBE_PREPARERX

Address offset: 0x0B0





Subscribe configuration for task PREPARERX



6.18.9.10 SUBSCRIBE_PREPARETX

Address offset: 0x0B4

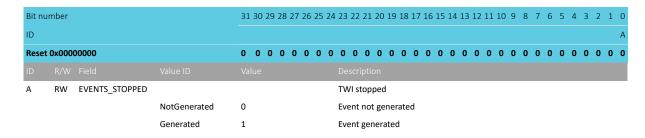
Subscribe configuration for task PREPARETX

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task PREPARETX will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.18.9.11 EVENTS_STOPPED

Address offset: 0x104

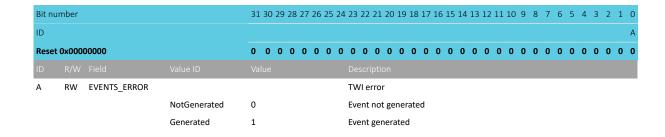
TWI stopped



6.18.9.12 EVENTS_ERROR

Address offset: 0x124

TWI error



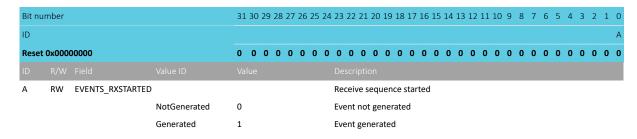




6.18.9.13 EVENTS_RXSTARTED

Address offset: 0x14C

Receive sequence started



6.18.9.14 EVENTS TXSTARTED

Address offset: 0x150

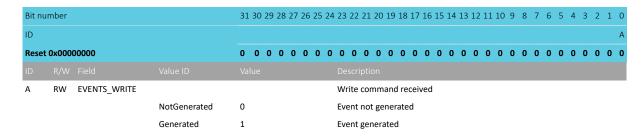
Transmit sequence started

Bit nu	ımber			31	30 29	28	27 2	6 25	24	23	22 2	21 2	0 19	9 18	3 17	16	15 1	L4 1	3 12	2 11	10	9	8	7	6	5	4	3	2	1 0
ID																														Α
Reset	0x000	00000		0	0 0	0	0 0	0	0	0	0	0 (0 0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0 (0 0
ID																														
Α	RW	EVENTS_TXSTARTED	ı							Tra	nsm	nit se	eque	ence	e sta	rtec	ł													
			NotGenerated	0						Eve	nt n	not g	gene	erat	ed															
			Generated	1						Eve	nt g	gene	rate	ed																

6.18.9.15 EVENTS_WRITE

Address offset: 0x164

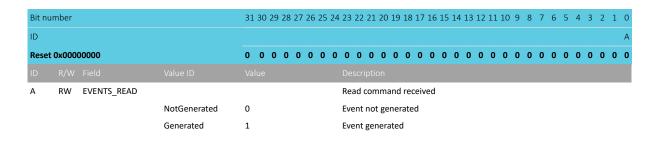
Write command received



6.18.9.16 EVENTS READ

Address offset: 0x168

Read command received

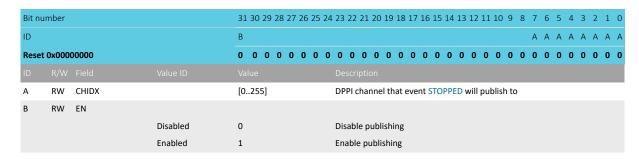




6.18.9.17 PUBLISH_STOPPED

Address offset: 0x184

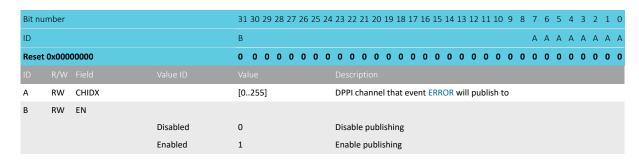
Publish configuration for event STOPPED



6.18.9.18 PUBLISH_ERROR

Address offset: 0x1A4

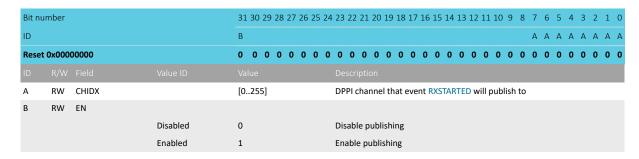
Publish configuration for event ERROR



6.18.9.19 PUBLISH RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED



6.18.9.20 PUBLISH_TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED



Bit nu	mber			31 30 29 2	28 27 :	26 25 2	24 23	3 22 :	21 20	19	18 1	7 16	15 1	4 13	12 1	11 10	9	8	7	6	5	4 :	3 2	1 ()
ID				В															Α	Α	Α.	A A	4 A	Α ,	1
Reset	0x0000	00000		0 0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0	0 0	0	0	0	0	0	0 (0	0 ()
ID																									I
Α	RW	CHIDX		[0255]			D	PPI cl	nanne	el tha	at ev	ent T	XSTA	RTEI	D wil	l put	lish	to							
В	RW	EN																							
			Disabled	0			Di	isable	pub	lishir	ng														
			Enabled	1			Er	nable	publ	ishin	g														

6.18.9.21 PUBLISH_WRITE

Address offset: 0x1E4

Publish configuration for event WRITE

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event WRITE will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.18.9.22 PUBLISH_READ

Address offset: 0x1E8

Publish configuration for event READ

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that event READ will publish to
В	RW	EN			
			Disabled	0	Disable publishing

6.18.9.23 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit nu	ımber			31	30	29 2	28	27 2	26	25 2	4 2	23 22	2 2:	1 20	19	9 18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																				В	Α												
Reset	0x000	00000		0	0	0	0	0	0	0 ()	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID												Desc																					
Α	RW	WRITE_SUSPEND									9	Short	cut	bet	we	een	eve	nt	WR	ITE	an	d ta	ısk	SUS	PEN	۱D							
			Disabled	0							[Disab	le :	shor	tcı	ut																	
			Enabled	1							E	Enab	le s	hor	tcu	it																	
В	RW	READ_SUSPEND									9	Short	cut	bet	twe	een	eve	nt	REA	AD a	and	tas	k S	USP	ENI	D							
			Disabled	0							[Disab	le :	shor	tcı	ut																	
			Enabled	1							E	Enab	le s	hor	tcu	it																	





6.18.9.24 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	mber			31	30	29 28	8 27	7 26	25 2	4 2	3 22	21	20 1	19 1	8 1	7 16	15	14	13	12 1	11:	10 9	8	7	6	5	4 3	3 2	1	0
ID								Н	G				F	E								E	3						Α	
Reset	0x000	00000		0	0	0 0	0	0	0 () (0 0	0	0	0 (0	0	0	0	0	0	0	0 (0	0	0	0	0 (0	0	0
ID																														
Α	RW	STOPPED								Ε	nable	e or	disa	able	inte	errup	ot fo	or ev	/en	t ST	OPI	PED								
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		
В	RW	ERROR								Ε	nable	or	disa	able	inte	errup	ot fo	or ev	/en	t ER	RO	R								
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		
E	RW	RXSTARTED								Ε	nable	e or	disa	able	inte	erru	ot fo	or ev	/en	t RX	STA	ARTE	D							
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		
F	RW	TXSTARTED								Ε	nable	e or	disa	able	inte	erru	ot fo	or ev	/en	t TX	STA	RTE	D							
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		
G	RW	WRITE								Ε	nable	or	disa	able	inte	errup	ot fo	or ev	/en	t W	RIT	E								
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		
Н	RW	READ								Ε	nable	e or	disa	able	inte	errup	ot fo	or ev	/en	t RE	AD									
			Disabled	0						D	Disabl	e																		
			Enabled	1						Ε	nable	9																		

6.18.9.25 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31	30 :	29 2	8 2	7 26	5 25	5 24	1 23	3 22	2 2:	1 20	19	18	17	16	15	14	13	12 :	11	10	9	8 7	7 (5 5	4	3	2	1 0
ID								Н	G	i				F	Ε										В							А
Reset	0x000	00000		0	0	0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0 0
ID																																
Α	RW	STOPPED									W	/rite	e '1'	' to	ena	ble	int	errı	ıpt	for	eve	nt S	ТО	PPE	D							
			Set	1							Er	nab	le																			
			Disabled	0							Re	ead	: Di	isab	led																	
			Enabled	1							Re	ead	: Er	nabl	ed																	
В	RW	ERROR									W	/rite	e '1'	' to	ena	ble	int	errı	ıpt	for	eve	nt E	RR	OR								
			Set	1							Er	nab	le																			
			Disabled	0							Re	ead	: Di	isab	led																	
			Enabled	1							Re	ead	: Er	nabl	ed																	
E	RW	RXSTARTED									W	/rite	e '1'	' to	ena	ble	int	errı	ıpt	for	eve	nt F	XS	TAR	TEC)						
			Set	1							Er	nab	le																			
			Disabled	0							Re	ead	: Di	isab	led																	
			Enabled	1							Re	ead	: Er	nabl	ed																	
F	RW	TXSTARTED									W	/rite	e '1'	' to	ena	ble	int	errı	ıpt	for	eve	nt T	XS	TAR	TEC)						
			Set	1							Er	nab	le																			
			Disabled	0							Re	ead	: Di	isab	led																	
			Enabled	1							Re	ead	: Er	nabl	ed																	





Bit nu	ımber			31	30	29 2	28 2	27 26	6 2	5 24	23	22	21	20	19	18 1	7 1	.6 1	5 1	4 1	3 12	2 11	10	9	8	7	6	5	4	3	2	1 0
ID								Н	1 (3				F	Ε									В								Α
Reset	0x000	00000		0	0	0	0	0 0) (0 0	0	0	0	0	0	0 () (0 0) (0	0	0	0	0	0	0	0	0	0	0	0 (0 0
ID																																
G	RW	WRITE									Wr	ite	'1' 1	to e	nab	le ir	iter	rup	t fo	r ev	ent	WI	RITE									
			Set	1							Ena	able	е																			
			Disabled	0							Rea	ad:	Dis	able	d																	
			Enabled	1							Rea	ad:	Ena	ble	d																	
Н	RW	READ									Wr	ite	'1' 1	to e	nab	le ir	iter	rup	t fo	r ev	ent	RE	AD									
			Set	1							Ena	able	е																			
			Disabled	0							Rea	ad:	Dis	able	d																	
			Enabled	1							Rea	ad:	Ena	ble	d																	

6.18.9.26 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	mber			31	30	29 2	28 2	7 26	5 25	5 24	1 23	3 22	2 2:	1 20	19	9 18	3 17	7 16	5 15	14	13	12	11	l 10) 9	8	7	6	5	4	3 2	2 1	0
ID								Н	l G	i				F	Е										В							Δ	۱
Reset	0x000	00000		0	0	0 (0 0	0 (0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0	0 (
A	RW	STOPPED									W	/rite	· '1'	' to	dis	able	e in	ter	up	fo:	r ev	ent	ST	OP	PEC)							
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		
В	RW	ERROR									W	/rite	· '1'	' to	dis	able	e in	ter	up	fo	r ev	ent	ER	RRC	R								
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		
E	RW	RXSTARTED									W	/rite	'1	' to	dis	able	e in	ter	up	fo	r ev	ent	R	(ST	ART	ED							
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		
F	RW	TXSTARTED									W	/rite	· '1'	' to	dis	able	e in	ter	up	fo	r ev	ent	.TX	(ST/	ART	ED							
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		
G	RW	WRITE									W	/rite	'1	' to	dis	able	e in	ter	up	fo	r ev	ent	W	RIT	Έ								
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		
Н	RW	READ									W	/rite	'1	' to	dis	able	e in	ter	up	fo	r ev	ent	RE	AD)								
			Clear	1							Di	isab	le																				
			Disabled	0							Re	ead:	: Di	isab	led	ı																	
			Enabled	1							Re	ead:	: Er	nabl	ed																		

6.18.9.27 ERRORSRC

Address offset: 0x4D0

Error source



Bit number			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				C B A
Reset 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
ID				Description
Α	RW OVERFLOW			RX buffer overflow detected, and prevented
	W1C			
		NotDetected	0	Error did not occur
		Detected	1	Error occurred
В	RW DNACK			NACK sent after receiving a data byte
	W1C			
		NotReceived	0	Error did not occur
		Received	1	Error occurred
С	RW OVERREAD			TX buffer over-read detected, and prevented
	W1C			
		NotDetected	0	Error did not occur
		Detected	1	Error occurred

6.18.9.28 MATCH

Address offset: 0x4D4

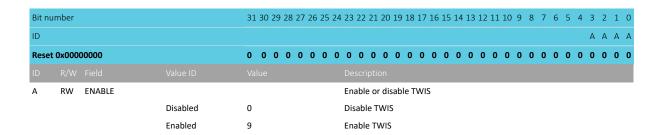
Status register indicating which address had a match



6.18.9.29 ENABLE

Address offset: 0x500

Enable TWIS



6.18.9.30 PSEL.SCL

Address offset: 0x508

Pin select for SCL signal



Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	
ID					
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.18.9.31 PSEL.SDA

Address offset: 0x50C

Pin select for SDA signal

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.18.9.32 RXD

RXD EasyDMA channel

6.18.9.32.1 RXD.PTR

Address offset: 0x534 RXD Data pointer

Bit nu	umber		31	30	29	28 2	27 2	26 2	5 2	4 23	3 2:	2 21	. 20	19	18 1	17 1	5 1	5 14	13	12	11	10	9	8	7	6	5	4	3	2	1 0	ı
ID			Α	Α	Α	Α.	A	A A	۱ ۸	4 A	Δ	. A	Α	Α	Α	A A	. 4	A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	А А	l
Rese	t 0x000	00000	0	0	0	0	0	0 () (0 0	0	0	0	0	0	0 0) C	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	l
ID																																l
А	RW	PTR								R)	(D	Data	э ро	inte	r																	

See the memory chapter for details about which memories are available for EasyDMA.

6.18.9.32.2 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in RXD buffer

Α	RW	MAXCNT	[10x1FFF]	Maximum number of bytes in RXD buffer
ID				
Rese	t 0x000	00000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit nu	umber		31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0



6.18.9.32.3 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last RXD transaction

Α	R	AMOUNT	[10x1FFF]	Number of by	tes trar	sferre	d in t	the l	ast R	XD t	ran	sact	tion					
ID				Description														
Rese	t 0x000	00000	0 0 0 0 0 0 0 0	0 0 0 0	0 0 0	0 0	0	0	0 0	0	0	0	0	0 0	0	0	0	0 0
ID									4 А	Α	Α	Α	Α	A A	A	Α	Α	А А
Bit n	umber		31 30 29 28 27 26 25 24	23 22 21 20	19 18 17	16 1	5 14	13 1	.2 11	. 10	9	8	7	6 5	5 4	3	2	1 0

6.18.9.32.4 RXD.LIST

Address offset: 0x540

EasyDMA list type

Bit no	umber			31 30 29 2	28 27 2	26 25 2	4 23 2	22 21	20 1	9 18	17 10	6 15	14 1	.3 12	11	10 9	8	7	6	5	4	3	2	1 0
ID																								А А
Rese	t 0x000	00000		0 0 0	0 0 (0 0 (0	0 0	0 0	0	0 0	0	0 (0 0	0	0 (0	0	0	0	0	0	0	0 0
ID																								
Α	RW	LIST					List	type																
			Disabled	0			Disa	able E	asyDi	MA lis	st													
			ArrayList	1			Use	array	list															

6.18.9.33 TXD

TXD EasyDMA channel

6.18.9.33.1 TXD.PTR

Address offset: 0x544

TXD Data pointer

Α	RW	PTR			TX	D Da	ta poi	inter															
ID																							
Rese	t 0x000	00000	0 0 0 0 0	0	0 0	0 (0 0	0 0	0 (0	0	0 0	0	0	0	0	0	0	0 (0 0	0	0	0
ID			A A A A A	Α	А А	Α /	A A	A A	A A	A	Α	А А	Α	Α	Α	Α	Α	Α	A A	A А	Α	Α	Α
Bit n	umber		31 30 29 28 27 20	5 25	24 23	22 2	1 20	19 18	17 1	6 15	14	13 12	11	10	9	8	7	6	5 4	4 3	2	1	0

See the memory chapter for details about which memories are available for EasyDMA.

6.18.9.33.2 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in TXD buffer

	RW/	MAXCNT	[1 Ox1FFF]	Maximum number of bytes in TXD huffer
ID				
Reset	0x0000	00000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit nu	mber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

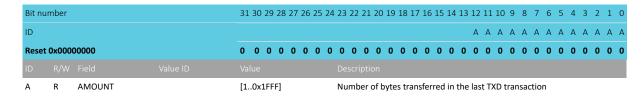




6.18.9.33.3 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last TXD transaction



6.18.9.33.4 TXD.LIST

Address offset: 0x550 EasyDMA list type

Bit number		31 30 29 28 27	26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID			A A
Reset 0x00000000		0 0 0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
ID R/W Field			Description
A RW LIST			List type
	Disabled	0	Disable EasyDMA list
	ArrayList	1	Use array list

6.18.9.34 ADDRESS[n] (n=0..1)

Address offset: $0x588 + (n \times 0x4)$

TWI slave address n

Α	RW	ADDRESS		WI slave	addres	SS													
ID																			
Rese	t 0x000	00000	0 0 0 0 0 0 0 0	0 0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0	0	0	0	0 (0	0
ID														Α	Α	Α	A A	A A	A
Bit n	umber		31 30 29 28 27 26 25 24	23 22 21	20 19 :	18 17	16 1	5 14	13 1	2 11	10 9	8	7	6	5	4	3 2	2 1	0

6.18.9.35 CONFIG

Address offset: 0x594

Configuration register for the address match mechanism

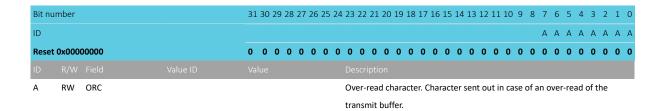
Bit nu	ımber			31	30 2	29 2	28 2	7 2	6 25	5 24	- 23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2 :	1 0
ID																																E	ВА
Reset	0x000	00001		0	0	0 (0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 1
ID																																	
A-B	RW	ADDRESS[i] (i=01)									En	able	or	dis	abl	e a	ddr	ess	ma	itch	ning	g on	ΑE	DDR	ESS	[i]							
			Disabled	0							Dis	abl	ed																				
			Enabled	1							En	able	ed																				

6.18.9.36 ORC

Address offset: 0x5C0



Over-read character. Character sent out in case of an over-read of the transmit buffer.



6.18.10 Electrical specification

6.18.10.1 TWIS slave timing specifications

Symbol	Description	Min.	Тур.	Max.	Units
f _{TWIS,SCL}	Bit rates for TWIS ²¹	100		400	kbps
t _{TWIS,START}	Time from PREPARERX/PREPARETX task to ready to receive/transmit		1.5		μs
t _{TWIS,SU_DAT}	Data setup time before positive edge on SCL – all modes	300			ns
t _{TWIS,HD_DAT}	Data hold time after negative edge on SCL – all modes	500			ns
t _{TWIS,HD_STA,100kbps}	TWI slave hold time from for START condition (SDA low to SCL low), 100 kbps $$	5200			ns
t _{TWIS,HD_STA,400kbps}	TWI slave hold time from for START condition (SDA low to SCL low), 400 kbps $$	1300			ns
t _{TWIS,SU_STO,100kbps}	TWI slave setup time from SCL high to STOP condition, 100 kbps	5200			ns
t _{TWIS,SU_STO,400kbps}	TWI slave setup time from SCL high to STOP condition, 400 kbps	1300			ns
t _{TWIS,BUF,100kbps}	TWI slave bus free time between STOP and START conditions, 100 kbps		4700		ns
t _{TWIS,BUF,400kbps}	TWI slave bus free time between STOP and START conditions, 400 kbps		1300		ns

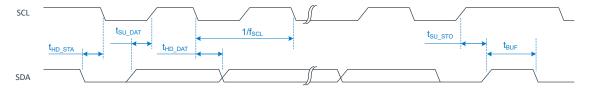


Figure 104: TWIS timing diagram, 1 byte transaction

6.19 UARTE — Universal asynchronous receiver/transmitter with EasyDMA

The Universal asynchronous receiver/transmitter with EasyDMA (UARTE) offers fast, full-duplex, asynchronous serial communication with built-in flow control (CTS, RTS) support in hardware at a rate up to 1 Mbps, and EasyDMA data transfer from/to RAM.

Listed here are the main features for UARTE:

- Full-duplex operation
- Automatic hardware flow control
- Optional even parity bit checking and generation
- EasyDMA
- Up to 1 Mbps baudrate
- · Return to IDLE between transactions supported (when using HW flow control)
- One or two stop bit



²¹ High bit rates or stronger pull-ups may require GPIOs to be set as High Drive, see GPIO chapter for more details.

· Least significant bit (LSB) first

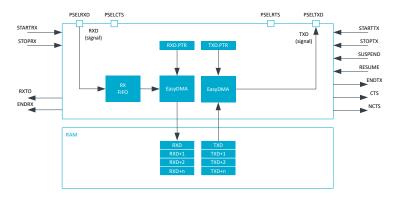


Figure 105: UARTE configuration

The GPIOs used for each UART interface can be chosen from any GPIO on the device and are independently configurable. This enables great flexibility in device pinout and efficient use of board space and signal routing.

Note: The external crystal oscillator must be enabled to obtain sufficient clock accuracy for stable communication. See CLOCK — Clock control on page 70 for more information.

6.19.1 EasyDMA

The UARTE implements EasyDMA for reading and writing to and from the RAM.

If the TXD.PTR and the RXD.PTR are not pointing to the Data RAM region, an EasyDMA transfer may result in a HardFault or RAM corruption. See Memory on page 21 for more information about the different memory regions.

The .PTR and .MAXCNT registers are double-buffered. They can be updated and prepared for the next RX/TX transmission immediately after having received the RXSTARTED/TXSTARTED event.

The ENDRX and ENDTX events indicate that the EasyDMA is finished accessing the RX or TX buffer in RAM.

6.19.2 Transmission

The first step of a DMA transmission is storing bytes in the transmit buffer and configuring EasyDMA. This is achieved by writing the initial address pointer to TXD.PTR, and the number of bytes in the RAM buffer to TXD.MAXCNT. The UARTE transmission is started by triggering the STARTTX task.

After each byte has been sent over the TXD line, a TXDRDY event will be generated.

When all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have been transmitted, the UARTE transmission will end automatically and an ENDTX event will be generated.

A UARTE transmission sequence is stopped by triggering the STOPTX task. A TXSTOPPED event will be generated when the UARTE transmitter has stopped.

If the ENDTX event has not already been generated when the UARTE transmitter has come to a stop, the UARTE will generate the ENDTX event explicitly even though all bytes in the TXD buffer, as specified in the TXD.MAXCNT register, have not been transmitted.

If flow control is enabled through the HWFC field in the CONFIG register, a transmission will be automatically suspended when CTS is deactivated and resumed when CTS is activated again, as shown in the following figure. A byte that is in transmission when CTS is deactivated will be fully transmitted before the transmission is suspended.



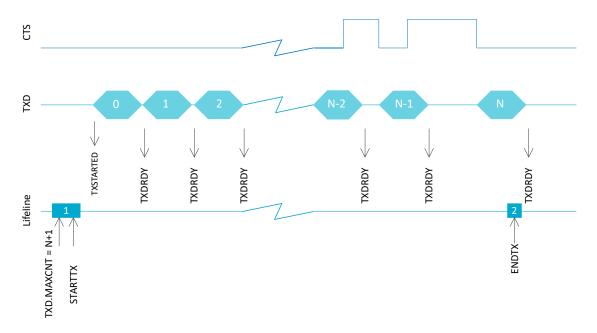


Figure 106: UARTE transmission

The UARTE transmitter will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTTX or after it has been stopped via STOPTX and the TXSTOPPED event has been generated. See POWER — Power control on page 63 for more information about power modes.

6.19.3 Reception

The UARTE receiver is started by triggering the STARTRX task. The UARTE receiver is using EasyDMA to store incoming data in an RX buffer in RAM.

The RX buffer is located at the address specified in the RXD.PTR register. The RXD.PTR register is double-buffered and it can be updated and prepared for the next STARTRX task immediately after the RXSTARTED event is generated. The size of the RX buffer is specified in the RXD.MAXCNT register. The UARTE generates an ENDRX event when it has filled up the RX buffer, as seen in the following figure.

For each byte received over the RXD line, an RXDRDY event will be generated. This event is likely to occur before the corresponding data has been transferred to Data RAM.

The RXD.AMOUNT register can be queried following an ENDRX event to see how many new bytes have been transferred to the RX buffer in RAM since the previous ENDRX event.



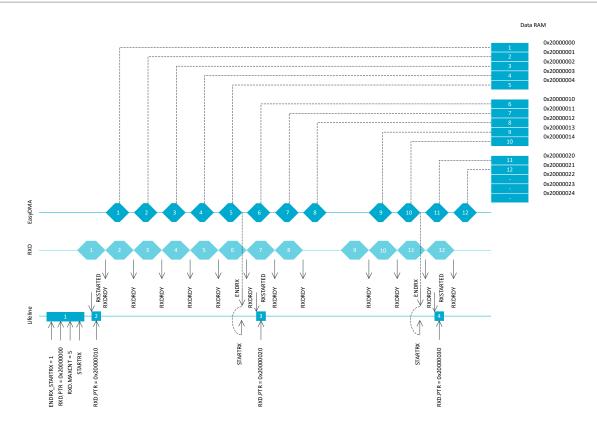


Figure 107: UARTE reception

The UARTE receiver is stopped by triggering the STOPRX task. An RXTO event is generated when the UARTE has stopped. The UARTE will make sure that an impending ENDRX event will be generated before the RXTO event is generated. This means that the UARTE will guarantee that no ENDRX event will be generated after RXTO, unless the UARTE is restarted or a FLUSHRX command is issued after the RXTO event is generated.

Note: If the ENDRX event has not been generated when the UARTE receiver stops, indicating that all pending content in the RX FIFO has been moved to the RX buffer, the UARTE will generate the ENDRX event explicitly even though the RX buffer is not full. In this scenario the ENDRX event will be generated before the RXTO event is generated.

To determine the amount of bytes the RX buffer has received, the CPU can read the RXD.AMOUNT register following the ENDRX event or the RXTO event.

The UARTE is able to receive up to four bytes after the STOPRX task has been triggered, as long as these are sent in succession immediately after the RTS signal is deactivated. After the RTS is deactivated, the UART is able to receive bytes for a period of time equal to the time needed to send four bytes on the configured baud rate.

After the RXTO event is generated the internal RX FIFO may still contain data, and to move this data to RAM the FLUSHRX task must be triggered. To make sure that this data does not overwrite data in the RX buffer, the RX buffer should be emptied or the RXD.PTR should be updated before the FLUSHRX task is triggered. To make sure that all data in the RX FIFO is moved to the RX buffer, the RXD.MAXCNT register must be set to RXD.MAXCNT > 4, as seen in the following figure. The UARTE will generate the ENDRX event after completing the FLUSHRX task even if the RX FIFO was empty or if the RX buffer does not get filled up. To be able to know how many bytes have actually been received into the RX buffer in this case, the CPU can read the RXD.AMOUNT register following the ENDRX event.



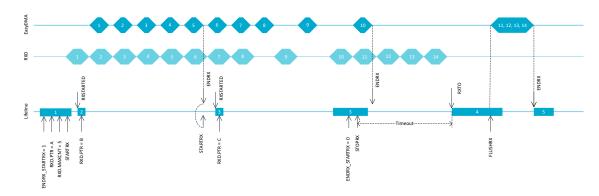


Figure 108: UARTE reception with forced stop via STOPRX

If HW flow control is enabled through the HWFC field in the CONFIG register, the RTS signal will be deactivated when the receiver is stopped via the STOPRX task or when the UARTE is only able to receive four more bytes in its internal RX FIFO.

With flow control disabled, the UARTE will function in the same way as when the flow control is enabled except that the RTS line will not be used. This means that no signal will be generated when the UARTE has reached the point where it is only able to receive four more bytes in its internal RX FIFO. Data received when the internal RX FIFO is filled up, will be lost.

The UARTE receiver will be in its lowest activity level, and consume the least amount of energy, when it is stopped, i.e. before it is started via STARTRX or after it has been stopped via STOPRX and the RXTO event has been generated. See POWER — Power control on page 63 for more information about power modes.

6.19.4 Frror conditions

An ERROR event, in the form of a framing error, will be generated if a valid stop bit is not detected in a frame. Another ERROR event, in the form of a break condition, will be generated if the RXD line is held active low for longer than the length of a data frame. Effectively, a framing error is always generated before a break condition occurs.

An ERROR event will not stop reception. If the error was a parity error, the received byte will still be transferred into Data RAM, and so will following incoming bytes. If there was a framing error (wrong stop bit), that specific byte will NOT be stored into Data RAM, but following incoming bytes will.

6.19.5 Using the UARTE without flow control

If flow control is not enabled, the interface will behave as if the CTS and RTS lines are kept active all the time.

6.19.6 Parity and stop bit configuration

Automatic even parity generation for both transmission and reception can be configured using the register CONFIG on page 350. See the register description for details.

The amount of stop bits can also be configured through the register CONFIG on page 350.

6.19.7 Low power

When putting the system in low power and the peripheral is not needed, lowest possible power consumption is achieved by stopping, and then disabling the peripheral.

The STOPTX and STOPRX tasks may not be always needed (the peripheral might already be stopped), but if STOPTX and/or STOPRX is sent, software shall wait until the TXSTOPPED and/or RXTO event is received in response, before disabling the peripheral through the ENABLE register.



6.19.8 Pin configuration

The different signals RXD, CTS (Clear To Send, active low), RTS (Request To Send, active low), and TXD associated with the UARTE are mapped to physical pins according to the configuration specified in the PSEL.RXD, PSEL.RTS, and PSEL.TXD registers respectively.

The PSEL.RXD, PSEL.CTS, PSEL.RTS, and PSEL.TXD registers and their configurations are only used as long as the UARTE is enabled, and retained only for the duration the device is in ON mode. PSEL.RXD, PSEL.RTS, PSEL.RTS, and PSEL.TXD must only be configured when the UARTE is disabled.

To secure correct signal levels on the pins by the UARTE when the system is in OFF mode, the pins must be configured in the GPIO peripheral as described in the following table.

Only one peripheral can be assigned to drive a particular GPIO pin at a time. Failing to do so may result in unpredictable behavior.

UARTE signal	UARTE pin	Direction	Output value
RXD	As specified in PSEL.RXD	Input	Not applicable
CTS	As specified in PSEL.CTS	Input	Not applicable
RTS	As specified in PSEL.RTS	Output	1
TXD	As specified in PSEL.TXD	Output	1

Table 47: GPIO configuration before enabling peripheral

6.19.9 Registers

Instances

Instance	Base address	TrustZone			Split access	Description		
		Мар	Att	DMA				
UARTEO: S	0x50008000	US	NS	SA	No	Universal asynchronous receiver/		
UARTE0 : NS	0x40008000	03	INS	3A	NO	transmitter with EasyDMA 0		
UARTE1:S	0x50009000	US	NS	SA	No	Universal asynchronous receiver/		
UARTE1: NS	0x40009000	03	JS INS SA		NO	transmitter with EasyDMA 1		
UARTE2:S	0x5000A000	US	NS	SA	No	Universal asynchronous receiver/		
UARTE2 : NS	0x4000A000	03	NS	3A	NO	transmitter with EasyDMA 2		
UARTE3:S	0x5000B000	US	NS	SA	No	Universal asynchronous receiver/		
UARTE3: NS	0x4000B000	03	143	SA	NO	transmitter with EasyDMA 3		

Register overview

Register	Offset	TZ	Description
TASKS_STARTRX	0x000		Start UART receiver
TASKS_STOPRX	0x004		Stop UART receiver
TASKS_STARTTX	0x008		Start UART transmitter
TASKS_STOPTX	0x00C		Stop UART transmitter
TASKS_FLUSHRX	0x02C		Flush RX FIFO into RX buffer
SUBSCRIBE_STARTRX	0x080		Subscribe configuration for task STARTRX
SUBSCRIBE_STOPRX	0x084		Subscribe configuration for task STOPRX
SUBSCRIBE_STARTTX	0x088		Subscribe configuration for task STARTTX
SUBSCRIBE_STOPTX	0x08C		Subscribe configuration for task STOPTX
SUBSCRIBE_FLUSHRX	0x0AC		Subscribe configuration for task FLUSHRX
EVENTS_CTS	0x100		CTS is activated (set low). Clear To Send.
EVENTS_NCTS	0x104		CTS is deactivated (set high). Not Clear To Send.



Register	Offset	TZ	Description
EVENTS_RXDRDY	0x108		Data received in RXD (but potentially not yet transferred to Data RAM)
EVENTS_ENDRX	0x110		Receive buffer is filled up
EVENTS_TXDRDY	0x11C		Data sent from TXD
EVENTS_ENDTX	0x120		Last TX byte transmitted
EVENTS_ERROR	0x124		Error detected
EVENTS_RXTO	0x144		Receiver timeout
EVENTS_RXSTARTED	0x14C		UART receiver has started
EVENTS_TXSTARTED	0x150		UART transmitter has started
EVENTS_TXSTOPPED	0x158		Transmitter stopped
PUBLISH_CTS	0x180		Publish configuration for event CTS
PUBLISH_NCTS	0x184		Publish configuration for event NCTS
PUBLISH_RXDRDY	0x188		Publish configuration for event RXDRDY
PUBLISH_ENDRX	0x190		Publish configuration for event ENDRX
PUBLISH_TXDRDY	0x19C		Publish configuration for event TXDRDY
PUBLISH_ENDTX	0x1A0		Publish configuration for event ENDTX
PUBLISH_ERROR	0x1A4		Publish configuration for event ERROR
PUBLISH_RXTO	0x1C4		Publish configuration for event RXTO
PUBLISH_RXSTARTED	0x1CC		Publish configuration for event RXSTARTED
PUBLISH_TXSTARTED	0x1D0		Publish configuration for event TXSTARTED
PUBLISH_TXSTOPPED	0x1D8		Publish configuration for event TXSTOPPED
SHORTS	0x200		Shortcuts between local events and tasks
INTEN	0x300		Enable or disable interrupt
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
ERRORSRC	0x480		Error source
			This register is read/write one to clear.
ENABLE	0x500		Enable UART
PSEL.RTS	0x508		Pin select for RTS signal
PSEL.TXD	0x50C		Pin select for TXD signal
PSEL.CTS	0x510		Pin select for CTS signal
PSEL.RXD	0x514		Pin select for RXD signal
BAUDRATE	0x524		Baud rate. Accuracy depends on the HFCLK source selected.
RXD.PTR	0x534		Data pointer
RXD.MAXCNT	0x538		Maximum number of bytes in receive buffer
RXD.AMOUNT	0x53C		Number of bytes transferred in the last transaction
TXD.PTR	0x544		Data pointer
TXD.MAXCNT	0x548		Maximum number of bytes in transmit buffer
TXD.AMOUNT	0x54C		Number of bytes transferred in the last transaction
CONFIG	0x56C		Configuration of parity and hardware flow control

6.19.9.1 TASKS_STARTRX

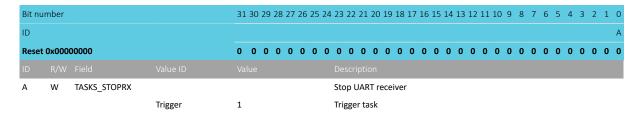
Address offset: 0x000 Start UART receiver

Bit no	umber			3	1 30	29	28	27	26 2	5 2	24 2	3 2	22 2	1 2	0 1	9 1	8 17	7 16	15	14	13	12	11 1	.0 !	9 8	7	6	5	4	3	2	1 0
ID																																Α
Rese	t 0x000	00000		0	0	0	0	0	0 (0	0 ()	0 () (0 (0 (0 0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 0
ID																																
Α	W	TASKS_STARTRX									S	tar	t UA	٩RT	rec	ceiv	er															
			Trigger	1							Т	rig	ger	tasl	k																	



6.19.9.2 TASKS_STOPRX

Address offset: 0x004 Stop UART receiver



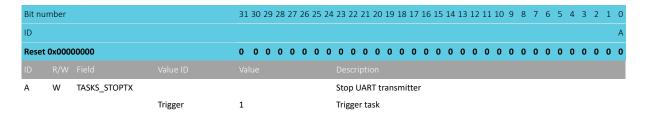
6.19.9.3 TASKS STARTTX

Address offset: 0x008 Start UART transmitter

Bit no	umber			31 30 29 28 27	26 25	24 23	3 22 2	1 20	19 1	18 17	16 1	5 14	13 12	2 11	10 9	8	7	6	5	4 3	2	1 0
ID																						А
Rese	t 0x000	00000		0 0 0 0 0	0 0	0 0	0 (0 0	0	0 0	0 0	0	0 0	0	0 0	0	0	0	0	0 (0	0 0
ID																						
Α	W	TASKS_STARTTX				St	art U	ART t	ransı	mitter	-											
			Trigger	1		Tr	igger	task														

6.19.9.4 TASKS_STOPTX

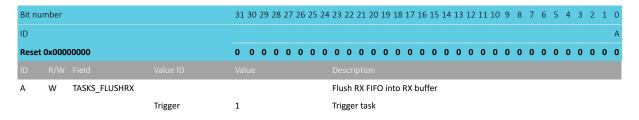
Address offset: 0x00C Stop UART transmitter



6.19.9.5 TASKS_FLUSHRX

Address offset: 0x02C

Flush RX FIFO into RX buffer

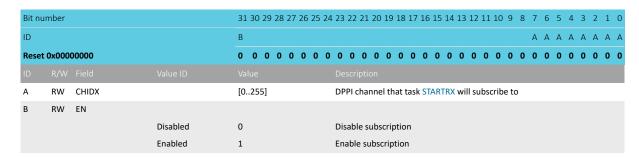


6.19.9.6 SUBSCRIBE_STARTRX

Address offset: 0x080



Subscribe configuration for task STARTRX



6.19.9.7 SUBSCRIBE_STOPRX

Address offset: 0x084

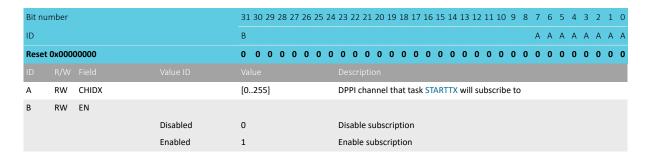
Subscribe configuration for task STOPRX

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that task STOPRX will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.19.9.8 SUBSCRIBE_STARTTX

Address offset: 0x088

Subscribe configuration for task STARTTX

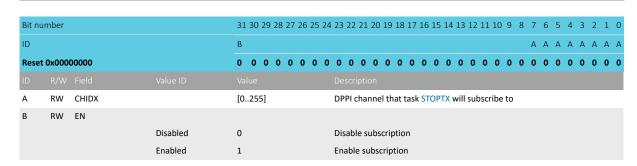


6.19.9.9 SUBSCRIBE_STOPTX

Address offset: 0x08C

Subscribe configuration for task STOPTX





6.19.9.10 SUBSCRIBE_FLUSHRX

Address offset: 0x0AC

Subscribe configuration for task FLUSHRX

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task FLUSHRX will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription
			Enabled	1	Enable subscription

6.19.9.11 EVENTS_CTS

Address offset: 0x100

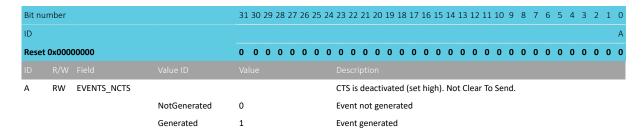
CTS is activated (set low). Clear To Send.

