

Introduction to nRF Connect SDK

Cellular IoT made easy

Webinar

Nordic Semiconductor

September 2019

Duration: approx 45 mins

Today's host

Bjørn Kvaale

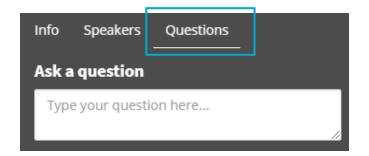


Product Marketing
Engineer

- Master of Science degree in Engineering Cybernetics & Robotics from the Norwegian University of Science & Technology
- Two years of experience working in the tech support group at Nordic
 - Focusing on SW related support cases, with a major focus on Bluetooth mesh & the nRF91 Series.

This webinar

- Duration: 45 mins.
- Questions are encouraged!
 Please type your question in the
 Questions tab on the right sidebar.
- All questions are anonymously posted.
- We will do our best to answer all questions at the end of the webinar
- We will share a Q&A after the webinar with updated answers if necessary



Content

- What is nRF Connect SDK
- RTOS Intro
- Setting Up & Configuring nRF Connect SDK
- Overview of what is included in nRF Connect Platform

What is nRF Connect SDK?

- Software development kit for the nRF9160
- Integrates the Zephyr RTOS
- Publicly hosted on GitHub
 - version control management with Git
- Free SEGGER Embedded Studio support
- Support for Desktop & Cloud apps

Nordic Application Frameworks & Reference Designs

Zephyr kernel & middleware

IP protocols CoAP, HTTP, MQTT, LWM2M System

Memory mng. DFU File systems

Nordic Low Layer FW

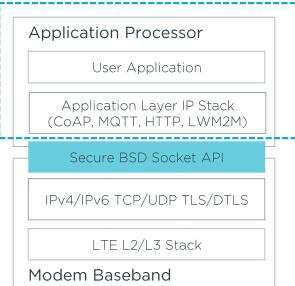
Root of Trust bootloader & secure domain arch.

MAC layers: BSD, Bluetooth LE, 802.15.4, Zigbee,Thread

Drivers inc. NFC, Crypto, SPI, UART, USB

Software architecture

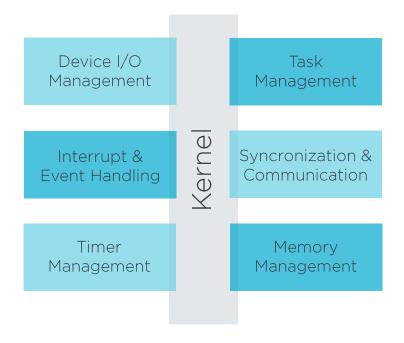
nRF Connect SDK



- Complete and easy to use solution
- Connectivity and application software
- Support for OTA Modem and Application updates
- Reference design with multiple sensors
- Support for "thin modem" operation

What is an RTOS?

- Real Time Operating System
 - Goal is to ensure predictable/deterministic execution pattern
 - Embedded systems often have strict timing requirements
 - Scheduler decides which task to execute at which time
 - Achievable by setting a priority for each execution thread



Why use an open source RTOS?

Trend towards open RTOS for MCUs in IoT

- Greater number of open standards in applications
 - Vendor implementations not necessarily better, just different
- Free use & distribution
 - The price is right
- Security & stability for IoT devices
 - Proven success: open review, open information sharing
- 3rd-party expertise develop around open source







Why the Zephyr RTOS?

- Zephyr designed & built for low power wireless
- Zephyr is independent
 - Linux Foundation Project
- Zephyr is scalable
 - Very small configurations for memory constrained devices (< 8 kB)
 - Powerful, feature-rich, configurations for large memory, high-processing power devices
- Zephyr includes popular IP standards
 - Nordic can focus on other important features



Zephyr Project Members

Nordic a member & contributor since 2016

- We will continue to work with Zephyr
- -> ensure best in class features & performance











Silver Members















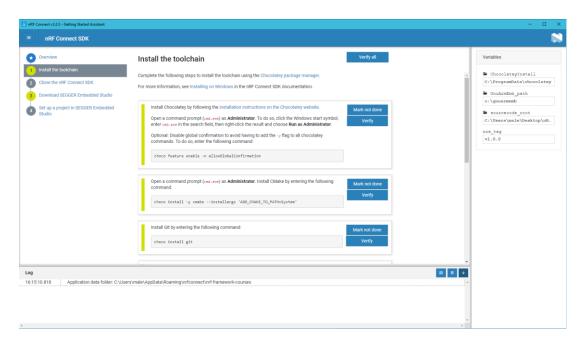


- Hosted on GitHub, supported by git version control & west
 - West is a command line tool for programming & flashing, provides multiple repository management support
 - All code pre-integrated in one SDK
- Can fork nRF Connect SDK code & contribute to the SDK
- Allows syncing of nRF Connect SDK code for use in private repos
- Setup the toolchain & download the SDK version using nRF Connect for Desktop "Getting Started Assistant" app









