

BEFORE

ble_app_blinky_c_pca10056_s140 - SEGGER Embedded Studio for ARM V4.52c (64-bit) - Licensed to Ashok ra - Embedded Club (Stopped)

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Disassembly

main.c sdk_config.h nrf_pwm.h app_error_weak.c nrfx_pwm.c nrfx_pwm.h app_error_handler_gcc.c apply_old_config.h nrfx_prs.c

```

20001E38 .word 0x20001E38
main.c — 576
static void app_pwm_init(void)
{
    B500      push {lr}
    B085      sub sp, sp, #20
main.c — 586
* a way that increase and decrease
* continuously on succeeding chanr
*/
nrf_drv_pwm_config_t const config0 = {
    4A10      ldr r2, =0x00034D00
    AB01      add r3, sp, #4
    CA07      ldm r2, {r0-r2}
    E8830007  stm r3, {r0-r2}
main.c — 603
    .load_mode = NRF_PWM_LOAD_INDIVIDUAL,
    .step_mode = NRF_PWM_STEP_AUTO
};
//APP_ERROR_CHECK(
nrf_drv_pwm_init(&m_pwm0, &config0);
AB01      add r3, sp, #4
4A0F      ldr r2, =0x0003000F

```

Watch 1

Never	x ₂ x ₈ x ₁₀ x ₁₆ x ₁₀ [±] 'x'	Value
m_pwm0	p_registers	<struct> 0x4001c000
	drv_inst_idx	0x00
config0	output_pins	<struct> \23\377\377
	[0]	0x9b
	[1]	0xff
	[2]	0xff
	[3]	0xff
	irq_priority	0x07
	base_clock	NRF_PWM_CLK_1MHz
	count_mode	NRF_PWM_MODE_UP
	top_value	0xcf85
	load_mode	NRF_PWM_LOAD_INDIVIDUAL
	step_mode	NRF_PWM_STEP_AUTO

AFTER

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Disassembly

app_error_fault_handler + 0:

main.c sdk_config.h nrf_pwm.h app_error_weak.c nrfx_pwm.c nrfx_pwm.h app_error_handler_gcc.c apply_old_config.h nrfx_prs.c

```

0028E10 4B1E      ldr r3, =0x000338E0
0028E12 1A13      subs r3, r2, r3
0028E24 08DB      lsrs r3, r3, #3
0028E26 041B      lsls r3, r3, #16
0028E28 F0430301  orr r3, r3, #1
0028E2C 9A06      ldr r2, [sp, #24]
0028E2E 4911      ldr r1, =0x00033D00
0028E30 4618      mov r0, r3
0028E32 F7FEFFC7  b1 0x00027DC4 <nrfx_pwm.h>
app_error_weak.c — 96
break;
BF00      nop
app_error_weak.c — 97
}
#endif
NRF_BREAKPOINT_COND;
4B0F      ldr r3, =0xE000EDF0
681B      ldr r3, [r3]
F0030301 and r3, r3, #1
2B00      cmp r3, #0
D000      beq 0x00028E46
BE00      bkpt #0
app_error_weak.c — 103
#endif // DEBUG
NRF_LOG_WARNING("System reset");
NVIC_SystemReset();
else
app_error_save_and_stop(id, pc, info);
#endif // DEBUG
}
110 /*lint -restore */

```

Watch 1

Never	x ₂ x ₈ x ₁₀ x ₁₆ x ₁₀ [±] 'x'	Value
m_pwm0	p_registers	<struct> 0x4001c000
	drv_inst_idx	0x00
config0	output_pins	<struct> \360\021
	[0]	0xf0
	[1]	0x11
	[2]	0x00
	[3]	0x20
	irq_priority	0x6b
	base_clock	NRF_PWM_CLK_16MHz
	count_mode	NRF_PWM_MODE_UP
	top_value	0x7edf
	load_mode	0x84
	step_mode	0x2b