Bit no	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					A
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	EVENTS_CTS			CTS is activated (set low). Clear To Send.
			NotGenerated	0	Event not generated
			Generated	1	Event generated

6.19.9.12 EVENTS_NCTS

Address offset: 0x104

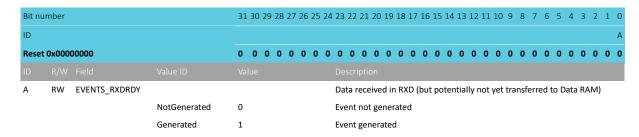
CTS is deactivated (set high). Not Clear To Send.



6.19.9.13 EVENTS_RXDRDY

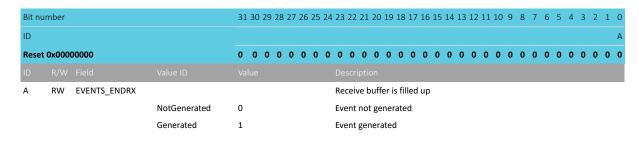


Data received in RXD (but potentially not yet transferred to Data RAM)



6.19.9.14 EVENTS ENDRX

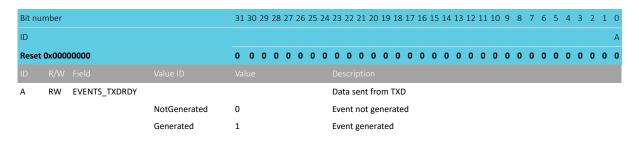
Address offset: 0x110 Receive buffer is filled up



6.19.9.15 EVENTS TXDRDY

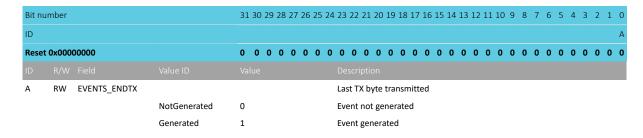
Address offset: 0x11C

Data sent from TXD



6.19.9.16 EVENTS ENDTX

Address offset: 0x120 Last TX byte transmitted

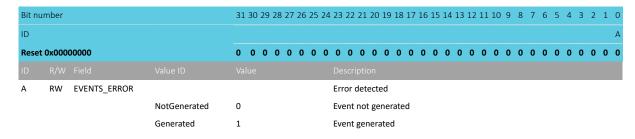


6.19.9.17 EVENTS ERROR



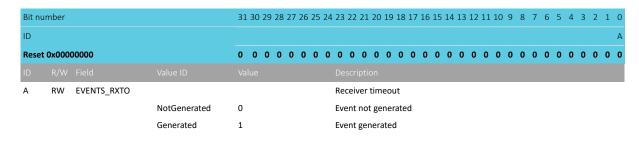


Error detected



6.19.9.18 EVENTS RXTO

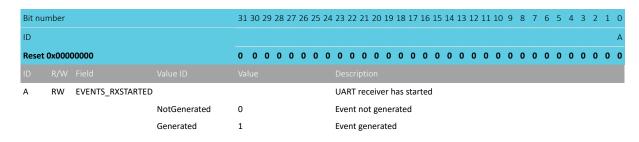
Address offset: 0x144
Receiver timeout



6.19.9.19 EVENTS_RXSTARTED

Address offset: 0x14C

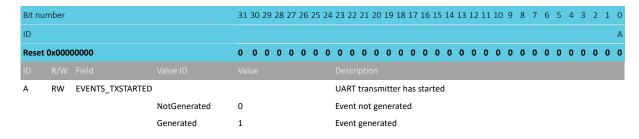
UART receiver has started



6.19.9.20 EVENTS TXSTARTED

Address offset: 0x150

UART transmitter has started

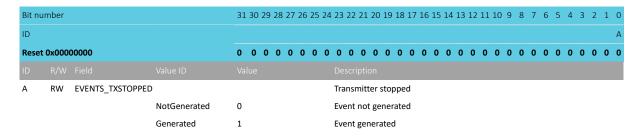


6.19.9.21 EVENTS_TXSTOPPED





Transmitter stopped



6.19.9.22 PUBLISH CTS

Address offset: 0x180

Publish configuration for event CTS

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event CTS will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.19.9.23 PUBLISH_NCTS

Address offset: 0x184

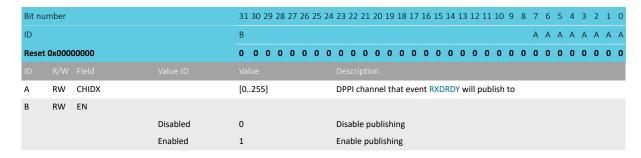
Publish configuration for event NCTS

Bit nu	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event NCTS will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.19.9.24 PUBLISH_RXDRDY

Address offset: 0x188

Publish configuration for event RXDRDY



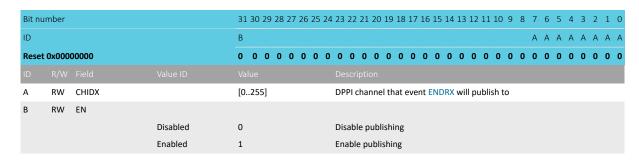




6.19.9.25 PUBLISH_ENDRX

Address offset: 0x190

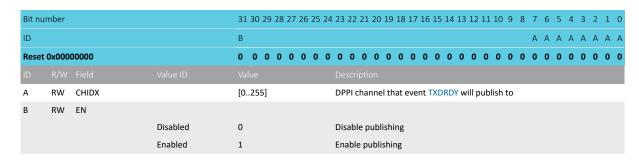
Publish configuration for event ENDRX



6.19.9.26 PUBLISH_TXDRDY

Address offset: 0x19C

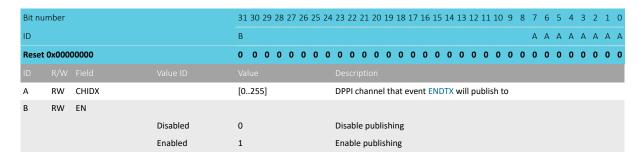
Publish configuration for event TXDRDY



6.19.9.27 PUBLISH ENDTX

Address offset: 0x1A0

Publish configuration for event ENDTX

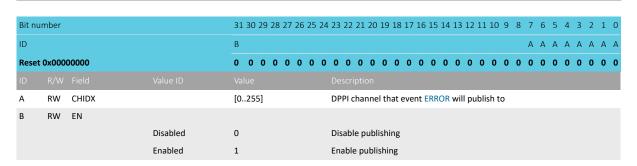


6.19.9.28 PUBLISH_ERROR

Address offset: 0x1A4

Publish configuration for event ERROR





6.19.9.29 PUBLISH_RXTO

Address offset: 0x1C4

Publish configuration for event RXTO

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event RXTO will publish to
В	RW	EN			
			Disabled	0	Disable publishing
			Enabled	1	Enable publishing

6.19.9.30 PUBLISH_RXSTARTED

Address offset: 0x1CC

Publish configuration for event RXSTARTED

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				В	A A A A A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CHIDX		[0255]	DPPI channel that event RXSTARTED will publish to
A B	RW RW	CHIDX EN		[0255]	DPPI channel that event RXSTARTED will publish to
			Disabled	0255]	DPPI channel that event RXSTARTED will publish to Disable publishing

6.19.9.31 PUBLISH_TXSTARTED

Address offset: 0x1D0

Publish configuration for event TXSTARTED

Bit n	umber			31 30 29 28	8 27 26 25	24 2	3 22	21 2	20 1	9 18	8 17	16	15 1	4 1	.3 12	11	10	9 8	3 7	6	5	4	3 2	1	0
ID				В															Α	Α	Α	Α	A A	A	Α
Rese	t 0x000	00000		0 0 0 0	0 0 0	0 (0 0	0	0 (0	0	0	0	0 (0 0	0	0	0 (0	0	0	0	0 0	0	0
ID																									
Α	RW	CHIDX		[0255]		D	PPI	chan	nel t	that	eve	nt T	XST	ART	ED w	vill p	ubli	ish to)						
В	RW	EN																							
			Disabled	0		D	isab	le pu	ıblisl	hing	3														
			Enabled	1		Е	nabl	e pu	blish	ning															

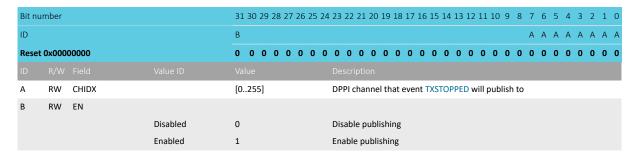




6.19.9.32 PUBLISH_TXSTOPPED

Address offset: 0x1D8

Publish configuration for event TXSTOPPED



6.19.9.33 SHORTS

Address offset: 0x200

Shortcuts between local events and tasks

Bit nu	ımber			31	30	29 2	28	27 2	26	25	24	23	22 2	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID																													D	С				
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																		
С	RW	ENDRX_STARTRX										Shc	rtcı	ut k	betv	vee	en e	ver	nt E	ND	RX	and	d ta	sk	STA	RTF	RX							
			Disabled	0								Disa	able	sh	ort	cut																		
			Enabled	1								Ena	ble	sh	orto	ut																		
D	RW	ENDRX_STOPRX										Shc	rtcı	ut k	betv	vee	en e	ver	nt E	ND	RX	and	d ta	sk	STO	PR	X							
			Disabled	0								Disa	able	sh	ort	cut																		
			Enabled	1								Ena	ble	sh	orto	ut																		

6.19.9.34 INTEN

Address offset: 0x300

Enable or disable interrupt

Bit nu	ımber			31 3	0 29	28 2	7 26	5 25 2	4 2	23 22	2 21	1 20	19	18	17	16 1	5 1	4 1	13 :	12 1	1 1	9	8	7	6	5	4	3	2	1 0
ID										L		J	1		Н							G	F	Ε			D		C I	ВА
Reset	0x000	00000		0 (0 0	0 (0 0	0 (0 (0 0	0	0	0	0	0	0 ()	0	0	0 (0	0	0	0	0	0	0	0	0 (0 0
ID																														
Α	RW	CTS							Е	nab	le o	r di	sabl	e in	iter	rupt	foi	ev	en	t CT	S									
			Disabled	0					C	Disab	le																			
			Enabled	1					Е	nab	le																			
В	RW	NCTS							Е	nab	le o	r di	sabl	e in	iter	rupt	foi	ev	en	t NC	TS									
			Disabled	0					C	Disab	le																			
			Enabled	1					E	nab	le																			
С	RW	RXDRDY							E	nab	le o	r di	sabl	e in	iter	rupt	foi	ev	en	t RX	DRE	Υ								
			Disabled	0					C	Disab	le																			
			Enabled	1					E	nab	le																			
D	RW	ENDRX							E	nab	le o	r di	sabl	e in	iter	rupt	foi	ev	en	t EN	DRX									
			Disabled	0					C	Disab	le																			
			Enabled	1					E	nab	le																			
Е	RW	TXDRDY							Е	nab	le o	r di	sabl	e in	iter	rupt	foi	ev	en	t TX	DRD	Υ								





Bit nu	ımber			31	1 30	29 2	28 2	27 26	5 25 2	24 2	23 2	2 21	L 20	19	18	17	16 1	15 :	14 1	.3 1	2 1	1 10	9	8	7	6	5	4	3	2	1	0
ID											1	L	J	-1		Н							G	F	Ε			D		С	В	Α
Reset	t 0x000	00000		0	0	0	0	0 0	0	0	0 (0 0	0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0	0	0
ID																																
			Disabled	0						С	Disa	ble																				_
			Enabled	1						Е	Enab	ole																				
F	RW	ENDTX								Е	Enab	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	EN	DTX										
			Disabled	0						0	Disa	ble																				
			Enabled	1						Е	Enak	ole																				
G	RW	ERROR								E	nat	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	ERI	ROR										
			Disabled	0						0	Disa	ble																				
			Enabled	1						Е	Enat	ole																				
Н	RW	RXTO								E	Enak	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	RX	ГО										
			Disabled	0						0	Disa	ble																				
			Enabled	1						Е	Enak	ole																				
1	RW	RXSTARTED								Е	nat	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	RX:	STAR	TEC)								
			Disabled	0						[Disa	ble																				
			Enabled	1						Е	Enat	ole																				
J	RW	TXSTARTED								Е	Enak	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	TXS	STAR	TEC)								
			Disabled	0						С	Disa	ble																				
			Enabled	1						E	Enak	ole																				
L	RW	TXSTOPPED								Е	nat	ole o	r di	sabl	le ir	nter	rupt	fo	r ev	ent	TXS	ТОР	PE)								
			Disabled	0							Disa	ble																				
			Enabled	1						Е	nat	ole																				

6.19.9.35 INTENSET

Address offset: 0x304

Enable interrupt

Bit nu	ımber			31	30	29 2	8 27	7 26	25 2	4 2	3 2	2 23	1 20	19	18	17 1	6 1	5 14	13	12	11 1	10 9	8	7	6	5	4	3 2	2 1	. 0
ID											L	L	J	1		Н						G	F	Ε			D	(С В	3 A
Reset	0x000	00000		0	0	0 (0 0	0	0 (0 (0 (0 0	0	0	0	0 () (0	0	0	0	0 0	0	0	0	0	0	0 (0	0
ID																														
Α	RW	CTS								V	Vrit	e '1'	' to	enak	ole i	nter	rup	t fo	eve	ent (CTS									
			Set	1						Е	nab	ole																		
			Disabled	0						R	lead	d: Di	isab	led																
			Enabled	1						R	lead	d: Er	nabl	ed																
В	RW	NCTS								W	Vrit	e '1'	' to	enat	ole i	nter	rup	t fo	eve	ent l	NCT:	S								
			Set	1						Е	nab	ole																		
			Disabled	0						R	lead	d: Di	isab	led																
			Enabled	1						R	lead	d: Er	nabl	ed																
С	RW	RXDRDY								V	Vrit	e '1'	' to	enat	ole i	nter	rup	t fo	eve	ent F	RXD	RDY								
			Set	1						Е	nab	ole																		
			Disabled	0						R	lead	d: Di	isab	led																
			Enabled	1						R	lead	d: Er	nabl	ed																
D	RW	ENDRX								V	Vrit	e '1'	' to	enat	ole i	nter	rup	t fo	eve	ent E	ND	RX								
			Set	1						Е	nab	ole																		
			Disabled	0						R	lead	d: Di	isab	led																
			Enabled	1						R	lead	d: Er	nabl	ed																
E	RW	TXDRDY								V	Vrit	e '1'	' to	enak	ole i	nter	rup	t fo	eve	ent 1	IDX	RDY								
			Set	1						Е	nab	ole																		
			Disabled	0						R	lead	d: Di	isab	led																



Bit nu	mber			31	30	29 2	28 2	27 26	6 2	5 24	23	22	21	20	19	18	17	16	15	14	13	12 1	l1	10	9	8	7	6	5	4	3	2	1	0
ID												L		J	L		Н								G	F	Ε			D		С	В	Α
Reset	0x000	00000		0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																		
			Enabled	1							Rea	ad: I	Ena	ble	d																			
F	RW	ENDTX									Wr	ite '	'1' t	o e	nat	ole i	int	errı	ıpt	for	eve	nt E	NE	XTC										
			Set	1							Ena	able	•																					
			Disabled	0							Rea	ad: ۱	Disa	ble	ed																			
			Enabled	1							Rea	ad: I	Ena	ble	d																			
G	RW	ERROR									Wr	ite '	'1' t	o e	nab	ole i	int	errı	ıpt	for	eve	nt E	RR	OR										
			Set	1							Ena	able	9																					
			Disabled	0							Rea	ad: ۱	Disa	ble	ed																			
			Enabled	1							Rea	ad: I	Ena	ble	d																			
Н	RW	RXTO									Wr	ite '	'1' t	o e	nat	ole i	int	errı	ıpt	for	eve	nt R	XT	O										
			Set	1							Ena	able	<u> </u>																					
			Disabled	0							Rea	ad: I	Disa	able	d																			
			Enabled	1							Rea	ad: ۱	Ena	ble	d																			
I	RW	RXSTARTED									Wr	ite '	'1' t	o e	nat	ole i	int	errı	ıpt	for	eve	nt R	XS	TAR	TE	D								
			Set	1							Ena	able	2																					
			Disabled	0							Rea	ad: ۱	Disa	ble	ed																			
			Enabled	1							Rea	ad: I	Ena	ble	d																			
J	RW	TXSTARTED									Wr	ite '	'1' t	o e	nab	ole i	int	errı	ıpt	for	eve	nt T	XS	TAR	TE	D								
			Set	1							Ena	able	•																					
			Disabled	0							Rea	ad: ۱	Disa	ble	ed																			
			Enabled	1							Rea	ad: ۱	Ena	ble	d																			
L	RW	TXSTOPPED									Wr	ite '	'1' t	o e	nab	ole	int	errı	ıpt	for	eve	nt T	XS	TOF	PE	D								
			Set	1							Ena	able	2																					
			Disabled	0							Rea	ad: ۱	Disa	ble	ed																			
			Enabled	1							Rea	ad: ۱	Ena	ble	d																			

6.19.9.36 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					L J I H G F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	CTS			Write '1' to disable interrupt for event CTS
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
В	RW	NCTS			Write '1' to disable interrupt for event NCTS
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
С	RW	RXDRDY			Write '1' to disable interrupt for event RXDRDY
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled
D	RW	ENDRX			Write '1' to disable interrupt for event ENDRX
			Clear	1	Disable





Bit nu	mber			33	1 30	29	28	27 2	26	25 2	4 23	3 22	21	20	19 1	.8 1	7 1	5 15	14	13	12	11	10	9	8	7	6 !	5 4	3	2	1	0
ID												L		J	l l	ŀ	4							G	F	E		D		С	В	Α
Reset	0x000	00000		0	0	0	0	0	0	0 (0	0	0	0	0 (0 (0 0	0	0	0	0	0	0	0	0	0	0 (0	0	0	0	0
			Disabled	0							Re	ead:	Disa	ble	ed																	Ī
			Enabled	1							Re	ead:	Ena	ble	d																	
E	RW	TXDRDY									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	TX	DRD	Υ								
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	able	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
F	RW	ENDTX									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	EN	DTX									
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	able	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
G	RW	ERROR									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	ER	ROR									
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	able	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
Н	RW	RXTO									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	RX	ТО									
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	ble	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
I	RW	RXSTARTED									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	RX:	STAF	RTE	D							
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	able	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
J	RW	TXSTARTED									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	TX:	STAF	TE	D							
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	able	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	
L	RW	TXSTOPPED									W	/rite	'1' t	o d	isab	le ii	nter	rup	t fo	ev	ent	TX:	STOR	PE	D							
			Clear	1							Di	isabl	e																			
			Disabled	0							Re	ead:	Disa	ble	ed																	
			Enabled	1							Re	ead:	Ena	ble	d																	

6.19.9.37 ERRORSRC

Address offset: 0x480

Error source

This register is read/write one to clear.

Bit nu	ımber		31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Reset	0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
Α	RW OVERRUN			Overrun error
	W1C			A start bit is received while the previous data still lies in RXD. (Previous data
				is lost.)
		NotPresent	0	Read: error not present
		Present	1	Read: error present
В	RW PARITY			Parity error
	W1C			A character with bad parity is received, if HW parity check is enabled.





Bit nu	umber		31 30 29 28 27 26 25	5 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				D C B A
Rese	t 0x00000000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				Description
		NotPresent	0	Read: error not present
		Present	1	Read: error present
С	RW FRAMING			Framing error occurred
	W1C			A valid stop bit is not detected on the serial data input after all bits in a
				character have been received.
		NotPresent	0	Read: error not present
		Present	1	Read: error present
D	RW BREAK			Break condition
	W1C			The serial data input is '0' for longer than the length of a data frame. (The
				data frame length is 10 bits without parity bit, and 11 bits with parity bit).
		NotPresent	0	Read: error not present
		Present	1	Read: error present

6.19.9.38 ENABLE

Address offset: 0x500

Enable UART

Bit n	umber			31 30 29	28 27 2	26 25	24 23	22 2	1 20 1	19 18	3 17 1	16 15	14	13 12	2 11	10 9	8	7	6	5	4	3	2 1	. 0
ID																						A	4 <i>A</i>	A
Rese	t 0x000	00000		0 0 0	0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0 0	0	0	0	0	0	0 (0 0	0
ID																								
Α	RW	ENABLE					En	able c	or disa	able (JART	E												
			Disabled	0			Dis	able	UART	E														
			Enabled	8			En	able (JARTE	Ε														

6.19.9.39 PSEL.RTS

Address offset: 0x508

Pin select for RTS signal

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18	8 17 16 1	5 14 1	3 12 1	1 10 !	9 8	7	6	5	4	3 2	2 1	0
ID				В										Α	A A	A	Α
Reset	t OxFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1	1 1 1	1 1 1	. 1 1	1	1 1	1	1	1	1	1 1	. 1	1
ID																	
Α	RW	PIN		[031]	Pin number												
A B	RW RW	PIN CONNECT		[031]	Pin number Connection												
			Disconnected	[031]													

6.19.9.40 PSEL.TXD

Address offset: 0x50C Pin select for TXD signal



Bit nu	mber			31 3	0 29 :	28 27	7 26	25 2	4 23	3 22	21 20	0 19	18	17	16 1	5 14	1 13	12	11 1	.0 !	9 8	7	6	5	4	3 2	. 1	0
ID				В																					Α	A A	A	Α
Reset	0xFFFF	FFFF		1 1	l 1	1 1	1	1	1 1	1	1 1	. 1	1	1	1 :	1 1	1	1	1	1	L 1	1	1	1	1	1 1	1	1
ID																												
Α	RW	PIN		[03	1]				Pii	n nı	ımber	r																
В	RW	CONNECT							Co	onne	ection																	
			Disconnected	1					Di	scoi	nnect																	
			Connected	0					Co	onne	ect																	

6.19.9.41 PSEL.CTS

Address offset: 0x510
Pin select for CTS signal

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A
Reset	0xFFFF	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.19.9.42 PSEL.RXD

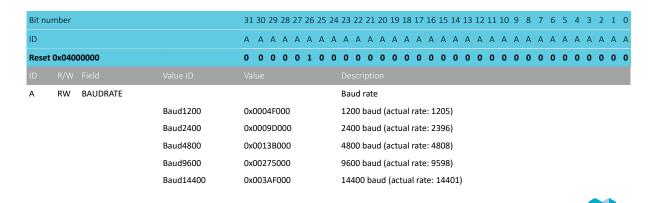
Address offset: 0x514
Pin select for RXD signal

Bit nu	mber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	АААА
Reset	0xFFFI	FFFF		1 1 1 1 1 1 1 1	1111111111111111111111111111
ID					Description
Α	RW	PIN		[031]	Pin number
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

6.19.9.43 BAUDRATE

Address offset: 0x524

Baud rate. Accuracy depends on the HFCLK source selected.





Bit number		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		_ A A A A A A A A A A A A A A A A A A A
Reset 0x04000000		0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field		
	Baud19200	0x004EA000 19200 baud (actual rate: 19208)
	Baud28800	0x0075C000 28800 baud (actual rate: 28777)
	Baud31250	0x00800000 31250 baud
	Baud38400	0x009D0000 38400 baud (actual rate: 38369)
	Baud56000	0x00E50000 56000 baud (actual rate: 55944)
	Baud57600	0x00EB0000 57600 baud (actual rate: 57554)
	Baud76800	0x013A9000 76800 baud (actual rate: 76923)
	Baud115200	0x01D60000 115200 baud (actual rate: 115108)
	Baud230400	0x03B00000 230400 baud (actual rate: 231884)
	Baud250000	0x04000000 250000 baud
	Baud460800	0x07400000 460800 baud (actual rate: 457143)
	Baud921600	0x0F000000 921600 baud (actual rate: 941176)
	Baud1M	0x10000000 1 megabaud

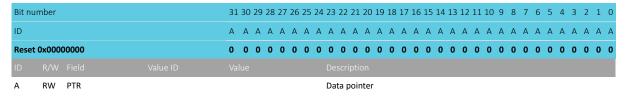
6.19.9.44 RXD

RXD EasyDMA channel

6.19.9.44.1 RXD.PTR

Address offset: 0x534

Data pointer



See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.44.2 RXD.MAXCNT

Address offset: 0x538

Maximum number of bytes in receive buffer

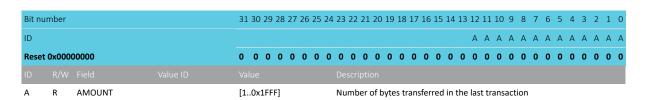
Α	RW MAXCN	NT .	[10x1FFF]	Maximum number of bytes in receive buffer
ID				Description
Rese	t 0x00000000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit nu	ımber		31 30 29 28 27 26 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

6.19.9.44.3 RXD.AMOUNT

Address offset: 0x53C

Number of bytes transferred in the last transaction





6.19.9.45 TXD

TXD EasyDMA channel

6.19.9.45.1 TXD.PTR

Address offset: 0x544

Data pointer

Bit nu	mber		31	30	29	28	27 2	26 2	5 2	24 2	23 2	2 2	21 2	20 1	.9 1	8 17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2 1	1 0
ID			А	Α	Α	Α	Α	Α /	Δ.	A	Α ,	Α,	Α /	Α /	Δ ,	A A	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Δ ,	4 A
Reset	0x000	00000	0	0	0	0	0	0 (0	0	0	0 (0 (0 (0 (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0
ID																																
Α	RW	PTR									Data	рс	oint	er																		

See the memory chapter for details about which memories are available for EasyDMA.

6.19.9.45.2 TXD.MAXCNT

Address offset: 0x548

Maximum number of bytes in transmit buffer

ID	R/W	Field	Value ID	Value Description [10x1FFF] Maximum number of bytes in transmit buffer
Reset	t 0x000	00000		0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID				A A A A A A A A A A A A A A A A A A A
Bit nu	umber			31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1

6.19.9.45.3 TXD.AMOUNT

Address offset: 0x54C

Number of bytes transferred in the last transaction

Bit nu	mber		31 3	29 2	8 27 2	6 25	24 2	3 22	21	20 1	.9 18	3 17	16 1	5 1	4 13	12	11	10	9	8	7	6	5 4	1 3	2	1	C
ID																Α	Α	Α	Α	Α	Α	Α,	4 <i>A</i>	A A	Α	Α	Δ
Reset	0x000	00000	0 0	0 0	0 0	0 0	0 (0	0	0	0 0	0	0	0 (0	0	0	0	0	0	0	0	0 (0	0	0	D
ID																											Ī
Α	R	AMOUNT	[10	x1FFF]			N	luml	oer c	f by	tes t	rans	ferre	ed ir	the	las	t tra	nsa	cti	on							_

6.19.9.46 CONFIG

Address offset: 0x56C

Configuration of parity and hardware flow control



Bit nu	ımber			31 30 29 28 27	26 25 2	4 23 22 21 2	20 19 1	8 17 10	5 15	14 1	13 12	11	10 9	8	7	6	5	4 3	2	1	0
ID																		СВ	В	В	
Reset	0x000	00000		0 0 0 0 0	0 0 0	0 0 0	0 0 0	0 0	0	0	0 0	0	0 (0	0	0	0	0 0	0	0	0
	RW	HWFC				Hardware	flow co	ntrol													
			Disabled	0		Disabled															
			Enabled	1		Enabled															
В	RW	PARITY				Parity															
			Excluded	0x0		Exclude pa	rity bit														
			Included	0x7		Include ev	en parit	y bit													
С	RW	STOP				Stop bits															
			One	0		One stop b	oit														
			Two	1		Two stop b	oits														

6.19.10 Electrical specification

6.19.10.1 UARTE electrical specification

Symbol	Description	Min.	Тур.	Max.	Units
f _{UARTE}	Baud rate for UARTE ²² .			1000	kbps
t _{UARTE,CTSH}	CTS high time	1			μs
t _{UARTE,START}	Time from STARTRX/STARTTX task to transmission started		0.25		μs

6.20 WDT — Watchdog timer

A countdown watchdog timer using the low-frequency clock source (LFCLK) offers configurable and robust protection against application lock-up.

The watchdog timer is started by triggering the START task.

The watchdog can be paused during long CPU sleep periods for low power applications and when the debugger has halted the CPU. The watchdog is implemented as a down-counter that generates a TIMEOUT event when it wraps over after counting down to 0. When the watchdog timer is started through the START task, the watchdog counter is loaded with the value specified in the CRV register. This counter is also reloaded with the value specified in the CRV register when a reload request is granted.

The watchdog's timeout period is given by:

```
timeout [s] = ( CRV + 1 ) / 32768
```

When started, the watchdog will automatically force the 32.768 kHz RC oscillator on as long as no other 32.768 kHz clock source is running and generating the 32.768 kHz system clock, see chapter CLOCK — Clock control on page 70.

6.20.1 Reload criteria

The watchdog has eight separate reload request registers, which shall be used to request the watchdog to reload its counter with the value specified in the CRV register. To reload the watchdog counter, the special value 0x6E524635 needs to be written to all enabled reload registers.

One or more RR registers can be individually enabled through the RREN register.



High baud rates may require GPIOs to be set as High Drive, see GPIO chapter for more details.

6.20.2 Temporarily pausing the watchdog

By default, the watchdog will be active counting down the down-counter while the CPU is sleeping and when it is halted by the debugger. It is however possible to configure the watchdog to automatically pause while the CPU is sleeping as well as when it is halted by the debugger.

6.20.3 Watchdog reset

A TIMEOUT event will automatically lead to a watchdog reset.

See Reset on page 56 for more information about reset sources. If the watchdog is configured to generate an interrupt on the TIMEOUT event, the watchdog reset will be postponed with two 32.768 kHz clock cycles after the TIMEOUT event has been generated. Once the TIMEOUT event has been generated, the impending watchdog reset will always be effectuated.

The watchdog must be configured before it is started. After it is started, the watchdog's configuration registers, which comprise registers CRV, RREN, and CONFIG, will be blocked for further configuration.

The watchdog can be reset from several reset sources, see Reset behavior on page 57.

When the device starts running again, after a reset, or waking up from OFF mode, the watchdog configuration registers will be available for configuration again.

6.20.4 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
WDT : S	0x50018000	uc	NC	NIA	N-	Matabalantina
WDT : NS	0x40018000	US	NS	NA	No	Watchdog timer

Register overview

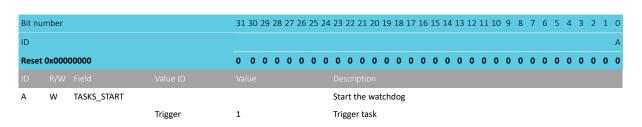
Register	Offset	TZ	Description
TASKS_START	0x000		Start the watchdog
SUBSCRIBE_START	0x080		Subscribe configuration for task START
EVENTS_TIMEOUT	0x100		Watchdog timeout
PUBLISH_TIMEOUT	0x180		Publish configuration for event TIMEOUT
INTENSET	0x304		Enable interrupt
INTENCLR	0x308		Disable interrupt
RUNSTATUS	0x400		Run status
REQSTATUS	0x404		Request status
CRV	0x504		Counter reload value
RREN	0x508		Enable register for reload request registers
CONFIG	0x50C		Configuration register
RR[n]	0x600		Reload request n

6.20.4.1 TASKS START

Address offset: 0x000

Start the watchdog





6.20.4.2 SUBSCRIBE_START

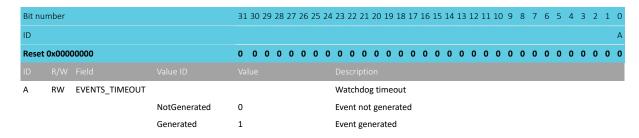
Address offset: 0x080

Subscribe configuration for task START

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				В	A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	$0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \$
ID					Description
Α	RW	CHIDX		[0255]	DPPI channel that task START will subscribe to
В	RW	EN			
			Disabled	0	Disable subscription

6.20.4.3 EVENTS_TIMEOUT

Address offset: 0x100 Watchdog timeout



6.20.4.4 PUBLISH_TIMEOUT

Address offset: 0x180

Publish configuration for event TIMEOUT

Bit nu	umber			31 30 29	28 27 26 25	24	23 2	2 21	20	19	18 1	7 1	6 15	5 14	13	12	11 1	0 9	8	7	6	5	4	3 2	. 1	. 0
ID				В																Α	Α	Α .	Α ,	Δ Δ	. 4	A A
Reset	t 0x000	00000		0 0 0	0 0 0 0	0	0 (0 0	0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0 (0	0	0
ID																										
Α	RW	CHIDX		[0255]			DPP	I cha	inne	l tha	at ev	/ent	TIN	1EO	UT	will	pub	ish 1	o							
В	RW	EN																								
			Disabled	0			Disa	ble p	oubl	ishir	ng															
			Enabled	1			Enab	ble p	ubli	shin	g															

6.20.4.5 INTENSET

Address offset: 0x304

Enable interrupt



Bit nu	ımher			31 30 29 28 27 26 25	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				01 00 23 20 27 20 20	Δ
-	0x0000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	TIMEOUT			Write '1' to enable interrupt for event TIMEOUT
			Set	1	Enable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.20.4.6 INTENCLR

Address offset: 0x308

Disable interrupt

Bit nu	mber			31 30 29 28 27 26 2	25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID					
Reset	0x000	00000		0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	TIMEOUT			Write '1' to disable interrupt for event TIMEOUT
			Clear	1	Disable
			Disabled	0	Read: Disabled
			Enabled	1	Read: Enabled

6.20.4.7 RUNSTATUS

Address offset: 0x400

Run status

Bit nu	mber			31 30	29 2	28 27	26	25 2	24 2	3 22	2 21	20	19 1	18 1	7 16	5 15	14	13	12	11 1	.0 9	8	7	6	5	4	3	2	1 0
ID																													
Reset	0x000	00000		0 0	0	0 0	0	0	0 (0 0	0	0	0	0 (0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 (0
ID																													
	R	RUNSTATUSWDT							lr	ndica	ates	whe	ethe	er or	not	the	e wa	itch	dog	is r	unni	ng							
			NotRunning	0					٧	Vatc	hdo	g no	t ru	ınnir	ng														
			Running	1					٧	Vatc	hdo	g is ı	runı	ning															

6.20.4.8 REQSTATUS

Address offset: 0x404

Request status

			DisabledOrRec	guested0		RR[i] regi	ster is 1	not en	abled	d, or	are a	lreac	ly rec	uest	ting	relo	oad				
A-H	R	RR[i] (i=07)				Request	status f	or RR	[i] reg	ister											
Reset	0x000	00001		0 0 0 0 0	0 0	0 0 0	0 0	0 0	0 (0	0 (0	0 (0	0	0	0	0	0 (0	1
ID															Н	G	F	Ε	D (В	Α
Bit nu	mber			31 30 29 28 27 2	6 25 24	23 22 21	20 19	18 17	16 1	5 14	13 1	2 11	10 9	8	7	6	5	4	3 2	2 1	0

6.20.4.9 CRV





Counter reload value



6.20.4.10 RREN

Address offset: 0x508

Enable register for reload request registers

Bit nu	mber			31 3	0 29 2	28 2	7 26	25	24 2	3 22	2 21	20	19 1	l8 17	7 16	15	14	13	12 :	11 1	0 9	8	7	6	5	4	3	2 1	0
ID																							Н	G	F	Ε	D	СВ	Α
Reset	0x0000	00001		0 0	0	0 0	0 0	0	0 (0 0	0	0	0	0 0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	1
ID																													
A-H	RW	RR[i] (i=07)							Е	nab	le o	r dis	able	RR[i] re	gist	ter												
			Disabled	0					C	Disab	le R	R[i]	regi	ster															
			Enabled	1					E	nab	le RI	R[i] ı	regis	ster															

6.20.4.11 CONFIG

Address offset: 0x50C Configuration register

Bit number			31 30	29 2	8 27	26 2	5 24	23 22	2 21 :	20 19	9 18	17	16 1	5 14	13	12 1	1 10	9	8	7 6	5	4	3 2	2 :	1 0
ID																							С		
Reset 0x0000	0001		0 0	0 (0 0	0 (0	0 0	0	0 0	0	0	0 (0	0	0 (0 0	0	0 (0 0	0	0	0 () () 1
ID R/W																									
RW	SLEEP							Confi	igure	the	watc	hdo	g to	eith	er b	e pai	used,	or l	cept	run	ning	, wh	nile t	he	CPU
								is sle	eping	3															
		Pause	0					Paus	e wat	tchdo	og wl	hile	the	CPU	is sl	eepii	ng								
		Run	1					Keep	the v	watcl	hdog	g rur	nning	g wh	ile t	he Cl	PU is	slee	ping	3					
C RW	HALT							Confi	igure	the	watc	hdo	g to	eith	er b	e pai	used,	or l	cept	run	ning	, wh	nile t	he	CPU
								is hal	lted b	y the	e del	bug	ger												
		Pause	0					Paus	e wat	tchdo	og wl	hile	the	CPU	is h	alted	by th	ne d	ebu	gger					
		Run	1					Keep	the v	watc	hdog	g rur	nning	g wh	ile t	he Cl	PU is	halt	ed b	y th	e de	ebug	ger		

6.20.4.12 RR[n] (n=0..7)

Address offset: $0x600 + (n \times 0x4)$

Reload request n

Bit nu	ımber			31	30 2	9 28	3 27	7 26	25	24	23	22	21	20	19	18 :	L7 1	16 1	5 1	4 1	3 12	2 11	. 10	9	8	7	6	5	4	3	2 1	1 0
ID				Α	A A	A A	. A	A	Α	Α	Α	Α	Α	Α	Α	Α	A ,	A A	A A	\ <i>A</i>	A	. A	Α	Α	Α	Α	Α	Α	Α	A	4 Α	4 A
Reset	0x000	00000		0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0 () () (0	0	0	0	0	0	0	0	0	0	0 (0 0
ID																																
Α	W	RR									Re	loa	d re	que	st r	egi	ter															
			Reload	0x6	E524	4635	5				Val	lue	to r	equ	ıest	a r	eloa	d o	f th	e w	atc	hdo	g tiı	ner								



6.20.5 Electrical specification

6.20.5.1 Watchdog Timer Electrical Specification

Symbol	Description	Min.	Тур.	Max.	Units
t _{WDT}	Time out interval	31 μs		36 h	



7 LTE modem

The nRF9161 SiP contains a Low-Power Wide-Area (LPWA) network processor with dedicated flash/RAM, which controls the radio and baseband hardware components. LTE capabilities are provided by installing Nordic Semiconductor firmware, which complies with 3GPP LTE release 14 Cat-M1 and Cat-NB1/NB2 standards.