- nRF Connect for Desktop
- nRF Getting Started
 Assistant app
- Platform dependent guides
- Windows, macOS, Linux

Configure, build & debug with Segger Embedded Studio

- Select which SDK features to auto-include
- Add your code
- Add configurations for your product PCB

Four main repositories:

- nRF Connect SDK
- nrfxlib, Zephyr, MCUboot
 - Fork nRF repo into own branch
 - Update nRF repo using git
 - Update project repos using west

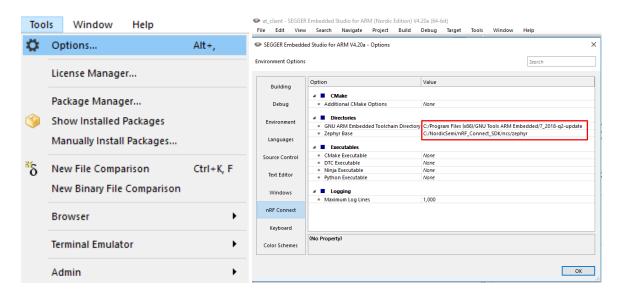


nRF Connect SDK

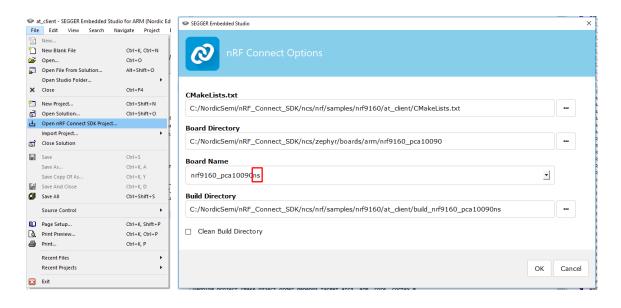
nrfxlib

Zephyr

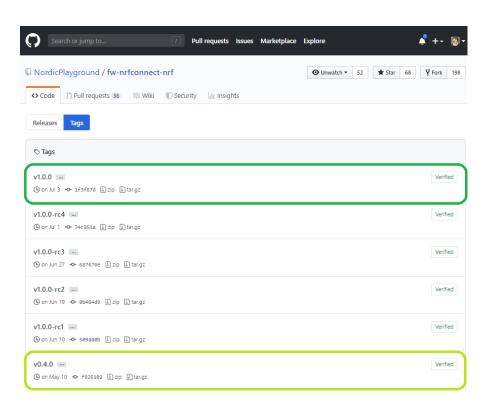
MCUboot



- Open SeggerEmbedded Studio
- Set GNU ARM Embedded Toolchain directory
- Use v7-2018-q2!
- Set Zephyr Base repository



- Setting up the asset tracker example in nRF Connect SDK
- Using the v1.0.0 tag
- Use the non-secure board name for application



- Start with a tagged release to ensure higher quality assurance
- https://github.com/NordicPlay ground/fw-nrfconnectnrf/tags
- Additional documentation
- https://developer.nordicsemi.c om/nRF_Connect_SDK/doc/l atest/nrf/getting_started.html

Project Configuration

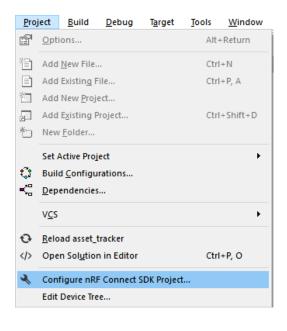
Current SES release: v4.20a

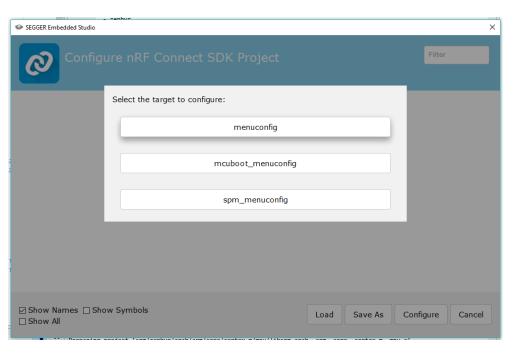
Project configuration is controlled through Kconfig and DTS

To configure project:
 Project -> 'Configure nRF Connect SDK Project' (menuconfig)

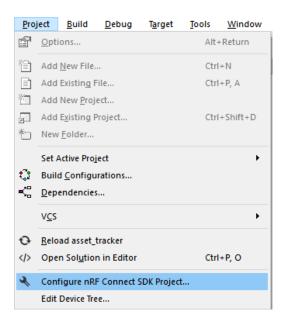
To configure Device Tree:
 Project -> 'Edit Device Tree'