The following is an overview of the LTE modem, with a figure showing key components:

- RF transceiver
- Modem baseband (BB)
- · Embedded flash/RAM
- LPWA network processor and peripherals

They provide functions for the LTE L1, L2, and L3 (layers 1, 2, and 3 respectively) as well as IP communication layers. Peripherals provide hardware services for the LPWA network processor operating system and secure execution environment.

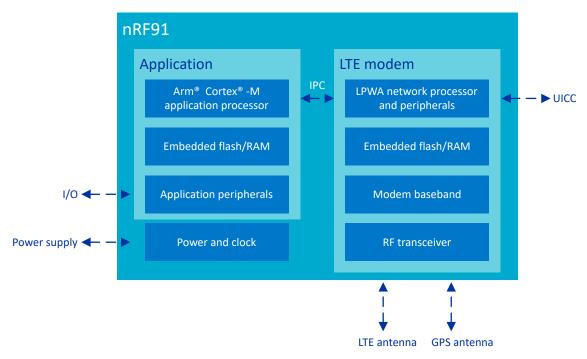


Figure 109: nRF9161 LTE modem functional overview

Application and LPWA network domains interact through the interprocessor communication (IPC) mechanism. The LTE modem is accessible to users through the modem API.

The application processor is the system master and is responsible for starting and stopping the LTE modem. The LPWA network processor enables the clocks and power required for its own operation. The platform handles shared resources, such as clocks, and does not need user participation. In cases where a hard fault is detected in the modem, the application domain will perform a hard reset of the modem.

The nRF9161 LTE modem feature set depends on the modem firmware version and the application firmware. For more information on the LTE modem API, see nRF Connect SDK API documentation and nRF91 AT Commands.

The key features of the LTE modem are:

• Complete modem with baseband and RF transceiver



- 3GPP release 14 compliant LTE categories:
 - Cat-M1 (eMTC enhanced machine type communication)
 - Cat-NB1 (NB-IoT narrowband Internet of things)
 - Cat-NB2 (NB-IoT)
- · Power saving modes
- Supports LTE bands from 700 MHz to 2.2 GHz through a single 50Ω antenna pin
 - ANT antenna pin is DC grounded
- RX sensitivity: -108 dBm for Cat-M1 and -114 dBm for Cat-NB1 and Cat-NB2
 - As defined in 3GPP conformance test specification TS 36.521-1
- 1.8 V MIPI RF Front-End (MIPI RFFE) digital control interface and MAGPIO control interface for external RF applications.
- LTE modem internal ADC that is also used for some AT command interface services, for example, for battery monitoring
- 1.8 V UICC (universal integrated circuit card) interface, based on ISO/IEC 7816-3 and compliant with:
 - UICC (ETSI TS 102 221)
 - eUICC (ETSI TS 103 383)

Note: The nRF9161 modem feature set depends on the modem firmware version and the application firmware.

7.1 SIM card interface

The LTE modem supports the universal integrated circuit card (UICC) interface.

Only UICCs with electrical interfaces specified in ISO/IEC 7816-3 are supported. UICCs with IC-USB, CLF or MMC interfaces are not supported.

The supported UICC/eUICC interface is compliant with:

- ETSI TS 102 221: Smart Cards; UICC-Terminal interface; Physical and logical characteristics
- ETSI TS 103 383: Smart Cards; Embedded UICC; Requirements Specification

The physical interface towards the eUICC is the same as that towards the removable UICC.

By default, only the class C (supply voltage 1.8 V nominal) operation is supported. Support for legacy class B (supply voltage 3.0 V nominal) operation must be built with external components, including an external power supply and the level shifters towards the LTE modem UICC interface.

The LTE modem supports powering down the UICC during PSM and eDRX idle mode if the UICC supports this feature as specified in 3GPP TS 24.301. To reach the lowest total power consumption of the complete cellular IoT product, only UICCs supporting power down mode during PSM and eDRX idle mode sleep intervals should be considered.

The LTE modem controls the physical interfaces towards the UICC and implements the transport protocol over the four-pin ISO/IEC 7816-3 interface:

- VCC (power supply) LTE modem drives this
- CLK (clock signal) LTE modem drives this
- RST (reset signal) LTE modem drives this
- I/O (input/output serial data) Bi-directional

The interface between the LTE modem, the UICC (SIM card) connector, and the ESD device is shown in the following figure.



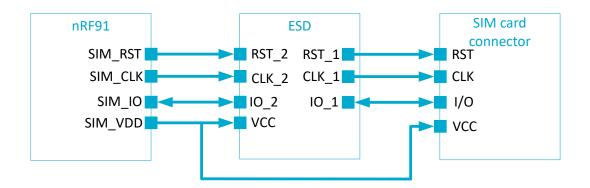


Figure 110: Connections between LTE modem, card connector, and the ESD device

Only standard transmission speeds are supported as specified in ETSI TS 102 221.

Note: Before removing the UICC, the LTE modem must be stopped through the modem API.

An electrostatic discharge (ESD) protection device compatible with UICC cards must be used between the removable card and the LTE modem, to protect LTE modem against harmful ESD from the card connector.

7.2 ITF coexistence interface

The LTE modem uses a dedicated three-pin interface for RF interference avoidance towards a companion radio device such as an external positioning device or *Bluetooth*[®] Low Energy device.

The interface has the following outputs:

- COEXO Output from the LTE modem to the external device. When internal GPS is used, COEXO can be used as active high control for the external LNA component.
- COEX1 Output from the LTE modem to the external device. When internal GPS is used, COEX1 delivers the GPS 1PPS (one pulse per second) time mark pulse. The 1PPS feature must not be used when LTE is enabled.
- COEX2 Output from the LTE modem to the external device. When active high, this indicates that the LTE modem transceiver is turned on. COEX2 can also be treated as an active low grant from the LTE modem to the external device, indicating permission to transmit and receive.

Note: Using the COEX2 pin requires an external pull-down resistor in the 100 k Ω size range.

The COEX interface timing in relation to the LTE modem state is shown in the following figure.

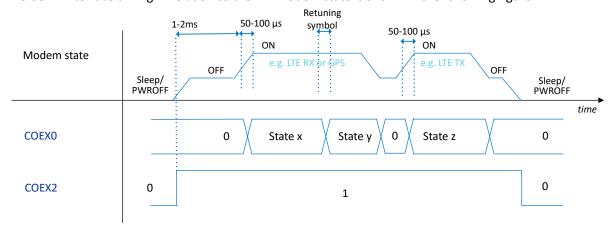


Figure 111: COEX interface timing



7.3 LTE RF control external interface

The LTE modem provides dedicated 1.8 V digital interfaces for controlling external RF applications, such as antenna tuner devices.

The LTE modem supports the following pins:

- MIPI RFFE interface pins VIO, SCLK, SDATA
- MAGPIO interface pins MAGPIO0, MAGPIO1, MAGPIO2

The LTE modem accurately drives the timing of these outputs according to the LTE protocol, to set the correct antenna tuner settings per used frequency, for example. The LTE modem API must be used to inform the LTE modem about the external RF application, so that LTE modem knows to drive it.

Note: For details regarding the modem API and supported RF external control features, see nRF91 AT Commands.

Note: The MIPI RFFE capacitive load at SCLK or SDATA pins must not exceed 15 pF.

The MIPI RFFE interface timing in relation to modem state is shown in the following figure.

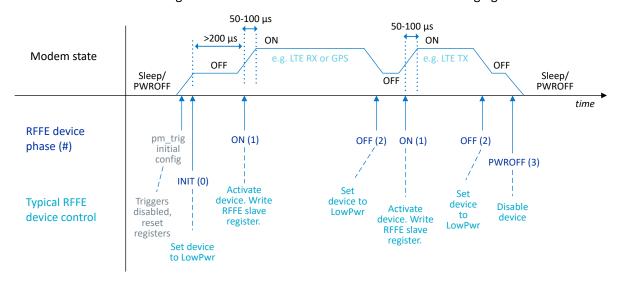


Figure 112: MIPI RFFE interface timing

The MAGPIO interface timing in relation to the LTE modem state is shown in the following figure.

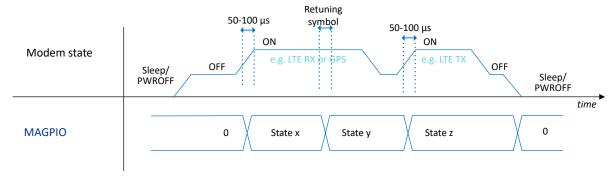


Figure 113: MAGPIO interface timing



7.4 RF front-end interface

The nRF9161 has a single-ended (SE) 50 Ω antenna interface to which an antenna is directly connected.

7.5 Registers

7.6 Electrical specification

7.6.1 Key RF parameters for Cat-M1

Note: For certification status, please refer to Regulatory information on page 461.

Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE Rel-14		
			Cat-M1 HD	-	
			FDD		
Bands supported	Bands supported		B1, B2, B3,		
			B4, B5, B8,		
			B12, B13,		
			B18, B19,		
			B20, B25,		
			B26, B28,		
			B66, B85		
Transmission bandwidth	Maximum bandwidth		1.4		MHz

7.6.2 Key RF parameters for Cat-NB1 and Cat-NB2

Note: For certification status, please refer to Regulatory information on page 461.

Note: There is no foreseen NB-IoT network deployment for FCC bands closer than 200 kHz from band edge, hence our device will not transmit in FCC bands on channels that are closer than 200kHz to band edge.



Symbol	Description	Min.	Тур.	Max.	Units
Supported LTE	Supported LTE standards		LTE Rel-14		
			Cat-NB1		
			and Cat-		
			NB2 HD-		
			FDD		
Bands supported	Bands supported		B1, B2, B3,		
			B4, B5, B8,		
			B12, B13,		
			B17, B19,		
			B20, B25,		
			B26, B28,		
			B65, B66,		
			B85		
Transmission bandwidth	Maximum bandwidth		200		kHz

7.6.3 Receiver parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	RX operation frequency range at ANT pin	728		2200	MHz
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low band	LTE 1.4 MHz without coverage extension	-103	-108		dBm
Sensitivity, mid band	LTE 1.4 MHz without coverage extension	-103	-107		dBm

7.6.4 Receiver parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_RX}	operation frequency range at ANT pin 728		2200	MHz	
Z _{in}	Input impedance, single-ended		50		Ω
Sensitivity, low band	NB 200 kHz without coverage extension	-108	-114		dBm
Sensitivity, mid band	NB 200 kHz without coverage extension	-108	-113		dBm

7.6.5 Transmitter parameters for Cat-M1

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_TX}	TX operation frequency range at ANT pin	698		1980	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output power	Maximum output power		23		dBm
Minimum output power	Minimum output power		-40		dBm
Pout maximum accuracy	Pout maximum accuracy		±2		dB

7.6.6 Transmitter parameters for Cat-NB1 and Cat-NB2

Symbol	Description	Min.	Тур.	Max.	Units
Freq _{range_ANT_TX}	TX operation frequency range at ANT pin	698		2010	MHz
Z _{out}	Output impedance, single-ended		50		Ω
Maximum output power	Maximum output power		23		dBm
Minimum output power	Minimum output power		-40		dBm
Pout maximum accuracy	Pout maximum accuracy		±2		dB



8 DECT NR+

The nRF9161 SiP contains a Low-Power Wide-Area (LPWA) network processor with dedicated flash/RAM, which controls the radio and baseband hardware components. DECT NR+ (NR+) capabilities are provided by installing Nordic Semiconductor firmware, that implements the physical layer (PHY) level operation of the NR+ radio protocol stack according to ETSI specifications (TS 103 636-2 and TS 103 636-3).

NR+ is a non-cellular radio standard included as part of the 5G standards by the International Telecommunication Union (ITU). It is designed for massive Machine Type Communication (mMTC) and for Ultra-Reliable Low Latency Communication (URLLC).

NR+ operates on the global and license-exempt 1.9 GHz band, which significantly cuts deployment costs by eliminating the need for frequency planning or heavy certification. The NR+ device developer can design optimal radio behavior since there is no need for third-party cellular infrastructure. Additionally, the range and dense topology properties of NR+ make it highly scalable. A square kilometer can be covered by as little as 100 devices or scaled up to over 1 million devices while maintaining the same reliable, low-latency communication.

The physical radio layer in NR+ reuses known techniques from cellular radios, reaching the same level of reliability that is proven by billions of devices already in the field.

The following are key features of NR+:

- · License-exempt global band
- Built-in coexistence of multiple networks in the same location
- Flexible, low-latency system and network architectures
- High reliability, using hybrid ARQ
- Possibility of hiding the network, using AES-128 encryption and integrity protection
- Data rate up to 3.4 Mbps, depending on modulation

See ETSI TS 103 636-1 for more information.

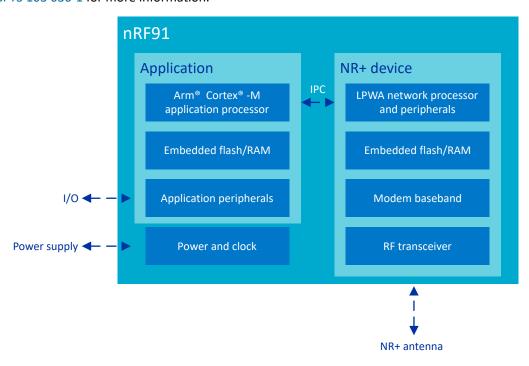


Figure 114: nRF9161 NR+ device functional overview



Application and LPWA network domains interact through the interprocessor communication (IPC) mechanism. The application processor is the system master and is responsible for starting and stopping the NR+ device. The LPWA network processor enables the clocks and power required for its own operation. The platform handles shared resources, such as clocks, and does not need user participation.

8.1 massive Machine Type Communication (mMTC)

mMTC is used for large networks with machine-type devices, connecting tens of billions of nodes that operate for many years using small batteries and transmit small amounts of data.

Typical use cases involve collecting measurements from many sensors, such as smart metering, which requires a low-maintenance and low-cost autonomous network structure.

A key feature of NR+ is its self-healing and self-organizing properties. Each node can function as a router to an access point with a connection to the internet. Nodes can change to a routing role based on the needs of the network. Multiple access points to the internet can be supported in a single network. These properties eliminates single points of failure and resolves high-traffic situations that can occur in dense IoT networks.

8.2 Ultra-Reliable Low-Latency Communication (URLLC)

URLLC enables mission-critical wireless use cases where failure is not an option.

Examples include management of self-driving factory vehicles, high-speed robots working alongside human operators in warehouses, and critical infrastructure in buildings, cities, and utilities.

NR+ is designed to reach one-millisecond latency between devices, opening the possibility for low-latency systems to consider wireless operation, even where ranges are over a kilometer. This makes NR+ an open, standardized alternative to existing proprietary technology.

8.3 DECT NR+ on the nRF9161

Nordic Semiconductor provides NR+ firmware that implements the physical layer (PHY) level operation of the NR+ radio protocol stack according to ETSI specifications (*TS 103 636-2 and TS 103 636-3*).

The NR+ standard and stack are still in development, contact the Nordic Semiconductor sales department for more information on the NR+ firmware.

The nRF9161 SiP supports NR+ bands 1, 2, and 9. The antenna interface and recommendations are the same as for the LTE modem. NR+ does not require a SIM or eSIM.

Note: While running DECT NR+ firmware, the nRF9161 SiP does not support LTE modem. See the LTE modem section for more information on alternative firmware.

8.4 Key RF Parameters

NR+ RF performance parameters are shown in the following table.



Description	Min	Тур	Max	Unit
Bands supported		1, 2, 9		
Transmission Bandwidth		1.728		MHz
Occupied Bandwidth		1.539		MHz
Antenna impedance, single-ended		50		Ω
RX: Sensitivity ²³ , modulation MCS1		-103		dBm
TX: Maximum output power		19		dBm
TX: Minimum output power		-40		dBm

Table 48: Common parameters

8.5 DECT NR+ coexistence interface

NR+ uses a dedicated two-pin coexistence interface to avoid RF interference to a companion radio device such as an external positioning device or a Bluetooth Low Energy device.

The user can configure COEX0 and COEX2 pin functions through the NR+ AT commands.

Note: Using the COEX2 pin requires an external pull-down resistor in the 100 k Ω range.



The sensitivity level has not been measured using the same method as decribed in ETSI TS 103 636-2 chapter "7.2 Reference sensitivity". The reported sensitivity level is the signal level where 10% packet error rate (PER) occurs. This measurement method does not measure the throughput and does not include HARQ.

9 GPS receiver

The LPWA network processor supports GPS reception, if the onboard network protocol firmware supports it.

GPS receiver operation is time multiplexed with the LTE modem, and GPS and QZSS position can be received while the LTE modem is in RRC Idle mode, power saving mode (PSM), or completely deactivated.

The application processor is the system master and responsible for starting and stopping the GPS receiver. GPS can be run standalone or concurrently with QZSS. The GPS and QZSS reception can be configured through the GNSS interface API.

Note: For details regarding the GNSS API, refer to nRF Connect SDK API documentation.

Key features of the GPS receiver are as follows:

- GPS L1 C/A reception
- QZSS L1 C/A reception
- Optimized for low-power and low-cost IoT applications
- Modes of operation:
 - Single shot
 - Position fix per fixed interval, configurable to a value between 10 s to 65536 s
 - · Continuous tracking
- Power saving mode:
 - · Duty-cycled continuous tracking operation
- One pulse per second (1PPS) signal:
 - A pulse repeating once per second, accurately synchronized to coordinated universal time (UTC) full seconds
 - For more details on 1PPS programmability and power vs. accuracy trade-offs, see GNSS API documentation
 - Available on device COEX1 pin
 - For more details, see LTE modem on page 357, coexistence interface
- Antenna interface:
 - · External low-noise amplifier (LNA) with SAW filter recommended on the GPS antenna input
 - · Dedicated GPS antenna, or shared antenna with LTE
 - · GPS antenna pin is DC grounded

Note: There must be minimum 27dB attenuation to out of band power to avoid blocking high power RF signals to GPS receiver input. This can be achieved by using a SAW filter, for example, at the external LNA output.

9.1 Electrical specification

The following is a summary of GPS receiver performance parameters.



Condition	Value
Environment	Open sky
Temperature	25°C
GPS sleep clock source	тсхо

Table 49: Common typical conditions

Note: Local and temporal conditions might lead to considerable variation in TTFF, positioning accuracy, 1PPS signal accuracy.

The figures in the following table assume the use of an external low-noise amplifier (LNA) with SAW filter.

Symbol	Description	Value	Unit
Sensitivity, cold	Acquisition sensitivity, cold start	-146.5	dBm
Sensitivity, hot	Acquisition sensitivity, hot start	-152.5	dBm
Sensitivity, tracking	Tracking sensitivity	-156.5	dBm
TTFF, cold	Time to first fix (TTFF), cold start	30.5	s
TTFF, hot	TTFF, hot start	1.3	s
TTFF, A-GPS	TTFF, A-GPS start	1.3	s
Accuracy, 2D, periodic	Positioning accuracy (CEP50), periodic tracking ²⁴	3.4	m
Accuracy, 2D, periodic, A-GPS	Positioning accuracy (CEP50), periodic tracking ²⁴ with A-GPS ²⁵	3.1	m
Accuracy, 2D, continuous	Positioning accuracy (CEP50), continuous tracking	2.0	m
Accuracy, 2D, continuous, A-GPS	Positioning accuracy (CEP50), continuous tracking with A-GPS ²⁵	1.8	m
1PPS accuracy	1PPS signal accuracy, continuous tracking	±35	ns

Table 50: GPS electrical specification



²⁴ Fix interval 2 min.

²⁵ Including NeQuick ionospheric model parameters.

10 Debug and trace

The debug and trace system offers a flexible and powerful mechanism for non-intrusive debugging.

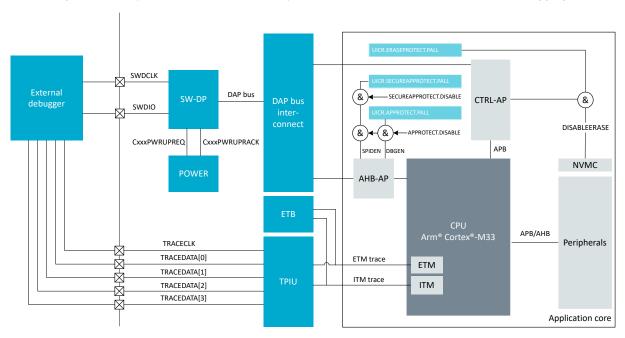


Figure 115: Debug and trace overview

The main features of the debug and trace system include:

- Two-pin serial wire debug (SWD) interface, protocol version 1
- Access port connection
 - Breakpoint unit (BPU) supports eight hardware breakpoint comparators
 - Data watchpoint and trace (DWT) unit supports four watchpoint comparators
 - Instrumentation trace macrocell (ITM)
 - Embedded trace macrocell (ETM)
 - Access protection through APPROTECT, ERASEPROTECT and SECUREAPPROTECT
- Embedded trace buffer (ETB)
- · Trace port interface unit (TPIU)
 - 4-bit parallel trace of ITM and ETM trace data

Note: When a system contains multiple CPU domains, it is important to be aware that if one domain (subsystem A) has master rights on another domain (subsystem B), the master subsystem can access some data from the slave subsytem. In this example, even if subsystem B is locked by APPROTECT or ERASEPROTECT, subsystem A can access some data for subsystem B. Consequently, even if the security permissions are managed per subsystem, it is mandatory to have a global approach to the protection. Protecting a slave subsystem does not guarantee system security if the master subsystem is not protected.

10.1 DAP - Debug access port

An external debugger can access the device via the debug access port (DAP).



The DAP implements a standard Arm CoreSight serial wire debug port (SW-DP). The SW-DP implements the serial wire debug (SWD) protocol that is a two-pin serial interface, see SWDCLK and SWDIO illustrated in figure Debug and trace overview on page 368.

In addition to the default access port in the application CPU (AHB-AP), the DAP includes a custom control access port (CTRL-AP), described in more detail in CTRL-AP - Control access port on page 437.

Note:

- The SWDIO line has an internal pull-up resistor.
- The SWDCLK line has an internal pull-down resistor.

There are several access ports that connect to different parts of the system. An overview is given in the table below.

AP ID	Туре	Description
0	AHB-AP	Application subsystem access port
3	APB-AP	CoreSight subsystem access port
4	CTRL-AP	Application subsystem control access port

Table 51: Access port overview

The standard Arm components are documented in *Arm CoreSight SoC-400 Technical Reference Manual, revision r3p2*. The control access port (CTRL-AP) is proprietary, and described in more detail in CTRL-AP - Control access port on page 437.

10.2 Access port protection

Access port protection blocks the debugger from read and write access to all CPU registers and memory-mapped addresses when enabled. If needed, a debugger can be restricted to debug non-secure code only and access non-secure memory regions and peripherals using register SECUREAPPROTECT on page 41. Register APPROTECT on page 40 blocks all debugger access.

The following table gives an overview of the access port protection methods.

Debugging capability	Description
Non-secure code	The application core AHB-AP DBGEN signal controls all non-secure access through the application core AHB-AP. This can be used to provide readback protection of the flash contents. See Debugger access control for non-secure debug access on page 370. For more information about the DBGEN signal, see the <i>Arm CoreSight SoC-400 Technical Reference Manual, Revision r3p2</i> .
Secure code	The application core AHB-AP SPIDEN signal controls all secure access through the application core AHB-AP. This means that only the non-secure code can be debugged and accessed when secure accesses are blocked. To enable access to the secure access port, non-secure code must be unprotected. See Debugger access control for secure debug access on page 370. For more information about the SPIDEN signal, see the <i>Arm CoreSight SoC-400 Technical Reference Manual, Revision r3p2</i> .

Table 52: Application core access port protection overview



If a RAM or flash region has its permission set to allow code execution, the content of this region is visible to the debugger even if the read permission is not set. This allows a debugger to display the content of the code being executed. For more information on configuring permissions, see SPU — System protection unit on page 257.

Access port protection controlled by hardware and software

By default, access port protection is enabled.

The following table describes how non-secure debugger access is controlled.

Debugging capability	UICR.APPROTECT. PALL	APPROTECT. DISABLE	APPROTECT. FORCEPROTECT	Secure debug access
Non-secure code	HwUnprotected	SwUnprotected	Reset value	-
No debugging possible	Protected	Reset value	Force	-

Table 53: Debugger access control for non-secure debug access

The following table describes how secure debugger access is controlled.

Debugging capability	UICR. SECUREAPPROTECT. PALL	SECUREAPPROTECT. DISABLE	SECUREAPPROTECT. FORCEPROTECT	Non-secure debug access
Secure code	HwUnprotected	SwUnprotected	Reset value	Permitted
No debugging possible	Protected	Reset value	Force	Permitted
No debugging possible	-	-	-	Not permitted

Table 54: Debugger access control for secure debug access

Access port protection is enabled when the hardware and software disabling conditions are not present. For additional security, it is recommended to write Protected to UICR.SECUREAPPROTECT and UICR.APPROTECT, and have firmware write Force to SECUREAPPROTECT.FORCEPROTECT and APPROTECT.FORCEPROTECT.

Note: Registers SECUREAPPROTECT.FORCEPROTECT and APPROTECT.FORCEPROTECT are reset in System ON IDLE or after any reset.

Access port protection is disabled by issuing an ERASEALL command through CTRL-AP. Read ERASEALLSTATUS until the ERASEALL sequence is ready. When ERASEALL is ready, trigger and then release soft reset from the RESET register. Read APPROTECT.STATUS to ensure that access port protection is disabled. If access port is not disabled, do a reset and repeat the ERASEALL command. This command erases the flash, UICR, and RAM, including UICR.SECUREAPPROTECT and UICR.APPROTECT. CTRL-AP is described in more detail in CTRL-AP - Control access port on page 437. Access port protection remains disabled until one of the following occurs:

- Pin reset
- Power or brownout reset



- Watchdog reset
- Wake from System OFF if not in Emulated System OFF

To keep access port protection disabled, the following actions must be performed:

- Program UICR.SECUREAPPROTECT and UICR.APPROTECT to HwUnprotected. This disables the
 hardware part of the access port protection scheme after the first reset of any type. The hardware part
 of the access port protection stays disabled as long as UICR.SECUREAPPROTECT and UICR.APPROTECT
 are not overwritten.
- Firmware must write SECUREAPPROTECT.DISABLE and APPROTECT.DISABLE to SwUnprotected. This disables the software part of the access port protection scheme.

Note: Register SECUREAPPROTECT.DISABLE and APPROTECT.DISABLE are reset in System ON IDLE or after pin reset, power or brownout reset, watchdog reset, or wake from System OFF as mentioned above.

The following figure shows how a device with access port protection enabled is erased, programmed, and configured to allow debugging. Operations sent from the debugger and registers written by firmware affects the access port state.

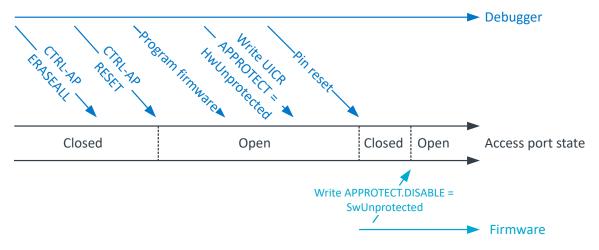


Figure 116: Access port unlocking

10.2.2 Registers

Instances

Instance	Base address	TrustZone			Split access	Description	
		Мар	Att	DMA			
APPROTECT : S	0x50039000	HF	NS	NA	Yes	APPROTECT control	
APPROTECT : NS	0x40039000	ПГ	INS	INA	res	APPROTECT CONTROL	

Register overview

Register	Offset	TZ	Description
SECUREAPPROTECT.DISABLE	0xE00	S	Software disable SECUREAPPROTECT mechanism
SECUREAPPROTECT.FORCEPROTECT	0xE00	S	Software force SECUREAPPROTECT mechanism
APPROTECT.DISABLE	0xE10	NS	Software disable APPROTECT mechanism
APPROTECT.FORCEPROTECT	0xE10	NS	Software force APPROTECT mechanism

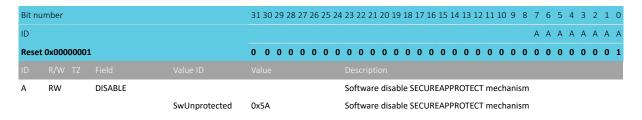




10.2.2.1 SECUREAPPROTECT. DISABLE

Address offset: 0xE00

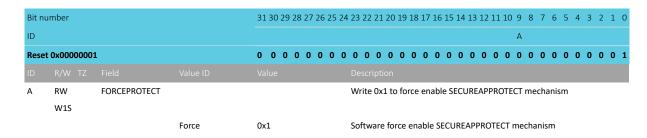
Software disable SECUREAPPROTECT mechanism



10.2.2.2 SECUREAPPROTECT.FORCEPROTECT

Address offset: 0xE00

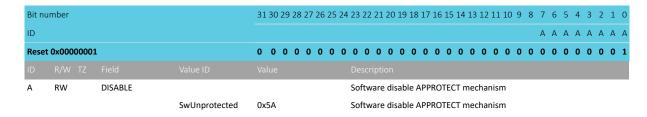
Software force SECUREAPPROTECT mechanism



10.2.2.3 APPROTECT.DISABLE

Address offset: 0xE10

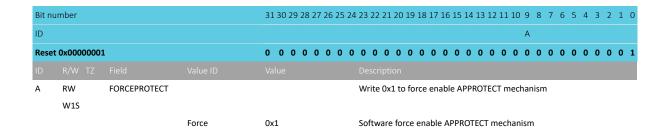
Software disable APPROTECT mechanism



10.2.2.4 APPROTECT.FORCEPROTECT

Address offset: 0xE10

Software force APPROTECT mechanism







10.3 Debug interface mode

Before the external debugger can access the CPU's access port (AHB-AP) or the control access port (CTRL-AP), the debugger must first request the device to power up via CxxxPWRUPREQ in the SWJ-DP.

As long as the debugger is requesting power via CxxxPWRUPREQ, the device will be in debug interface mode. Otherwise, the device is in normal mode. When a debug session is over, the external debugger must make sure to put the device back into normal mode and then a pin reset should be performed. The reason is that the overall power consumption is higher in debug interface mode compared to normal mode.

Some peripherals behave differently in debug interface mode compared to normal mode. The differences are described in more detail in the chapters of the affected peripherals.

For details on how to use the debug capabilities, please read the debug documentation of your IDE.

If the device is in System OFF when power is requested via CxxxPWRUPREQ, the system will wake up and the DIF flag in RESETREAS on page 68 will be set.

10.4 Real-time debug

The device supports real-time debugging, which allows interrupts to execute to completion in real time when breakpoints are set in thread mode or lower priority interrupts.

Real-time debugging thus enables the developer to set a breakpoint and single-step through their code without a failure of the real-time event-driven threads running at higher priority. For example, this enables the device to continue to service the high-priority interrupts of an external controller or sensor without failure or loss of state synchronization while the developer steps through code in a low-priority thread.

10.5 Registers

Register overview

Register	Offset	Description
TARGETID	0x042	The TARGETID register provides information about the target when the host is connected to a single
		device.
		The TARGETID register is accessed by a read of DP register 0x4 when the DPBANKSEL bit in the
		SELECT register is set to 0x2.

10.5.1 TARGETID

Address offset: 0x042

The TARGETID register provides information about the target when the host is connected to a single device.

The TARGETID register is accessed by a read of DP register 0x4 when the DPBANKSEL bit in the SELECT register is set to 0x2.



Bit nu	ımber			31	30	29	28	27 :	26 2	5 2	4 2	23 2	2 2	21 2	20 1	.9 1	.8 1	7 1	6 1	5 1	4 1	3 1	2 1:	1 10	9	8	7	6	5	4	3	2	1	0
ID				D	D	D	D	С	C (С (C (С	С (C (C (C (С (2 (2				В	В	В	В	В	В	В	В	В	В	В	Α
Reset	0x100	90289		0	0	0	1	0	0 (0 (0 (0	0 (0 (0 :	1 (0 (0 :	1 () () (0	0	0	1	0	1	0	0	0	1	0	0	1
ID																																		
Α	R	UNUSED									R	Rese	erve	ed, I	rea	d-a	S-01	ne																
В	R	TDESIGNER									Α	An 1	.1-b	oit c	ode	e: JI	EDE	C JI	EP1	06	con	tinu	ıati	on (cod	e aı	nd i	den	tity	/ со	de.	The	! ID	
											ic	den	tifie	es t	he	des	ign	er c	of th	ne p	art													
			NordicSemi	0x2	L44						Ν	Vor	dic !	Sen	nico	ond	uct	or A	ASA															
С	R	TPARTNO									Р	art	nu	mb	er																			
D	R	TREVISION									T	arg	et r	evi	sioi	า																		

10.6 Electrical specification

10.6.1 Trace port

Symbol	Description	Min.	Тур.	Max.	Units
T _{cyc}	Clock period, as defined by ARM (See ARM Infocenter, Embedded Trace	62.5			ns
	Macrocell Architecture Specification, Trace Port Physical Interface, Timing				
	specifications)				

10.7 Trace

The nRF9161 supports ETM and ITM trace.

Available trace sinks:

- 2 kB internal embedded trace buffer (ETB)
- External trace port interface through TPIU

Trace data from the ETM and the ITM can be sent to an internal embedded trace buffer (ETB) or an external debugger via a 4-bit wide parallel trace port (TPIU), see TRACEDATA[0] through TRACEDATA[3], and TRACECLK in Debug and trace overview on page 368.

The following diagram shows the trace components architecture of the device's embedded Arm CoreSight subsystem.

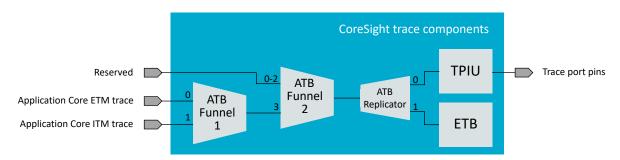


Figure 117: Trace components architecture

The standard Arm components are documented in *Arm CoreSight SoC-400 Technical Reference Manual, revision r3p2*. For details on how to use the trace capabilities, please read the debug documentation of your IDE.

TPIU's trace pins are multiplexed with GPIOs, see Pin assignments on page 450 for more information.

Note: To configure the trace data delivery to the device trace port, use the MDK system start-up file included as of MDK version 8.26.0.

Trace speed is configured in the TRACEPORTSPEED (Retained) on page 448 register. The speed of the trace pins depends on the DRIVE setting of the GPIOs that the trace pins are multiplexed with. See GPIO — General purpose input/output on page 97 for information about how to set drive settings. Only SOS1 and H0H1 drives are suitable for debugging. SOS1 is the default DRIVE at reset. If parallel or serial trace port signals are not fast enough in the debugging conditions, all GPIOs in use for tracing should be set to high drive (H0H1). The user shall make sure that DRIVE setting for these GPIOs is not overwritten by software during the debugging session.

10.7.1 ATB Funnel

The ARM® ATB Funnel funnels trace bus mesages from several sources into one output bus.

This document only provides a register-level description of this ARM component. See the ARM[®] CoreSight[™] SoC-400 Technical Reference Manual for more details

10.7.1.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
ATBFUNNEL1	0xE005A000	HF	NS	NA	No	ATBFUNNEL unit 1
ATBFUNNEL2	0xE005B000	HF	NS	NA	No	ATBFUNNEL unit 2

Register overview

Register	Offset	TZ	Description
CTRLREG	0x000		The IDFILTERO register enables the programming of ID filtering for master port 0.
PRIORITYCTRLREG	0x004		The Priority_Ctrl_Reg register defines the order in which inputs are selected. Each 3-bit field
			is a priority for each particular slave interface.
ITATBDATA0	0xEEC		The ITATBDATAO register performs different functions depending on whether the access is a
			read or a write.
ITATBCTR2	0xEF0		The ITATBCTR2 register performs different functions depending on whether the access is a
			read or a write.
ITATBCTR1	0xEF4		The ITATBCTR1 register performs different functions depending on whether the access is a
			read or a write.
ITATBCTR0	0xEF8		The ITATBCTRO register performs different functions depending on whether the access is a
			read or a write.
ITCTRL	0xF00		The ITCTRL register enables the component to switch from a functional mode, which is the
			default behavior, to integration mode where the inputs and outputs of the component can be $\frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}{2} \left(\frac{1}{2} \right) \left($
			directly controlled for the purposes of integration testing and topology detection.
CLAIMSET	0xFA0		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMSET register sets bits in the claim tag, and determines the number of claim bits
			implemented.
CLAIMCLR	0xFA4		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the
			claim tag.
LAR	0xFB0		This is used to enable write access to device registers.



Register	Offset	TZ	Description
LSR	0xFB4		This indicates the status of the lock control mechanism. This lock prevents accidental writes
			by code under debug. Accesses to the extended stimulus port registers are not affected by
			the lock mechanism. This register must always be present although there might not be any
			lock access control mechanism. The lock mechanism, where present and locked, must block
			write accesses to any control register, except the Lock Access Register. For most components
			this covers all registers except for the Lock Access Register.
AUTHSTATUS	0xFB8		Indicates the current level of tracing permitted by the system
DEVID	0xFC8		Indicates the capabilities of the component.
DEVTYPE	0xFCC		The DEVTYPE register provides a debugger with information about the component when the
			Part Number field is not recognized. The debugger can then report this information.
PIDR4	0xFD0		Coresight peripheral identification registers.
PIDR[0]	0xFE0		Coresight peripheral identification registers.
PIDR[1]	0xFE4		Coresight peripheral identification registers.
PIDR[2]	0xFE8		Coresight peripheral identification registers.
PIDR[3]	0xFEC		Coresight peripheral identification registers.
CIDR[0]	0xFF0		Coresight component identification registers.
CIDR[1]	0xFF4		Coresight component identification registers.
CIDR[2]	0xFF8		Coresight component identification registers.
CIDR[3]	0xFFC		Coresight component identification registers.

10.7.1.1.1 CTRLREG

Address offset: 0x000

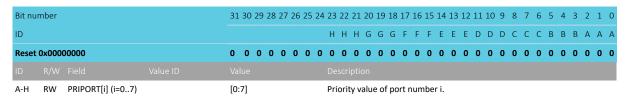
The IDFILTERO register enables the programming of ID filtering for master port 0.

Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					IIIIHGFEDCBA
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
А-Н	RW	ENS[i] (i=07)			Enable slave port i.
			Disabled	0	Slave port disabled. This excludes the port from the priority selection
					scheme.
			Enabled	1	Slave port enabled.
1	RW	нт		[0:14]	Hold Time. The formatting scheme can become inefficient when fast
					switching occurs, and you can use this setting to minimize switching.
					When a source has nothing to transmit, then another source is selected
					irrespective of the minimum number of transactions. The ATB funnel holds
					for the minimum hold time and one additional transaction. The actual hold
					time is the register value plus 1. The maximum value that can be entered is
					0b1110 and this equates to 15 transactions. 0b1111 is reserved.

10.7.1.1.2 PRIORITYCTRLREG

Address offset: 0x004

The Priority_Ctrl_Reg register defines the order in which inputs are selected. Each 3-bit field is a priority for each particular slave interface.

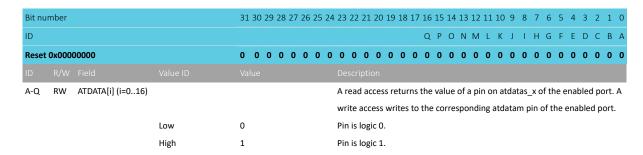




10.7.1.1.3 ITATBDATA0

Address offset: 0xEEC

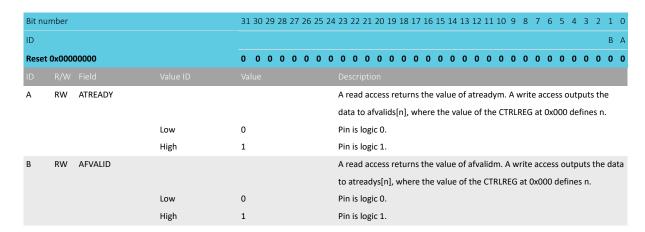
The ITATBDATAO register performs different functions depending on whether the access is a read or a write.



10.7.1.1.4 ITATBCTR2

Address offset: 0xEF0

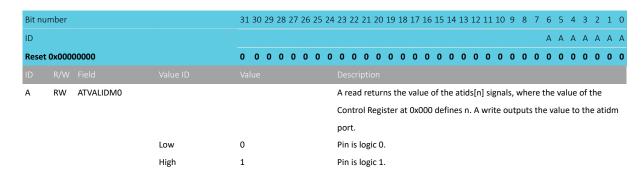
The ITATBCTR2 register performs different functions depending on whether the access is a read or a write.



10.7.1.1.5 ITATBCTR1

Address offset: 0xEF4

The ITATBCTR1 register performs different functions depending on whether the access is a read or a write.



10.7.1.1.6 ITATBCTR0

Address offset: 0xEF8

The ITATBCTRO register performs different functions depending on whether the access is a read or a write.

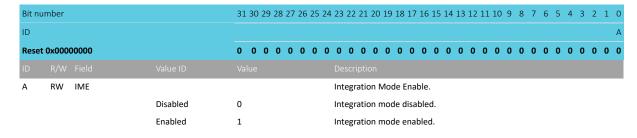


Bit numbers Signature Sign						
Reset 0x00000000000000000000000000000000000	Bit n	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
RW ATVALID Low 0 Pin is logic 0. High 1 A read returns the value of the atvalids[n] signal, where the value of the atvalidm. A read returns the value of the atvalids[n] signal, where the value of the CTRLREG at 0x000 defines n. A write outputs the value to atvalidm. Pin is logic 0. A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 0. RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.	ID					C C B A
A RW ATVALID Low 0 Pin is logic 0. High 1 Pin is logic 1. A read returns the value of the atvalids[n] signal, where the value to atvalidm. A read returns the value of the atvalids[n] signal, where the value of the CTRLREG at 0x000 defines n. A write outputs the value to atvalidm. A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.	Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
CTRLREG at 0x000 defines n. A write outputs the value to atvalidm. Low 0 Pin is logic 0. High 1 Pin is logic 1. A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 1. A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.						Description
Low 0 Pin is logic 0. High 1 Pin is logic 1. A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.	Α	RW	ATVALID			A read returns the value of the atvalids[n] signal, where the value of the
High 1 Pin is logic 1. B RW AFREADY A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.						CTRLREG at 0x000 defines n. A write outputs the value to atvalidm.
B RW AFREADY A read returns the value of the afreadys[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.				Low	0	Pin is logic 0.
Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym. Low 0 Pin is logic 0. High 1 Pin is logic 1. A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.				High	1	Pin is logic 1.
Low 0 Pin is logic 0. High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.	В	RW	AFREADY			A read returns the value of the afreadys[n] signal, where the value of the
High 1 Pin is logic 1. C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.						Ctrl_Reg at 0x000 defines n. A write outputs the value to afreadym.
C RW ATBYTES A read returns the value of the atbytess[n] signal, where the value of the Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.				Low	0	Pin is logic 0.
Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm. Low 0 Pin is logic 0.				High	1	Pin is logic 1.
Low 0 Pin is logic 0.	С	RW	ATBYTES			A read returns the value of the atbytess[n] signal, where the value of the
						Ctrl_Reg at 0x000 defines n. A write outputs the value to atbytesm.
High 1 Pin is logic 1.				Low	0	Pin is logic 0.
				High	1	Pin is logic 1.

10.7.1.1.7 ITCTRL

Address offset: 0xF00

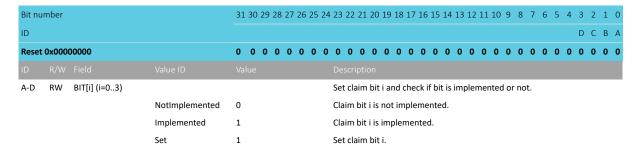
The ITCTRL register enables the component to switch from a functional mode, which is the default behavior, to integration mode where the inputs and outputs of the component can be directly controlled for the purposes of integration testing and topology detection.



10.7.1.1.8 CLAIMSET

Address offset: 0xFA0

Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMSET register sets bits in the claim tag, and determines the number of claim bits implemented.

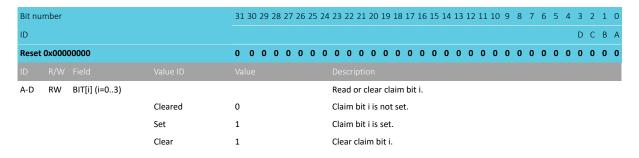


10.7.1.1.9 CLAIMCLR

Address offset: 0xFA4



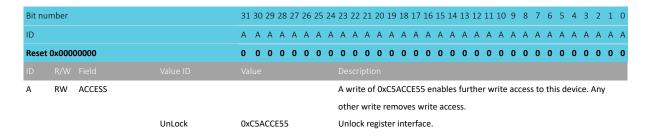
Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the claim tag.



10.7.1.1.10 LAR

Address offset: 0xFB0

This is used to enable write access to device registers.



10.7.1.1.11 LSR

Address offset: 0xFB4

This indicates the status of the lock control mechanism. This lock prevents accidental writes by code under debug. Accesses to the extended stimulus port registers are not affected by the lock mechanism. This register must always be present although there might not be any lock access control mechanism. The lock mechanism, where present and locked, must block write accesses to any control register, except the Lock Access Register. For most components this covers all registers except for the Lock Access Register.

Bit n	umber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	PRESENT			Indicates that a lock control mechanism exists for this device.
			NotImplemented	0	No lock control mechanism exists, writes to the Lock Access Register are
					ignored.
			Implemented	1	Lock control mechanism is present.
В	RW	LOCKED			Returns the current status of the Lock.
			UnLocked	0	Write access is allowed to this device.
			Locked	1	Write access to the component is blocked. All writes to control registers are $% \left(1\right) =\left(1\right) \left($
					ignored. Reads are permitted.
С	RW	TYPE			Indicates if the Lock Access Register is implemented as 8-bit or 32-bit.
			Bits32	0	This component implements a 32-bit Lock Access Register.
			Bits8	1	This component implements an 8-bit Lock Access Register.



10.7.1.1.12 AUTHSTATUS

Address offset: 0xFB8

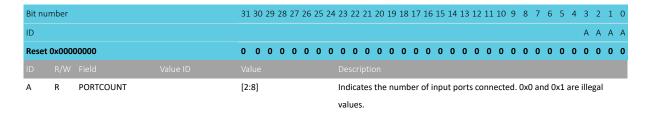
Indicates the current level of tracing permitted by the system

ber			31 30 29 28 27 26 25 2	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
				D D C C B B A A
x0000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
				Description
RW	NSID			Non-secure Invasive Debug
		NotImplemented	0	The feature is not implemented.
		Implemented	1	The feature is implemented.
RW	NSNID			Non-secure Non-Invasive Debug
		NotImplemented	0	The feature is not implemented.
		Implemented	1	The feature is implemented.
RW	SID			Secure Invasive Debug
		NotImplemented	0	The feature is not implemented.
		Implemented	1	The feature is implemented.
RW	SNID			Secure Non-Invasive Debug
		NotImplemented	0	The feature is not implemented.
		Implemented	1	The feature is implemented.
	R/W RW RW	x00000000 R/W Field RW NSID RW NSNID	xXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX	Notimplemented 1 Notimpl

10.7.1.1.13 DEVID

Address offset: 0xFC8

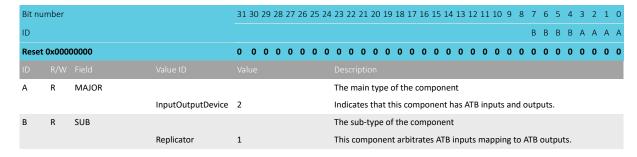
Indicates the capabilities of the component.



10.7.1.1.14 DEVTYPE

Address offset: 0xFCC

The DEVTYPE register provides a debugger with information about the component when the Part Number field is not recognized. The debugger can then report this information.

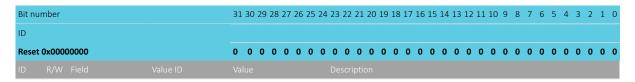


10.7.1.1.15 PIDR4

Address offset: 0xFD0



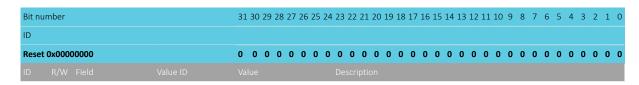
Coresight peripheral identification registers.



10.7.1.1.16 PIDR[0]

Address offset: 0xFE0

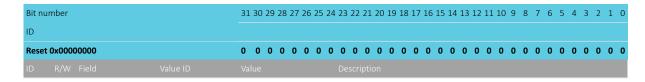
Coresight peripheral identification registers.



10.7.1.1.17 PIDR[1]

Address offset: 0xFE4

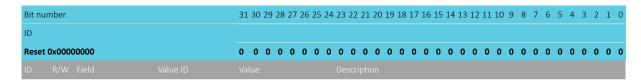
Coresight peripheral identification registers.



10.7.1.1.18 PIDR[2]

Address offset: 0xFE8

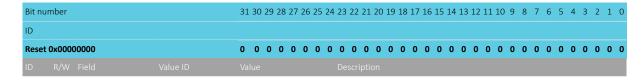
Coresight peripheral identification registers.



10.7.1.1.19 PIDR[3]

Address offset: 0xFEC

Coresight peripheral identification registers.

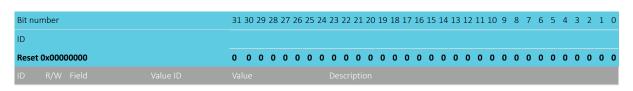


10.7.1.1.20 CIDR[0]

Address offset: 0xFF0

Coresight component identification registers.

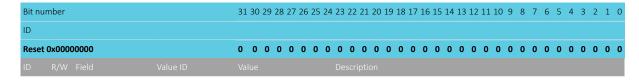




10.7.1.1.21 CIDR[1]

Address offset: 0xFF4

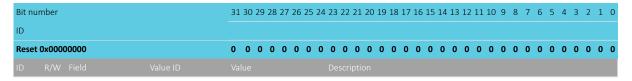
Coresight component identification registers.



10.7.1.1.22 CIDR[2]

Address offset: 0xFF8

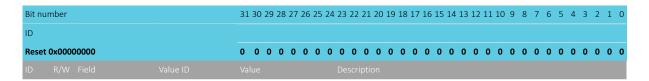
Coresight component identification registers.



10.7.1.1.23 CIDR[3]

Address offset: 0xFFC

Coresight component identification registers.



10.7.2 ATB Replicator

The ARM® ATB Replicator replicates incoming trace bus mesages across its outputs.

This document only provides a register-level description of this ARM component. See the ARM[®] CoreSight[™] SoC-400 Technical Reference Manual for more details

10.7.2.1 Registers

Instances

Instance	Base address	TrustZone	:		Split access	Description
		Мар	Att	DMA		
ATBREPLICATOR	0xE0058000	HF	NS	NA	No	ATBREPLICATOR



Register overview

Register	Offset	TZ	Description
IDFILTER0	0x000		The IDFILTER0 register enables the programming of ID filtering for master port 0.
IDFILTER1	0x004		The IDFILTER1 register enables the programming of ID filtering for master port 1.
ITATBCTR1	0xEF8		The ITATBCTR1 register returns the value of the atreadym0, atreadym1, and atvalids inputs in
			integration mode.
ITATBCTR0	0xEFC		The ITATBCTRO register controls the value of the atvalidm0, atvalidm1, and atreadys outputs
			in integration mode.
ITCTRL	0xF00		The ITCTRL register enables the component to switch from a functional mode, which is the
			default behavior, to integration mode where the inputs and outputs of the component can be
			directly controlled for the purposes of integration testing and topology detection.
CLAIMSET	0xFA0		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMSET register sets bits in the claim tag, and determines the number of claim bits
			implemented.
CLAIMCLR	0xFA4		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the
			claim tag.
LAR	0xFB0		This is used to enable write access to device registers.
LSR	0xFB4		This indicates the status of the lock control mechanism. This lock prevents accidental writes
			by code under debug. Accesses to the extended stimulus port registers are not affected by
			the lock mechanism. This register must always be present although there might not be any
			lock access control mechanism. The lock mechanism, where present and locked, must block
			write accesses to any control register, except the Lock Access Register. For most components
			this covers all registers except for the Lock Access Register.
AUTHSTATUS	0xFB8		Indicates the current level of tracing permitted by the system
DEVID	0xFC8		Indicates the capabilities of the component.
DEVTYPE	0xFCC		The DEVTYPE register provides a debugger with information about the component when the $$
			Part Number field is not recognized. The debugger can then report this information.
PIDR4	0xFD0		Coresight peripheral identification registers.
PIDR[0]	0xFE0		Coresight peripheral identification registers.
PIDR[1]	0xFE4		Coresight peripheral identification registers.
PIDR[2]	0xFE8		Coresight peripheral identification registers.
PIDR[3]	0xFEC		Coresight peripheral identification registers.
CIDR[0]	0xFF0		Coresight component identification registers.
CIDR[1]	0xFF4		Coresight component identification registers.
CIDR[2]	0xFF8		Coresight component identification registers.
CIDR[3]	0xFFC		Coresight component identification registers.

10.7.2.1.1 IDFILTER0

Address offset: 0x000

The IDFILTERO register enables the programming of ID filtering for master port 0.

Bit nu	ımber			31 30 29 28 27 26 25	5 24	1 23	22 2	21 2	0 19	18 1	.7 16	5 15	14	13 1	.2 11	. 10	9	8 7	' 6	5	4	3	2 1	. 0
ID																		F	l G	F	Ε	D	C E	3 A
Reset	0x000	00000		0 0 0 0 0 0 0	0	0	0	0 0	0	0	0 0	0	0	0	0 0	0	0	0 (0	0	0	0	0 (0
ID																								
A-H	RW	ID0_[i]0_[i]F (i=07)				Ena	ble	or d	lisab	le ID	filte	ring	for	IDs	OxiO_	_OxiF								
			NotFiltered	0		Trai	nsac	ction	ıs wi	th th	ese	IDs a	are	pass	ed o	n to	ATB	mas	ter	por	t 0.			
			Selected	1		Trai	nsac	ction	ıs wi	th th	ese	IDs a	are	disca	rde	by	the i	repli	cato	or.				

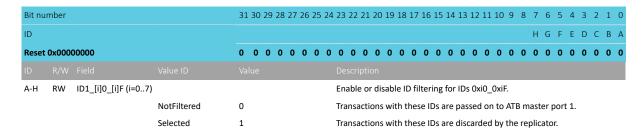




10.7.2.1.2 IDFILTER1

Address offset: 0x004

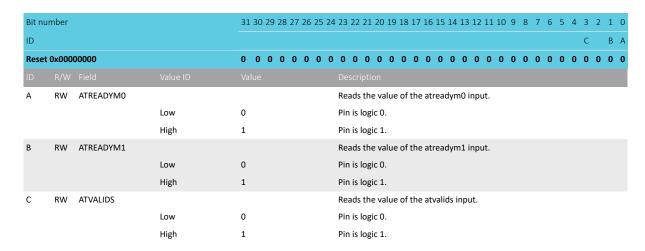
The IDFILTER1 register enables the programming of ID filtering for master port 1.



10.7.2.1.3 ITATBCTR1

Address offset: 0xEF8

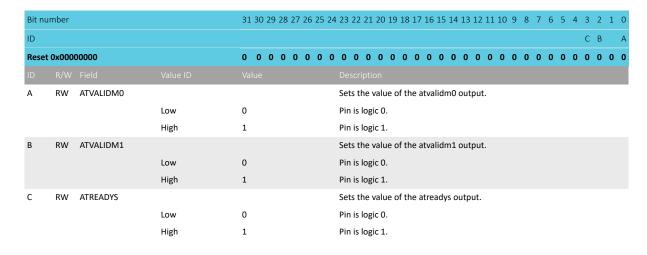
The ITATBCTR1 register returns the value of the atreadym0, atreadym1, and atvalids inputs in integration mode.



10.7.2.1.4 ITATBCTR0

Address offset: 0xEFC

The ITATBCTR0 register controls the value of the atvalidm0, atvalidm1, and atreadys outputs in integration mode.

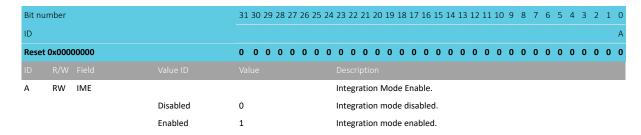




10.7.2.1.5 ITCTRL

Address offset: 0xF00

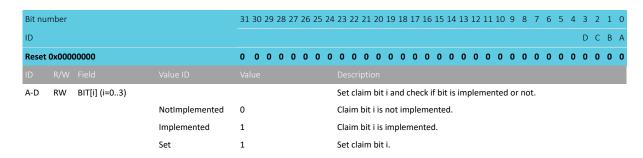
The ITCTRL register enables the component to switch from a functional mode, which is the default behavior, to integration mode where the inputs and outputs of the component can be directly controlled for the purposes of integration testing and topology detection.



10.7.2.1.6 CLAIMSET

Address offset: 0xFA0

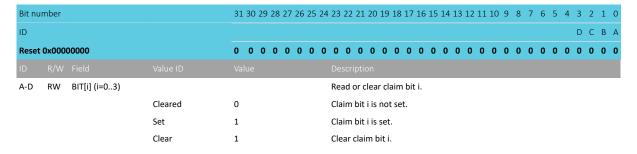
Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMSET register sets bits in the claim tag, and determines the number of claim bits implemented.



10.7.2.1.7 CLAIMCLR

Address offset: 0xFA4

Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the claim tag.



385

10.7.2.1.8 LAR

Address offset: 0xFB0

This is used to enable write access to device registers.

NORDIC'

Bit nu	mber			31	. 30	29	28	27	26	25	24	23	22	21	20 :	19 1	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1 0
ID				Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	А А
Reset	0x000	00000		0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																		
Α	RW	ACCESS										Αw	/rite	e of	0x0	C5A	CC	E55	er	nab	les	fur	the	er w	rite	ac	ces	s to	thi	s d	evio	e. A	ny	
												oth	er١	writ	e re	emo	ove	s w	rite	e ac	ces	SS.												
			UnLock	0x	C5/	ACCE	55					Unl	ock	re	gist	er iı	nte	rfa	ce.															

10.7.2.1.9 LSR

Address offset: 0xFB4

This indicates the status of the lock control mechanism. This lock prevents accidental writes by code under debug. Accesses to the extended stimulus port registers are not affected by the lock mechanism. This register must always be present although there might not be any lock access control mechanism. The lock mechanism, where present and locked, must block write accesses to any control register, except the Lock Access Register. For most components this covers all registers except for the Lock Access Register.

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	PRESENT			Indicates that a lock control mechanism exists for this device.
			NotImplemented	0	No lock control mechanism exists, writes to the Lock Access Register are
					ignored.
			Implemented	1	Lock control mechanism is present.
В	RW	LOCKED			Returns the current status of the Lock.
			UnLocked	0	Write access is allowed to this device.
			Locked	1	Write access to the component is blocked. All writes to control registers are
					ignored. Reads are permitted.
С	RW	TYPE			Indicates if the Lock Access Register is implemented as 8-bit or 32-bit.
			Bits32	0	This component implements a 32-bit Lock Access Register.
			Bits8	1	This component implements an 8-bit Lock Access Register.

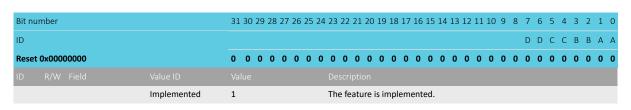
10.7.2.1.10 AUTHSTATUS

Address offset: 0xFB8

Indicates the current level of tracing permitted by the system

Bit nu	umber			31 30	29 2	28 27	26	25 24	1 23	22	21 2	0 19	18	17	16 15	14	13	12	11 :	10 9	8	7	6	5	4	3 2	2 1	0
ID																						D	D	С	С	ВЕ	3 A	Α
Rese	t 0x000	00000		0 0	0	0 0	0	0 0	0	0	0 (0 0	0	0	0 0	0	0	0	0	0 0	0	0	0	0	0	0 0	0	0
ID																												
Α	RW	NSID							No	n-se	ecure	e Inv	asiv	e De	bug													
			NotImplemented	0					Th	e fea	ature	e is r	ot i	mpl	emer	itec	l.											
			Implemented	1					Th	e fea	ature	e is i	mple	eme	nted													
В	RW	NSNID							No	n-se	ecure	e No	n-In	vasi	ve De	bu	g											
			NotImplemented	0					Th	e fea	ature	e is r	ot i	mpl	emer	itec	l.											
			Implemented	1					Th	e fea	ature	e is i	mple	eme	nted													
С	RW	SID							Se	cure	Inva	sive	Del	bug														
			NotImplemented	0					Th	e fea	ature	e is r	ot i	mpl	emer	ited	۱.											
			Implemented	1					Th	e fea	ature	e is i	mple	eme	nted													
D	RW	SNID							Sec	cure	Nor	n-Inv	asiv	e D	ebug													
			NotImplemented	0					Th	e fea	ature	e is r	ot i	mpl	emer	itec	l.											

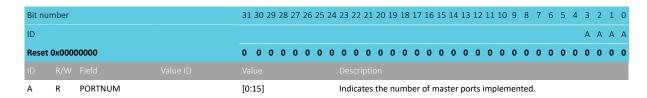




10.7.2.1.11 DEVID

Address offset: 0xFC8

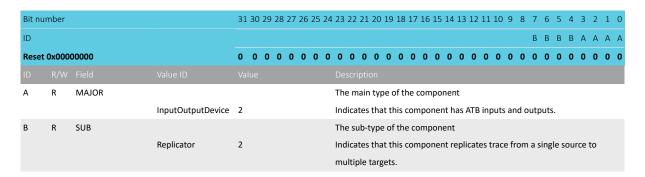
Indicates the capabilities of the component.



10.7.2.1.12 DEVTYPE

Address offset: 0xFCC

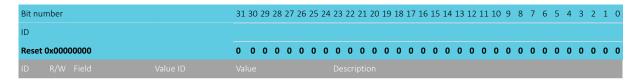
The DEVTYPE register provides a debugger with information about the component when the Part Number field is not recognized. The debugger can then report this information.



10.7.2.1.13 PIDR4

Address offset: 0xFD0

Coresight peripheral identification registers.

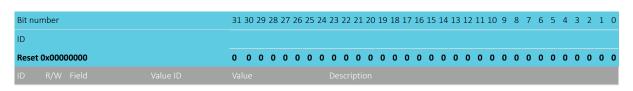


10.7.2.1.14 PIDR[0]

Address offset: 0xFE0

Coresight peripheral identification registers.

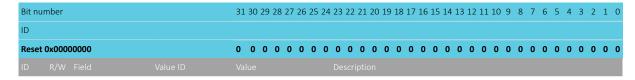




10.7.2.1.15 PIDR[1]

Address offset: 0xFE4

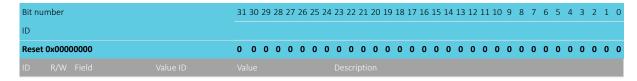
Coresight peripheral identification registers.



10.7.2.1.16 PIDR[2]

Address offset: 0xFE8

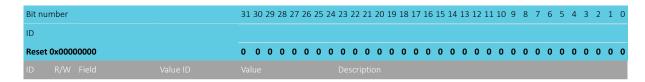
Coresight peripheral identification registers.



10.7.2.1.17 PIDR[3]

Address offset: 0xFEC

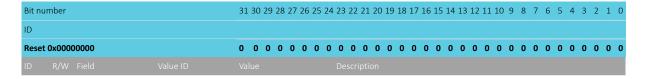
Coresight peripheral identification registers.



10.7.2.1.18 CIDR[0]

Address offset: 0xFF0

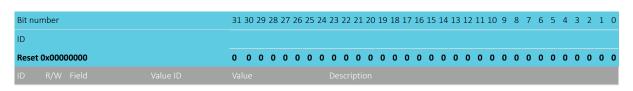
Coresight component identification registers.



10.7.2.1.19 CIDR[1]

Address offset: 0xFF4

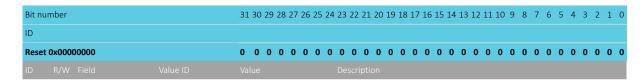
Coresight component identification registers.



10.7.2.1.20 CIDR[2]

Address offset: 0xFF8

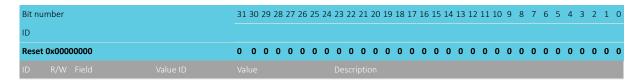
Coresight component identification registers.



10.7.2.1.21 CIDR[3]

Address offset: 0xFFC

Coresight component identification registers.



10.7.3 ETB — Embedded trace buffer

The ARM embedded trace buffer captures trace and stores it in an on-chip RAM for later inspection.

This document only provides a register-level description of this ARM component. See the Arm[®] CoreSight SoC-400 Technical Reference Manual for more details.

10.7.3.1 Registers

Instances

Instance	Base address	TrustZone	•		Split access	Description
		Мар	Att	DMA		
ETB	0xE0051000	HF	NS	NA	No	ETB

Register overview

Register	Offset	TZ	Description
RDP	0x4		ETB RAM Depth Register
STS	0xC		ETB Status Register
RRD	0x10		ETB RAM Read Data Register
RRP	0x14		ETB RAM Read Pointer Register
RWP	0x18		ETB RAM Write Pointer Register
TRG	0x1C		ETB Trigger Counter Register
CTL	0x20		ETB Control Register
RWD	0x24		ETB RAM Write Data Register
FFSR	0x300		ETB Formatter and Flush Status Register



Register	Offset	TZ	Description
FFCR	0x304		ETB Formatter and Flush Control Register
ITMISCOP0	0xEE0		Integration Test Miscellaneous Output Register 0
ITTRFLINACK	0xEE4		Integration Test Trigger In and Flush In Acknowledge Register
ITTRFLIN	0xEE8		Integration Test Trigger In and Flush In Register
ITATBDATA0	0xEEC		Integration Test ATB Data Register 0
ITATBCTR2	0xEF0		Integration Test ATB Control Register 2
ITATBCTR1	0xEF4		Integration Test ATB Control Register 1
ITATBCTR0	0xEF8		Integration Test ATB Control Register 0
ITCTRL	0xF00		Integration Mode Control Register
CLAIMSET	0xFA0		Claim Tag Set Register
CLAIMCLR	0xFA4		Claim Tag Clear Register
LAR	0xFB0		Lock Access Register
LSR	0xFB4		Lock Status Register
AUTHSTATUS	0xFB8		Authentication Status Register
DEVID	0xFC8		Device Configuration Register
DEVTYPE	0xFCC		Device Type Identifier Register
PERIPHID4	0xFD0		Peripheral ID4 Register
PERIPHIDO	0xFE0		Peripheral IDO Register
PERIPHID1	0xFE4		Peripheral ID1 Register
PERIPHID2	0xFE8		Peripheral ID2 Register
PERIPHID3	0xFEC		Peripheral ID3 Register
COMPID0	0xFF0		Component IDO Register
COMPID1	0xFF4		Component ID1 Register
COMPID2	0xFF8		Component ID2 Register
COMPID3	0xFFC		Component ID3 Register

10.7.3.1.1 RDP

Address offset: 0x4

ETB RAM Depth Register

Defines the depth, in words, of the trace RAM. This value is configurable in the RTL, but fixed at synthesis. Supported depth in powers of 2 only.



10.7.3.1.2 STS

Address offset: 0xC

ETB Status Register

This register indicates the status of the ETB.

NORDIC

Bit nu	mber		31 30 29 2	8 27 26 25	24 23 22	2 21 20	19 18	3 17	16 15	5 14 1	L3 1	2 11	10	9	8 7	6	5	4 3	2	1 0
ID																		0	С	В А
Reset	0x000	00008	0 0 0 0	0 0 0	0 0 0	0 0	0 0	0	0 0	0	0 (0 0	0	0	0 0	0	0	0 1	0	0 0
ID																				
Α	R	FULL			RAM	Full. Th	e flag	indi	icates	whe	n th	e RAI	M w	rite	poin	ter	has	wrap	ped	
					arour	nd.														
В	R	TRIGGERED			The T	riggered	d bit i	is set	whe	n a tr	igge	r has	bee	n o	bser	ved	Thi	s do	es	
					not ir	ndicate 1	that a	trig	ger h	as be	en e	mbe	dde	d in	the	trac	e da	ta by	the	
					forma	atter, bu	ıt is d	eter	mine	d by t	he p	rogr	amn	ning	of t	he F	orm	atte	rano	t
					Flush	Contro	l Regi	ster.												
С	R	ACQCOMP			The a	cquisiti	on co	mple	ete fla	ag inc	licat	es th	at ca	ptu	ıre h	as b	een	com	plet	ed
					when	the for	matte	er st	ops b	ecaus	e of	fany	of th	ne n	neth	ods	defi	ned	in th	e
					Form	atter an	ıd Flu	sh C	ontro	l Reg	ster	, or T	race	Cap	tEn	= 0.	This	alsc	res	ults in
					FtSto	pped in	the F	orm	atter	and I	lusl	n Stat	tus F	Regi	ster	goin	g HI	GH.		
D	R	FTEMPTY			Form	atter pi	peline	e em	pty. A	All dat	a st	ored	to R	AM						

10.7.3.1.3 RRD

Address offset: 0x10

ETB RAM Read Data Register

When trace capture is disabled, the contents of the ETB Trace RAM at the location addressed by the RAM Read Pointer Registers are placed in this register. Reading this register increments the RAM Read Pointer Register and triggers a RAM access cycle. If trace capture is enabled (FtStopped=0, TraceCaptEn=1), and ETB RAM reading is attempted, a read from this register outputs 0xFFFFFFFF and the RAM Read Pointer Register does not auto-increment. A constant stream of 1s being output corresponds to a synchronization output in the formatter protocol, which is not applicable to the ETB, and so can be used to signify a read error, when formatting is enabled.

Bit nu	mber		31	30	29	28	27	26	25	24	23	22	21	20	19	18	17 :	16 :	15 1	14 1	13 1	.2 1	1 1) 9	8	7	6	5	4	3	2	1 0
ID			Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	A .	Α	Α.	Α ,	λ Δ	A	A	Α	Α	Α	Α	Α	Α	A A
Reset	0x000	00000	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0 0
ID																																
Α	R	RAM_READ_DATA									Da	ta re	ead	fro	m 1	the	ЕТЕ	3 Tra	ace	RA	M.											

10.7.3.1.4 RRP

Address offset: 0x14

ETB RAM Read Pointer Register

The RAM Read Pointer Register sets the read pointer used to read entries from the Trace RAM over the APB interface. When this register is written to, a RAM access is initiated. The RAM Read Data Register is then updated. The register can also be read to determine the current memory location being referenced. This register must not be written to when trace capture is enabled (FtStopped=0, TraceCaptEn=1). If access is attempted, the register is not updated.

Bit n	umber		31 30 29 28 27	26 25 24 23	22 21 20	19 18	17 16	15 14	1 13 1	2 11 1	0 9	8	7	6	5 4	. 3	2	1 (5
ID											Α	Α	Α	Α .	A A	A	Α	Α Α	Δ
Rese	et 0x00000000		0 0 0 0 0	0 0 0 0	0 0 0	0 0	0 0	0 0	0 0	0 (0 0	0	0	0	0 0	0	0	0 (o
ID																			I
Α	RW RAM_READ_	POINTER		Set	Sets the read pointer used to read entries from the Trace RAM over the APB													3	
				inte	rface.														



10.7.3.1.5 RWP

Address offset: 0x18

ETB RAM Write Pointer Register

The RAM Write Pointer Register sets the write pointer used to write entries from the CoreSight bus into Trace RAM. During trace capture the pointer increments when the DataValid flag is asserted by the Formatter. When this register increments from its maximum value back to zero, the Full flag is set. This register can also be written to over APB to set the pointer for write accesses carried out through the APB interface. This register must not be written to when trace capture is enabled (FtStopped=0, TraceCaptEn=1). If access is attempted, the register is not updated. The register can also be read to determine the current memory location being referenced. It is recommended that addresses are 128-bit aligned when the formatter is used in normal or continuous modes.

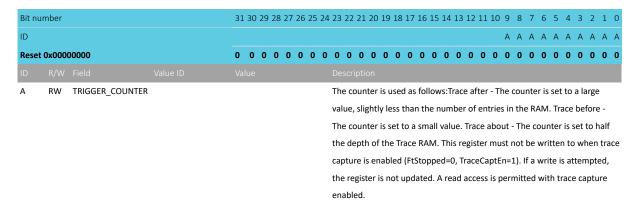
Bit n	umber			31	30 2	9 28	8 27	7 26	25	24	23	22	21 2	20 1	9 1	8 17	16	15	14	13	12	11 1	.0 9	8	7	6	5	4	3	2	1 0
ID																							А	A	Α	Α	Α	Α	Α	Α	А А
Rese	t 0x000	00000		0	0 0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0 0
ID																															
A RW RAM_WRITE_POINTER										Sets the write pointer used to write entries from the CoreSight bus into the														the							
											Tra	ice f	RAN	1.																	

10.7.3.1.6 TRG

Address offset: 0x1C

ETB Trigger Counter Register

The Trigger Counter Register disables write access to the Trace RAM by stopping the Formatter after a defined number of words have been stored following the trigger event. The number of 32-bit words written into the Trace RAM following the trigger event is equal to the value stored in this register+1.

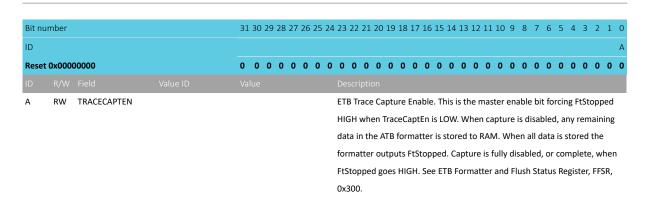


10.7.3.1.7 CTL

Address offset: 0x20 ETB Control Register

This register controls trace capture by the ETB.



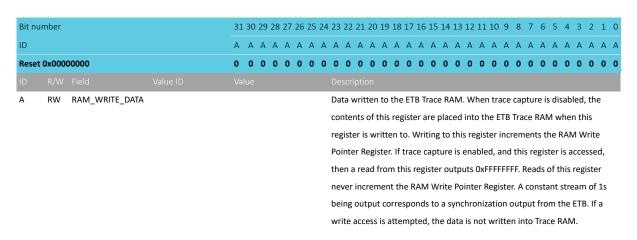


10.7.3.1.8 RWD

Address offset: 0x24

ETB RAM Write Data Register

Data written to the ETB Trace RAM.

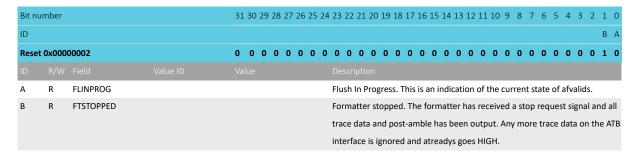


10.7.3.1.9 FFSR

Address offset: 0x300

ETB Formatter and Flush Status Register

This register indicates the implemented Trigger Counter multipliers and other supported features of the trigger system.



10.7.3.1.10 FFCR

Address offset: 0x304

ETB Formatter and Flush Control Register



This register controls the generation of stop, trigger, and flush events. To disable formatting and put the formatter into bypass mode, bits 1 and 0 must be clear. If both bits are set, then the formatter inserts triggers into the formatted stream. All three flush generating conditions can be enabled together. However, if a second or third flush event is generated then the current flush completes before the next flush is serviced. Flush from flushin takes priority over flush from Trigger, which in turn completes before a manually activated flush. All Trigger indication conditions can be enabled simultaneously although this can cause the appearance of multiple triggers if flush using trigger is also enabled. Both 'Stop On' settings can be enabled, although if flush on trigger, FOnTrig, is set up then none of the flushed data is stored. When the system stops, it returns ATREADY and does not store the accepted data packets. This is to avoid stalling of any other connected devices using a Trace Replicator. If an event in the Formatter and Flush Control Register is required, it must be enabled before the originating event starts. Because requests from flushes and triggers can originate in an asynchronous clock domain, the exact time the component acts on the request cannot be determined with respect to configuring the control. Note - To perform a stop on flush completion through a manually-generated flush request, two write operations to the register are required: one to enable the stop event, if it is not already enabled; one to generate the manual flush.

Bit nu	mber		31	30 2	9 28	27 2	26 25	24	23 22	2 21	. 20	19	18	17	16	15	14	13	12	11	. 10	9	8	7	6	5	4	3 2	2 1	. 0
ID																		J	1		Н	G	F		Ε	D	С		В	ВА
Reset	0x000	00000	0	0 (0	0	0 0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (0	0
ID																														
Α	RW	ENFTC							Do no	ot e	mbe	ed '	Trig	ger	s in	to t	he	for	ma	tte	d st	rea	m. ·	Trac	e d	isat	ole	cycle	s ar	nd
									trigge	ers a	are i	ind	icat	ed	by 1	RA	CEO	CTL	, w	her	e fi	ttec	l. C	an (only	be be	cha	ange	d w	hen
									FtSto	рре	d is	Н	GH.	Th	is b	it is	cle	ar	on	res	et.									
В	RW	ENFCONT							Conti	inuc	us i	mo	de i	n t	he E	ТВ	COI	rres	ро	nds	to	nor	ma	ıl m	ode	wi	th t	he		
									embe	eddi	ng d	of t	rigg	ers	. Ca	n c	nly	be	ch	ang	ged	wh	en	FtSt	op	oed	is ŀ	HIGH	. Th	iis
							bit is clear on reset.																							
С	RW	FONFLIN							Set th	nis k	oit to	о е	nab	le ı	ıse	of t	he	flus	shir	ı cc	nn	ecti	on.	Thi	s is	cle	ar c	n re	set.	
D	RW	FONTRIG							Gene	rate	e flu	ısh	usir	ng 1	rigg	ger	eve	nt.	Se	t th	is b	it t	o ca	ause	e a t	flus	h of	f dat	a in	the
											em when a Trigger Event occurs. This bit is										is c	s clear on reset. A Trigger Event								
								is defined as when the Trigger counter reaches zero (where fitted) or, in the															the							
								case of the trigger counter being zero (or not fitted), when trigin is HIGH.																						
E	RW	FONMAN							Settir	ng tl	his b	oit	caus	ses	a fl	ush	to	be	gei	ner	ate	d. T	his	is c	leai	red	wh	en tl	nis f	lush
									has b	een	ser	rvic	ed.	Th	is bi	t is	cle	ar	on	res	et.									
F	RW	TRIGIN							Indica	ate	a tri	igg	er o	n t	rigir	be	eing	as	ser	ted	l.									
G	RW	TRIGEVT							Indica	ate	a tri	igg	er o	n a	Trig	gge	r Ev	/en	t.											
Н	RW	TRIGFL							Indica	ates	a tı	rigg	ger (on	Flus	h c	om	ple	tio	n (a	fre	ady	s b	eing	re	turr	ned).		
I	RW	STOPFL							This f	forc	es tl	he	FIFC) to	dra	ain	off	any	y pa	art-	con	nple	etec	d pa	icke	ts.	Set	ting	this	bit
									enab	les 1	this	fur	nctio	on l	but	thi	sis	cle	ar c	on r	ese	t (d	lisa	ble	d).					
J	RW	STOPTRIG							Stop	the	fori	ma	tter	aft	er a	Tr	igge	er E	ver	nt is	s ob	ser	vec	l. Re	eset	to	disa	able	b	
									(zero).																				