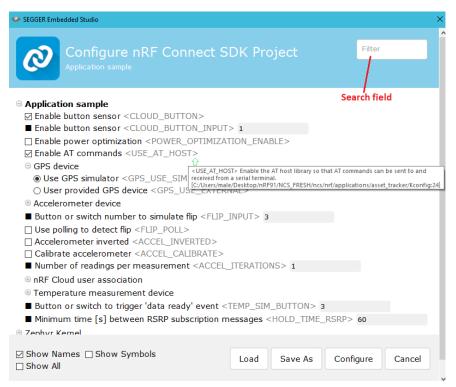
Configuring an nRF Connect SDK project



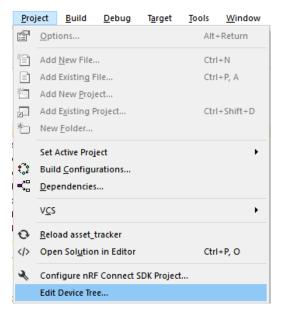


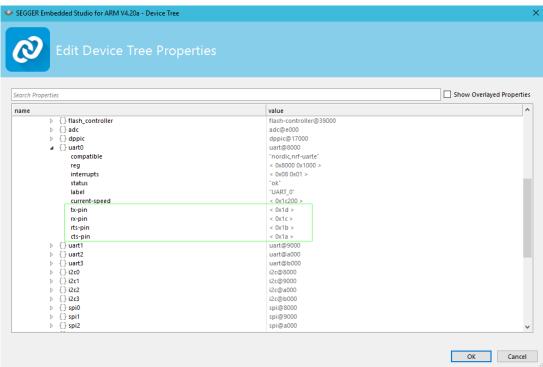
Configuring an nRF Connect SDK project



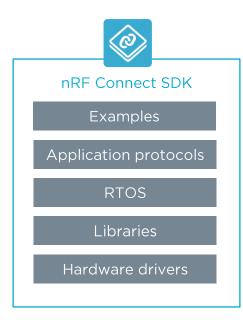


Configuring an nRF Connect SDK project







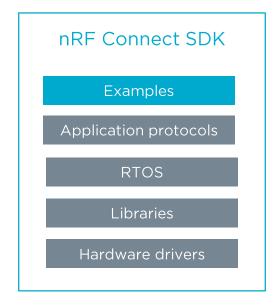






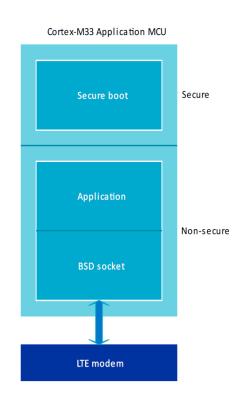
nRF Connect SDK

- Asset tracker
- LTE sensor gateway
- AT client
- Simple MQTT
- nRF CoAP Client
- LwM2M Client
- HTTP Application Update
- AWS FOTA sample
- Secure Services Sample
- Secure Partition Manager (SPM)



nRF9160: Secure Partition Manager

- Configures SPU & then jumps to application
 - SPU: system protection unit
 - No DFU
- Secure: CPU thinks the executed code is secure
 - Arm CryptoCell
 - Not restricted
- Non-secure: CPU thinks the executed code is NOT secure
 - Restricted
 - Modem only works in this mode