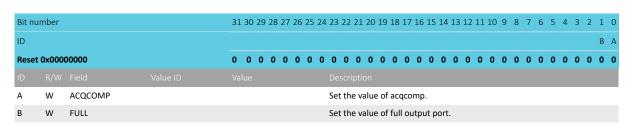
10.7.3.1.11 ITMISCOPO

Address offset: 0xEE0

Integration Test Miscellaneous Output Register 0

The Integration Test Miscellaneous Output Register 0 controls the values of some outputs from the ETB.



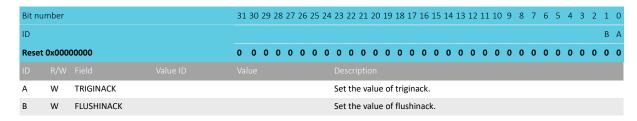


10.7.3.1.12 ITTRFLINACK

Address offset: 0xEE4

Integration Test Trigger In and Flush In Acknowledge Register

The Integration Test Trigger In and Flush In Acknowledge Register enables control of the triginack and flushinack outputs from the ETB.

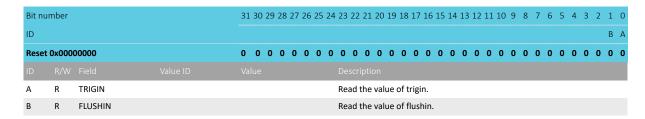


10.7.3.1.13 ITTRFLIN

Address offset: 0xEE8

Integration Test Trigger In and Flush In Register

The Integration Test Trigger In and Flush In Register contains the values of the flushin and trigin inputs to the ETB.



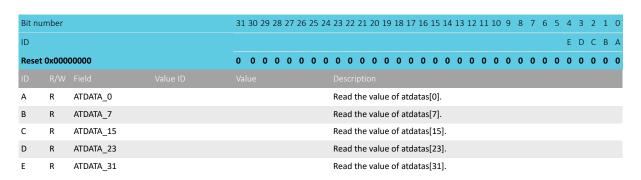
10.7.3.1.14 ITATBDATA0

Address offset: 0xEEC

Integration Test ATB Data Register 0

The Integration Test ATB Data Register 0 contains the value of the atdatas inputs to the ETB. The values are only valid when atvalids is HIGH.



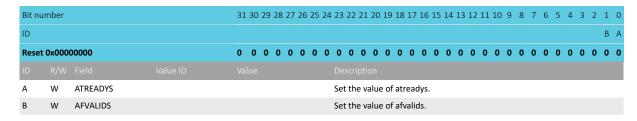


10.7.3.1.15 ITATBCTR2

Address offset: 0xEF0

Integration Test ATB Control Register 2

The Integration Test ATB Control Register 2 enables control of the atreadys and afvalids outputs of the ETB.

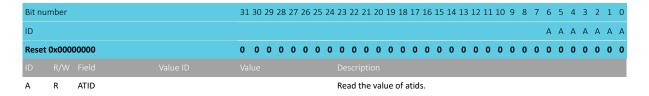


10.7.3.1.16 ITATBCTR1

Address offset: 0xEF4

Integration Test ATB Control Register 1

The Integration Test ATB Control Register 1 contains the value of the atids input to the ETB. This is only valid when atvalids is HIGH.



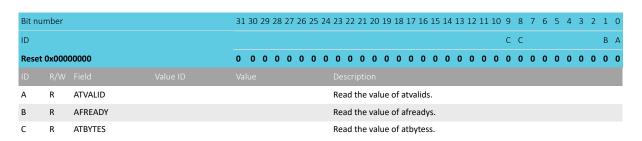
10.7.3.1.17 ITATBCTR0

Address offset: 0xEF8

Integration Test ATB Control Register 0

The Integration Test ATB Control Register 0 captures the values of the atvalids, afreadys, and atbytess inputs to the ETB. To ensure the integration registers work correctly in a system, the value of atbytess is only valid when atvalids, bit [0], is HIGH.



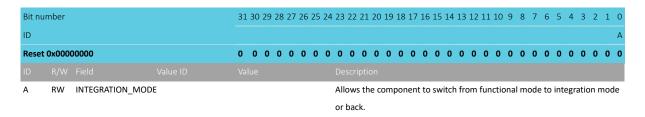


10.7.3.1.18 ITCTRL

Address offset: 0xF00

Integration Mode Control Register

This register is used to enable topology detection. For more information see the CoreSight Architecture Specification. This register enables the component to switch from a functional mode, the default behavior, to integration mode where the inputs and outputs of the component can be directly controlled for the purpose of integration testing and topology solving. Note: When a device has been in integration mode, it might not function with the original behavior. After performing integration or topology detection, you must reset the system to ensure correct behavior of CoreSight and other connected system components that are affected by the integration or topology detection.

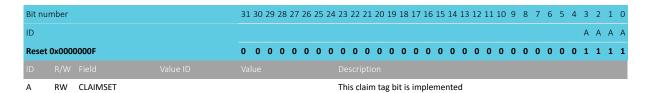


10.7.3.1.19 CLAIMSET

Address offset: 0xFA0

Claim Tag Set Register

This is used in conjunction with Claim Tag Clear Register, CLAIMCLR. This register forms one half of the Claim Tag value. This location allows individual bits to be set, write, and returns the number of bits that can be set, read.



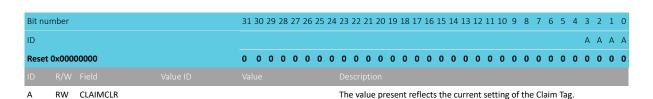
10.7.3.1.20 CLAIMCLR

Address offset: 0xFA4

Claim Tag Clear Register

This register is used in conjunction with Claim Tag Set Register, CLAIMSET. This register forms one half of the Claim Tag value. This location enables individual bits to be cleared, write, and returns the current Claim Tag value, read.

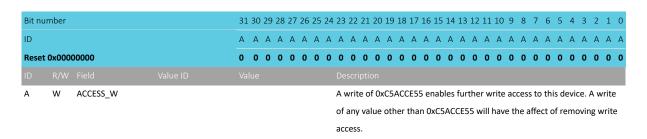




10.7.3.1.21 LAR

Address offset: 0xFB0 Lock Access Register

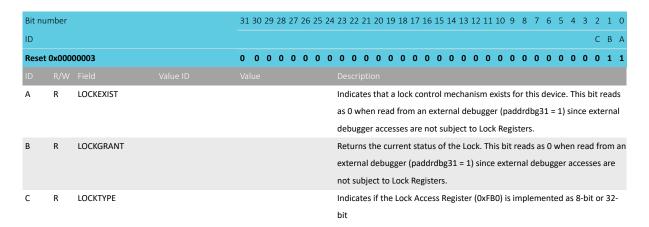
This is used to enable write access to device registers. External accesses from a debugger (paddrdbg31 = 1) are not subject to the Lock Registers. A debugger does not have to unlock the component in order to write and modify the registers in the component.



10.7.3.1.22 LSR

Address offset: 0xFB4 Lock Status Register

This indicates the status of the Lock control mechanism. This lock prevents accidental writes by code under debug. When locked, write access is blocked to all registers, except the Lock Access Register. External accesses from a debugger (paddrdbg31 = 1) are not subject to the Lock Registers. This register reads as 0 when read from an external debugger (paddrdbg31 = 1).



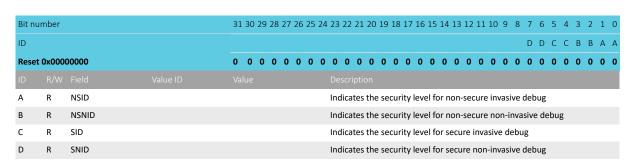
10.7.3.1.23 AUTHSTATUS

Address offset: 0xFB8

Authentication Status Register

Reports what functionality is currently permitted by the authentication interface.

NORDIC*

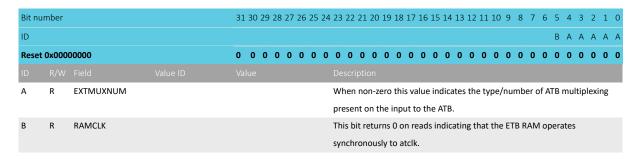


10.7.3.1.24 DEVID

Address offset: 0xFC8

Device Configuration Register

This register indicates the capabilities of the ETB.

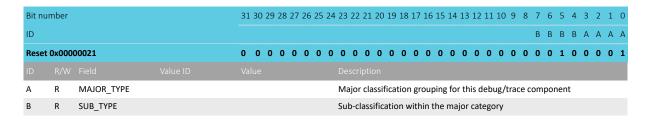


10.7.3.1.25 DEVTYPE

Address offset: 0xFCC

Device Type Identifier Register

It provides a debugger with information about the component when the Part Number field is not recognized. The debugger can then report this information.



10.7.3.1.26 PERIPHID4

Address offset: 0xFD0
Peripheral ID4 Register

Part of the set of Peripheral Identification registers. Contains part of the designer identity and the memory footprint indicator.

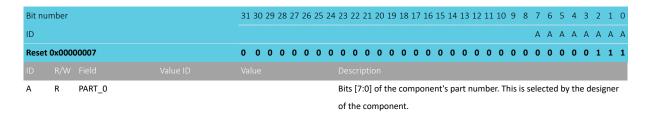


Bit nui	mhar		21.2	80 29 3	20 27	7 20 1	25 24	וח	11 1	11 7	0 10	10	17	10	1 Г	11.	12 1	2 1	1 10	. 0	0	7 /	_	г ,	4	3 2	. 1	1 0
bit fiui	nber		21.2	00 29 .	28 27	/ 20 .	25 24	23	22 Z	(1 2)	0 13	9 10	1/	10	12	14 .	13 1	.2 1	1 10	9	•				+ .	3 ₂		. 0
ID																						В	3 I	ВЕ	3 /	A A	\ <i>A</i>	A A
Reset	0x000	00004	0 (0 0	0 0	0	0 0	0	0 (0 0	0	0	0	0	0	0	0	0 0	0	0	0	0 () (0 () (0 1) 0
ID																												
Α	R	DES_2						JED	EC c	ont	inua	atio	n co	de i	ndi	cati	ng t	he o	lesi	gner	of 1	he o	om	npo	ner	nt (a	lon	g
								wit	h the	e ide	enti	ty c	ode)														
В	R	SIZE						This	s is a	4-k	oit v	alue	e tha	at ir	ndic	ate	s the	e tot	al c	onti	guo	us si	ze (of t	he	mei	nor	у
								win	dow	v use	ed b	y th	is c	om	pon	ent	in p	ow	ers o	of 2	fron	n the	e st	and	lard	d 4K	B. I	f
								a co	omp	one	nt c	only	req	uire	s th	ne s	tand	dard	4KE	the	n tl	nis s	hou	ıld r	rea	d as	0x	0,
								4KE	3 onl	ly, fo	or 8	KB s	et t	o 0>	(1, :	16K	В ==	0x2	2, 32	KB :	== 0	х3, а	and	lso	on			

10.7.3.1.27 PERIPHIDO

Address offset: 0xFE0
Peripheral ID0 Register

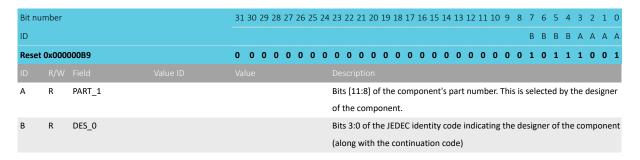
Part of the set of Peripheral Identification registers. Contains part of the designer specific part number.



10.7.3.1.28 PERIPHID1

Address offset: 0xFE4
Peripheral ID1 Register

Part of the set of Peripheral Identification registers. Contains part of the designer specific part number and part of the designer identity.

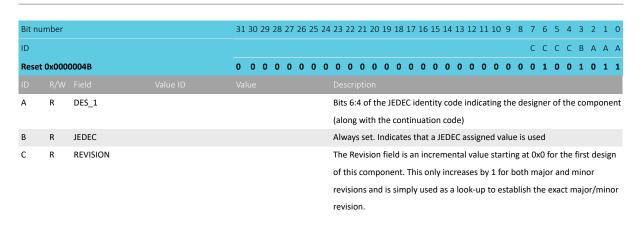


10.7.3.1.29 PERIPHID2

Address offset: 0xFE8
Peripheral ID2 Register

Part of the set of Peripheral Identification registers. Contains part of the designer identity and the product revision.

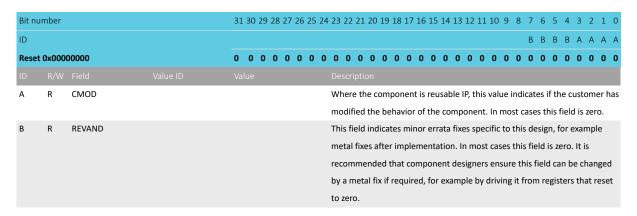




10.7.3.1.30 PERIPHID3

Address offset: 0xFEC
Peripheral ID3 Register

Part of the set of Peripheral Identification registers. Contains the RevAnd and Customer Modified fields.



10.7.3.1.31 COMPIDO

Address offset: 0xFF0
Component ID0 Register

A component identification register, that indicates that the identification registers are present.

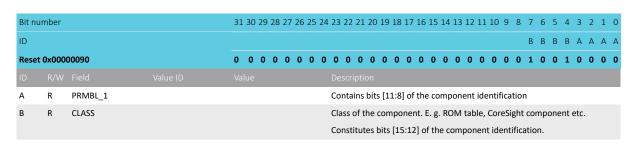


10.7.3.1.32 COMPID1

Address offset: 0xFF4
Component ID1 Register

A component identification register, that indicates that the identification registers are present. This register also indicates the component class.



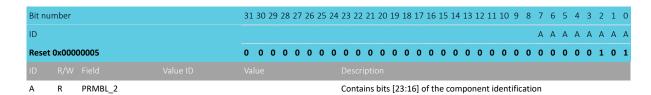


10.7.3.1.33 COMPID2

Address offset: 0xFF8

Component ID2 Register

A component identification register, that indicates that the identification registers are present.

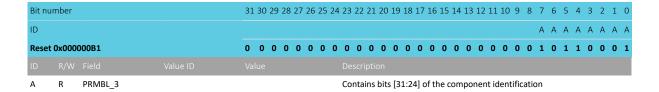


10.7.3.1.34 COMPID3

Address offset: 0xFFC

Component ID3 Register

A component identification register, that indicates that the identification registers are present.



10.7.4 ETM — Embedded trace macrocell

The ARM embedded trace macorcell implements instruction, data and event tracing.

This document only provides a register-level description of this ARM component. See the Arm[®] Embedded Trace Macrocell Architecture Specification for more details

10.7.4.1 Registers

Instances

Instance	Base address	TrustZone	•		Split acces	s Description
		Мар	Att	DMA		
FTM	0vE00/11000	HE	NS	NΔ	No	FTM

Register overview

Register	Offset	TZ	Description
TRCPRGCTLR	0x004		Enables the trace unit.



Register	Offset	TZ	Description
TRCPROCSELR	0x008		Controls which PE to trace.
			Might ignore writes when the trace unit is enabled or not idle.
			Before writing to this register, ensure that TRCSTATR.IDLE == 1 so that the trace unit can
			synchronize with the chosen PE.
			Implemented if TRCIDR3.NUMPROC is greater than zero.
TRCSTATR	0x00C		Idle status bit
TRCCONFIGR	0x010		Controls the tracing options
			This register must always be programmed as part of trace unit initialization.
			Might ignore writes when the trace unit is enabled or not idle.
TRCEVENTCTLOR	0x20		Controls the tracing of arbitrary events.
			If the selected event occurs a trace element is generated in the trace stream according to the
			settings in TRCEVENTCTL1R.DATAEN and TRCEVENTCTL1R.INSTEN.
TRCEVENTCTL1R	0x24		Controls the behavior of the events that TRCEVENTCTLOR selects.
			This register must always be programmed as part of trace unit initialization.
			Might ignore writes when the trace unit is enabled or not idle.
TRCSTALLCTLR	0x2C		Enables trace unit functionality that prevents trace unit buffer overflows.
			Might ignore writes when the trace unit is enabled or not idle.
			Must be programmed if TRCIDR3.STALLCTL == 1.
TRCTSCTLR	0x30		Controls the insertion of global timestamps in the trace streams.
			When the selected event is triggered, the trace unit inserts a global timestamp into the trace
			streams.
			Might ignore writes when the trace unit is enabled or not idle.
			Must be programmed if TRCCONFIGR.TS == 1.
TRCSYNCPR	0x34		Controls how often trace synchronization requests occur.
			Might ignore writes when the trace unit is enabled or not idle.
			If writes are permitted then the register must be programmed.
TRCCCCTLR	0x38		Sets the threshold value for cycle counting.
			Might ignore writes when the trace unit is enabled or not idle.
			Must be programmed if TRCCONFIGR.CCI==1.
TRCBBCTLR	0x3C		Controls which regions in the memory map are enabled to use branch broadcasting.
			Might ignore writes when the trace unit is enabled or not idle.
			Must be programmed if TRCCONFIGR.BB == 1.
TRCTRACEIDR	0x40		Sets the trace ID for instruction trace. If data trace is enabled then it also sets the trace ID for
			data trace, to (trace ID for instruction trace) + 1.
			This register must always be programmed as part of trace unit initialization.
			Might ignore writes when the trace unit is enabled or not idle.
TRCQCTLR	0x44		Controls when Q elements are enabled.
			Might ignore writes when the trace unit is enabled or not idle.
			This register must be programmed if it is implemented and TRCCONFIGR.QE is set to any
			value other than 0b00.
TRCVICTLR	0x080		Controls instruction trace filtering.
			Might ignore writes when the trace unit is enabled or not idle.
			Only returns stable data when TRCSTATR.PMSTABLE == 1.
			Must be programmed, particularly to set the value of the SSSTATUS bit, which sets the state
			of the start/stop logic.





Register	Offset	TZ	Description
TRCVIIECTLR	0x084		ViewInst exclude control.
			Might ignore writes when the trace unit is enabled or not idle.
			This register must be programmed when one or more address comparators are implemented.
TRCVISSCTLR	0x088		Use this to set, or read, the single address comparators that control the ViewInst start/stop
			logic. The start/stop logic is active for an instruction which causes a start and remains active
			$up\ to\ and\ including\ an\ instruction\ which\ causes\ a\ stop,\ and\ then\ the\ start/stop\ logic\ becomes$
			inactive.
			Might ignore writes when the trace unit is enabled or not idle.
			If implemented then this register must be programmed.
TRCVIPCSSCTLR	0x08C		Use this to set, or read, which PE comparator inputs can control the ViewInst start/stop logic.
			Might ignore writes when the trace unit is enabled or not idle.
			If implemented then this register must be programmed.
TRCVDCTLR	0x0A0		Controls data trace filtering.
			Might ignore writes when the trace unit is enabled or not idle.
			This register must be programmed when data tracing is enabled, that is, when either
			TRCCONFIGR.DA == 1 or TRCCONFIGR.DV == 1.
TRCVDSACCTLR	0x0A4		ViewData include / exclude control.
			Might ignore writes when the trace unit is enabled or not idle.
			This register must be programmed when one or more address comparators are implemented. $ \\$
TRCVDARCCTLR	0x0A8		ViewData include / exclude control.
			Might ignore writes when the trace unit is enabled or not idle.
			This register must be programmed when one or more address comparators are implemented.
TRCSEQEVR[n]	0x100		Moves the sequencer state according to programmed events.
			Might ignore writes when the trace unit is enabled or not idle.
			When the sequencer is used, all sequencer state transitions must be programmed with a valid
			event.
TRCSEQRSTEVR	0x118		Moves the sequencer to state 0 when a programmed event occurs.
			Might ignore writes when the trace unit is enabled or not idle.
			When the sequencer is used, all sequencer state transitions must be programmed with a valid
			event.
TRCSEQSTR	0x11C		Use this to set, or read, the sequencer state.
			Might ignore writes when the trace unit is enabled or not idle.
			Only returns stable data when TRCSTATR.PMSTABLE == 1.
			When the sequencer is used, all sequencer state transitions must be programmed with a valid
			event.
TRCEXTINSELR	0x120		Use this to set, or read, which external inputs are resources to the trace unit.
			Might ignore writes when the trace unit is enabled or not idle.
			Only returns stable data when TRCSTATR.PMSTABLE == 1.
			When the sequencer is used, all sequencer state transitions must be programmed with a valid
			event.
TRCCNTRLDVR[n]	0x140		This sets or returns the reload count value for counter n.
			Might ignore writes when the trace unit is enabled or not idle.
TRCCNTCTLR[n]	0x150		Controls the operation of counter n.
			Might ignore writes when the trace unit is enabled or not idle.





Register	Offset	TZ	Description
TRCCNTVR[n]	0x160		This sets or returns the value of counter n.
			The count value is only stable when TRCSTATR.PMSTABLE == 1.
			If software uses counter n then it must write to this register to set the initial counter value.
			Might ignore writes when the trace unit is enabled or not idle.
TRCRSCTLR[n]	0x200		Controls the selection of the resources in the trace unit.
			Might ignore writes when the trace unit is enabled or not idle.
			If software selects a non-implemented resource then CONSTRAINED UNPREDICTABLE
			behavior of the resource selector occurs, so the resource selector might fire unexpectedly or
			might not fire. Reads of the TRCRSCTLRn might return UNKNOWN.
TRCSSCCR0	0x280		Controls the single-shot comparator.
TRCSSCSRO	0x2A0		Indicates the status of the single-shot comparators. TRCSSCSR0 is sensitive toinstruction
			addresses.
TRCSSPCICR0	0x2C0		Selects the processor comparator inputs for Single-shot control.
TRCPDCR	0x310		Controls the single-shot comparator.
TRCPDSR	0x314		Indicates the power down status of the ETM.
TRCITATBIDR	0xEE4		Sets the state of output pins.
TRCITIATBINR	0xEF4		Reads the state of the input pins.
TRCITIATBOUTR	0xEFC		Sets the state of the output pins.
TRCITCTRL	0xF00		Enables topology detection or integration testing, by putting ETM-M33 into integration mode.
TRCCLAIMSET	0xFA0		Sets bits in the claim tag and determines the number of claim tag bits implemented.
TRCCLAIMCLR	0xFA4		Clears bits in the claim tag and determines the current value of the claim tag.
TRCAUTHSTATUS	0xFB8		Indicates the current level of tracing permitted by the system
TRCDEVARCH	0xFBC		The TRCDEVARCH identifies ETM-M33 as an ETMv4.2 component
TRCDEVTYPE	0xFCC		Controls the single-shot comparator.
TRCPIDR[n]	0xFD0		Coresight peripheral identification registers.
TRCCIDR[n]	0xFF0		Coresight component identification registers.

10.7.4.1.1 TRCPRGCTLR

Address offset: 0x004 Enables the trace unit.

Bit n	umber			31 30	29 2	28 27	26	25 2	24 2	3 22	2 21	L 20	19	18	L7 1	6 1	5 14	13	12	11 1	0 9	8	7	6	5	4	3 2	1	0
ID																													Α
Rese	t 0x000	00000		0 0	0	0 0	0	0	0 (0	0	0	0	0	0 (0	0	0	0	0 (0 0	0	0	0	0	0 (0	0	0
ID																													
Α	RW	EN							Т	race	un	it er	nabl	e bi	t														
			Disabled	0					Т	he t	race	e ur	nit is	dis	ble	d. A	ll tra	ace	resc	urce	es ar	e in	acti	ve a	and	no t	race	e is	
									g	ene	rate	d.																	
			Enabled	1					Т	he t	race	e ur	nit is	ena	ble	d.													

10.7.4.1.2 TRCPROCSELR

Address offset: 0x008

Controls which PE to trace.

Might ignore writes when the trace unit is enabled or not idle.

Before writing to this register, ensure that TRCSTATR.IDLE == 1 so that the trace unit can synchronize with the chosen PE.

Implemented if TRCIDR3.NUMPROC is greater than zero.



Α	RW	PROCSEL	PE select bits that select the PE to trace.
ID			Value Description
Reset	0x000	00000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID			АААА
Bit nu	ımber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0

10.7.4.1.3 TRCSTATR

Address offset: 0x00C

Idle status bit

Bit nu	mber			31	30 29	28	27 2	26 2	5 24	- 23	22	21	20 1	.9 1	18 1	7 1	6 1	5 1	4 1	3 1	2 1:	1 10	9	8	7	6	5	4 3	2	1	0
ID																														В	Α
Reset	0x000	00000		0	0 0	0	0	0 (0	0	0	0	0 (0	0 (0 () () () () (0	0	0	0	0	0	0	0 0	0	0	0
ID																															
Α	RW	IDLE								Tra	ace ı	ınit	ena	ble	e bit																
			NotIdle	0						Th	e tra	ice	unit	is	not	idle	2.														
			Idle	1						Th	e tra	ice	unit	isi	idle																
В	RW	PMSTABLE								Pro	ogra	mn	ners'	' m	ode	l sta	able	bi	t												
			NotStable	0						Th	e pr	ogr	amn	ner	s' m	od	el is	nc	t st	abl	e.										
			Stable	1						Th	e pr	ogr	amn	ner	s' m	od	el is	sta	able												

10.7.4.1.4 TRCCONFIGR

Address offset: 0x010

Controls the tracing options

This register must always be programmed as part of trace unit initialization.

Might ignore writes when the trace unit is enabled or not idle.

Bit nu	umber			31	30 29	28	27	26 2	5 24	4 23	22	21 2	0 1	19 1	8 1	7 1	5 15	5 14	13	12	11	10	9	8	7 (5 5	4	3	2	1 0
ID															Ν	1 L	. K	J	J	-1	Н	G	G	G	= [D	С	В	Α
Rese	t 0x000	00000		0	0 0	0	0	0 (0	0	0	0 ()	0 0) (0	0	0	0	0	0	0	0	0 () (0	0	0	0	0 0
ID																														
Α	RW	LOADASPOINST								Inst	truc	ction	PC	loa	d fi	eld.	. Th	is fi	eld	con	trol	ls w	hetl	her	oad	lins	truc	tion	ıs aı	re
										trac	ced	as P	0 i	nstrı	uct	ons	i.													
			No	0						Do	not	t trac	e I	oad	ins	tru	ctio	ns a	s P	0 in	stru	ıctic	ns.							
			Yes	1						Tra	ce I	load	ins	truc	tio	ns a	s P) in	stru	ctic	ns.									
В	RW	STOREASPOINST								Inst	truc	ction	PC	fiel	d. T	This	fie	ld c	onti	rols	wh	ethe	er st	tore	ins	truc	tion	s ar	e tra	aced
										as I	P0 i	nstru	ıct	ions																
			No	0						Do	not	t trac	e s	tore	in	stru	ctio	ons	as F	0 ir	str	ucti	ons							
			Yes	1						Tra	ce s	store	in	stru	ctic	ns a	as F	0 ir	nstr	ucti	ons									
С	RW	ВВ								Bra	nch	n bro	ad	cast	mo	de	bit.													
			Disabled	0						Bra	nch	n bro	ad	cast	mo	de	is d	isal	oled	١.										
			Enabled	1						Bra	nch	n bro	ad	cast	mo	de	is e	nat	led											
D	RW	CCI								Cyc	le d	coun	tin	g ins	tru	ctic	n t	race	e bit											
			Disabled	0						Cyc	le d	coun	tin	g in	the	ins	tru	ctio	n tr	ace	is c	disak	oled	i.						
			Enabled	1						Cyc	le d	coun	tin	g in	the	ins	tru	ctio	n tr	ace	is e	enab	led	١.						
E	RW	CID								Cor	nte	xt ID	tra	cing	, bi	t.														
			Disabled	0						Cor	nte	xt ID	tra	cing	is	disa	ble	d.												
			Enabled	1						Cor	nte	xt ID	tra	cing	is	ena	ble	d.												
F	RW	VMID								Virt	tual	l con	tex	t ide	ent	ifier	tra	cin	g bi	t.										
			Disabled	0						Virt	tual	l con	tex	t ide	ent	ifier	tra	cin	g is	disa	ble	d.								
			Disabled	0						Virt	tual	l con	tex	t ide	ent	ifier	tra	cin	g is	disa	ble	d.								



Bit nu	mber			31 3	0 29 2	28 27	26 2	25 24	23 22	21 20	19 :	18 1	L7 16	5 15	14	13 1	2 1	1 10	9	8	7	6	5 4	4 3	2	1	D
ID												ı	M L	K	J	J	l F	I G	G	G	F	E	ı	D C	В	Α	
Reset	0x0000	00000		0 (0 0	0 0	0 (0 0	0 0	0 0	0	0	0 0	0	0	0 (0 0	0	0	0	0	0	0 (0 0	0	0	D
																											Ī
			Enabled	1					Virtua	al cont	ext ic	den	tifier	tra	cing	is er	nabl	ed.	Т	_		_	_	_	_	_	
G	RW	COND							Cond	itional	instr	uct	ion t	raci	ng b	it.											
			Disabled	0					Cond	itional	instr	uct	ion t	raci	ng is	disa	ble	d.									
			LoadOnly	1					Cond	itional	load	ins	truct	ion	s are	tra	ed.										
			StoreOnly	2					Cond	itional	store	e ins	struc	tior	ıs ar	e tra	ced										
			LoadAndStore	3					Cond	itional	load	and	d sto	re ir	nstru	ıctio	ns a	re ti	race	ed.							
			All	7					All co	nditior	nal in	stru	uctio	ns a	re t	race	d.										
Н	RW	TS							Globa	al times	stam	p tr	acin	g bit	i.												
			Disabled	0					Globa	al times	stam	p tr	acin	g is	disa	bled											
			Enabled	1					Globa	al times	stam	p tr	acin	g is	enal	oled.											
1	RW	RS							Retur	n stack	ena	ble	bit.														
			Disabled	0					Retur	n stack	is d	isab	led.														
			Enabled	1					Retur	n stack	is e	nab	led.														
J	RW	QE							Q ele	ment e	nabl	le fi	eld.														
			Disabled	0					Q ele	ments	are o	disa	bled														
			OnlyWithoutInstCou	1					Q ele	ments	with	ins	truct	ion	cou	nts a	re e	enab	led	. Q 6	eler	nen	ts w	vitho	ut		
									instru	iction o	coun	ts a	re di	sabl	ed.												
			Enabled	3					Q ele	ments	with	and	d wit	hou	it ins	struc	tior	cou	ınts	are	en	able	ed.				
K	RW	VMIDOPT							Contr	ol bit t	o sel	lect	the '	Virt	ual d	onte	ext i	dent	tifie	r va	lue	use	d b	y the	9		
									trace	unit, b	oth 1	for t	race	ger	nera	tion	and	in t	he '	Virtu	ual (cont	text	idei	ntifie	er	
									comp	arator	5.																
			VTTBR_EL2	0					VTTB	R_EL2.	VMI) is	used	. If t	the 1	trace	un	it su	ppc	orts	a Vi	rtua	al co	onte	xt		
									ident	ifier la	ger t	thar	n the	VT	TBR_	_EL2	.VM	ID, t	he	upp	er ι	inus	sed	bits	are		
									alway	s zero.	If th	e tr	ace	unit	sup	port	s a '	Virtu	ıal d	cont	ext	idei	ntifi	er la	rger	r	
									than	8 bits a	nd it	fthe	e VT0	CR_I	EL2.	VS b	t fo	rces	use	of	an 8	3-bit	t Vir	rtual	con	text	
									ident	ifier, bi	ts [1	5:8]	of t	he t	race	uni	t Vir	tual	COI	ntex	t id	enti	fier	are	alwa	ays	
									zero.																		
			CONTEXTIDR_EL2	1					CONT	EXTIDI	R_EL	2 is	used	i.													
L	RW	DA							Data	addres	s tra	cing	g bit.														
			Disabled	0					Data	addres	s tra	cing	g is d	isab	led.												
			Enabled	1					Data	addres	s tra	cing	g is e	nab	led.												
М	RW	DV							Data	value t	racin	ng b	it.														
			Disabled	0					Data	value t	racin	ng is	disa	ble	d.												
			Enabled	1					Data	value t	racin	ng is	ena	bled	i.												

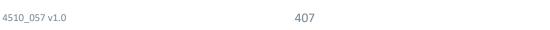
10.7.4.1.5 TRCEVENTCTLOR

Address offset: 0x20

Controls the tracing of arbitrary events.

If the selected event occurs a trace element is generated in the trace stream according to the settings in TRCEVENTCTL1R.DATAEN and TRCEVENTCTL1R.INSTEN.

Α	RW	EVENT	[0:255]			Selec	t whic	h eve	nt sho	ould a	gene	rate	trace	eler	nent	s.						
ID																						
Rese	t 0x000	00000	0 0 0	0 0 0	0 0	0 0	0 0	0	0 0	0 (0	0	0 0	0	0 0	0	0	0	0	0 0	0	0
ID																Α	Α	Α	Α	А А	Α	Α
Bit nu	umber		31 30 29	28 27 2	6 25 24	23 22	21 2	0 19 1	18 17	16 1	5 14	13 1	.2 11	. 10	9 8	7	6	5	4	3 2	1	0





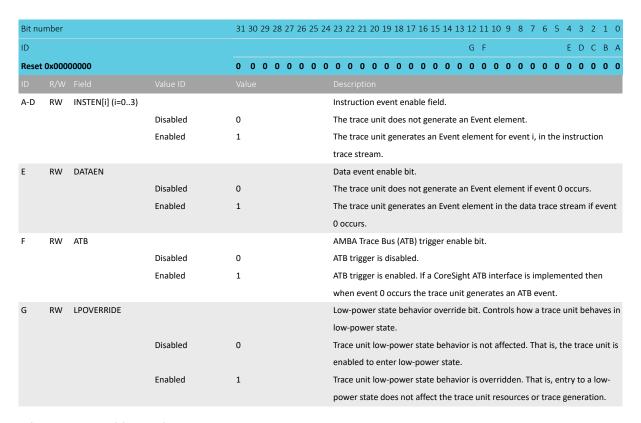
10.7.4.1.6 TRCEVENTCTL1R

Address offset: 0x24

Controls the behavior of the events that TRCEVENTCTLOR selects.

This register must always be programmed as part of trace unit initialization.

Might ignore writes when the trace unit is enabled or not idle.



10.7.4.1.7 TRCSTALLCTLR

Address offset: 0x2C

Enables trace unit functionality that prevents trace unit buffer overflows.

Might ignore writes when the trace unit is enabled or not idle.

Must be programmed if TRCIDR3.STALLCTL == 1.

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					G F E D C B A A A A
Reset	0x0000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	LEVEL		[15:0]	Threshold level field.
					If LEVEL is nonzero then a trace unit might suppress the generation of:
					Global timestamps in the instruction trace stream and the data trace
					stream.
					Cycle counting in the instruction trace stream, although the cumulative
					cycle count remains correct.
			Min	0	Zero invasion. This setting has a greater risk of a FIFO overflow
			Max	15	Maximum invasion occurs but there is less risk of a FIFO overflow.



Bit nu	ımber			31	30	29 28	8 27	26	25 24	1 2	3 22	2 2:	1 20	0 1	9 1	8 1	.7	16 1	15	14	13	12	11	10	9	8	7	6	5	4	3 2	2 1	. 0
ID																					G	F	Ε	D	С	В					A A	\ <i>A</i>	λ A
Reset	0x000	00000		0	0	0 0	0 0	0	0 0		0	0	0) (0 () (0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 () (0 0
В	RW	ISTALL								Ir	stru	ıcti	ion	sta	ıll b	it. (Co	ntro	ls i	f a	tra	ce	uni	t ca	n s	tall	the	PE '	whe	en t	he		
										ir	stru	ıcti	on	tra	ice	buf	fer	spa	ace	is	les	s th	an	LΕV	/EL.								
			Disabled	0						Т	ne t	rac	e u	nit	mι	ıstı	no	t sta	all t	he	PE												
			Enabled	1						Т	ne t	rac	e u	nit	caı	ı st	all	the	PE														
С	RW	DSTALL								D	ata	sta	ll b	it. (Cor	tro	ls i	if a	tra	ce	uni	t ca	ın s	tall	the	PE	wh	en 1	the	dat	a tr	ace	
										b	uffe	r sp	oac	e is	s le	s t	ha	n LE	VE	L.													
			Disabled	0						Т	ne t	rac	e u	nit	mι	ıstı	no	t sta	all t	he	PE												
			Enabled	1						Т	ne t	rac	e u	nit	caı	ı st	all	the	PE														
D	RW	INSTPRIORITY								Р	riori	tize	e in	str	uct	ion	tra	ace	bit	. Co	ont	rol	if	a tr	ace	un	it ca	ın p	rio	ritiz	е		
										ir	stru	ıcti	on	tra	ice	wh	en	the	in	stru	ıcti	on	tra	ce b	buff	er s	pac	e is	les	s th	an	LEV	EL.
			Disabled	0						Т	ne t	rac	e u	nit	mι	ıstı	no	t pr	ior	itize	e in	str	uct	ion	tra	ce.							
			Enabled	1						Т	ne t	rac	e u	nit	caı	n pr	rio	ritiz	e ir	nstr	uc	tior	tra	ace	. A 1	trac	e u	nit r	nig	ht p	rio	itiz	e
										ir	stru	ıcti	on	tra	ice	by I	pre	ever	ntir	ıg c	ut	out	of	dat	a tr	ace	, or	oth	er	mea	ans	whi	ch
										е	ısur	e t	hat	th	e ir	str	uc	tior	tr	ace	ha	ıs a	hig	hei	r pr	iori	ty tl	nan	the	da	ta t	race	<u>.</u>
E	RW	DATADISCARDLOAD								D	ata	dis	car	d fi	ield	. Co	ont	rols	if	a tı	rac	e u	nit	can	dis	car	d da	ata t	rac	e e	lem	ent	s on
										а	load	w b	hei	n th	he o	data	a tı	race	bı	uffe	r s	pac	e is	les	ss tl	nan	LEV	ÆL.					
			Disabled	0						Т	ne t	rac	e u	nit	mι	ıstı	no	t dis	ca	rd a	any	da	ta t	rac	e e	lem	ent	s.					
			Enabled	1						Т	ne t	rac	e u	nit	caı	n di	sca	ard	Ρ1	and	d P	2 e	em	ent	ts a	SSO	ciat	ed v	vith	ı da	ta lo	oad	s.
F	RW	DATADISCARDSTORE								D	ata	dis	car	d fi	ield	. Co	ont	rols	if	a tı	rac	e u	nit	can	dis	car	d da	ata t	rac	e e	lem	ent	s on
										а	stor	e v	vhe	en t	the	dat	ta 1	trac	e b	uff	er s	spa	ce i	is le	ess t	har	ı LE	VEL					
			Disabled	0						Т	ne t	rac	e u	nit	mι	ıstı	no	t dis	ca	rd a	any	da	ta t	rac	e e	lem	ent	s.					
			Enabled	1						Т	ne t	rac	e u	nit	caı	n di	sca	ard	Р1	and	d P	2 e	lem	ent	ts a	SSO	ciat	ed v	vith	ı da	ta s	tore	es.
G	RW	NOOVERFLOW								Ti	ace	ov	erf	low	v pr	eve	ent	ion	bit														
			Disabled	0						Ti	ace	ov	erf	low	v pr	eve	ent	ion	is	disa	able	ed.											
			Enabled	1						Ti	ace	ov	erf	low	v pr	eve	ent	ion	is	ena	ble	d.	Thi	s m	igh	t ca	use	a si	gni	fica	nt		
										р	erfo	rm	and	e i	mp	act																	

10.7.4.1.8 TRCTSCTLR

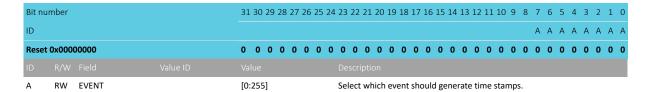
Address offset: 0x30

Controls the insertion of global timestamps in the trace streams.