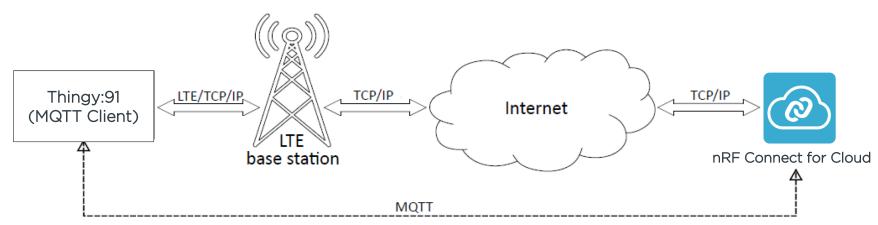
nRF9160: Secure Partition Manager

- SPM sets security of all user peripherals & GPIOs to non-secure
- Peripherals need to be non-secure in order for application to use them
 - Application runs in non-secure domain

```
static void spm config peripherals(void)
        struct periph cfg {
#ifndef CONFIG SPM BOOT SILENTLY
                char *name;
#endif
                u8 t id;
                u8_t nonsecure;
        /* - All user peripherals are allocated to the Non-Secure domain.
         * - All GPIOs are allocated to the Non-Secure domain.
        static const struct periph_cfg periph[] = {
               PERIPH("NRF PO", NRF PO, CONFIG SPM NRF PO NS),
               PERIPH("NRF_CLOCK", NRF_CLOCK, CONFIG_SPM_NRF_CLOCK_NS),
               PERIPH("NRF_RTC1", NRF_RTC1, CONFIG_SPM_NRF_RTC1_NS),
               PERIPH("NRF NVMC", NRF NVMC, CONFIG SPM NRF NVMC NS),
               PERIPH("NRF UARTE1", NRF UARTE1, CONFIG SPM NRF UARTE1 NS),
               PERIPH("NRF_UARTE2", NRF_UARTE2, CONFIG_SPM_NRF_UARTE2_NS),
               /* There is no DTS node for the peripherals below,
                 * so address them using nrfx macros directly.
               PERIPH("NRF_IPC", NRF_IPC_S, CONFIG_SPM_NRF_IPC_NS),
               PERIPH("NRF_VMC", NRF_VMC_S, CONFIG_SPM_NRF_VMC_NS),
               PERIPH("NRF_FPU", NRF_FPU_S, CONFIG_SPM_NRF_FPU_NS),
               PERIPH("NRF EGU1", NRF EGU1 S, CONFIG SPM NRF EGU1 NS),
               PERIPH("NRF_EGU2", NRF_EGU2_S, CONFIG_SPM_NRF_EGU2_NS),
               PERIPH("NRF TWIM2", NRF TWIM2 S, CONFIG SPM NRF TWIM2 NS),
               PERIPH("NRF_SPIM3", NRF_SPIM3_S, CONFIG_SPM_NRF_SPIM3_NS),
               PERIPH("NRF TIMERO", NRF TIMERO S, CONFIG SPM NRF TIMERO NS),
               PERIPH("NRF TIMER1", NRF TIMER1 S, CONFIG SPM NRF TIMER1 NS),
               PERIPH("NRF_TIMER2", NRF_TIMER2_S, CONFIG_SPM_NRF_TIMER2_NS),
               PERIPH("NRF SAADC", NRF SAADC S, CONFIG SPM NRF SAADC NS),
               PERIPH("NRF GPIOTE1", NRF GPIOTE1 NS,
                                      CONFIG SPM NRF GPIOTE1 NS),
        PRINT("Peripheral\t\tDomain\t\tStatus\n");
        if (IS ENABLED(CONFIG SPM NRF P0 NS)) {
                /* Configure GPIO pins to be Non-Secure */
               NRF SPU->GPIOPORT[0].PERM = 0;
        for (size t i = 0: i < ARRAY SIZE(periph): i++) {
```

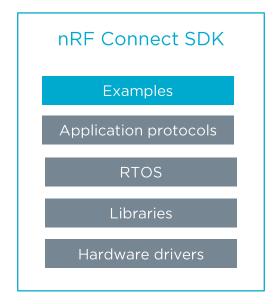
nRF9160: Asset Tracker

- Sends real GPS coordinates, accelerometer, temperature, humidity & air pressure data to nRF Connect for Cloud
- Source code for connecting to server



nRF Connect SDK

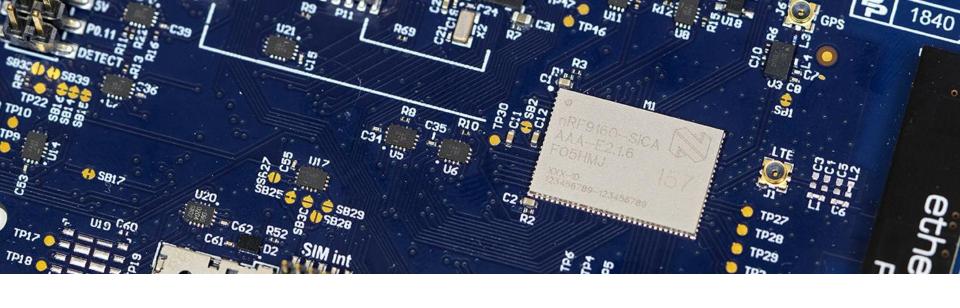
- Application protocols
 - MQTT
 - CoAP
 - HTTP
 - LwM2M
- Zephyr RTOS
- Libraries
 - MCUboot secure bootloader
- Hardware drivers are available through nrfxlib
 - DPPI, GPIO, GPIOTE, I2S, PDM, SAADC, TIMER, UARTE, WDT, etc



nRF Connect for Cloud



- Examples
- Asset tracker displays GPS coordinates on map and switch state
- LTE sensor gateway displays sensor data
- nRF9160 DK management
- SIM card activation



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Demo

Q&A