When the selected event is triggered, the trace unit inserts a global timestamp into the trace streams.

Might ignore writes when the trace unit is enabled or not idle.

Must be programmed if TRCCONFIGR.TS == 1.



10.7.4.1.9 TRCSYNCPR

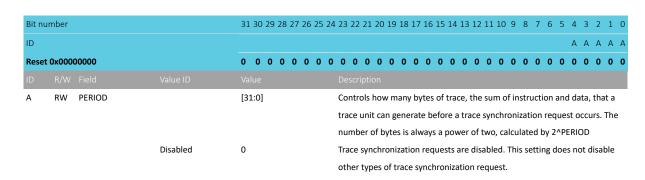
Address offset: 0x34

Controls how often trace synchronization requests occur.

Might ignore writes when the trace unit is enabled or not idle.

If writes are permitted then the register must be programmed.





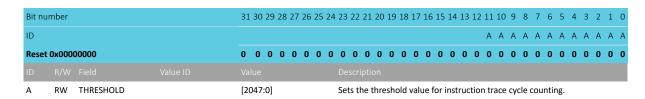
10.7.4.1.10 TRCCCCTLR

Address offset: 0x38

Sets the threshold value for cycle counting.

Might ignore writes when the trace unit is enabled or not idle.

Must be programmed if TRCCONFIGR.CCI==1.



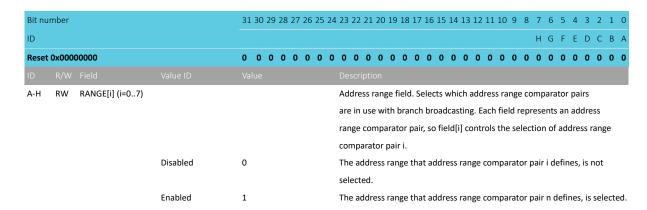
10.7.4.1.11 TRCBBCTLR

Address offset: 0x3C

Controls which regions in the memory map are enabled to use branch broadcasting.

Might ignore writes when the trace unit is enabled or not idle.

Must be programmed if TRCCONFIGR.BB == 1.



10.7.4.1.12 TRCTRACEIDR

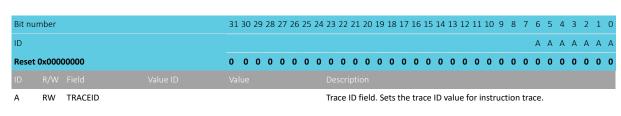
Address offset: 0x40

Sets the trace ID for instruction trace. If data trace is enabled then it also sets the trace ID for data trace, to (trace ID for instruction trace) + 1.

This register must always be programmed as part of trace unit initialization.

Might ignore writes when the trace unit is enabled or not idle.





Bit[0] must be zero if data trace is enabled. If data trace is enabled then a trace unit sets the trace ID for data trace, to TRACEID+1.

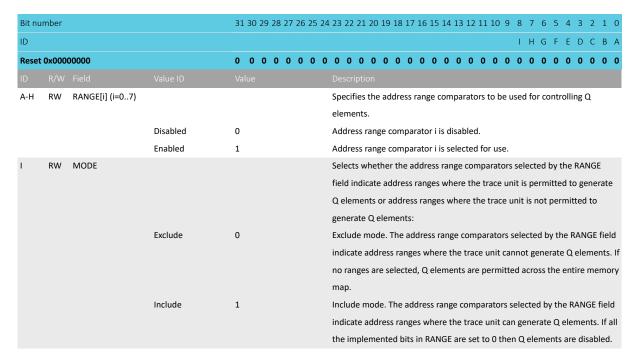
10.7.4.1.13 TRCQCTLR

Address offset: 0x44

Controls when Q elements are enabled.

Might ignore writes when the trace unit is enabled or not idle.

This register must be programmed if it is implemented and TRCCONFIGR.QE is set to any value other than 0b00.



10.7.4.1.14 TRCVICTLR

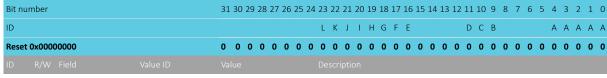
Address offset: 0x080

Controls instruction trace filtering.

Might ignore writes when the trace unit is enabled or not idle.

Only returns stable data when TRCSTATR.PMSTABLE == 1.

Must be programmed, particularly to set the value of the SSSTATUS bit, which sets the state of the start/stop logic.



RW EVENT_SEL Select which resource number should be filtered.



Bit nu	mber			31	30	29 2	28 2	7 26	6 25	5 24	23	22	21 2	20 2	19 1	L8 1	7 1	6 1	5 14	13	3 12	2 11	. 10	9	8	7	6	5	4	3 2	2 1	. 0
ID											L	K	J	ı	н	G	F E					D	С	В					Α	Α Α	λ A	Α
Reset	0x000	00000		0	0	0	0 0	0 0	0	0	0	0	0	0	0	0	0 () (0	0	0	0	0	0	0	0	0	0	0	0 (0 0	0
			Disabled	0							This	s ev	/ent	is r	not	filte	erec	l.														_
			Enabled	1							This	s ev	/ent	is f	filte	red																
В	RW	SSSTATUS									Wh	en	TRC	IDF	R4.N	IUN	1AC	PAI	RS >	0 0	or T	RCI	DR4	1.NI	JM	PC >	> 0, 1	this	bit	reti	urns	
											the	sta	itus	of t	the	sta	t/s	top	logi	c.												
			Stopped	0							The	sta	art/s	top	p lo	gic i	s in	the	sto	рр	ed s	stat	e.									
			Started	1							The	sta	art/s	top	p lo	gic i	s in	the	sta	rte	d st	ate										
С	RW	TRCRESET									Con	ntro	ols w	he	the	r a t	rac	e ur	nit n	nus	t tr	ace	a R	ese	t ex	сер	tior	١.				
			Disabled	0							The	tra	ace ı	unit	t do	es i	not	trac	e a	Res	et	exc	epti	ion	unl	ess	it tr	ace	s th	e		
											exc	ept	ion	or i	inst	ruc	ion	im	med	liat	ely	prio	or to	o th	e R	ese	t exc	ep	tion			
			Enabled	1							The	tra	ace ı	unit	t alv	way	s tra	aces	s a F	ese	et e	xce	ptic	on.								
D	RW	TRCERR									Wh	en	TRC	IDF	R3.T	RCE	RR:	==1	, thi	s bi	t co	ontr	ols	wh	eth	er a	tra	e u	nit	mus	st tr	ace
											a Sy	/ste	em e	rro	r ex	cep	otio	n.														
			Disabled	0							The	tra	ace ı	unit	t do	es i	not	trac	e a	Sys	ten	n er	ror	exc	ept	ion	unl	ess	it tr	ace	s th	e
											exc	ept	ion	or i	inst	ruc	ion	im	med	liat	ely	prio	or to	o th	e S	yste	m e	rro	rex	cept	tion	
			Enabled	1							The	tra	ace ı	unit	t alv	way	s tra	aces	a S	yst	em	err	or e	exce	pti	on,	rega	rdl	ess	of tl	he	
											valu	ue d	of Vi	ew	Inst	t.																
E-H	RW	EXLEVEL[i]_S (i=03)									In S	ecu	ure s	tat	e, e	ach	bit	COI	ntro	ls v	vhe	the	r in	stru	ctio	on t	racii	ng i	s er	abl	ed f	or
											the	со	rres	por	ndin	ıg E	xce	otio	n le	vel	i.											
			Disabled	1							The	tra	ace ı	unit	t do	es i	not	gen	era	e ii	nstr	uct	ion	tra	ce,	in S	ecu	re s	tate	, fo	r	
											Exc	ept	ion	lev	el i.																	
			Enabled	0							The	tra	ace ı	unit	t ge	ner	ates	ins	stru	ctio	n t	race	e, in	Se	cure	e sta	ate,	for	Exc	epti	on	
											leve	el i.																				
I-L	RW	EXLEVEL[i]_NS (i=0	3)								In N	lon	-sec	ure	e sta	ate,	eac	h b	it co	ntr	ols	wh	eth	er i	nsti	ruct	ion	trac	ing	is e	nab	led
											for	the	cor	res	por	ndir	g E	xce	otio	n le	vel	i.										
			Disabled	1									ace ı				not	gen	era	e ii	nstr	uct	ion	tra	ce,	in N	lon-	sec	ure	stat	e, f	or
											Exc	ept	ion	lev	el i.																	
			Enabled	0										unit	t ge	ner	ates	ins	stru	ctio	n t	race	e, in	No.	n-s	ecu	re s	ate	, fo	r Ex	cep	tion
											leve	el i.																				

10.7.4.1.15 TRCVIIECTLR

Address offset: 0x084

ViewInst exclude control.

Might ignore writes when the trace unit is enabled or not idle.

This register must be programmed when one or more address comparators are implemented.



Bit nu	mber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					PONMLKJI HGFEDCBA
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
A-H	RW	INCLUDE[i] (i=07)			Include range field. Selects which address range comparator pairs are in use
					with ViewInst include control.
			Disabled	0	The address range that address range comparator pair i defines, is not
					selected for ViewInst include control.
			Enabled	1	The address range that address range comparator pair i defines, is selected
					for ViewInst include control.
I-P	RW	EXCLUDE[i] (i=07)			Exclude range field. Selects which address range comparator pairs are in use
					with ViewInst exclude control.
			Disabled	0	The address range that address range comparator pair i defines, is not
					selected for ViewInst exclude control.
			Enabled	1	The address range that address range comparator pair i defines, is selected
					for ViewInst exclude control.

10.7.4.1.16 TRCVISSCTLR

Address offset: 0x088

Use this to set, or read, the single address comparators that control the ViewInst start/stop logic. The start/stop logic is active for an instruction which causes a start and remains active up to and including an instruction which causes a stop, and then the start/stop logic becomes inactive.

Might ignore writes when the trace unit is enabled or not idle.

If implemented then this register must be programmed.

Bit nu	mber			31	30 29	28	27 2	6 25	24	23	22	21	20	19	18	17	16	15 1	L4 1	.3 1	2 1	1 10	9	8	7	6	5	4	3	2	1 0
ID										Р	0	N	М	L	K	J	1								Н	G	F	Ε	D	С	В А
Reset	0x000	00000		0	0 0	0	0 (0 0	0	0	0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0	0	0 0
ID																															
А-Н	RW	START[i] (i=07)								Se	lec	ts w	hicl	h sii	ngle	e ad	ldre	ss c	om	par	atoı	s ar	e ir	use	e wi	th١	√iev	vIn:	st st	art	/stop
										со	ntr	ol, f	or t	he	pur	pos	e of	sta	rtir	ng t	race	١.									
			Disabled	0						Th	e s	ingle	e ac	ddre	ess	con	npai	rato	ri,	is n	ot s	elec	ted	as a	a sta	art	resc	our	ce.		
			Enabled	1						Th	ie s	ingle	e ac	ddre	ess (con	npai	rato	ri,	is s	elec	ted	as a	sta	rt r	eso	urc	e.			
I-P	RW	STOP[i] (i=07)								Se	lec	ts w	hic	h sii	ngle	e ad	ldre	ss c	om	par	atoı	s ar	e ir	use	e wi	th١	√iev	vIn:	st st	art	/stop
										со	ntr	ol, f	or t	he	pur	pos	e of	sto	рр	ng	trac	e									
			Disabled	0						Th	e s	ingl	e ac	ddre	ess (con	npai	rato	ri,	is n	ot s	elec	ted	as a	a st	ор і	reso	our	ce.		
			Enabled	1						Th	e s	ingl	e ac	ddre	ess	con	npai	rato	r i,	is s	elec	ted	as a	sto	p r	eso	urce	e.			

10.7.4.1.17 TRCVIPCSSCTLR

Address offset: 0x08C

Use this to set, or read, which PE comparator inputs can control the ViewInst start/stop logic.

Might ignore writes when the trace unit is enabled or not idle.

If implemented then this register must be programmed.



D.:									05.																		_			_	
Bit nu	mber			31.	30 29	28	3 2 /	26	25 .	24	23 2	!2 2	21 2	0 1	9 1	.8 1	/ 1	61	5 14	113	3 12	11	10	9	8 7	6	5	4	3	2	1 0
ID											Р (l C	N N	VI L	L H	K J	J								Н	G	F	Ε	D	С	ВА
Reset	0x000	00000		0	0 0	0	0	0	0	0	0 (0 (0 (0 () (0 () () (0	0	0	0	0	0	0 0	0	0	0	0	0	0 0
ID																															
A-H	RW	START[i] (i=07)									Sele	cts	wh	ich	PE	con	npa	rato	or ir	ıpu	ts ar	e in	use	wi	th V	ewl	nst	sta	rt/st	ор	
											cont	rol	, for	r the	e pi	urp	ose	of	star	ting	g tra	ce									
			Disabled	0							The	sin	gle	PE d	con	npa	rato	or ir	nput	: i, i	s no	t se	lect	ed a	as a	stari	t re	sou	rce.		
			Enabled	1							The	sin	gle	PE d	con	npa	rato	or ir	put	i, i	s se	lect	ed a	s a	star	res	our	rce.			
I-P	RW	STOP[i] (i=07)									Sele	cts	wh	ich	PE	con	npa	rato	or ir	ıpu'	ts ar	e in	use	wi	th V	ewl	nst	sta	rt/st	ор	
											cont	rol	, for	r the	е рі	urp	ose	of	stop	pir	g tr	ace									
			Disabled	0							The	sin	gle	PE d	con	npa	rato	or ir	put	i, i	s no	t se	lect	ed a	as a	stop	res	soui	rce.		
			Enabled	1							The	sin	gle	PE d	con	npa	rato	or ir	put	i, i	s se	lect	ed a	s a	stop	res	our	ce.			
				1									_													·			ce.		

10.7.4.1.18 TRCVDCTLR

Address offset: 0x0A0

Controls data trace filtering.

Might ignore writes when the trace unit is enabled or not idle.

This register must be programmed when data tracing is enabled, that is, when either TRCCONFIGR.DA == 1 or TRCCONFIGR.DV == 1.

Bit nu	mber			31	30	29	28	27 2	26	25 2	1 23	22	21	20	19	18	3 1	7 10	5 1!	5 14	13	3 12	2 11	. 10	9	8	7	6	5	4	3	2 1	. 0
ID																						L	K	J	1	1	Н	G	F	Ε	D (СВ	8 A
Reset	0x000	00000		0	0	0	0	0	0	0 (0	0	0	0	0	0	C	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0
ID																																	
A-H	RW	EVENT[i] (i=07)									Eve	ent	unit	t er	nab	le l	bit																
			Disabled	0							The	e tr	race	eve	ent	is	no	t se	lec	ted	for	tra	ce 1	ilte	ring								
			Enabled	1							The	e tr	race	eve	ent	is	sel	lect	ed '	or 1	rac	e fi	ltei	ing									
1	RW	SPREL									Cor	ntro	ols v	vhe	eth	er a	a t	race	ur	it t	ace	es c	lata	for	tra	nsfe	ers	that	are	e re	lativ	e to)
											the	Sta	ack	Poi	inte	er (SP).															
			Enabled	0							The	e tr	race	uni	it c	loe	s r	ot a	iffe	ct t	he 1	trac	ing	of:	ı-92	ela	tive	tra	nsf	ers.			
			DataOnly	2							The	e tr	race	un	it c	loe	s r	ot 1	rac	e th	ie a	dd	ress	ро	rtio	n o	f SP	-rel	ativ	e tr	ans	fers	. If
											dat	a v	/alue	e tr	aci	ng	is	ena	ble	d th	en	the	tra	ice i	unit	gei	nera	ates	a F	21 d	ata	add	ress
											ele	me	ent.																				
			Disabled	3							The	e tr	race	uni	it c	loe	s r	ot 1	rac	e tł	ie a	dd	ress	or	valı	ne b	ort	ion	of	SP-	rela	tive	:
													ers.																				
J	RW	PCREL											ols v							it t	ace	es c	lata	for	tra	nsfe	ers	that	are	e re	lativ	e to)
													rogra																				
			Enabled	0									race										_										
			Disabled	1									race	un	it c	loe	s r	ot 1	rac	e th	ie a	ıdd	ress	or	valı	ne b	ort	ion	of	PC-	rela	itive	2
.,													ers.																	1			
K	RW	TBI											ols v	vhi	ch	int	ori	mat	ion	a tı	ace	ur	iit p	орі	ulat	es II	1 bi	ts[6	3:5	6] C	of th	ie da	ata
			Cinclinational	_							ado							_	-10	2.5	c1 4	_ -					1			:+[=:	-1 -	£ 41	_
			SignExtend	0									race				_		-		-					me	vaii	ue a	IS D	IT[5	5] 0	T the	e
			Conv	1									addr race						_							ma	باديد		c h	i+c[4	20.0	61.0	£
			Сору	1									ace ata a				gıı	יוע כ	JSLC	3.3	טן נ	.0 11	ave	LITE	: Sa	ille	vali	ue a	15 D	ιιςι	.5.5	0 [0	''
	RW	TRCEXDATA											ols t				na (of d	ata	tra	nefa	arc '	for	٥٧٢	anti	ons	an	d av	ror	ntio	n ro	turr	nc
-	1100	THEENDAIN											mv6				_								- Pti	0113	un	u c,	icc	3010		cuii	.5
			Disabled	0									tion												าร ลเ	re n	ot t	rac	-d				
			Enabled	1								•	tion																		her	asp	ects
				-								•	wDa																				
											0, 1									· u	ata			213				JUL	۵.				





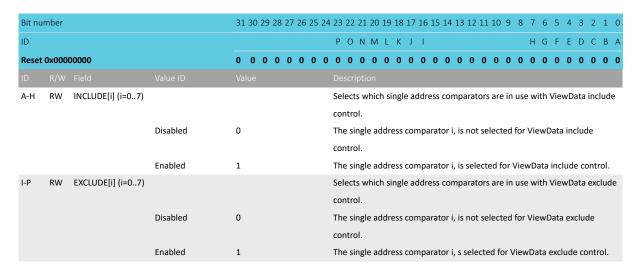
10.7.4.1.19 TRCVDSACCTLR

Address offset: 0x0A4

ViewData include / exclude control.

Might ignore writes when the trace unit is enabled or not idle.

This register must be programmed when one or more address comparators are implemented.



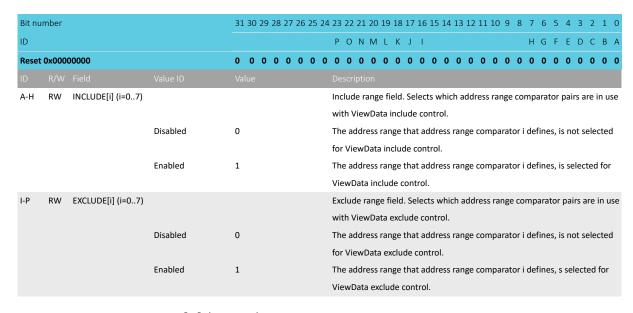
10.7.4.1.20 TRCVDARCCTLR

Address offset: 0x0A8

ViewData include / exclude control.

Might ignore writes when the trace unit is enabled or not idle.

This register must be programmed when one or more address comparators are implemented.



10.7.4.1.21 TRCSEQEVR[n] (n=0..2)

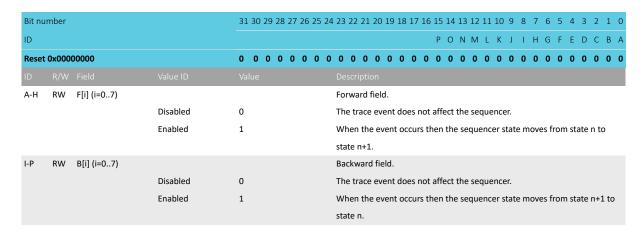
Address offset: $0x100 + (n \times 0x4)$

Moves the sequencer state according to programmed events.



Might ignore writes when the trace unit is enabled or not idle.

When the sequencer is used, all sequencer state transitions must be programmed with a valid event.



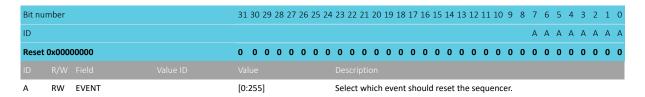
10.7.4.1.22 TRCSEQRSTEVR

Address offset: 0x118

Moves the sequencer to state 0 when a programmed event occurs.

Might ignore writes when the trace unit is enabled or not idle.

When the sequencer is used, all sequencer state transitions must be programmed with a valid event.



10.7.4.1.23 TRCSEQSTR

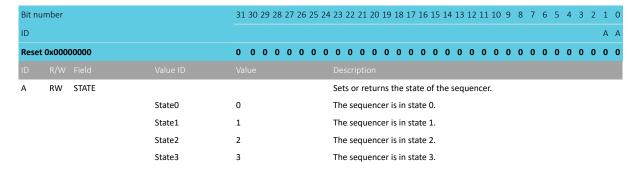
Address offset: 0x11C

Use this to set, or read, the sequencer state.

Might ignore writes when the trace unit is enabled or not idle.

Only returns stable data when TRCSTATR.PMSTABLE == 1.

When the sequencer is used, all sequencer state transitions must be programmed with a valid event.



10.7.4.1.24 TRCEXTINSELR

Address offset: 0x120



Use this to set, or read, which external inputs are resources to the trace unit.

Might ignore writes when the trace unit is enabled or not idle.

Only returns stable data when TRCSTATR.PMSTABLE == 1.

When the sequencer is used, all sequencer state transitions must be programmed with a valid event.

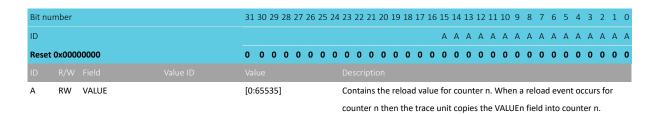
Bit nu	ımber		31	30	29	28	27	26	25	24 :	23	22 2	21 2	0 19	9 18	17	16	15	14 :	L3 1	2 1	1 10	9	8	7	6	5	4	3	2	1 0
ID			D	D	D	D	D	D	D	D	С	С	C (С	С	С	С	В	В	В	3 E	В	В	В	Α	Α	Α	Α	Α	Α	А А
Reset	0x000	00000	0	0	0	0	0	0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0 (0	0	0	0	0	0	0	0	0	0 0
ID											Des																				
A-D	RW	SEL[i] (i=03)	[0:	:25!	5]					ı	Eac	h fie	eld i	n th	is co	olled	tion	ı se	lect	s ar	ı ex	tern	al ir	npu	t as	a r	eso	urc	e fo	r th	e
										1	trac	e u	nit.																		

10.7.4.1.25 TRCCNTRLDVR[n] (n=0..3)

Address offset: $0x140 + (n \times 0x4)$

This sets or returns the reload count value for counter n.

Might ignore writes when the trace unit is enabled or not idle.



10.7.4.1.26 TRCCNTCTLR[n] (n=0..3)

Address offset: $0x150 + (n \times 0x4)$

Controls the operation of counter n.

Might ignore writes when the trace unit is enabled or not idle.

Bit nu	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					D C B B B B B B B A A A A A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	CNTEVENT		[0:255]	Selects an event, that when it occurs causes counter n to decrement.
В	RW	RLDEVENT		[0:255]	Selects an event, that when it occurs causes a reload event for counter n.
С	RW	RLDSELF			Controls whether a reload event occurs for counter n, when counter n
					reaches zero.
			Disabled	0	The counter is in Normal mode.
			Enabled	1	The counter is in Self-reload mode.
D	RW	CNTCHAIN			For TRCCNTCTLR3 and TRCCNTCTLR1, this bit controls whether counter n
					decrements when a reload event occurs for counter n-1.
			Disabled	0	Counter n does not decrement when a reload event for counter n-1 occurs.
			Enabled	1	Counter n decrements when a reload event for counter n-1 occurs. This
					concatenates counter n and counter n-1, to provide a larger count value.

10.7.4.1.27 TRCCNTVR[n] (n=0..3)

Address offset: $0x160 + (n \times 0x4)$

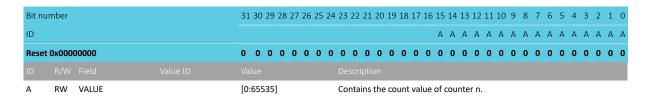


This sets or returns the value of counter n.

The count value is only stable when TRCSTATR.PMSTABLE == 1.

If software uses counter n then it must write to this register to set the initial counter value.

Might ignore writes when the trace unit is enabled or not idle.



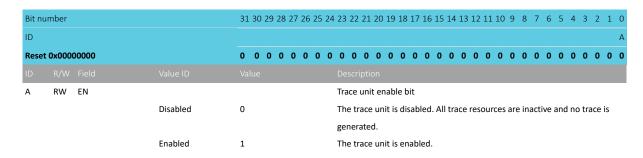
10.7.4.1.28 TRCRSCTLR[n] (n=2..31)

Address offset: $0x200 + (n \times 0x4)$

Controls the selection of the resources in the trace unit.

Might ignore writes when the trace unit is enabled or not idle.

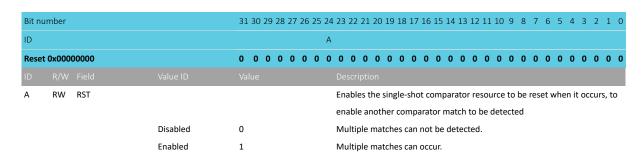
If software selects a non-implemented resource then CONSTRAINED UNPREDICTABLE behavior of the resource selector occurs, so the resource selector might fire unexpectedly or might not fire. Reads of the TRCRSCTLRn might return UNKNOWN.



10.7.4.1.29 TRCSSCCR0

Address offset: 0x280

Controls the single-shot comparator.



10.7.4.1.30 TRCSSCSR0

Address offset: 0x2A0

Indicates the status of the single-shot comparators. TRCSSCSR0 is sensitive toinstruction addresses.

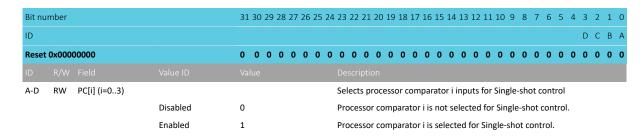


Bit nu	ımber			31	30 2	29 2	28 27	7 26	25 2	24	23 2	22 2	21 2	20 1	19 1	18 1	L7 1	6 1	5 1	4 13	3 12	11	10	9	8	7	6	5	4	3 2	2 1	. 0
ID				Е																										0 (C E	3 A
Reset	t 0x000	00000		0	0	0 (0 0	0	0	0	0	0	0	0 (0	0	0	0 () (0	0	0	0	0	0	0	0	0	0	0 (0	0
ID											Des																					
Α	RW	INST									Inst	ruc	tion	n ad	ddre	ess	con	npai	ato	r su	ppo	ort										
			False	0							Sing	gle-s	sho	t in	stru	ucti	on a	add	ress	со	mpa	ariso	ons	not	sup	ро	rtec	١.				
			True	1							Sing	gle-s	sho	t in	stru	ucti	on a	add	ress	со	mpa	ariso	ons	sup	por	ted						
В	RW	DA									Data	a ac	ddre	ess (con	npa	rat	or s	upp	ort												
			False	0							Data	a ac	ddre	ess (con	npa	risc	ns	not	sup	роі	ted										
			True	1							Data	a ac	ddre	ess (con	npa	risc	ns	sup	por	ted											
С	RW	DV									Data	a va	alue	coı	mp	ara	tor	sup	por	t												
			False	0							Data	a va	alue	coı	mp	aris	ons	no	t su	ppc	orte	d.										
			True	1							Data	a va	alue	co	mp	aris	ons	su	оро	rte	d.											
D	RW	PC									Prod	cess	s co	unt	ter	valu	ue c	om	para	tor	sul	ро	rt									
			False	0							Prod	cess	s co	unt	ter	valu	ue c	om	pari	son	s no	ot si	upp	orte	ed.							
			True	1							Prod	cess	s co	unt	ter	valu	ue c	om	pari	son	s sı	ippo	orte	d.								
E	RW	STATUS									Sing	gle-s	sho	t sta	atu	s. T	his	indi	cate	es v	vhe	ther	any	y of	the	se	lect	ed	con	par	ato	rs
											have	e m	natc	hed	d.																	
			NoMatch	0							Mat	tch	has	no	t o	ccui	rrec	l.														
			Match	1							Mat	tch	has	oco	cur	red	at l	eas	t on	ce.												

10.7.4.1.31 TRCSSPCICRO

Address offset: 0x2C0

Selects the processor comparator inputs for Single-shot control.



10.7.4.1.32 TRCPDCR

Address offset: 0x310

Controls the single-shot comparator.

Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID				Δ	A
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	PU			Power up request, to request that power to ETM and access to the trace
					registers is maintained.
			Disabled	0	Power not requested.
			Enabled	1	Power requested.

10.7.4.1.33 TRCPDSR

Address offset: 0x314

Indicates the power down status of the ETM.



Bit nu	umber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					В А
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	POWER			Indicates ETM is powered up
			NotPoweredUp	0	ETM is not powered up. All registers are not accessible.
			PoweredUp	1	ETM is powered up. All registers are accessible.
В	RW	STICKYPD			Sticky power down state.
					This bit is set to 1 when power to the ETM registers is removed, to indicate
					that programming state has been lost. It is cleared after a read of the
					TRCPDSR
			NotPoweredDown	0	Trace register power has not been removed since the TRCPDSR was last
					read.
			PoweredDown	1	Trace register power has been removed since the TRCPDSR was last read.

10.7.4.1.34 TRCITATBIDR

Address offset: 0xEE4

Sets the state of output pins.

Bit nu	mber		31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4	3 2 1 0
ID			G F E	D C B A
Reset	0x000	00000	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0
ID				
A-G	RW	ID[i] (i=06)	Drives the ATIDMI[i] output pin.	

10.7.4.1.35 TRCITIATBINR

Address offset: 0xEF4

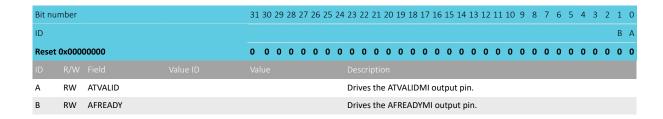
Reads the state of the input pins.

Bit nu	ımber		31 30 29	28 27 2	26 25 :	24 23	22	21 2	0 19	18 17	7 16	15 1	4 13	12 1	1 10	9 8	7	6	5	4 3	2	1	0
ID																						В	Α
Reset	0x000	00000	0 0 0	0 0	0 0	0 0	0	0 0	0	0 0	0	0 0	0	0 (0	0 0	0	0	0	0 (0	0	0
ID																							
Α	RW	ATVALID				Re	turn	s the	e valu	ie of t	he A	TVAL	.IDM	l inp	ut pir	١.							
В	RW	AFREADY				Re	turn	s the	e valu	ie of t	he A	FREA	ADYN	11 inp	ut pi	n.							

10.7.4.1.36 TRCITIATBOUTR

Address offset: 0xEFC

Sets the state of the output pins.



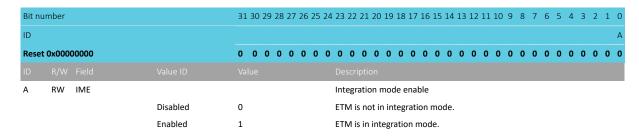




10.7.4.1.37 TRCITCTRL

Address offset: 0xF00

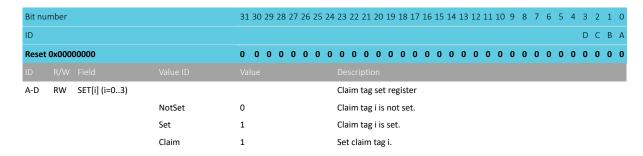
Enables topology detection or integration testing, by putting ETM-M33 into integration mode.



10.7.4.1.38 TRCCLAIMSET

Address offset: 0xFA0

Sets bits in the claim tag and determines the number of claim tag bits implemented.



10.7.4.1.39 TRCCLAIMCLR

Address offset: 0xFA4

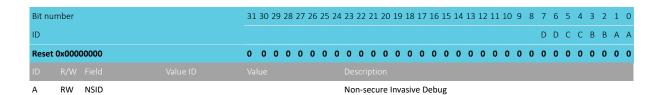
Clears bits in the claim tag and determines the current value of the claim tag.



10.7.4.1.40 TRCAUTHSTATUS

Address offset: 0xFB8

Indicates the current level of tracing permitted by the system





Bit nu	ımber			31	30	29 2	28 :	27 2	6 2	5 2	4 23	3 22	2 2:	1 20	19	18	17	16	15	14 :	13 :	12	11	10	9	8	7	6	5	4	3 2	. 1	. 0
ID																											D	D	С	С	ВВ	Δ	A
Reset	t 0x000	00000		0	0	0 (0	0 (0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0	0	0
			NotImplemented	0							Tł	he f	eat	ure	is n	ot i	mpl	eme	ent	ed.													
			Implemented	1							Tł	he f	eat	ure	is ir	nple	eme	nte	d.														
В	RW	NSNID									N	on-	sec	ure	Nor	ı-In	vasi	ve [Deb	ug													
			NotImplemented	0							Tł	he f	eat	ure	is n	ot i	mpl	em	ent	ed.													
			Implemented	1							Tł	he f	eat	ure	is ir	nple	eme	nte	d.														
С	RW	SID									Se	ecu	re I	nvas	ive	Del	oug																
			NotImplemented	0							Tł	he f	eat	ure	is n	ot i	mpl	eme	ent	ed.													
			Implemented	1							Tł	he f	eat	ure	is ir	nple	eme	nte	d.														
D	RW	SNID									Se	ecu	re N	lon-	Inv	asiv	e D	ebu	g														
			NotImplemented	0							Tł	he f	eat	ure	is n	ot i	mpl	eme	ent	ed.													
			Implemented	1							Tł	he f	eat	ure	is ir	nple	eme	nte	d.														

10.7.4.1.41 TRCDEVARCH

Address offset: 0xFBC

The TRCDEVARCH identifies ETM-M33 as an ETMv4.2 component

Bit nu	ımber			31	30 2	29 28	8 27	26	25	24	23	3 22	2 2:	1 20) 19	9 18	3 17	16	15	14	13	12	11	. 10	9	8	7	6	5	4	3	2	1 0
ID				D	D	D D) D	D	D	D	D	D	D	C	В	В	В	В	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α	Α.	Α,	A A
Reset	0x000	00000		0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 0
ID																																	
Α	R	ARCHID									Ar	chi	tec	ture	e ID)																	
			ETMv42	0x4	A13	;					Со	m	oon	ent	is	an E	TM	v4	con	npc	ne	nt											
В	R	REVISION									Ar	chi	tec	ture	e re	evisi	on																
			v2	2							Со	m	on	ent	is	par	of	arcl	hite	ectu	ıre	4.2											
С	R	PRESENT									Th	nis r	egi	ste	r is	imp	len	en	ted														
			Absent	0							Th	ne r	egi	ster	ris	not	imp	len	ner	ited	d.												
			Present	1							Th	ne r	egi	ster	risi	imp	lem	ent	ed.														
D	R	ARCHITECT									De	efin	es '	the	arc	hite	ect o	of tl	ne (con	npo	ne	nt										
			Arm	0x2	3В						Th	is p	oeri	iphe	eral	l wa	s ar	chit	tect	ted	by	Arı	n.										

10.7.4.1.42 TRCDEVTYPE

Address offset: 0xFCC

Controls the single-shot comparator.

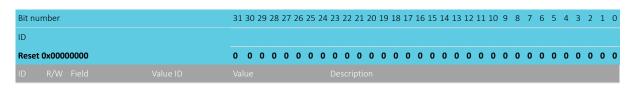
Bit nu	umber			31	30 29	28	27 2	6 25	5 24	23	22	21 2	20 1	9 1	8 17	7 16	15	14	13	12	11 1	0 9	8	7	6	5	4	3 2	2 :	1 0
ID																								В	В	В	В	A A	Α Α	А А
Reset	t 0x000	00000		0	0 0	0	0 (0 0	0	0	0	0	0 (0 0	0	0	0	0	0	0	0	0 0	0	0	0	0	0	0 () (0 0
ID																														
Α	R	MAJOR								The	e ma	ain t	уре	e of	the	con	про	ner	nt											
			TraceSource	3						Per	iph	eral	is a	tra	ce s	our	ce.													
В	R	SUB								The	su	b-ty	ре	of th	ne c	om	oon	ent												
			ProcessorTrace	1						Per	iph	eral	is a	pro	ces	sor	trad	ce s	our	ce.										

10.7.4.1.43 TRCPIDR[n] (n=0..7)

Address offset: $0xFD0 + (n \times 0x4)$

Coresight peripheral identification registers.

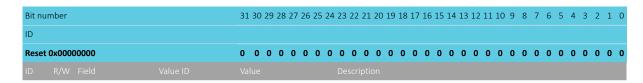
NORDIC*



10.7.4.1.44 TRCCIDR[n] (n=0..3)

Address offset: $0xFF0 + (n \times 0x4)$

Coresight component identification registers.



10.7.5 TPIU — Trace port interface unit

The ARM^{\circledR} $\mathsf{CoreSight}^{\intercal}$ TPIU connects an ATB to an external trace port.

This document only provides a register-level description of this ARM component. See the ARM[®] CoreSight[™] SoC-400 Technical Reference Manual for more details

10.7.5.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
TPIU	0xE0054000	HF	NS	NA	No	TPIU

Register overview

Register	Offset	TZ	Description
SUPPORTEDPORTSIZES	0x000		Each bit location is a single port size that is supported on the device.
CURRENTPORTSIZE	0x004		Each bit location is a single port size. One bit can be set, and indicates the current port size.
SUPPORTEDTRIGGERMODES	0x100		The Supported_trigger_modes register indicates the implemented trigger counter multipliers
			and other supported features of the trigger system.
TRIGGERCOUNTERVALUE	0x104		The Trigger_counter_value register enables delaying the indication of triggers to any external
			connected trace capture or storage devices.
TRIGGERMULTIPLIER	0x108		The Trigger_multiplier register contains the selectors for the trigger counter multiplier.
SUPPPORTEDTESTPATTERNMODES	0x200		The Supported_test_pattern_modes register provides a set of known bit sequences or
			patterns that can be output over the trace port and can be detected by the TPA or other
			associated trace capture device.
CURRENTTESTPATTERNMODES	0x204		Current_test_pattern_mode indicates the current test pattern or mode selected.
TPRCR	0x208		The TPRCR register is an 8-bit counter start value that is decremented. A write sets the initial
			counter value and a read returns the programmed value.
FFSR	0x300		The FFSR register indicates the current status of the formatter and flush features available in
			the TPIU.
FFCR	0x304		The FFCR register controls the generation of stop, trigger, and flush events.
FSCR	0x308		The FSCR register enables the frequency of synchronization information to be optimized to
			suit the Trace Port Analyzer (TPA) capture buffer size.



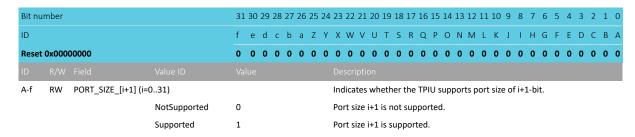
Register	Offset	TZ	Description
EXTCTLINPORT	0x400		Two ports can be used as a control and feedback mechanism for any serializers, pin sharing
			multiplexers, or other solutions that might be added to the trace output pins either for pin
			control or a high-speed trace port solution.
EXTCTLOUTPORT	0x404		Two ports can be used as a control and feedback mechanism for any serializers, pin sharing
			multiplexers, or other solutions that might be added to the trace output pins either for pin
			control or a high speed trace port solution. These ports are raw register banks that sample or
			export the corresponding external pins.
ITTRFLINACK	0xEE4		The ITTRFLINACK register enables control of the triginack and flushinack outputs from the
			TPIU.
ITTRFLIN	0xEE8		The ITTRFLIN register contains the values of the flushin and trigin inputs to the TPIU.
ITATBDATA0	0xEEC		The ITATBDATAO register contains the value of the atdatas inputs to the TPIU. The values are
			valid only when atvalids is HIGH.
ITATBCTR2	0xEF0		Enables control of the atreadys and afvalids outputs of the TPIU.
ITATBCTR1	0xEF4		The ITATBCTR1 register contains the value of the atids input to the TPIU. This is only valid
			when atvalids is HIGH.
ITATBCTR0	0xEF8		The ITATBCTRO register captures the values of the atvalids, afreadys, and atbytess inputs to
			the TPIU. To ensure the integration registers work correctly in a system, the value of atbytess
			is only valid when atvalids, bit[0], is HIGH.
ITCTRL	0xF00		Used to enable topology detection. This register enables the component to switch from a
			functional mode, the default behavior, to integration mode where the inputs and outputs of $% \left\{ \left(1\right) \right\} =\left\{ \left($
			the component can be directly controlled for integration testing and topology solving.
CLAIMSET	0xFA0		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMSET register sets bits in the claim tag, and determines the number of claim bits
			implemented.
CLAIMCLR	0xFA4		Software can use the claim tag to coordinate application and debugger access to trace
			unit functionality. The claim tags have no effect on the operation of the component. The
			CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the
			claim tag.
LAR	0xFB0		This is used to enable write access to device registers.
LSR	0xFB4		This indicates the status of the lock control mechanism. This lock prevents accidental writes
			by code under debug. Accesses to the extended stimulus port registers are not affected by
			the lock mechanism. This register must always be present although there might not be any
			lock access control mechanism. The lock mechanism, where present and locked, must block
			write accesses to any control register, except the Lock Access Register. For most components
			this covers all registers except for the Lock Access Register.
AUTHSTATUS	0xFB8		Indicates the current level of tracing permitted by the system
DEVID	0xFC8		Indicates the capabilities of the component.
DEVTYPE	0xFCC		The DEVTYPE register provides a debugger with information about the component when the
			Part Number field is not recognized. The debugger can then report this information.
PIDR4	0xFD0		Coresight peripheral identification registers.
PIDR[0]	0xFE0		Coresight peripheral identification registers.
PIDR[1]	0xFE4		Coresight peripheral identification registers.
PIDR[2]	0xFE8		Coresight peripheral identification registers.
PIDR[3]	0xFEC		Coresight peripheral identification registers.
CIDR[0]	0xFF0		Coresight component identification registers.
CIDR[1]	0xFF4		Coresight component identification registers.
CIDR[2]	0xFF8		Coresight component identification registers.

10.7.5.1.1 SUPPORTEDPORTSIZES

Address offset: 0x000



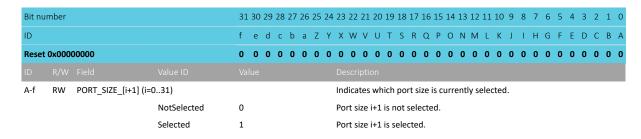
Each bit location is a single port size that is supported on the device.



10.7.5.1.2 CURRENTPORTSIZE

Address offset: 0x004

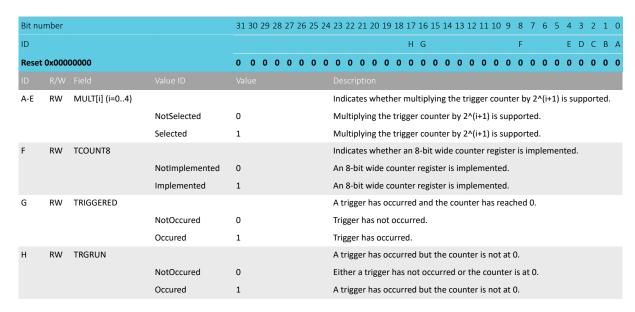
Each bit location is a single port size. One bit can be set, and indicates the current port size.



10.7.5.1.3 SUPPORTEDTRIGGERMODES

Address offset: 0x100

The Supported_trigger_modes register indicates the implemented trigger counter multipliers and other supported features of the trigger system.

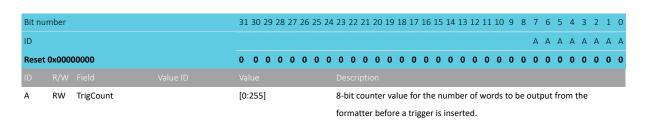


10.7.5.1.4 TRIGGERCOUNTERVALUE

Address offset: 0x104

The Trigger_counter_value register enables delaying the indication of triggers to any external connected trace capture or storage devices.

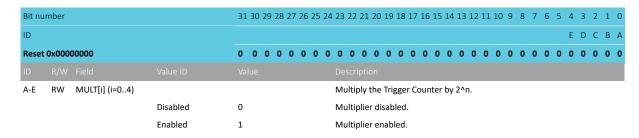




10.7.5.1.5 TRIGGERMULTIPLIER

Address offset: 0x108

The Trigger_multiplier register contains the selectors for the trigger counter multiplier.



10.7.5.1.6 SUPPPORTEDTESTPATTERNMODES

Address offset: 0x200

The Supported_test_pattern_modes register provides a set of known bit sequences or patterns that can be output over the trace port and can be detected by the TPA or other associated trace capture device.

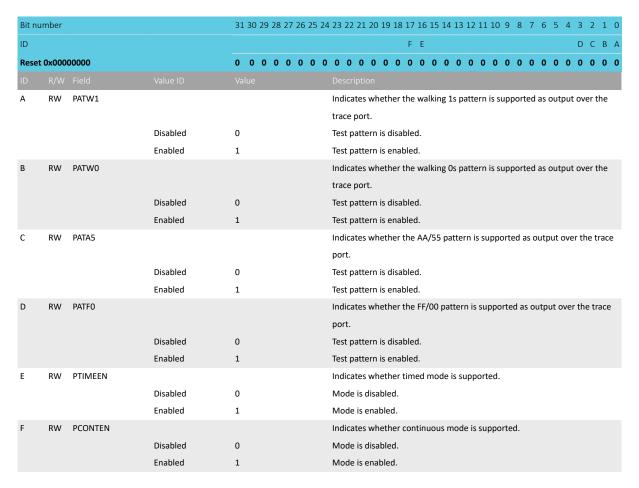
Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C B A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	RW	PATW1			Indicates whether the walking 1s pattern is supported as output over the
					trace port.
			NotSupported	0	Test pattern is not supported.
			Supported	1	Test pattern is supported.
В	RW	PATW0			Indicates whether the walking 0s pattern is supported as output over the
					trace port.
			NotSupported	0	Test pattern is not supported.
			Supported	1	Test pattern is supported.
С	RW	PATA5			Indicates whether the AA/55 pattern is supported as output over the trace
					port.
			NotSupported	0	Test pattern is not supported.
			Supported	1	Test pattern is supported.
D	RW	PATF0			Indicates whether the FF/00 pattern is supported as output over the trace
					port.
			NotSupported	0	Test pattern is not supported.
			Supported	1	Test pattern is supported.
Е	RW	PTIMEEN			Indicates whether timed mode is supported.
			NotSupported	0	Mode is not supported.
			Supported	1	Mode is supported.
F	RW	PCONTEN			Indicates whether continuous mode is supported.
			NotSupported	0	Mode is not supported.
			Supported	1	Mode is supported.



10.7.5.1.7 CURRENTTESTPATTERNMODES

Address offset: 0x204

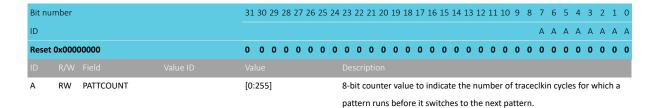
Current_test_pattern_mode indicates the current test pattern or mode selected.



10.7.5.1.8 TPRCR

Address offset: 0x208

The TPRCR register is an 8-bit counter start value that is decremented. A write sets the initial counter value and a read returns the programmed value.



10.7.5.1.9 FFSR

Address offset: 0x300

The FFSR register indicates the current status of the formatter and flush features available in the TPIU.



Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	FLINPROG			Flush in progress.
			NotInProgress	0	A flush is not in progress.
			InProgress	1	A flush is in progress.
В	RW	FTSTOPPED			The formatter has received a stop request signal and all trace data and post-
					amble is sent. Any additional trace data on the ATB interface is ignored and
					atreadys goes HIGH.
			Running	0	Formatter has not stopped.
			Stopped	1	Formatter has stopped.
С	RW	TCPRESENT			Indicates whether the TRACECTL pin is available for use.
			NotPresent	0	TRACECTL pin is not present.
			Present	1	TRACECTL pin is present.

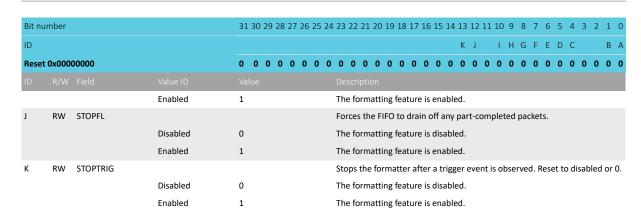
10.7.5.1.10 FFCR

Address offset: 0x304

The FFCR register controls the generation of stop, trigger, and flush events.

Bit nu	umber			31	30	29 2	28 2	7 26	5 25	24	23 2	22	21 2	20	19	18	17	16	15	14	13	3 1:	2 1	1 10	0 9	8	7	6	5	4	3	2	1	0
ID																					K	J		- 1	H	ı	F	Ε	D	С			В	Α
Reset	t 0x000	00000		0	0	0	0 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0) (0) (0	0	0	0	0	0	0	0	0
ID																																		
Α	RW	ENFTC									Doı	no	t em	be	d tr	igg	ers	in	to 1	the	foi	ma	itte	d st	trea	ım.	Tra	ce c	lisa	ble	cyc	es a	and	Π
											trigg	gei	rs are	e iı	ndic	ate	ed	by t	ra	ec	tl, v	whe	ere	pre	ser	ıt.								
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttiı	ng f	eat	ure	e is	en	abl	ed.													
В	RW	ENFCONT									ls ei	mb	bedd	led	in t	rig	ge	r pa	ick	ets	an	d ir	ndic	ate	s tl	nat	no (ycl	e is	usir	ng s	ync		
											pac	ket	ts.																					
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttir	ng f	eat	ure	e is	en	abl	ed.													
С	RW	FONFLIN									Ena	ble	es th	e ı	ıse	of t	the	flu	sh	in c	on	nec	tio	n.										
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttir	ng f	eat	ure	e is	en	abl	ed.													
D	RW	FONTRIG									Initi	iat	es a	ma	anua	al fl	lus	h o	f d	ata	in	the	sy	ster	n v	he	ı a i	rig	ger	eve	nt c	ccu	ırs.	
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttir	ng f	eat	ure	e is	en	abl	ed.													
E	RW	FONMANR									Gen	ner	ates	a t	flus	h. T	ſhi:	s bi	t is	se	to	0 1	wh	en t	his	flu	sh is	se	rvic	ed.				
			Disabled	0							The	e fo	rma	ttiı	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttir	ng f	eat	ure	e is	en	abl	ed.													
F	RW	FONMANW									Gen	ner	ates	a t	flusl	h. T	ſhi:	s bi	t is	se	to	1 ۱	wh	en t	his	flu	sh is	se	rvic	ed.				
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttiı	ng f	eat	ure	e is	en	abl	ed.													
G	RW	TRIGIN									Indi	ica	tes a	tr	igge	er v	vh	en t	rig	in i	s a	sse	rte	d.										
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	orma	ttir	ng f	eat	ure	e is	en	abl	ed.													
Н	RW	TRIGEVT									Indi	ica	tes a	tr	igge	er c	n a	a tr	igg	er	eve	nt.												
			Disabled	0							The	fo	rma	ttir	ng f	eat	ure	e is	dis	ab	ed													
			Enabled	1							The	fo	rma	ttir	ng f	eat	ure	e is	en	abl	ed.													
1	RW	TRIGFL									Indi	ica	tes a	tr	igge	er v	vh	en f	lus	h c	om	ple	tio	n o	n a	frea	dys	is r	etu	rne	d.			
			Disabled	0							The	fo	orma	ttir	ng f	eat	ure	e is	dis	ab	ed													

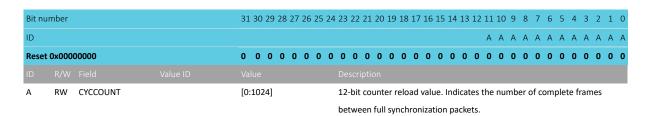




10.7.5.1.11 FSCR

Address offset: 0x308

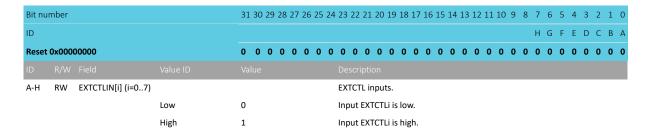
The FSCR register enables the frequency of synchronization information to be optimized to suit the Trace Port Analyzer (TPA) capture buffer size.



10.7.5.1.12 EXTCTLINPORT

Address offset: 0x400

Two ports can be used as a control and feedback mechanism for any serializers, pin sharing multiplexers, or other solutions that might be added to the trace output pins either for pin control or a high-speed trace port solution.

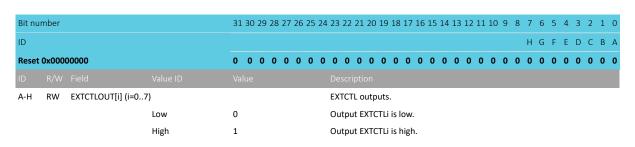


10.7.5.1.13 EXTCTLOUTPORT

Address offset: 0x404

Two ports can be used as a control and feedback mechanism for any serializers, pin sharing multiplexers, or other solutions that might be added to the trace output pins either for pin control or a high speed trace port solution. These ports are raw register banks that sample or export the corresponding external pins.

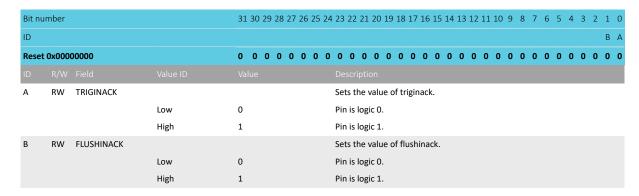




10.7.5.1.14 ITTRFLINACK

Address offset: 0xEE4

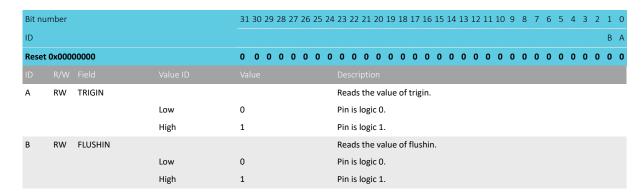
The ITTRFLINACK register enables control of the triginack and flushinack outputs from the TPIU.



10.7.5.1.15 ITTRFLIN

Address offset: 0xEE8

The ITTRFLIN register contains the values of the flushin and trigin inputs to the TPIU.

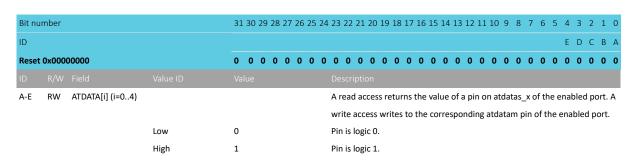


10.7.5.1.16 ITATBDATA0

Address offset: 0xEEC

The ITATBDATAO register contains the value of the atdatas inputs to the TPIU. The values are valid only when atvalids is HIGH.

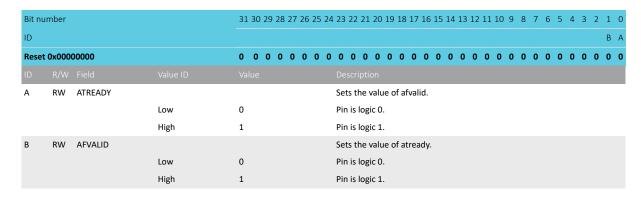




10.7.5.1.17 ITATBCTR2

Address offset: 0xEF0

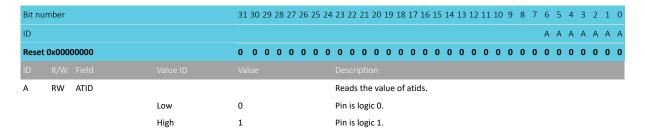
Enables control of the atreadys and afvalids outputs of the TPIU.



10.7.5.1.18 ITATBCTR1

Address offset: 0xEF4

The ITATBCTR1 register contains the value of the atids input to the TPIU. This is only valid when atvalids is HIGH.



10.7.5.1.19 ITATBCTR0

Address offset: 0xEF8

The ITATBCTRO register captures the values of the atvalids, afreadys, and atbytess inputs to the TPIU. To ensure the integration registers work correctly in a system, the value of atbytess is only valid when atvalids, bit[0], is HIGH.



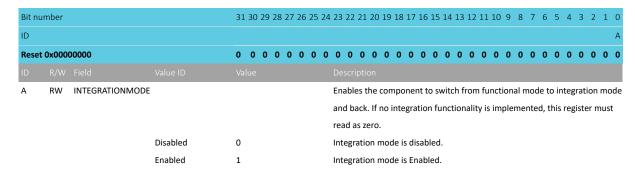
Bit n	umber			31 30 29 28	27 26 2	5 24	23 2	2 21 2	20 19	18	17 1	16 1	5 14	13	12	11 1	.0 9	8	7	6	5	4	3	2	1 0
ID																	(C C						В	Α
Rese	t 0x000	00000		0 0 0 0	0 0 0	0	0 0	0	0 0	0	0	0 (0	0	0	0	0 (0	0	0	0	0	0	0 (0 0
ID																									
Α	RW	ATVALID					Read	ls the	valu	e of	atva	lids.													
			Low	0			Pin is	logic	0.																
			High	1			Pin is	logic	1.																
В	RW	AFREADY					Read	ls the	valu	e of	afre	adys	5.												
			Low	0			Pin is	logic	0.																
			High	1			Pin is	logic	1.																
С	RW	ATBYTES					Read	ls the	valu	e of	atby	tess	i.												
			Low	0			Pin is	logic	0.																
			High	1			Pin is	logic	1.																

10.7.5.1.20 ITCTRL

Address offset: 0xF00

Used to enable topology detection. This register enables the component to switch from a functional mode, the default behavior, to integration mode where the inputs and outputs of the component can be directly controlled for integration testing and topology solving.

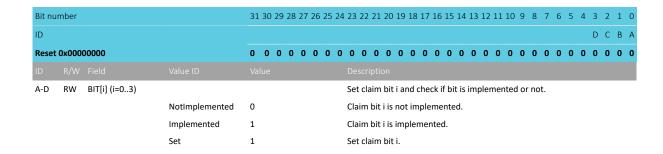
Note: When a device has been in integration mode, it might not function with the original behavior. After performing integration or topology detection, you must reset the system to ensure correct behavior of CoreSight and other connected system components that are affected by the integration or topology detection.



10.7.5.1.21 CLAIMSET

Address offset: 0xFA0

Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMSET register sets bits in the claim tag, and determines the number of claim bits implemented.



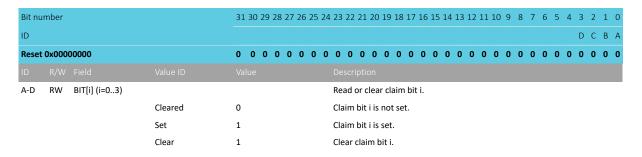




10.7.5.1.22 CLAIMCLR

Address offset: 0xFA4

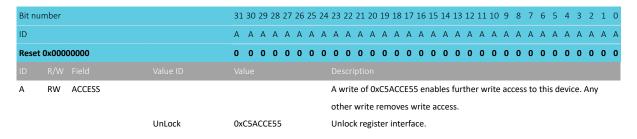
Software can use the claim tag to coordinate application and debugger access to trace unit functionality. The claim tags have no effect on the operation of the component. The CLAIMCLR register sets the bits in the claim tag to 0 and determines the current value of the claim tag.



10.7.5.1.23 LAR

Address offset: 0xFB0

This is used to enable write access to device registers.



10.7.5.1.24 LSR

Address offset: 0xFB4

This indicates the status of the lock control mechanism. This lock prevents accidental writes by code under debug. Accesses to the extended stimulus port registers are not affected by the lock mechanism. This register must always be present although there might not be any lock access control mechanism. The lock mechanism, where present and locked, must block write accesses to any control register, except the Lock Access Register. For most components this covers all registers except for the Lock Access Register.



Bit nu	umber			31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					СВА
Reset	t 0x000	00000		0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
Α	RW	PRESENT			Indicates that a lock control mechanism exists for this device.
			NotImplemented	0	No lock control mechanism exists, writes to the Lock Access Register are
					ignored.
			Implemented	1	Lock control mechanism is present.
В	RW	LOCKED			Returns the current status of the Lock.
			UnLocked	0	Write access is allowed to this device.
			Locked	1	Write access to the component is blocked. All writes to control registers are
					ignored. Reads are permitted.
С	RW	TYPE			Indicates if the Lock Access Register is implemented as 8-bit or 32-bit.
			Bits32	0	This component implements a 32-bit Lock Access Register.
			Bits8	1	This component implements an 8-bit Lock Access Register.

10.7.5.1.25 AUTHSTATUS

Address offset: 0xFB8

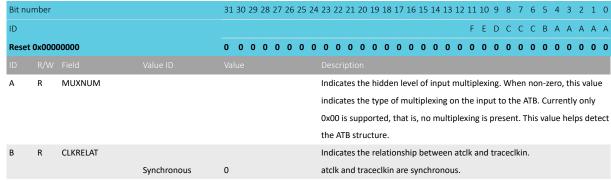
Indicates the current level of tracing permitted by the system



10.7.5.1.26 DEVID

Address offset: 0xFC8

Indicates the capabilities of the component.





D.11	-			24 20 20 20 27 26 25 2	4 22 22 24 20 40 47 47 47 47 42 42 44 40 0 0 7 6 5 4 2 2 4 0
BIT NU	ımber			31 30 29 28 27 26 25 24	4 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					F E D C C C B A A A A
Reset	0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					Description
			ASynchronous	1	atclk and traceclkin are asynchronous.
С	R	FIFOSIZE			FIFO size in powers of 2.
			Entries4	2	FIFO size of 4 entries, that is, 16 bytes.
D	R	TCLKDATA			Indicates whether trace clock plus data is supported.
			Supported	0	Trace clock and data is supported.
			NotSupported	1	Trace clock and data is not supported.
E	R	SWOMAN			Indicates whether Serial Wire Output, Manchester encoded format, is
					supported.
			NotSupported	0	Serial Wire Output, Manchester encoded format, is not supported.
			Supported	1	Serial Wire Output, Manchester encoded format, is supported.
F	R	SWOUARTNRZ			Indicates whether Serial Wire Output, UART or NRZ, is supported.
			NotSupported	0	Serial Wire Output, UART or NRZ, is not supported.
			Supported	1	Serial Wire Output, UART or NRZ, is supported.

10.7.5.1.27 DEVTYPE

Address offset: 0xFCC

The DEVTYPE register provides a debugger with information about the component when the Part Number field is not recognized. The debugger can then report this information.

Bit nu	ımber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID					B B B A A A A
Rese	t 0x000	00000		0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID					
Α	R	MAJOR			The main type of the component
			TraceSource	1	Peripheral is a trace sink.
В	R	SUB			The sub-type of the component
			TracePort	1	Indicates that this component is a trace port component.

10.7.5.1.28 PIDR4

Address offset: 0xFD0

Coresight peripheral identification registers.

Bit num	ber		31 30 29 28 27 26 2	5 24	23 22	2 21 2	0 19 1	.8 17 :	16 15	14 13	3 12 1	1 10 9	9 8	7	6	5 4	3	2 1	. 0
ID																			
Reset 0	x00000000		0 0 0 0 0 0	0	0 0	0 (0 0	0 0	0 0	0 0	0 (0 (0 0	0	0	0 0	0	0 0	0
ID	R/W Field	Value ID	Value		Desci	iptior	n												

10.7.5.1.29 PIDR[0]

Address offset: 0xFE0

Coresight peripheral identification registers.

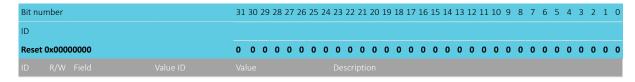
Bit number	31 30 29 28 27 26	25 24 23 22 21 20 19 18 1	7 16 15 14 13 12 11	10 9 8 7	6 5	4 3 2	1 0
ID							
Reset 0x00000000	0 0 0 0 0 0	0 0 0 0 0 0 0 0 0	000000	0 0 0 0	0 0	0 0 0	0 0



10.7.5.1.30 PIDR[1]

Address offset: 0xFE4

Coresight peripheral identification registers.



10.7.5.1.31 PIDR[2]

Address offset: 0xFE8

Coresight peripheral identification registers.

Bit number	31 30 29 28 27 26 25 2	24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		
Reset 0x00000000	0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID	Value	Description

10.7.5.1.32 PIDR[3]

Address offset: 0xFEC

Coresight peripheral identification registers.

Bit number	31 30 29 28 27 26 25 24 23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID	
Reset 0x00000000	0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID	Value Description

10.7.5.1.33 CIDR[0]

Address offset: 0xFF0

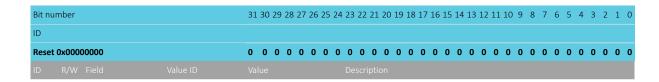
Coresight component identification registers.

Bit number	31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0
ID		
Reset 0x00000000	0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
ID R/W Field Value ID	Value	Description

10.7.5.1.34 CIDR[1]

Address offset: 0xFF4

Coresight component identification registers.



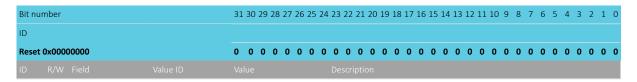




10.7.5.1.35 CIDR[2]

Address offset: 0xFF8

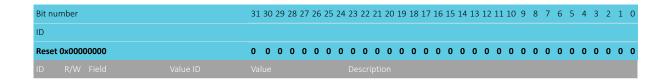
Coresight component identification registers.



10.7.5.1.36 CIDR[3]

Address offset: 0xFFC

Coresight component identification registers.



10.8 CTRL-AP - Control access port

The control access port (CTRL-AP) is a custom access port that enables control of the device when other debug access ports (DAP) have been disabled by the access port protection.

For an overview of the other debug access ports, see DAP - Debug access port on page 368.

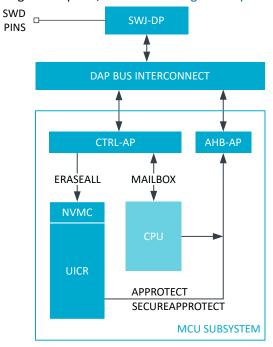


Figure 118: Control access port details

Access port protection (APPROTECT) blocks the debugger access to the AHB-AP, and prevents read and write access to all CPU registers and memory-mapped addresses. To enable port protection access for both secure and non-secure modes, use the registers SECUREAPPROTECT on page 41 and APPROTECT on



page 40 respectively. The debugger can use the register APPROTECT.STATUS on page 441 to read the status of secure and non-secure access port protection.

CTRL-AP has the following features:

- Soft reset
- Erase all
- · Mailbox interface
- Debug of protected devices

10.8.1 Reset request

The debugger can request the device to perform a soft reset.

Use the register RESET on page 440 to request a soft reset. Once the soft reset is performed, the reset reason is accessible on the on-chip firmware through the RESETREAS register. For more information about the soft reset, see Reset on page 56.

10.8.2 Erase all

The erase all function lets the debugger trigger an erase of flash, user information configuration registers (UICR), RAM, all peripheral settings, and also removes the access port protection.

To trigger an erase all function, the debugger writes to the register ERASEALL on page 440. The register ERASEALLSTATUS on page 440 will read as busy for the duration of the operation. After the next reset, the access port protection is removed.

If the debugger performs an erase all function on a slave MCU, the erase sequence will always erase the application MCU first, independently of how the application is protected, before erasing the slave MCU.

Erase all protection

It is possible to prevent the debugger from performing an erase all operation by writing to the UICR.ERASEPROTECT register. Once the register is configured and the device is reset, the CTRL-AP ERASEALL operation is disabled, and all flash write and erase operations are restricted to the firmware. In addition, it is still possible to write/erase from the debugger as long as the UICR.APPROTECT register is not set.

Note: Setting the UICR.ERASEPROTECT register only affects the erase all operation and not the debugger access.

The register ERASEPROTECT.STATUS on page 441 holds the status for erase protection.

10.8.3 Mailbox interface

CTRL-AP implements a mailbox interface which enables the CPU to communicate with a debugger over the SWD interface.

The mailbox interface consists of a transmit register MAILBOX.TXDATA on page 442 with its corresponding status register MAILBOX.TXSTATUS on page 442, and a receive register MAILBOX.RXDATA on page 442 with its corresponding status register MAILBOX.RXSTATUS on page 442. Status bits in the TXSTATUS/RXSTATUS registers are set and cleared automatically when the TXDATA/RXDATA registers are written to and read from, independently of the direction.



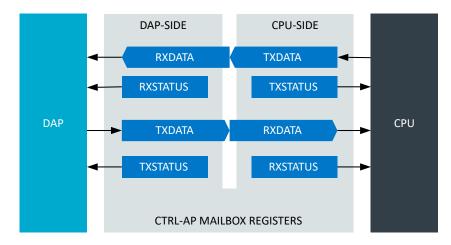


Figure 119: Mailbox register interface

Mailbox transfer sequence

- 1. Sender writes TXDATA.
- 2. Hardware sets sender's TXSTATUS to DataPending.
- 3. Hardware sets receiver's RXSTATUS to DataPending.
- 4. Receiver reads RXDATA.
- 5. Hardware sets receiver's RXSTATUS to NoDataPending.
- 6. Hardware sets sender's TXSTATUS to NoDataPending.

10.8.4 Disabling erase protection

The erase protection mechanism can be disabled to return a device to factory default settings on next reset.

The debugger can read the erase protection status in the register ERASEPROTECT.STATUS on page 441.

If ERASEPROTECT has been enabled, both the debugger and on-chip firmware must write the same non-zero 32-bit KEY value into their respective ERASEPROTECT.DISABLE registers to disable the erase protection. When both registers have been written with the same non-zero 32-bit KEY value, the device is automatically erased as described in Erase all on page 438. The access ports will be re-enabled on the next reset once the secure erase sequence has completed.

The write-once register ERASEPROTECT.LOCK on page 444 should be set to *Locked* as early as possible in the start-up sequence, preferably as soon as the on-chip firmware has determined it does not need to communicate with a debugger over the CTRL-AP mailbox interface. Once written, it will not be possible to remove the erase protection until the next reset.

10.8.5 Debugger registers

CTRL-AP has a set of registers that can only be accessed from the debugger over the SWD interface. These are not accessible from the CPU.

10.8.5.1 Debugger registers

Register overview

Register O	Offset	Description
RESET 0:	000x	System reset request
ERASEALL 0:)x004	Perform a secure erase of the device, where flash, SRAM and UICR will be erased in sequence. The
		device will be returned to factory default settings upon next reset.

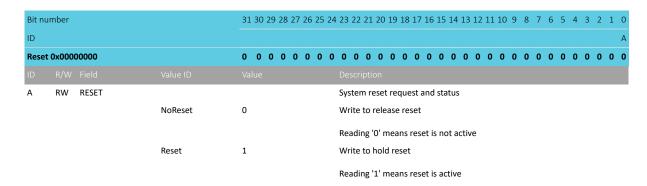


Register	Offset	Description
ERASEALLSTATUS	0x008	This is the status register for the ERASEALL operation.
APPROTECT.STATUS	0x00C	This is the status register for the UICR access port protection.
ERASEPROTECT.STATUS	0x018	This is the status register for the UICR ERASEPROTECT configuration.
ERASEPROTECT.DISABLE	0x01C	This register disables ERASEPROTECT and performs ERASEALL.
MAILBOX.TXDATA	0x020	Data sent from the debugger to the CPU.
MAILBOX.TXSTATUS	0x024	This register shows a status that indicates if data sent from the debugger to the CPU has been read.
MAILBOX.RXDATA	0x028	Data sent from the CPU to the debugger.
MAILBOX.RXSTATUS	0x02C	This register shows a status that indicates if data sent from the CPU to the debugger has been read.
IDR	0x0FC	CTRL-AP Identification Register, IDR

10.8.5.1.1 RESET

Address offset: 0x000 System reset request

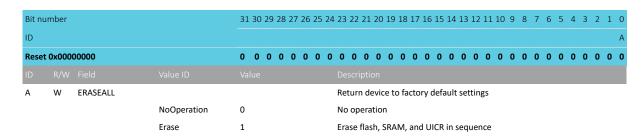
This register is automatically deactivated during an ERASEALL operation.



10.8.5.1.2 ERASEALL

Address offset: 0x004

Perform a secure erase of the device, where flash, SRAM and UICR will be erased in sequence. The device will be returned to factory default settings upon next reset.

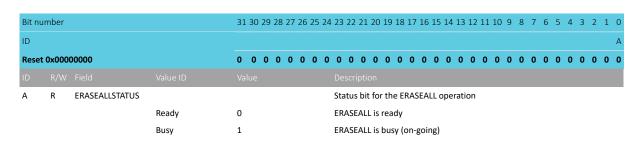


10.8.5.1.3 ERASEALLSTATUS

Address offset: 0x008

This is the status register for the ERASEALL operation.

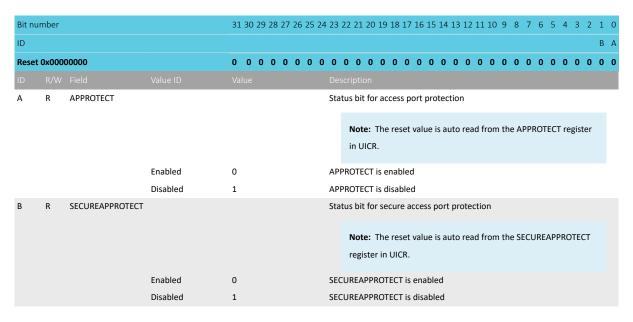




10.8.5.1.4 APPROTECT.STATUS

Address offset: 0x00C

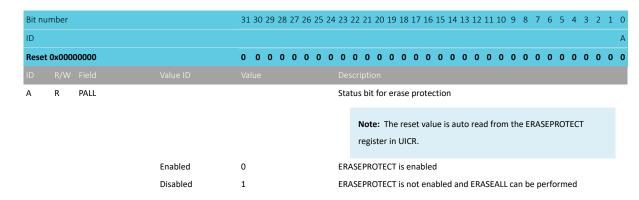
This is the status register for the UICR access port protection.



10.8.5.1.5 ERASEPROTECT.STATUS

Address offset: 0x018

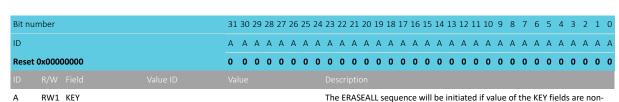
This is the status register for the UICR ERASEPROTECT configuration.



10.8.5.1.6 ERASEPROTECT.DISABLE

Address offset: 0x01C

This register disables ERASEPROTECT and performs ERASEALL.



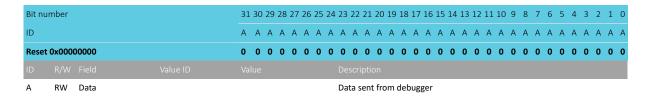
zero and the KEY fields match on both the CPU and debugger sides.

10.8.5.1.7 MAILBOX.TXDATA

Address offset: 0x020

Data sent from the debugger to the CPU.

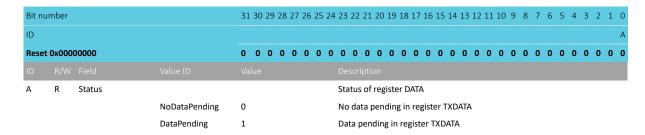
Writing to this register will automatically set a DataPending value in the TXSTATUS register.



10.8.5.1.8 MAILBOX.TXSTATUS

Address offset: 0x024

This register shows a status that indicates if data sent from the debugger to the CPU has been read.

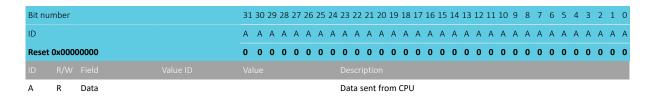


10.8.5.1.9 MAILBOX.RXDATA

Address offset: 0x028

Data sent from the CPU to the debugger.

Reading from this register will automatically set a NoDataPending value in the RXSTATUS register.

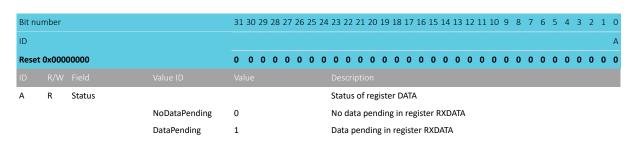


10.8.5.1.10 MAILBOX.RXSTATUS

Address offset: 0x02C

This register shows a status that indicates if data sent from the CPU to the debugger has been read.





10.8.5.1.11 IDR

Address offset: 0x0FC

CTRL-AP Identification Register, IDR

Bit nu	mber			31	30	29	28	27	26	25	24	23	3 22	2 2:	1 20) 19	9 18	8 1 ⁻	7 1	6 1	15	14	13	12	11	. 10	9	8	7	6	5	4	3	2	1	0
ID				Е	Ε	Е	Ε	D	D	D	D	С	. c	C	С	С	C	: C	C 6	3	В	В	В						Α	Α	Α	Α	Α	Α	Α	Α
Reset	0x128	80000		0	0	0	1	0	0	1	0	1	. 0	0	0	1	. 0	0) ()	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ID																																				
Α	R	APID										ΑF	P Id	ent	ific	atic	n																			
В	R	CLASS										Ac	cces	ss P	ort	(AF	P) c	las	S																	
			NotDefined	0x	0							No	o de	efin	ed	cla	SS																			
			MEMAP	0x	8							M	lem	ory	/ Ac	ces	s P	ort																		
С	R	JEP106ID										JE	DE	C JE	P10	06 i	dei	ntit	у с	ode	e															
D	R	JEP106CONT										JE	DE	C JE	P10)6 c	con	tinı	uat	ion	c	ode	9													
E	R	REVISION										Re	evis	ion																						

10.8.6 Registers

Instances

Instance	Base address	TrustZone	ustZone			Description					
		Мар	Att	DMA							
CTRL_AP_PERI	0x50006000	HF	S	NA	No	CTRL-AP-PERI					

Register overview

Register	Offset	TZ	Description
MAILBOX.RXDATA	0x400		Data sent from the debugger to the CPU.
MAILBOX.RXSTATUS	0x404		This register shows a status that indicates if data sent from the debugger to the CPU has been $$
			read.
MAILBOX.TXDATA	0x480		Data sent from the CPU to the debugger.
MAILBOX.TXSTATUS	0x484		This register shows a status that indicates if the data sent from the CPU to the debugger has
			been read.
ERASEPROTECT.LOCK	0x500		This register locks the ERASEPROTECT.DISABLE register from being written until next reset.
ERASEPROTECT.DISABLE	0x504		This register disables the ERASEPROTECT register and performs an ERASEALL operation.

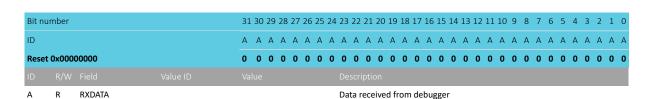
10.8.6.1 MAILBOX.RXDATA

Address offset: 0x400

Data sent from the debugger to the CPU.

Reading from this register will automatically set a NoDataPending value in the RXSTATUS register.

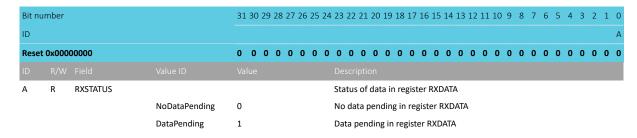
4510_057 v1.0 443 NORDI



10.8.6.2 MAILBOX.RXSTATUS

Address offset: 0x404

This register shows a status that indicates if data sent from the debugger to the CPU has been read.

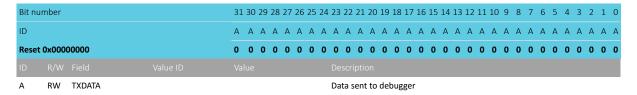


10.8.6.3 MAILBOX.TXDATA

Address offset: 0x480

Data sent from the CPU to the debugger.

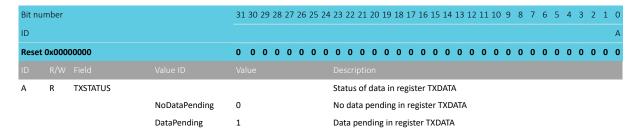
Writing to this register will automatically set a DataPending value in the TXSTATUS register.



10.8.6.4 MAILBOX.TXSTATUS

Address offset: 0x484

This register shows a status that indicates if the data sent from the CPU to the debugger has been read.

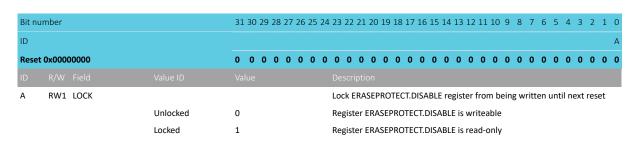


10.8.6.5 ERASEPROTECT.LOCK

Address offset: 0x500

This register locks the ERASEPROTECT.DISABLE register from being written until next reset.

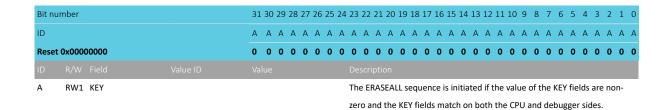




10.8.6.6 ERASEPROTECT.DISABLE

Address offset: 0x504

This register disables the ERASEPROTECT register and performs an ERASEALL operation.



10.9 TAD - Trace and debug control

Configuration interface for trace and debug

Please refer to the Trace section for more information about how to configure the trace and debug interface.

Note: Although there are PSEL registers for the trace port, each function can only be mapped to a single pin due to pin speed requirements. Setting the PIN field to anything else will not have any effect. See Pin assignment chapter for more information

10.9.1 Registers

Instances

Instance	Base address	TrustZone			Split access	Description
		Мар	Att	DMA		
TAD	0xE0080000	HF	S	NA	No	Trace and debug control



Register overview

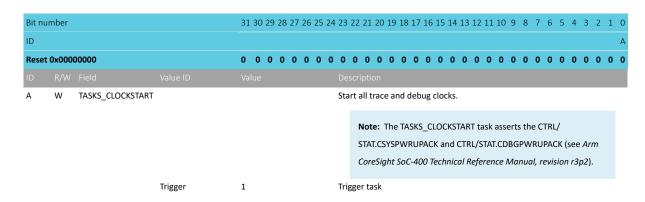
Register	Offset	TZ	Description
TASKS_CLOCKSTART	0x000		Start all trace and debug clocks.
TASKS_CLOCKSTOP	0x004		Stop all trace and debug clocks.
ENABLE	0x500		Enable debug domain and aquire selected GPIOs
PSEL.TRACECLK	0x504		Pin configuration for TRACECLK
PSEL.TRACEDATA0	0x508		Pin configuration for TRACEDATA[0]
PSEL.TRACEDATA1	0x50C		Pin configuration for TRACEDATA[1]
PSEL.TRACEDATA2	0x510		Pin configuration for TRACEDATA[2]
PSEL.TRACEDATA3	0x514		Pin configuration for TRACEDATA[3]
TRACEPORTSPEED	0x518		Clocking options for the Trace Port debug interface
			Reset behavior is the same as debug components
			This register is retained.

10.9.1.1 TASKS CLOCKSTART

Address offset: 0x000

Start all trace and debug clocks.

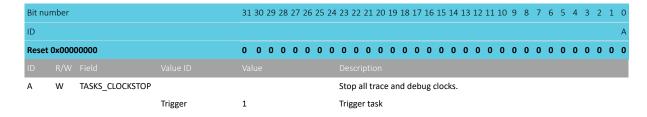
Note: The TASKS_CLOCKSTART task asserts the CTRL/STAT.CSYSPWRUPACK and CTRL/STAT.CDBGPWRUPACK (see *Arm CoreSight SoC-400 Technical Reference Manual, revision r3p2*).



10.9.1.2 TASKS CLOCKSTOP

Address offset: 0x004

Stop all trace and debug clocks.

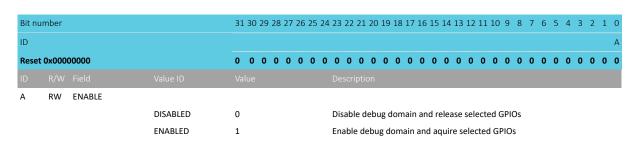


10.9.1.3 ENABLE

Address offset: 0x500

Enable debug domain and aquire selected GPIOs

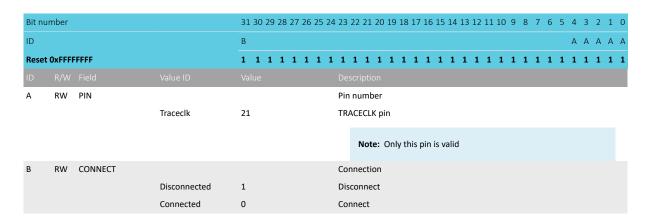




10.9.1.4 PSEL.TRACECLK

Address offset: 0x504

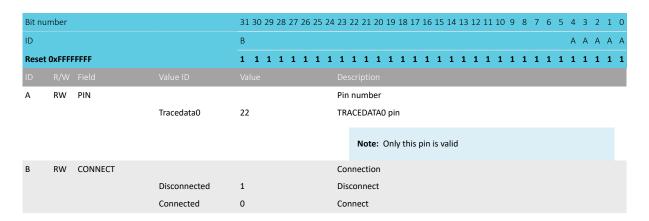
Pin configuration for TRACECLK



10.9.1.5 PSEL.TRACEDATAO

Address offset: 0x508

Pin configuration for TRACEDATA[0]

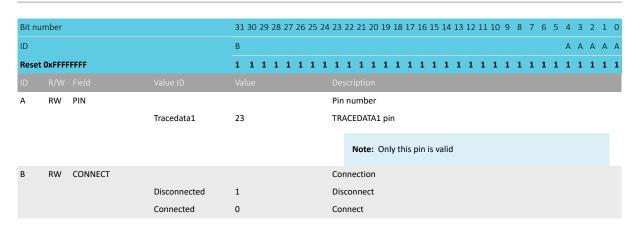


10.9.1.6 PSEL.TRACEDATA1

Address offset: 0x50C

Pin configuration for TRACEDATA[1]

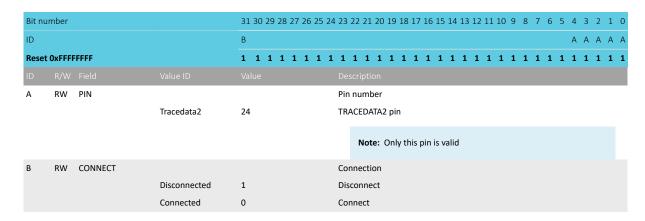




10.9.1.7 PSEL.TRACEDATA2

Address offset: 0x510

Pin configuration for TRACEDATA[2]



10.9.1.8 PSEL.TRACEDATA3

Address offset: 0x514

Pin configuration for TRACEDATA[3]

Bit nu	umber			31 30 29 28 27 26 25 24	23 22 21 20 19 18 17 16 15 14 13 12 11 10 9 8 7 6 5 4 3 2 1
ID				В	АААА
Reset	t OxFFFI	FFFF		1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
ID					
Α	RW	PIN			Pin number
			Tracedata3	25	TRACEDATA3 pin
					Note: Only this pin is valid
В	RW	CONNECT			Connection
			Disconnected	1	Disconnect
			Connected	0	Connect

10.9.1.9 TRACEPORTSPEED (Retained)

Address offset: 0x518

Clocking options for the Trace Port debug interface Reset behavior is the same as debug components





This register is retained.

Bit no	umber			31 30 29 28 2	27 26 25 24	23 22 2	21 20 19	9 18 17	16 15	14 1	3 12 1	1 10	9	8	7	6 !	5 4	3	2	1	0
ID																				Α	Α
Rese	t 0x000	00000		0 0 0 0	0 0 0 0	0 0 0	0 0 0	0 0	0 0	0 0	0	0 0	0	0	0	0 (0 0	0	0	0	0
ID																					
Α	RW	TRACEPORTSPEED				Speed o	of Trace	Port cl	ock. N	ote th	at the	TRA	ACEC	CLK p	oin o	outp	ut v	vill b	e di	ivid	ed
						again b	y two fr	om the	e Trace	Port	lock.										
			32MHz	0		Trace Po	ort cloc	k is:													
						32MHz															
			16MHz	1		Trace Po	ort cloc	k is:													
						16MHz															
			8MHz	2		Trace Po	ort cloc	k is:													
						8MHz															
			4MHz	3		Trace Po	ort cloc	k is:													
						4MHz															



11 Hardware and layout

The following sections describe nRF9161 hardware and layout specifications.

11.1 Pin assignments

This section describes the pin assignment and the pin functions of the nRF9161.

The device provides flexibility when it comes to routing and configuration of the GPIO pins. However, for some pins there are recommendations on pin usage and configuration. See following table for more information about this.

11.1.1 LGA pin assignments

The pin assignment table and figure describe the assignments.

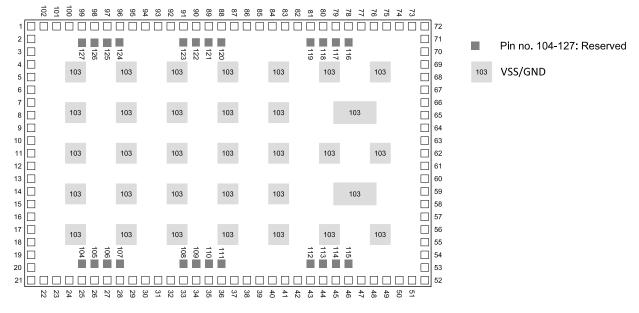


Figure 120: LGA pin assignments, top view

Pin no	Pin name	Function	Description
1	GND	Power	Ground
2	P0.05	Digital I/O (SoC)	General purpose I/O
3	P0.06	Digital I/O (SoC)	General purpose I/O
4	P0.07	Digital I/O (SoC)	General purpose I/O
5	GND	Power	Ground
6	GND	Power	Ground
7	GND	Power	Ground
8	GND	Power	Ground
9	GND	Power	Ground
10	RES		Do not connect/reserved for future use
11	GND	Power	Ground
12	VDD_GPIO	Power	GPIO power supply input and logic level
13	DEC0	Power	Power supply decoupling. Reserved for Nordic use.
14	GND	Power	Ground





Pin no	Pin name	Function	Description
15	P0.08	Digital I/O (SoC)	General purpose I/O
16	P0.09	Digital I/O (SoC)	General purpose I/O
17	GND	Power	Ground
18	P0.10	Digital I/O (SoC)	General purpose I/O
19	P0.11	Digital I/O (SoC)	General purpose I/O
20	P0.12	Digital I/O (SoC)	General purpose I/O
21	GND	Power	Ground
22	VDD2	Power	Supply voltage input
23	P0.13	Digital I/O (SoC)	General purpose I/O
	AIN0	Analog input	Analog input
24	P0.14	Digital I/O (SoC)	General purpose I/O
	AIN1	Analog input	Analog input
25	P0.15	Digital I/O (SoC)	General purpose I/O
	AIN2	Analog input	Analog input
26	P0.16	Digital I/O (SoC)	General purpose I/O
	AIN3	Analog input	Analog input
27	GND	Power	Ground
28	P0.17	Digital I/O (SoC)	General purpose I/O
	AIN4	Analog input	Analog input
29	P0.18	Digital I/O (SoC)	General purpose I/O
	AIN5	Analog input	Analog input
30	P0.19	Digital I/O (SoC)	General purpose I/O
	AIN6	Analog input	Analog input
31	GND	Power	Ground
32	nRESET	Digital I/O (SoC)	SoC reset pin ^{26,27}
33	SWDCLK	Digital input	Serial wire debug clock input for debug and programming
34	SWDIO	Digital I/O	Serial wire debug I/O for debug and programming
35	P0.20	Digital I/O (SoC)	General purpose I/O
	AIN7	Analog input	Analog input
36	GND	Power	Ground
37	P0.21	Digital I/O (SoC)	General purpose I/O
	TRACECLK	Trace clock	Trace buffer clock (optional)
38	P0.22	Digital I/O (SoC)	General purpose I/O
	TRACEDATA[0]	Trace data	Trace buffer TRACEDATA[0] (optional)
39	P0.23	Digital I/O (SoC)	General purpose I/O
	TRACEDATA[1]	Trace data	Trace buffer TRACEDATA[1] (optional)
40	P0.24	Digital I/O (SoC)	General purpose I/O
	TRACEDATA[2]	Trace data	Trace buffer TRACEDATA[2] (optional)
41	GND	Power	Ground
42	P0.25	Digital I/O (SoC)	General purpose I/O
	TRACEDATA[3]	Trace data	Trace buffer TRACEDATA[3] (optional)
43	SIM_RST	Digital I/O (SoC)	SIM reset
44	GND	Power	Ground
45	SIM_DET	Digital I/O (SoC)	SIM detect
			Not used. Must be left floating.
46	SIM_CLK	Digital I/O (SoC)	SIM clock
47	GND	Power	Ground
48	SIM_IO	Digital I/O (SoC)	SIM data
49	SIM_1V8	Power	SIM 1.8 V power supply output



External pull-up not allowed.
 For implementations that require the ERASEALL functionality, enable access to the nRESET pin. See Erase all on page 438 for more information.

Pin no	Pin name	Function	Description
50	GND	Power	Ground
51	RES		Do not connect/reserved for future use
52	GND	Power	Ground
53	MAGPIO2	Digital I/O (SoC)	1.8 V general purpose I/O
54	MAGPIO1	Digital I/O (SoC)	1.8 V general purpose I/O
55	MAGPIO0	Digital I/O (SoC)	1.8 V general purpose I/O
56	GND	Power	Ground
57	VIO	Power	MIPI RFFE control interface
58	SCLK	Digital I/O (SoC)	MIPI RFFE control interface
59	SDATA	Digital I/O (SoC)	MIPI RFFE control interface
60	GND	Power	Ground
61	ANT	RF	Single-ended 50 Ω LTE antenna pin
62	GND	Power	Ground
63	GND	Power	Ground
64	AUX	RF	Single-ended 50 Ω ANT loop-back pin
65	GND	Power	Ground
66	GND	Power	Ground
67	GPS	RF	Single-ended 50 Ω GPS input pin
68	GND	Power	Ground
69	GND	Power	Ground
70	RES		Do not connect/reserved for future use
71	RES		Do not connect/reserved for future use
72	GND	Power	Ground
73	RES		Do not connect/reserved for future use
74	GND	Power	Ground
75	GND	Power	Ground
76	GND	Power	Ground
77	GND	Power	Ground
78	GND	Power	Ground
79	GND	Power	Ground
80	GND	Power	Ground
81	GND	Power	Ground
82	GND	Power	Ground
83	P0.26	Digital I/O (SoC)	General purpose I/O
84	P0.27	Digital I/O (SoC)	General purpose I/O
85	GND	Power	Ground
86	P0.28	Digital I/O (SoC)	General purpose I/O
87	P0.29	Digital I/O (SoC)	General purpose I/O
88	P0.30	Digital I/O (SoC)	General purpose I/O
89	P0.31	Digital I/O (SoC)	General purpose I/O
90	GND	Power	Ground
91	COEX2	Digital I/O (SoC)	Coexistence interface
92	COEX1	Digital I/O (SoC)	Coexistence interface
93	COEXO	Digital I/O (SoC)	Coexistence interface
94	GND	Power	Ground
95	P0.00	Digital I/O (SoC)	General purpose I/O
96	P0.01	Digital I/O (SoC)	General purpose I/O
97	P0.02	Digital I/O (SoC)	General purpose I/O
98	GND	Power	Ground
99	P0.03	Digital I/O (SoC)	General purpose I/O
100	P0.04	Digital I/O (SoC)	General purpose I/O



Pin no	Pin name	Function	Description					
101	ENABLE		Enable for the SiP internal regulator for the nRF91 Soc					
			Note: The nRF91 will not start until this pin is enabled.					
102	VDD1	Power	Supply voltage					
103	GND	Power	Ground					
104-127	RES		Do not connect/reserved for future use					

Table 55: LGA pin assignments

11.2 Mechanical specifications

The mechanical specifications show the package dimensions in millimeters.

11.2.1 16.0 x 10.5 mm package

Dimensions in millimeters for the nRF9161 LGA 16.0 x 10.5 x 1.04 mm package.

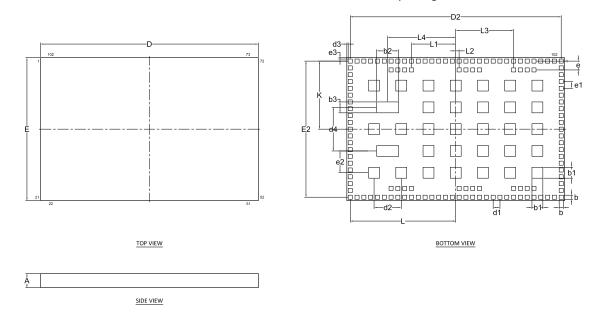


Figure 121: LGA 16.0 x 10.5 mm package

	Α	b	b1	D	E	е	d1	e1	D2	E2	b2	d2	e2	b3	d3	е3	d4	K	L	L1	L2	L3	L4
Min.	0.98			15.90	10.40	ı																	
Nom.	1.04	0.30	0.80	16.00	10.50	0.65	0.50	0.50	15.50	10.00	1.60	2.00	1.60	0.80	0.10	0.10	3.20	5.00	7.75	3.25	0.25	4.25	5.00
Max.	1.10			16.10	10.60	1																	

Table 56: LGA dimensions in millimeters

11.3 Reference circuitry

To ensure good RF performance when designing PCBs, using the PCB layouts and component values provided by Nordic Semiconductor is highly recommended .

Documentation for the different package reference circuits, including Altium Designer files, PCB layout files, and PCB production files can be downloaded from the product page at www.nordicsemi.com.

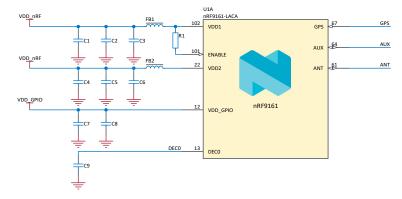


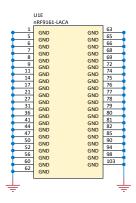
This section contains reference circuitry showing the components to support the design of on-chip features.

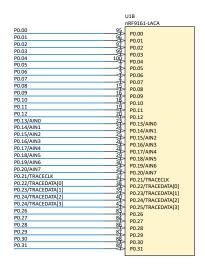
Note: This is not a complete list of configurations, but all required circuitry is shown for further configurations.

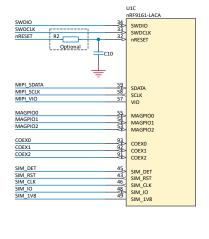
11.3.1 nRF9161 reference design

Circuit configuration schematic for the nRF9161 SiP.









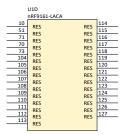


Figure 122: nRF9161 reference design

For Bill of Materials (BOM), PCB layout and thermal design, see the nRF9161 Hardware Design Guidelines.

11.4 Reflow conditions

The recommended reflow profile is JEDEC J-STD-020D. The maximum amount of reflows is three.

11.5 Shelf and floor life

If floor life is exceeded, see Shelf Life of Dry Packed Integrated Circuits for shelf and floor life and recommended baking (drying of parts) requirements.



12 Operating conditions

The operating conditions are the physical parameters that the chip can operate within.

Symbol	Parameter	Notes	Min.	Nom.	Max.	Units
VDD	Battery input voltage	Including voltage drop, ripple and spikes.	3.0	3.7	5.5	V
VDD_GPIO	GPIO input voltage		1.7		3.6	V
$GPIO_H$	GPIO high level voltage				VDD_GPIO	V
MAGPIO _H	MAGPIO high level voltage	Supply from internal LDO	1.7	1.8	1.9	V
VIO	VIO high level voltage	Supply from internal LDO	1.7	1.8	1.9	V
TA	Operating temperature		-40	25	85	°C
COEX	COEX high level voltage				VDD_GPIO	V
SIMIF	SIMIF output high level	Supply from internal LDO	1.7	1.8	1.9	V
	voltage					

Table 57: Operating conditions

Note: There can be excessive leakage at VDD and/or VDD_GPIO if any of these supply voltages is outside its range given in the table above.

Note: It is not recommended to use high voltage, high drive GPIO outputs ($V_{OH,HDH}$ and $V_{OH,HDL}$) with high frequency, high capacitance loads unless needed, as this may increase noise level and affect radio receiver performance. High drive/high load should especially be avoided on GPIO pins close to the radio front end.

12.1 VDD_GPIO considerations

VDD_GPIO is the supply to the general purpose I/O.

The following restrictions should be taken into considerations:

- VDD_GPIO should be applied after VDD has been supplied
- VDD GPIO should be removed before removing VDD
- If VDD is supplied and VDD_GPIO is grounded, an extra current consumption can be generated on VDD
- If ENABLE is low, VDD_GPIO should also be low



13 Absolute maximum ratings

Maximum ratings are the extreme limits to which the chip can be exposed for a limited amount of time without permanently damaging it. Exposure to absolute maximum ratings for prolonged periods of time may affect the reliability of the device.

	Note	Min.	Max.	Unit
Supply voltages				
VDD		-0.3	5.5 ²⁸	V
VDD_GPIO		-0.3	3.9	٧
SIM_1V8		1.65	1.95	V
VSS			0	V
I/O pin voltage				
$V_{I/O}$, $VDD_GPIO \le 3.6 V$		-0.3	VDD_GPIO + 0.3	V
$V_{I/O}$, VDD_GPIO > 3.6 V		-0.3	3.9	V
Radio				
ANT antenna input level			10	dBm
GPS antenna input level	LNA turned on, max gain		-15	dBm
RF port ruggedness	Maximum deviation from		10:1	VSWR
	50Ω without damaging the			
	module			
Environmental (LGA package)				
Storage temperature		-40	95	°C
MSL	Moisture Sensitivity Level		3	
ESD HBM	Human Body Model		1.5	kV
ESD HBM Class	Human Body Model Class		1C	
ESD CDM	Charged Device Model		250	V
Flash memory				
Endurance		10 000		Write/erase cycles
Retention		10 years at 85°C		
ATEX compliance				
Ci			83	μF
Li			9.0	μН
Ui			5.0	V
li			600	mA

Table 58: Absolute maximum ratings

No internal voltage boost converters

4510_057 v1.0

456 NORDIC

²⁸ ATEX compliance requires a maximum of 5.0 V.

14 Ordering information

This chapter contains information on IC marking, ordering codes, and container sizes.

14.1 SiP marking

The nRF9161 package is marked as shown in the following figure.

n	R	F	9	1	6	1	<l< th=""><th>A></th><th><c< th=""><th>A></th><th><h></h></th><th><p></p></th></c<></th></l<>	A>	<c< th=""><th>A></th><th><h></h></th><th><p></p></th></c<>	A>	<h></h>	<p></p>
							<y< th=""><th>Y></th><th><w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<></th></y<>	Y>	<w< th=""><th>W></th><th><l< th=""><th>L></th></l<></th></w<>	W>	<l< th=""><th>L></th></l<>	L>

Figure 123: SiP package marking

14.2 Box labels

The following figures show the box labels used for the nRF9161.



Figure 124: Inner box label



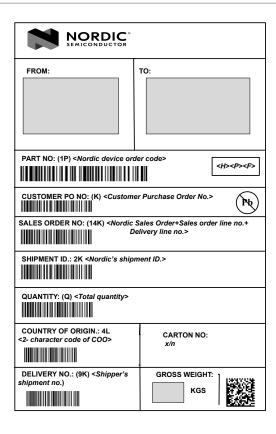


Figure 125: Outer box label

14.3 Order code

The following are the order codes and definitions for the nRF9161.



Figure 126: Order code



Abbreviation	Definition and implemented codes
N91/nRF91	nRF91 Series product
61	Part code
<la></la>	Package variant code
<ca></ca>	Function variant code
<h><p><f></f></p></h>	Build code H - Hardware version code P - Production configuration code (production site, etc.) F - Firmware version code (only visible on shipping container label)
<yy><ww><ll></ll></ww></yy>	Tracking code YY - Year code WW - Assembly week number LL - Wafer lot code
<cc></cc>	Container code

Table 59: Abbreviations

14.4 Code ranges and values

The nRF9161 code ranges and values are defined here.

<h>></h>	Description
[A Z]	Hardware version/revision identifier (incremental)

Table 60: Hardware version codes

<p></p>	Description
[09]	Production device identifier (incremental)
[A Z]	Engineering device identifier (incremental)

Table 61: Production configuration codes

<f></f>	Description
[A N, P Z]	Version of preprogrammed firmware
[0]	Delivered without preprogrammed firmware

Table 62: Production version codes



<yy></yy>	Description
[23 99]	Production year: 2023 to 2099

Table 63: Year codes

<ww></ww>	Description
[0152]	Week of production

Table 64: Week codes

<ll></ll>	Description
[AA ZZ]	Wafer production lot identifier

Table 65: Lot codes

<cc></cc>	Description
R7	7" Reel
R	13" Reel

Table 66: Container codes

14.5 Ordering options

The nRF9161 SiP ordering codes and minimum ordering quantity are described in the following table.

Order code	Minimum ordering quantity (MOQ)	Comment
nRF9161-LACA-R	2500	
nRF9161-LACA-R7	100	

Table 67: nRF9161 order codes



15 Regulatory information

The nRF9161 undergoes regulatory certifications, ensuring both regional compliances and compatibility with the LTE 3GPP specification.

15.1 Certified bands

The following table shows the FCC and ISED certified Cat-M1 bands for nRF9161.

Band	FCC certification	ISED certification
Band 2	Yes	Yes
Band 4	Yes	Yes
Band 5	Yes	Yes
Band 8	Yes	Yes
Band 12	Yes	Yes
Band 13	Yes	Yes
Band 25	Yes	Yes
Band 26	Yes	No
Band 66	Yes	Yes
Band 85	Yes	Yes

Table 68: FCC and ISED certified Cat-M1 bands

The following table shows the FCC and ISED certified Cat-NB1 and Cat-NB2 bands for nRF9161.



Band	FCC certification	ISED certification
Band 2	Yes	Yes
Band 4	Yes	Yes
Band 5	Yes	Yes
Band 8	Yes	Yes
Band 12	Yes	Yes
Band 13	Yes	Yes
Band 17	Yes	Yes
Band 25	Yes	Yes
Band 26	Yes	No
Band 66	Yes	Yes
Band 85	Yes	Yes

Table 69: FCC and ISED certified Cat-NB1/NB2 bands

15.2 Supported FCC/ISED rules

The nRF9161 module has been certified to comply with FCC and ISED rules.

The nRF9161 SiP has been certified to comply with the following FCC rules.

- 47 CFR Part 22
- 47 CFR Part 24
- 47 CFR Part 27
- 47 CFR Part 90
- 47 CFR Part 2.1091

The nRF9161 SiP has been certified to comply with the following ISED rules.

- RSS-132 Issue 4
- RSS-130 Issue 2
- RSS-139 Issue 4
- RSS-133 Issue 6

A host manufacturer who integrates the nRF9161 SiP to a host device, can apply the certifications to the host device, except for FCC Part 15 Subpart B which must be retested.

The host manufacturer can use nRF9161's FCC ID if the device meets the conditions of the FCC certificate. Normally, the conditions are the following:

- A minimum of 20 cm distance from the human body.
- No colocation with other transmitters. Typically, this condition needs to be reviewed by the FCC lab.
- Antenna gain below the requirements.

15.3 FCC/ISED regulatory notices

FCC/ISED regulatory notices cover modification and interference statements, wireless and FCC Class B digital device notices, permitted antennas and labeling requirements.



Modification statement

Nordic Semiconductor has not approved any changes or modifications to this device by the user. Any changes or modifications could void the user's authority to operate the equipment.

Nordic Semiconductor n'approuve aucune modification apportée à l'appareil par l'utilisateur, quelle qu'en soit la nature. Tout changement ou modification peuvent annuler le droit d'utilisation de l'appareil par l'utilisateur.

Interference statement

This device complies with Part 15 of the FCC Rules and Industry Canada's licence-exempt RSS standards. Operation is subject to the following two conditions: (1) this device may not cause interference, and (2) this device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes: (1) l'appareil ne doit pas produire de brouillage, et (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

Wireless notice

This equipment complies with FCC and ISED radiation exposure limits set forth for an uncontrolled environment. The antenna should be installed and operated with minimum distance of 20 cm between the radiator and your body. This transmitter must not be co-located or operating in conjunction with any other antenna or transmitter.

Cet appareil est conforme aux limites d'exposition aux rayonnements de l'ISDE pour un environnement non contrôlé. L'antenne doit être installée de façon à garder une distance minimale de 20 centimètres entre la source de rayonnements et votre corps. L'émetteur ne doit pas être colocalisé ni fonctionner conjointement avec à autre antenne ou autre émetteur.

Permitted antenna

This radio transmitter has been approved by FCC and ISED to operate with the antenna types listed below with the maximum permissible gain indicated. Antenna types not included in this list, having a gain greater than the maximum gain indicated for that type, are strictly prohibited for use with this device.



Band	Max gain
Band 2	9.0 dBi
Band 4	6.0 dBi
Band 5	7.1 dBi
Band 8	7.5 dBi
Band 12	6.6 dBi
Band 13	6.9 dBi
Band 17 (Cat-NB1/NB2)	6.6 dBi
Band 25	9.0 dBi
Band 26	7.0 dBi
Band 66	6.0 dBi
Band 85	6.6 dBi

Le présent émetteur radio a été approuvé par ISDE pour fonctionner avec les types d'antenne énumérés ci dessous et ayant un gain admissible maximal. Les types d'antenne non inclus dans cette liste, et dont le gain est supérieur au gain maximal indiqué, sont strictement interdits pour l'exploitation de l'émetteur.

Bande	Gain maximal
Bande 2	9.0 dBi
Bande 4	6.0 dBi
Bande 5	7.1 dBi
Band 8	7.5 dBi
Bande 12	6.6 dBi
Bande 13	6.9 dBi
Bande 17 (Cat-NB1/NB2)	6.6 dBi
Bande 25	9.0 dBi
Bande 26	7.0 dBi
Bande 66	6.0 dBi
Bande 85	6.6 dBi

FCC Class B digital device notice

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

• Reorient or relocate the receiving antenna

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- · Increase the separation between the equipment and receiver
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected
- Consult the dealer or an experienced radio/TV technician for help

CAN ICES-3 (B)/NMB-3 (B)

This Class B digital apparatus complies with Canadian ICES-003.

Cet appareil numérique de classe B est conforme à la norme canadienne ICES-003.

Labeling requirements for the host device

The host device shall be properly labelled to identify the modules within the host device. The certification label of the module shall be clearly visible at all times when installed in the host device, otherwise the host device must be labelled to display the FCC ID and IC of the module, preceded by the words "Contains transmitter module", or the word "Contains", or similar wording expressing the same meaning, as shown in the following examples:

Contains FCC ID: 2ANPO00NRF9161

Contains IC: 24529-NRF9161

L'équipement hôte doit être correctement étiqueté pour identifier les modules dans l'équipement. L'étiquette de certification du module doit être clairement visible en tout temps lorsqu'il est installé dans l'hôte, l'équipement hôte doit être étiqueté pour afficher le FCC ID et IC du module, précédé des mots "Contient le module émetteur", ou le mot "Contient", ou un libellé similaire exprimant la même signification, comme suit:

Contient FCC ID: 2ANPO00NRF9161 Contient IC: 24529-NRF9161

15.4 RF exposure considerations

The nRF9161 has been tested and certified as a mobile device for use of a minimum of 20 cm distance from the human body with no colocation with other transmitters. If the device is to be used closer than 20 cm from the human body and/or with other transmiters simultaneously, the host product manufacturer is required to perform additional evaluation, testing, or testing and Class 2 permissive change. It is required to take responsibility of the module through a change in the FCC ID (new application). The host product manufacturer must also inform the end user about RF Exposure conditions.

15.5 Host device manufacturer responsibility

The nRF9161 device is only authorized for the rules listed in Supported FCC/ISED rules on page 462. The host device manufacturer is responsible for compliance to any other FCC rules that apply to the host device not covered by the nRF9161 grant of certification. It is mandatory for the host device manufacturer to assure the final device's compliance with FCC Part 15 Subpart B even if certification has been granted to nRF9161.

15.6 Antenna interface

The nRF9161 module has a single-ended 50 Ω antenna port where the antenna solution shall be connected. nRF9161 is evaluated with a 50 Ω antenna load. To ensure good overall RF performance,

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antenna impedance and the characteristic impedance of the transmission line (i.e. cable) connecting the antenna and antenna port must be $50~\Omega$. Impedance mismatch may lead to performance degradation. Maximum antenna VSWR 2:1 is recommended but VSWR 3:1 can still be accepted in the final device. Respective minimum return loss values are 9.5 dB and 6.0 dB.

The length of the transmission line from the antenna to the nRF9161 antenna port should be kept as short as possible to minimize losses, as this loss is directly deteriorating the module's transmitted and received power. Additionally, low-loss matching circuit between the antenna and the nRF9161 antenna port is recommended to minimize loss caused by antenna and PCB routing mismatch. Reserving space from device manufacturer's application board for matching components (e.g. π -circuit) is recommended. This is because, for example, catalog antennas are typically tuned on reference board and differences to device mechanics may impact antenna impedance. It is also possible that device mechanics change during the development phase of the final device, and these modifications may impact antenna performance. Matching components can be used to compensate the impact of mechanics change to antenna impedance, and thus it may not be mandatory to modify the antenna itself.

The nRF9161 module has an internal ESD circuit in the antenna port, but additional ESD components at device manufacturer's application board may be used. The design of the ESD circuit shall be such that the impact on RF frequencies is negligible

Note: ESD filtering may be necessary for some active components that can be used at antenna path. Such components can be, for example, RF switches and antenna tuners. For further ESD requirements, see the RF switch and antenna tuner datasheets.

15.7 Antenna port test connector

To run conductive RF tests, a test connector nearby the nRF9161 antenna port in the RF transmission line is needed. The 50 Ω impedance requirement applies also to the test connector, and VSWR and insertion loss should be minimal. Regardless of whether the nRF9161 antenna port is connected to an actual antenna or test equipment, the load at the nRF9161 antenna should remain as close to 50 Ω as possible.

For a test connector, microwave coaxial switch connectors (for example, Murata MM8130-2600) are a good choice for this purpose. For conductive tests, a test cable is plugged in which connects the nRF9161 antenna port to the test equipment instead of the antenna. When the test cable is plugged off, the nRF9161 antenna port is connected to the antenna for real use case or radiated testing. The layout for the connector must be carefully designed to fulfil the 50 Ω requirement. For detailed guidance on this, see the coaxial switch connectors datasheets.



16 Legal notices

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